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Broken Stick Model for Irregular Longitudinal Data

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Abstract

Many longitudinal studies collect data that have irregular observation times, often requiring the application of linear mixed models with time-varying outcomes. This paper presents an alternative that splits the quantitative analysis into two steps. The first step converts irregularly observed data into a set of repeated measures through the broken stick model. The second step estimates the parameters of scientific interest from the repeated measurements at the subject level. The broken stick model approximates each subject's trajectory by a series of connected straight lines. The breakpoints, specified by the user, divide the time axis into consecutive intervals common to all subjects. Specification of the model requires just three variables: time, measurement and subject. The model is a special case of the linear mixed model, with time as a linear B-spline and subject as the grouping factor. The main assumptions are: subjects are exchangeable, trajectories between consecutive breakpoints are straight, random effects follow a multivariate normal distribution, and unobserved data are missing at random (MAR). The brokenstick v2.0.0 R package offers tools to calculate, predict, impute and visualise broken stick estimates. The package supports two optimisation methods, including options to constrain the variance-covariance matrix of the random effects. We demonstrate six applications of the model: detection of critical periods, estimation of the time-to-time correlations, profile analysis, curve interpolation, multiple imputation and personalised prediction of future outcomes by curve matching.

Keywords: brokenstick, R, linear mixed model, repeated measures, linear B-spline, personalised estimation, growth curve analysis, critical periods, time-to-time correlation, profile analysis, curve interpolation, multiple imputation, curve matching, two-step method, Kasim-Raudenbush method.

1. Introduction

Most longitudinal studies plan data collection to occur at a fixed set of time points. In practice, the realised times can differ - sometimes substantially - from the scheduled times.

There may be many reasons for such differences. For example, we planned a visit at the weekend or during a holiday, the subject didn't show up, the measurement device was out of order, or the investigator got ill. Varying observation times may also result from combining data from multiple studies, each collected according to its own design. Timing variation can be substantial in observational studies, especially if the survey lacks a pre-specified schedule. Longitudinal data with timing differences between subjects are said to be *irregular*.

Irregular observation times present significant challenges for quantitative analysis. For example, it isn't easy to calculate the time-to-time correlation matrix if the data spread thinly over time. It might also be complex to predict the future from past data if subject times differ. Observation times may also relate to the process of interest. For example, more severe patients get more frequent measurements; unmotivated cohort members respond more rarely, and so on. Conventional methods like MANOVA, regression or cluster analysis break down if observation times differ or if drop-out is selective.

While irregular observation times occur all over science, there is no universal or principled approach to resolve the problem. One straightforward fix is to take only those dates for which data are available (e.g., dates when stocks are traded), thus ignoring the times when markets are closed. One may also create bins of time intervals around the planned times, thereby ignoring within-period differences. Another ad-hoc method predicts the value at the scheduled time from neighbouring data, e.g. by linear interpolation or smoothing, typically reducing the variability in the data. Some quick fixes create data sets where the timing problem seems to have "gone away", which may tempt the analyst to ignore the potential effects of data patch-up on the substantive conclusions. While convenient and straightforward, the thoughtless application of these fixes introduces significant spurious relations over time, especially if the spacing of observations is highly irregular. (Rehfeld, Marwan, Heitzig, and Kurths 2011) Binning can lead to "surprisingly large" biases. (Towers 2014) If timing variation is related to the outcome of interest, these methods may result in biased estimates and exaggerated claims. (Pullenayegum and Lim 2016)

The linear mixed model for longitudinal data (Laird and Ware 1982; Fitzmaurice, Laird, and Ware 2011) is the standard for analysing irregular data. The model represents each subject's observed curve by a parametric function of time. The parameter estimates of this function are specific to each subject and modelled as random effects. The linear mixed model is beneficial for irregular data. It borrows strength across different realisations of the same process, summarising each trajectory by a small number of parameters that vary over subjects. The analyst can break down the distribution of these random effects as a function of individual characteristics. The linear mixed model is attractive when the number of measurements differs between individuals or when the measurements are taken at different times.

