### BIOS 7747: Machine Learning for Biomedical Applications

Supervised learning: regression

Antonio R. Porras (antonio.porras@cuanschutz.edu)

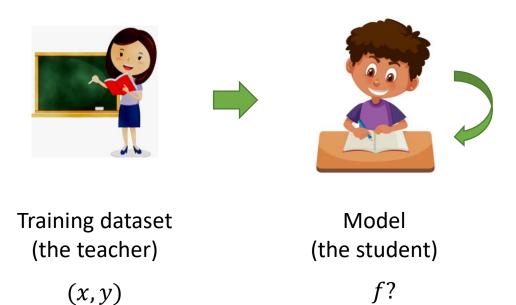
Department of Biostatistics and Informatics
Colorado School of Public Health
University of Colorado Anschutz Medical Campus

### Outline

- Supervised learning: regression
- □ Gradient descent optimization to solve regression problems
- Linear regression
- Need for non-linear regression models with examples

### Supervised learning

- Supervised learning
  - Learning from a dataset with known labels or outcomes
- Assumptions
  - The training dataset contains the "right" answers.
  - The right answers can be obtained from the available data



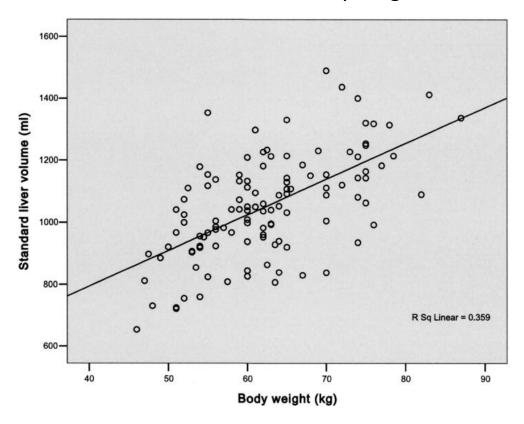
### Supervised learning: Regression

- What is a (mathematical) model?
  - Set of variables and their relationships expressed using a mathematical language (equations)
    - Variables: known (input variables or features) vs. predicted (output variables or predictions)
    - Relationships: linear vs. non-linear

- Regression models predict continuous variables
  - Note: known or input variables are not necessarily continuous.

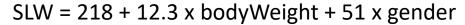
■ Example: standard liver volume for transplantation (SLW)

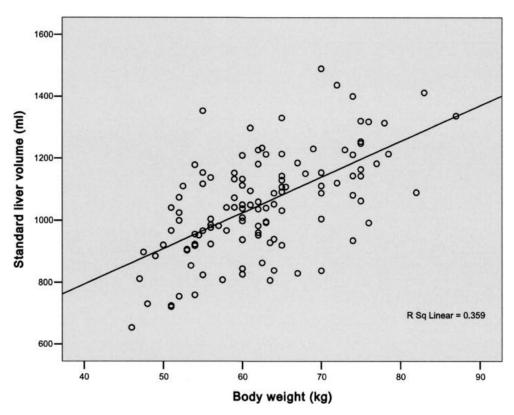
$$SLW = 218 + 12.3 \times bodyWeight$$



- How do we define a regression model?
  - Which are the input variables?
     Input variable: x
  - What is the predicted variable? Output variable: *y*
  - What types of relationship are there between variables?
     A hypothesis about relationships between variables is needed: f
     Most common: relationships are linear and variables are independent
  - Example of linear regression with a single variable:  $f(x) = \theta_o + \theta_1 x$ 
    - Parameters:  $\boldsymbol{\theta} = \{\theta_0, \theta_1\}$
  - Example of linear regression with multiple variables:  $f(x) = \theta_0 + \theta_1 x_0 + \theta_2 x_1 + \dots + \theta_M x_{M-1}$ 
    - M independent variables:  $\mathbf{x} = \{x_0, \dots, x_{M-1}\}$
    - M+1 parameters:  $\boldsymbol{\theta} = \{\theta_0, ..., \theta_{M+1}\}$
    - Linear regression for M independent variables:  $f(x) = \theta_0 + \sum_{p=0}^{M-1} \theta_{p+1} x_p$

■ Example: standard liver volume for transplantation (SLW)





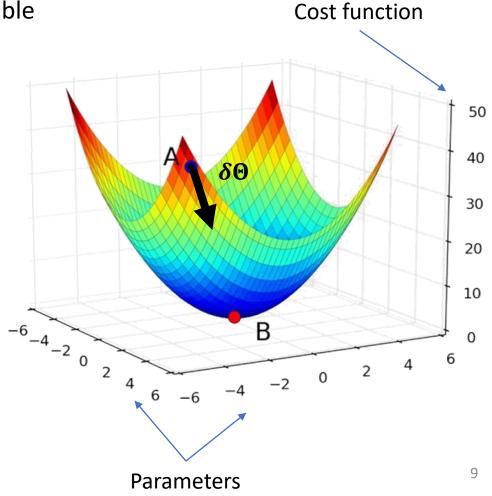
- How do we train a regression model?
  - Training dataset
    - Notation:
      - *N*: number of training samples
      - *M*: number of independent variables (features)
      - Training sample pair: (x, y)
      - Training sample with index  $i: (x^{(i)}, y^{(i)})$
  - Learning goal:  $f(x) \rightarrow y$ ?
    - We know (x, y) for the training dataset, how do we estimate  $\hat{y} = f(x)$  for new samples?
    - We hypothesize that  $f(x) \approx y$  in the training dataset [Assumption!!]
    - Model parameters:  $\theta = \arg\min \sum_{i=0}^{N-1} (f(\mathbf{x}^{(i)}; \boldsymbol{\theta}) y^{(i)})^2$ Cost function  $J(\boldsymbol{\theta})$

- How do we train a regression model?
  - Exhaustive parameter search is normally not feasible
  - Gradient descent optimization
    - 1. Set an initial value for  $oldsymbol{ heta}$ 
      - Based on prior hypothesis
      - $\theta_0 = \vec{0}$  is common when no prior hypotheses
    - 2. Do until convergence:

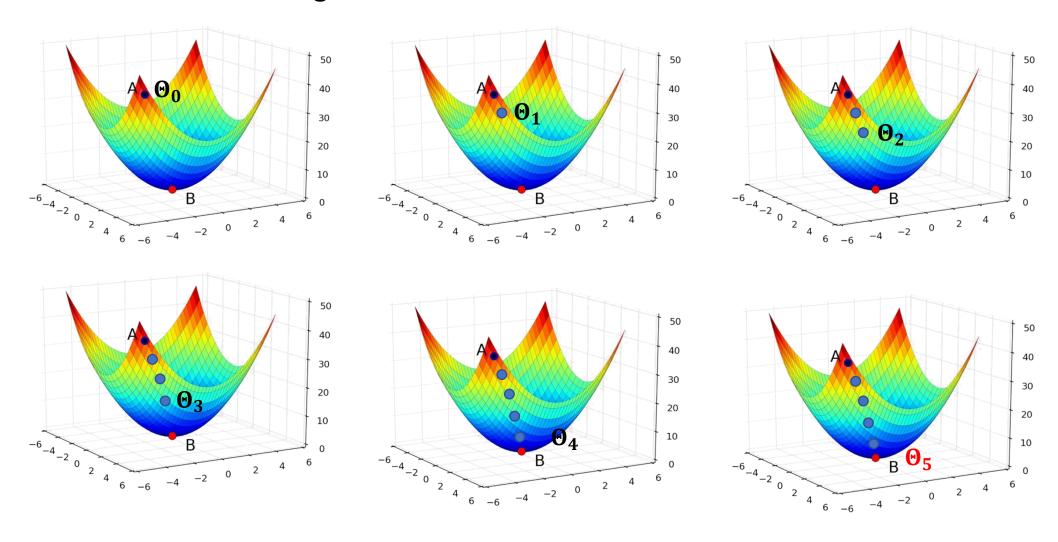
• 
$$\theta_{t+1} = \theta_t + \delta\theta_t$$
 so  $J(\theta_{t+1}) < J(\theta_t)$ 