This paper explores the use of the broken stick model to transform irregularly observed data into repeated measures. The broken stick model describes a curve by a series of connected straight lines. The model has a long history and is known under many other names, amongst others, segmented straight lines (Bellman and Roth 1969), piecewise regression (Toms and Lesperance 2003), structural change models (Bai and Perron 2003), broken line smoothing (Koutsoyiannis 2000) and segmented regression (Lerman 1980). The term broken stick goes back to at least MacArthur (1957), who used it in an analogy to indicate the abundance of species. Most of the literature on the broken stick model concentrates on the problem of finding optimal times at which the lines should connect. Instead, the present paper will focus on the problem of summarising irregular individual trajectories by estimates made at

a pre-specified time grid. This time grid is identical for all individuals, but it needs not be equidistant. Our model formulation is a special case of the linear mixed model, with time modelled as a set of random effects coded as a linear B-spline and subjects as the grouping factor. The output of the transformation is a set of repeated measures, where every subject obtains a score on every time point.

Many R packages offer tools for interpolation. The splines package (R Core Team 2020) and the akima package (Akima, Gebhardt, Petzold, and Mächler 2021) contains classic interpolation methods for one- and two-dimensional smoothing. Most contributed packages concentrate on time series or spatial interpolation, e.g. deldir, interp, fields, gapfill, geoR, gstat and spatial. See Li and Heap (2014) and Lepot, Aubin, and Clemens (2017) for overviews of the different concepts and methodologies. Most interpolation techniques rely on neighbouring information, in time, space or both. The broken stick model addresses the problem where many independent replications provide short irregular multivariate time series, say of 5-30 time points. The scientific interest is to dynamically predict and update future observations. The model applies the linear mixed model to increase stability for such series by borrowing information across replicates. As there are no satisfactory solutions to this problem, the brokenstick package intends to fill this gap.

Substantive researchers often favour repeated measures over the use of linear mixed models because of their simplicity. For example, we can easily fit a subject-level model to predict future outcomes conditional on earlier data with repeated measures data. While such simple regression models may be less efficient than modelling the complete data (Diggle, Heagerty, Liang, and Zeger 2002, Sec. 6.1), increased insight may be more valuable than increased precision.

The broken stick model requires a specification of a sensible set of time points at which the measurements ideally should have been taken. For each subject, the model predicts or imputes hypothetical observations at those times, so the substantive analysis applies to the repeated measures instead of the irregular data. This strategy is akin to Diggle's multi-stage approach model-fitting approach (Diggle 1988). The envisioned two-step analytic process aims to provide the best of both worlds.

Some applications of the broken stick model are:

- to approximate individual trajectories by a series of connected straight lines;
- to align irregularly observed curves to a joint age grid;
- to impute realisations of individual trajectories;
- to estimate the time-to-time correlation matrix;
- to predict future observations.

The original motivation for developing the broken stick model was to facilitate the statistical analysis and testing of critical ages in the onset of childhood obesity (de Kroon, Renders, van Wouwe, van Buuren, and Hirasing 2010), with extensions to multiple imputation (van Buuren 2018b). There is good support in R for fitting child growth data. We mention some related approaches. Methods for estimating growth references with parametric models are gamlss() from gamlss (Stasinopoulos and Rigby 2007) and its Bayesian incarnation bamlss() from bamlss (Umlauf, Klein, Simon, and Zeileis 2019). Nonparametric alternatives that estimate quantiles directly are rq() from quantreg (Koenker, Portnoy, Ng, Zeileis, Grosjean, and Ripley 2018) and expectreg.ls() from expectreg (Otto-Sobotka, Spiegel, Schnabel,

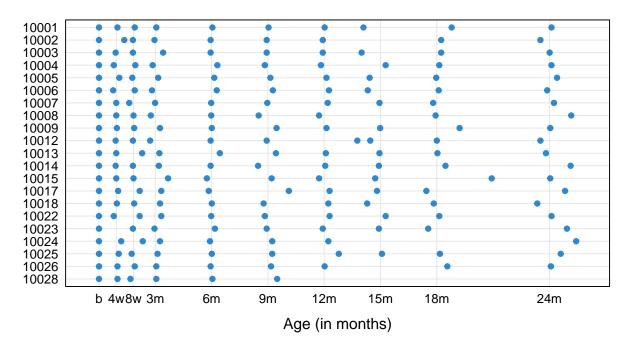


Figure 1: Abacus plot of observation times for the first 20 children of the SMOCC data.

Schulze Waltrup, Eilers, Kneib, and Kauermann 2021). Methods for modelling and smoothing growth curves fit trajectories per child include smooth.basisPar() from fda (Ramsay, Graves, and Hooker 2021), gam() from mgcv (Wood 2011), loess() and smooth.spline() from base stats (R Core Team 2020). Models that smooth by borrowing strength across children are face.sparse() from face (Xiao, Li, Checkley, and C. 2021), lmer() from lme4 (Bates, Mächler, Bolker, and Walker 2015), and sitar() from sitar (Cole 2021). The broken stick model fits in the latter tradition, and features an intuitive parametrisation of each individual growth curves by a series of connected straight lines. See Anderson, Hafen, Sofrygin, Ryan, and HBGDki Community (2019) for an overview and comparison of these methods.

The present paper highlights various computational tools from the **brokenstick** v 2.0.0 package. The package contains tools to fit the broken stick model to data, export the fitted model's parameters, create imputed values of the model, and predict broken stick estimates for new data. Also, the text illustrates how the tool helps to solve various analytic problems.

2. Illustration of broken stick model

As a first step, let us study the variation in the age of measurement of 200 children from the SMOCC study (Herngreen, van Buuren, van Wieringen, Reerink, Verloove-Vanhorick, and Ruys 1994). Lokku, Lim, Birken, Pullenayegum, and TARGet Kids! Collaboration, (2020) suggest the *abacus plot* to visualise this variation.

The blue points in Figure 1 indicate the observation times. Generally, the blue points are close to the scheduled ages (indicated by vertical lines), especially in the first half-year. Observation times vary more for older children. Several children have one or more missing visits (e.g. 10002, 10008, 10024). Some children (10012, 10015) had fairly close visits. Child 10028 dropped out after month 9.

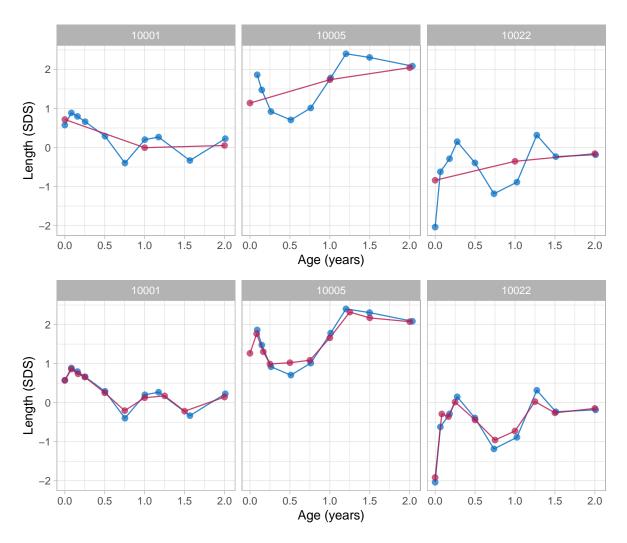


Figure 2: Broken stick model with two (top) and nine (bottom) line segments for three children. Blue = observed data, Red = Fitted broken stick curves.

Let us fit two models, with two and nine lines, respectively, to body length's standard deviation score (SDS).

Figure 2 shows the individual trajectories of three children. The blue points coincide with the

observed data, whereas the red curves are calculated according to the broken stick model.

There are two fitted models. The simpler model (top) uses just two line segments. The first line starts at birth and ends at the age of exactly 1 year. The second line spans the period between 1 to 2 years. Note that the two lines connect at the breakpoint, the age of 1 year. The red curves for the two-line model are a crude approximation to the data.

We can create a better model by setting breakpoints equal to the scheduled ages. Since there are 10 scheduled ages, we construct nine straight lines. In contrast to the two-line model, the nine-line broken stick model is sensitive to small bumps in the observed trajectory and closely fits the empirical data. The residual variance of the nine-line model is low (0.059), and the proportion of explained variance in SDS is high (0.98).