#### Step:

- Direction
- Magnitude



### ■ Gradient descent algorithm

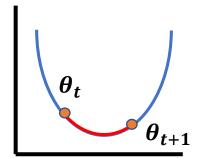


- □ Gradient descent algorithm: steps
  - $\frac{\partial}{\partial \Theta_t} J(\Theta_t)$  provides the direction and magnitude of change, but the magnitude converges to zero as the parameters approach their optimal value.
  - Introduction of a <u>learning rate</u>:

$$\theta_{t+1} = \theta_t + \delta\theta_t = \theta_t - \alpha \frac{\partial}{\partial \theta_t} J(\theta_t)$$

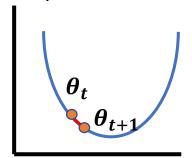
#### Large steps:

- Fewer iterations to converge
- May never reach optimal solution



#### Small steps:

- More iterations to converge
- Often gets closer to optimal solution (in convex problems)



Note: In non-linear, non-convex regression problems, small steps will be more likely to get caught in local minima. But large steps may get lost in the parameter space and produce unstable behaviors

Gradient descent algorithm: updating parameters

$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t - \alpha \frac{\partial}{\partial \boldsymbol{\theta}_t} J(\boldsymbol{\theta}_t)$$
 
$$\sum_{i=0}^{N-1} (f(\boldsymbol{x}^{(i)}; \boldsymbol{\theta}) - y^{(i)})^2$$

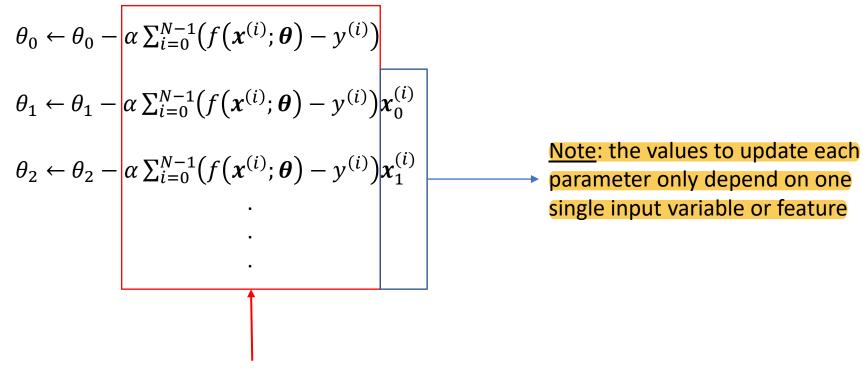
$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t - \alpha \left( 2 \sum_{i=0}^{N-1} (f(\boldsymbol{x}^{(i)}; \boldsymbol{\theta}) - y^{(i)}) \frac{\partial}{\partial \boldsymbol{\theta}_t} f(\boldsymbol{x}^{(i)}; \boldsymbol{\theta}) \right)$$

where 
$$f(\mathbf{x}; \mathbf{\Theta}) = \theta_o + \theta_1 x_0 + \theta_2 x_1 + \dots + \theta_M x_{M-1}$$

• In practice, we define the cost function as  $J(\mathbf{\Theta}) = \frac{1}{2} \sum_{i=0}^{N-1} (f(\mathbf{x}^{(i)}; \mathbf{\Theta}) - y^{(i)})^2$  to eliminate the constant in the derivation:

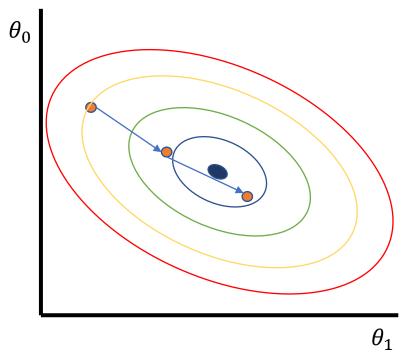
$$\boldsymbol{\theta}_{t+1} = \boldsymbol{\theta}_t - \alpha \sum_{i=0}^{N-1} (f(\boldsymbol{x}^{(i)}; \boldsymbol{\theta}) - y^{(i)}) \frac{\partial}{\partial \boldsymbol{\theta}_t} f(\boldsymbol{x}^{(i)}; \boldsymbol{\theta})$$

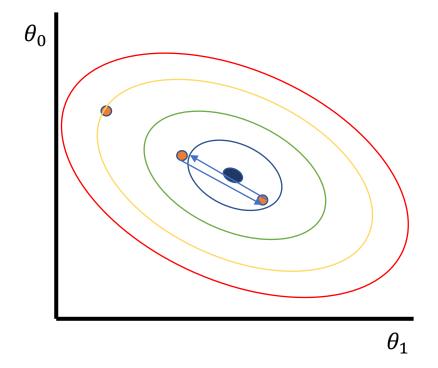
Gradient descent algorithm: updating parameters



Note: only need to be calculated once!