While the observation times in the data differ between children, the broken stick curves use identical time points across subjects. The idea is now that we can add the broken stick estimates to the child-level data by a long-to-wide conversion and analyse supplemented columns as repeated measures. A repeated measures analysis is usually simpler than the equivalent for the temporally misaligned data. For example, it is easy to calculate mean profiles for arbitrary groups, estimate the time-to-time covariance matrix, or build predictive models at the child level. See Hand and Taylor (1987) for a lucid overview of linear techniques for repeated measures.

3. Methodology

3.1. Notation

We adopt the notation of Fitzmaurice *et al.* (2011). Let Y_{ij} denote the response variable for the i^{th} subject on the j^{th} measurement occasion at time t_{ij} . Data are collected in a sample of N persons $i = 1, \ldots, N$. Let repeated measurements for the i^{th} subject be grouped as

$$Y_i = \begin{pmatrix} Y_{i1} \\ Y_{i2} \\ \vdots \\ Y_{in_i} \end{pmatrix}, \quad i = 1, \dots, N.$$

If the measures have been observed at a common same set of occasions, then we could drop the index i in t_{ij} since $t_{ij} = t_j$ for all i = 1, ..., N. Here we will focus on the case that t_{ij} varies over i.

In addition, let use define the $n_i \times p$ matrices

$$X_{i} = \begin{pmatrix} X_{i11} & X_{i12} & \cdots & X_{i1p} \\ X_{i21} & X_{i22} & \cdots & X_{i2p} \\ \vdots & \vdots & \ddots & \vdots \\ X_{in_{i}1} & X_{in_{i}2} & \cdots & X_{in_{i}p} \end{pmatrix}, \quad i = 1, \dots, N,$$

so that the rows of X_i contain p covariates associated with the responses at n_i measurement occasions. The columns may be time-varying covariates. If a certain covariate is fixed in time (e.g. sex, treatment, education), then all values within the corresponding column in X_i are identical.

3.2. Broken stick model

The broken stick model avoids modeling observation times t_{ij} directly by representing each t_{ij} as its relative position within a time interval. For example, suppose $t_{ij} = 0.6$ years and that the time interval is given by 0.5-1.0 years. The position relative to the left break age is $x_{\text{left}} = (1.0 - 0.6)/(1.0 - 0.5) = 0.8$, whereas relative to the right break age is $x_{\text{right}} = (0.6 - 0.5)/(1.0 - 0.5) = 0.2$. In order to fit the broken stick model, we need to replace time point $t_{ij} = 0.6$ by two values: 0.8 (for break age 0.5), and 0.2 (for break age 1.0). Note that both values add up to 1. Coding time in this way simplifies modeling continuous time by a set of discrete break ages.

More specifically, let t_{ij} be coded by a second-order (linear) B-spline using k internal knots κ placed at k+1 ordered ages

$$\kappa_0 = \kappa_1 < \dots < \kappa_k < \kappa_{k+1}$$

The internal knots $\kappa_1, \ldots, \kappa_k$ correspond to the set of ages for which we obtain broken stick estimates, and it could be specified by the user. The left boundary knot $\kappa_0 = \kappa_1$ is left-anchored to the minimum time $\min(t_{ij})$ in the data. This point defines the starting event of the participant, such as birth or study enrolment. The right hand boundary knot is $\kappa_{k+1} \geq \max(t_{ij})$.

The second-order B-spline (de Boor 1978, pp. 32),

$$H_s(t) = \begin{cases} (t - \kappa_{s-1})/(\kappa_s - \kappa_{s-1}) &, & \kappa_{s-1} < t \le \kappa_s, \\ (\kappa_{s+1} - t)/(\kappa_{s+1} - \kappa_s) &, & \kappa_s \le t < \kappa_{s+1}, \\ 0 &, & \text{otherwise.} \end{cases}$$

is applied to t_{ij} to obtain (k+1) transformed variables $x_{is} = t_{ij}$ with s = 1, ..., k+1. These variables can conveniently be grouped into the $n_i \times (k+1)$ matrix of covariates $X_i = (x_{i1}, ..., x_{ik}, x_{i(k+1)})$. Each row in X_i has only one or two non-zero elements, which sum to

Using this X_i , the broken stick model is a special case (with $Z_i = X_i$) of the two-stage random-effects model (Laird and Ware 1982)

$$Y_i = X_i \beta + X_i b_i + \epsilon_i$$

where the k+1 column vector β contains k+1 fixed effect coefficients common to all persons, where the k+1 column vector b_i accommodates for k+1 subject-specific random parameters, and where the n_i column vector ϵ_i holds subject-specific residuals.

In order to complete the model specification, we assume that the residuals are identically and independently distributed as $\epsilon_i \sim N(0, \sigma^2 I(n_i))$, where σ^2 is a common variance parameter, and where $I(n_i)$ is the identity matrix of order n_i . Thus, the equation represents population parameters (fixed effects), individual effects (random effects), and an amount of within-person dispersion that is the same for all persons. The section on estimation also considers a heterogeneous model that allows σ_i^2 to vary over subjects.

In summary, given the knot specification and the choice of the response scale, the parameters of the broken stick model are:

• β , a vector of k+1 fixed parameters;

- Ω , a $(k+1) \times (k+1)$ covariance matrix of the random effects;
- σ^2 , the within-person error variance.

The total number of parameters for a solution with k internal knots is thus equal to $(k^2 + 5k + 6)/2$. For example, a model of k = 3 knots (i.e. with two connected lines) has 15 parameters, a model with k = 4 has 21 parameters, and a model with k = 10 break ages has 78 parameters.

3.3. Model assumptions

At the person level, we assume $b_i \sim N(0,\Omega)$, i.e., the random coefficients of the subjects have a multivariate normal distribution with zero mean and a $(k+1) \times (k+1)$ covariance matrix Ω . The base model allows the elements of Ω to vary freely. For time-dependent data, constrained versions for Ω are also of interest. (Fitzmaurice et al. 2011, ch. 7). The estimation section highlights two such extensions. We also assume that the covariance between b_i and ϵ_i is zero. For simplicity, this paper is restricted to the case where X_i includes only time, and no other covariates. Also, we assume that X_i has no missing data.

The broken stick model builds upon three main modeling assumptions:

- The trajectory between break ages follows a straight line. This assumption may fail for processes that are convex or concave in time. For example, human height growth in centimeters growth is concave, so setting breakpoints far apart results introduces systematic model bias. Modeling height SDS instead of raw height will prevent this bias.
- The broken stick estimates follow a joint multivariate normal distribution. As this assumption may fail for skewed measurements, it could be beneficial to transform the outcomes so that their distribution will be closer to normal.
- The data are *Missing at Random* (MAR) given the outcomes from all subjects at all observation times. This assumption is restrictive in the sense that missingness may only depend on the observed outcomes, and not on covariates other than time. At the same time, the assumption is liberal in the sense that the missingness may depend on future outcomes. While this MAR-future assumption is unusual in the literature on drop-out and observation time models, it is a sensible strategy for creating imputations that preserve relations over time, especially for intermittent missing data. Of course, the subsequent substantive analysis on the imputed data needs to be aware of the causal direction of time.

3.4. Interpretation

Given the model estimates and the person data, we can calculate the random effect b_i . The broken stick parameter $\gamma_{is} = \beta_s + b_{is}$ is the subject-specific mean of Y_i at time κ_s , $s = 1, \ldots, k+1$. The set of γ_{is} parameters describes the mean response profile for subject i by k lines that connect at the k+1 coordinates (κ_s, γ_{is}) .

The broken stick parameter is the most likely value of outcome Y_i for subject i at time κ_s . The parameter is the centre of the posterior predictive distribution for normal Y_i . The two-sided $100(1-\alpha)\%$ prediction interval for the true, though often unobserved, value Y_{i,κ_s} is equal to

$$[Y_{i,\kappa_s}^{\text{lo}}, Y_{i,\kappa_s}^{\text{hi}}] = \gamma_{is} \pm t_{(1-\alpha/2;N-1)}\sigma,$$