□ Gradient descent algorithm: when to stop?





#### Stop criteria:

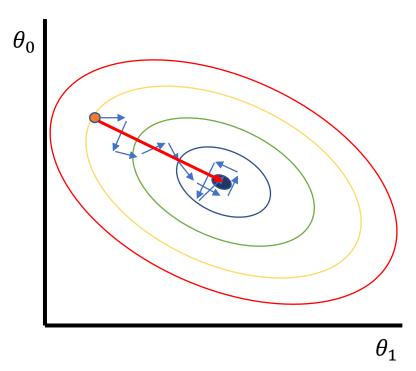
- Cost function does not improve more than a specific threshold after a fixed number of consecutive iterations.
- Fixed number of iterations

- □ Regular gradient descent algorithm:
  - What if we our dataset is "too" large?
    - Can't load everything on memory simultaneously: inefficient I/O bottleneck problem
    - "Too many" evaluations are required to calculate the gradient at one single iteration
- Stochastic gradient descent algorithm
  - Gradients are only calculated on a reduced number of samples grouped in batches
    - Gradient calculations are faster
    - Fewer evaluations are needed for gradient "estimation" (the gradient is only approximated)

Stochastic gradient descent algorithm: adding or averaging?

→ Real gradient

→ Batch gradient



#### Large batch size

- Batch gradient approximates the real gradient
- Higher trust in the direction potentially allows for higher learning rates

#### Small batch size

- Batch gradient may not represent the real gradient well
- Lower trust in the direction usually allow for smaller learning rates

Stochastic gradient descent algorithm: adding or averaging?

Addition: 
$$J(\mathbf{\Theta}) = \frac{1}{2} \sum_{i=0}^{N-1} (f(\mathbf{x}^{(i)}; \mathbf{\Theta}) - y^{(i)})^2$$

Magnitude of cost function and its gradient depends on the number of samples

Simpler implementation of regular gradient descent algorithm

Average: 
$$J(\mathbf{\Theta}) = \frac{1}{2N} \sum_{i=0}^{N-1} (f(\mathbf{x}^{(i)}; \mathbf{\Theta}) - y^{(i)})^2$$

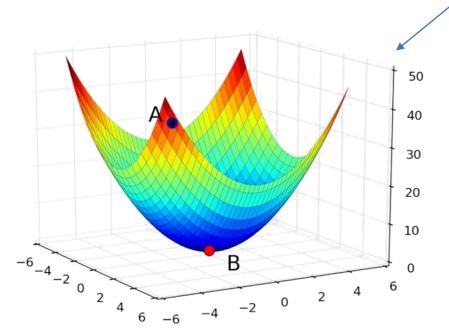
Magnitude of cost function and its gradient is independent from the number of samples

Provides stability when evaluating different batch sizes

But careful with different number of samples between batches!!!!

Linear regression has an analytical solution (if computationally feasible)

$$\boldsymbol{\theta} = \arg\min J(\boldsymbol{\theta}) = \arg\min \frac{1}{2} \sum_{i=0}^{N-1} (f(\boldsymbol{x}^{(i)}; \boldsymbol{\theta}) - y^{(i)})^2$$



In linear regression,  $J(\theta)$  is convex so:

- (1) The only local minimum is the global minimum
- (2) At the minimum:  $\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{\partial}{\partial \boldsymbol{\theta}} \left( \frac{1}{2} (\boldsymbol{X} \boldsymbol{\theta} \mathbf{y})^T (\boldsymbol{X} \boldsymbol{\theta} \mathbf{y}) \right) = 0$

$$\mathbf{X} = \begin{pmatrix} 1 & x_0^{(0)} & \dots & x_{M-1}^{(0)} \\ \vdots & & & \vdots \\ 1 & x_0^{(N-1)} & \dots & x_{M-1}^{(N-1)} \end{pmatrix} \qquad \mathbf{y} = \begin{pmatrix} y_0 \\ \vdots \\ y_{N-1} \end{pmatrix}$$

$$oldsymbol{ heta} = egin{pmatrix} heta_0 \ dots \ heta_M \end{pmatrix}$$

Linear regression has an analytical solution (if computationally feasible)