where $t_{(1-\alpha/2;N-1)}$ is the $100(1-\alpha/2)$ percentile of Student's t-distribution with N-1 degrees of freedom. For example, the 50% prediction interval $\gamma_{is} \pm 0.68\sigma$ will contain 50% of true values. For normal Y_i , the length of the 50% prediction interval is equivalent to the interquartile range (IQR). If the residual variation σ^2 is small (say $\sigma^2 < 0.1$), the IOR is about 0.22, so half of the true values will be within 0.22 SD of γ_{is} , a small difference. For large σ^2 (e.g. $\sigma^2 > 0.2$), the γ_i vector is a smoothed representation of Y_i . While smoothness amplifies low-frequency features of the trajectories, it could also introduce biases in the subsequent analysis by suppressing high-frequency variation. In that case, the analyst needs to check whether this reduction in variation does not affect the parameters of substantive interest. We may restore high-frequency variation by adding random draws from the residual distribution $N(0, \sigma^2)$. From there, it is a small step to multiple imputation, a well-developed methodology for drawing valid inferences from incomplete data. (Rubin 1987; van Buuren 2018b)

If $n_i >> k$ then the broken stick model provides a parsimonious representation of the measurements. Reversely, if $n_i << k$ then the model infers plausible values for subject i by building strength across persons. The broken stick model converts n_i irregularly observed measurements into a new set of k values γ_{is} at common ages $\kappa_1, ..., \kappa_k$, s = 1, ..., k.

Since each row in X_i sums to unity, the broken stick model does not have a global intercept. The linear B-spline coding effectively replaces the global random intercept term by k+1 local intercepts, one at each break age. The local intercept summarizes the information available in the adjacent left and right age intervals and ignores any information beyond the two adjacent knots. The broken stick estimates are thus primarily local. Outcome data observed outside the two adjacent age intervals influence the broken stick estimates only through the subject-level part of the model, in particular through Ω .

4. Estimation

4.1. Main function

The brokenstick() function estimates the parameters of the broken stick model. The user needs to specify the outcome, the predictor and the grouping variable, as well as the location of the knots on the predictor variable. A call produces an object of class brokenstick:

```
R> fit <- brokenstick(hgt_z ~ age | id, data = smocc_200,</pre>
                      knots = c(0, 0.5, 1, 2), boundary = c(0, 3),
                      seed = 12321)
R> fit
Class
             brokenstick (kr)
Variables
             hgt_z (outcome), age (predictor), id (group)
             1942 (n), 36 (nmis), 200 (groups)
Data
             22 (total), 5 (fixed), 5 (variance), 10 (covariance), 2 (error)
Parameters
             0 0.5 1 2 3
Knots
             -0.1 0.087 -0.029 0.072 0.36
Means
```

```
Residuals 0.1 0.13 0.15 0.17 0.39 (min, P25, P50, P75, max)
Mean resid 0.16
R-squared 0.89

Variance-covariance matrix
```

```
age_0 age_0.5 age_1 age_2 age_3
age_0 1.406
age_0.5 0.712 0.883
age_1 0.522 0.744 0.782
age_2 0.408 0.697 0.787 0.904
age_3 0.505 -0.218 -0.072 -0.253 7.687
```

The object contains the model setting, the data and the results. Here we find estimates of the fixed effects β under means, the residual variance σ^2 under mean resid and the variance-covariance matrix of the random effects Ω as get_omega(fit). We calculate the broken stick estimates at the knot location as a wide matrix through the predict() function as follows:

```
R> bse <- predict(fit, x = "knots", shape = "wide")</pre>
R> dim(bse)
[1] 200
R> head(bse, 3)
# A tibble: 3 x 6
                           '1'
                                   '2'
                                          '3'
           '0' '0.5'
  <dbl>
         <dbl> <dbl>
                        <dbl>
                                 <dbl>
                                        <dbl>
1 10001 0.786 0.252 0.0180
                               0.0414 0.972
2 10002 -0.271 -0.219 -0.438 -0.497
                                        0.572
3 10003 1.67
                2.00
                       1.27
                                1.10
                                       -0.105
```

As a result we now have each individual trajectory summarised by six estimates.