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{\partial}{\partial \boldsymbol{\theta}} \left( \frac{1}{2} (\boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{y})^T (\boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{y}) \right) = \mathbf{0}$$

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{1}{2} \frac{\partial}{\partial \boldsymbol{\theta}} \left( (\boldsymbol{\theta}^T \boldsymbol{X}^T - \boldsymbol{y}^T) (\boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{y}) \right) = \mathbf{0}$$

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{1}{2} \frac{\partial}{\partial \boldsymbol{\theta}} (\boldsymbol{\theta}^T \boldsymbol{X}^T \boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{\theta}^T \boldsymbol{X}^T \boldsymbol{y} - \boldsymbol{y}^T \boldsymbol{X} \boldsymbol{\theta} + \boldsymbol{y}^T \boldsymbol{y}) = \mathbf{0}$$

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{1}{2} [\boldsymbol{X}^T \boldsymbol{X} \boldsymbol{\theta} + \boldsymbol{X}^T \boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{X}^T \boldsymbol{y} - \boldsymbol{X}^T \boldsymbol{y}] = \mathbf{0}$$

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = \boldsymbol{X}^T \boldsymbol{X} \boldsymbol{\theta} - \boldsymbol{X}^T \boldsymbol{y} = \mathbf{0}$$
Normal equation
$$\boldsymbol{X}^T \boldsymbol{X} \boldsymbol{\theta} = \boldsymbol{X}^T \boldsymbol{y}$$

$$\boldsymbol{\theta} = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{y}$$

- Assumptions in **linear** regression:
  - Linearity

• Independence of predictors (no multicollinearity)

• Homoscedasticity: error (residual) variance does not depend on the independent variables

• Data are normally distributed

■ Evaluation of a regression model:

Residuals

- Mean absolute error:  $\frac{1}{N}\sum_{0}^{N-1} |f(x^{(i)}; \boldsymbol{\theta}) y^{(i)}|$
- Mean squared error (MSE):  $\frac{1}{N}\sum_{0}^{N-1}(f(x^{(i)}; \theta) y^{(i)})^2$  Penalizes large errors or residuals
- Coefficient of determination:  $R^2 = 1 \frac{\sum_{0}^{N-1} (f(x^{(i)};\theta) y^{(i)})^2}{\sum_{0}^{N-1} (y^{(i)} \bar{y})^2} \longrightarrow \text{MSE}$

No universal rule for interpretation

Does not decrease when adding features

 $R^2 = 1$ : Good model  $R^2 = 0$ : Model is not better than mean value  $R^2 < 0$ : Worse predictor than mean value

• Adjusted  $R^2$ :  $R_{adjusted}^2 = \frac{(1-R^2)(N-1)}{N-M-1}$  Better suited for model comparison

Penalized when adding more features

- Statistical significance in linear regression:
  - T-test on individual coefficients:
    - Coefficients:  $H_0$ :  $\theta_p = 0$  (i.e., the coefficient has no significant effect)
    - Not meaningful for the intercept
  - F-test on regression model:

 $H_0$ :  $\theta_p = 0 \ \forall p > 0$  (i.e., the regression model is not significantly better than the average value or intercept)

Is it really meaningful?

- Confidence and prediction intervals:
  - Confidence interval of the coefficients:

Note: For the intercept,  $x_0^{(i)} = 1$ 

$$\theta_p \pm t_{\alpha/2,N-M-1} * \sigma_{\theta_p}$$
 Since:  $\boldsymbol{\theta} = (\boldsymbol{X}^T \boldsymbol{X})^{-1} \boldsymbol{X}^T \boldsymbol{Y}$ , then  $\boldsymbol{\sigma_{\theta}} = \sqrt{\text{diag}\{\sigma_y^2 (\boldsymbol{X}^T \boldsymbol{X})^{-1}\}}$  where  $\sigma_y^2 = \frac{\sum_{\forall i} (y^{(i)} - \hat{y}^{(i)})^2}{N-M-1}$  is the variance of the residuals

• Confidence interval for the prediction given  $x^{(i)}$ :

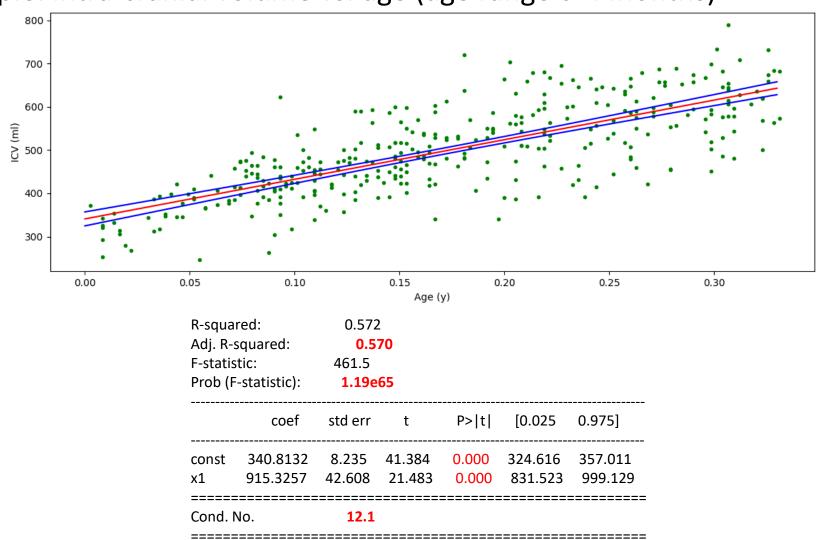
$$\hat{y} \pm t_{\alpha/2,N-M-1} * \hat{\sigma}$$

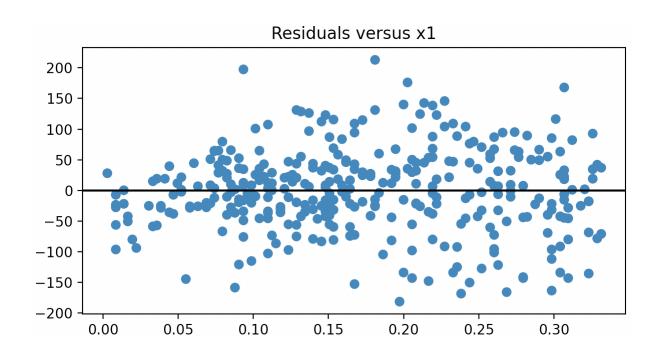
where 
$$\hat{\sigma} = \sqrt{\sigma_y^2 x^{(i)}^T (X^T X)^{-1} x^{(i)}}$$

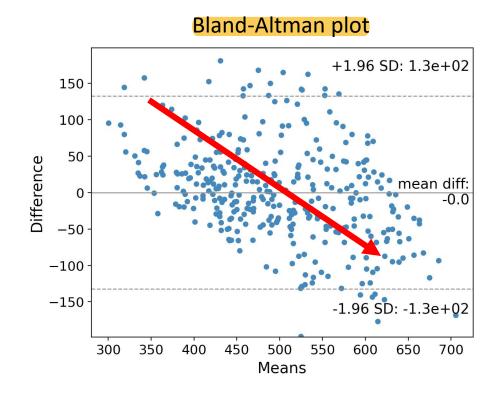
- Other measurements:
  - Condition number: measures the sensitivity of the coefficient estimates to small changes in the data matrix.

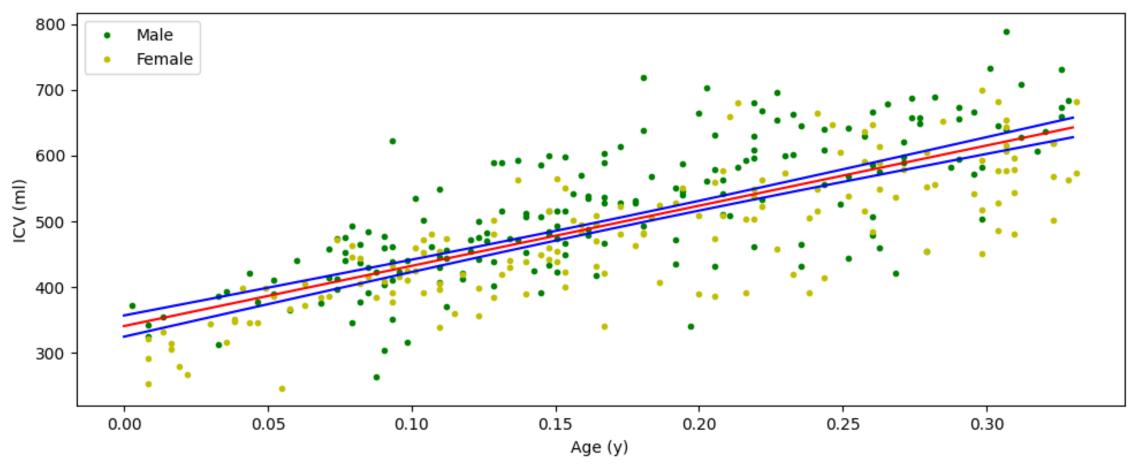
$$k(X) = ||X|| ||X^{-1}|| = \frac{eig_{max}(X)}{eig_{min}(X)}$$

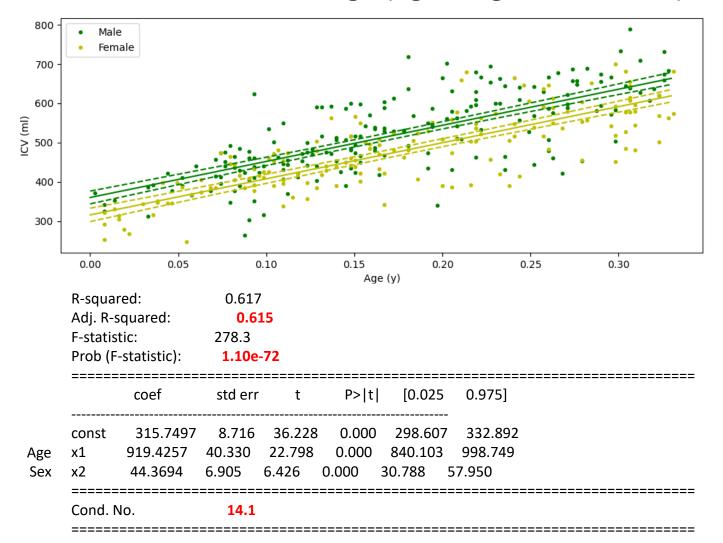
- Large numbers are related to ill-conditioned problems.
- Although thresholds have been proposed (e.g., 20, 30), this number varies when centering data or when the problem dimension change.

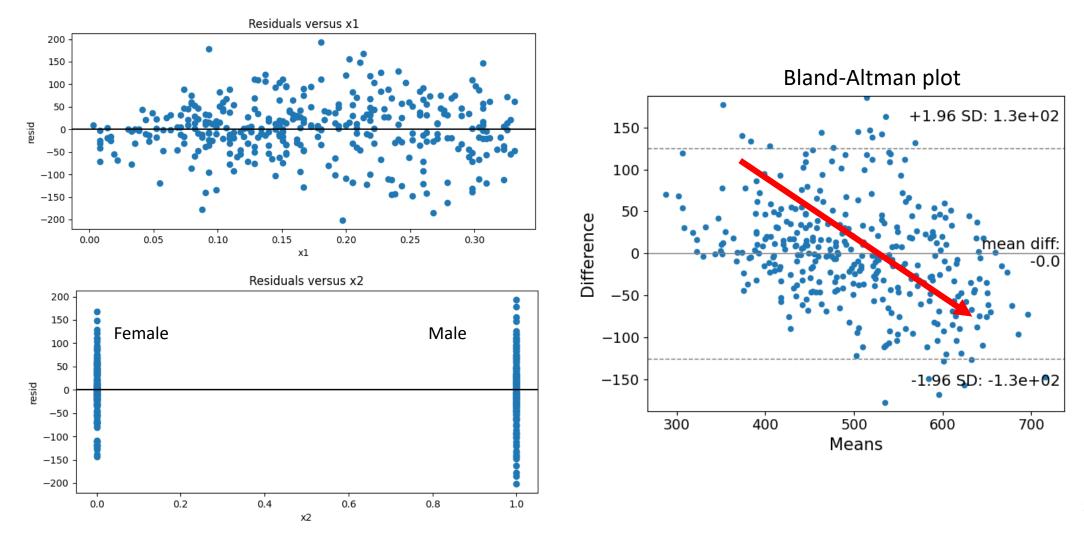




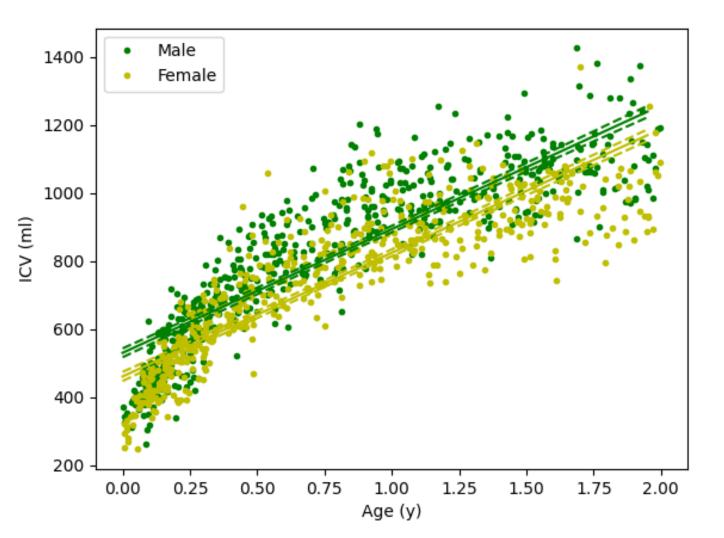








■ Example: intra-cranial volume vs. age (age range 0-2 years)



[0.025

.ona. No. 3./8

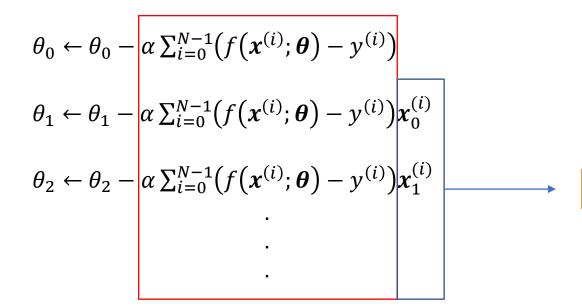
$$R^{2} = 1 - \frac{\sum_{0}^{N-1} (f(\mathbf{x}^{(i)}; \boldsymbol{\theta}) - y^{(i)})^{2}}{\sum_{0}^{N-1} (y^{(i)} - \bar{y})^{2}}$$

### Non-linear regression

- Linear regression is a powerful tool to investigate relationships between independent and dependent variables
- □ Linear regression most often cannot model accurately relationships between biological processes because they are normally not linear
  - One must be skeptical about performance evaluation metrics and statistical tests
- Non-linear functions often need to be considered:
  - Higher-order polynomials
  - Logarithmic and exponential functions
  - Sinusoidal functions
  - Radial basis functions (Gaussian kernels, splines...)

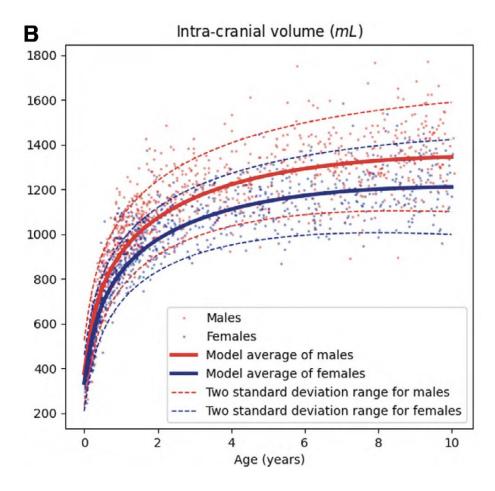
### Non-linear regression

Gradient descent algorithm: updating parameters



Only change in non-linear regression

# Non-linear regression



### **Next class**

Numpy

Statsmodels

□ Curve fit using Scipy