4.2. Estimation steps explained

We may break up the estimation process into two main steps. The first step calculates the matrix of B-splines for the time variable age by the core splines::bs() (R Core Team 2020) function:

```
R> library(splines)
R> data <- brokenstick::smocc_200
R> internal <- c(0, 0.5, 1, 2)
R> boundary <- c(0, 3)
R> X <- bs(data$age, knots = internal, Boundary.knots = boundary, degree = 1)
R> colnames(X) <- paste("age", c(internal, 3), sep = "_")
R> data <- cbind(data[, c("id", "age", "hgt_z")], X)
R> head(data)
```

```
age hgt_z age_0 age_0.5 age_1 age_2 age_3
    id
1 10001 0.000 0.57
                     1.00
                             0.00 0.0000
                                             0
2 10001 0.082 0.89
                     0.84
                             0.16 0.0000
                                             0
                                                   0
3 10001 0.159
              0.80
                     0.68
                             0.32 0.0000
                                             0
                                                   0
4 10001 0.255 0.66
                                                   0
                     0.49
                             0.51 0.0000
                                             0
5 10001 0.504 0.29
                             0.99 0.0076
                                                   0
                     0.00
                                             0
6 10001 0.753 -0.40
                     0.00
                             0.49 0.5058
                                             0
                                                   0
```

The numerical example shows that the bs() function transforms the age variable into five columns, the B-spline basis, with names like age_0 and age_0.5. If age coincides with one of these (e.g., as in the top row), then the corresponding column receives a 1. In all other cases, age distributes over two adjacent columns. To make things fit, we need an additional column (here age_3) at the last position, the right boundary knot. There is also a left boundary knot, and I have conveniently set that equal to the first breakpoint, marking the start of time. Setting degree = 1 specifies a B-spline gives the broken stick model its name and its characteristic shape.

The second step is to specify the model and estimate its parameters. We have two methods for this: "kr" and "lmer". Method "lmer" relies on the popular function lme4::lmer() (Bates et al. 2015) to fit a linear mixed normal model.

The formula removes the intercept and specifies each knot as a random effect with child id as grouping factor. The control argument suppresses the warning Model failed to converge with max|grad| = 0.0360913. Such warnings occur often if the model has many random effects. These warnings may also be thrown if some of the child data are outliers (for example pre-terms). I found that the broken estimates generally look sound and reasonable despite the warnings. Note however that my experience derives primarily from child growth data, so there is no guarantee that this apparent robustness will hold for other types of data. Warnings from lmer() become less frequent for a lower number of knots, for larger samples sizes and for better behaved data.

Object mod_lmer has class lmerMod so we may use standard plot(), predict() and summary methods offered by the lme4 package. Converting the result into broken stick estimates requires summing the fixed and random effects.

```
R> bse_lmer <- t(t(ranef(mod_lmer)$id) + fixef(mod_lmer))
R> head(round(bse_lmer, 3), 3)
```

```
age_0 age_0.5 age_1 age_2 age_3

10001 0.78 0.27 -0.01 0.076 0.125

10002 -0.28 -0.21 -0.46 -0.478 -0.083

10003 1.68 1.97 1.28 1.114 -0.865
```

The calculation time of lme4::lmer() rapidly increases with the number of random effects. More than ten random effects (knots) takes significant time, and beyond 15 knots is generally impossible to fit. The **brokenstick** package provides another alternative, the *Kasim-Raudenbush* (KR) sampler (Kasim and Raudenbush 1998). The method simulates draws from the posterior distributions of parameters from a two-level normal model with heterogeneous within-subject variances. The speed of the **Kasim-Raudenbush sampler** is almost insensitive to the number of random effects and depends primarily on the total number of iterations and somewhat on sample size. This method is available as the function kr() in the **brokenstick** package.

```
R> ctl_kr <- control_kr()
R> mod_kr <- kr(y = data$hgt_z, x = X, g = data$id, control = ctl_kr)</pre>
```

The call to control_kr() produces a list with settings for the sampler according to the conventions of the coda package (Plummer, Best, Cowles, and Vines 2006). The defaults in control_kr() should be reasonable across a wide range of cases. The list component mod_kr\$mod contains various objects of class mcmc with the sampling history and detailed results. For example, inspect the fixed effect estimates as

```
R> library(coda)
R> summary(mod_kr$mod$beta)
```

```
Iterations = 101:300
Thinning interval = 1
Number of chains = 1
Sample size per chain = 200
```

 Empirical mean and standard deviation for each variable, plus standard error of the mean:

```
Mean
                    SD Naive SE Time-series SE
        -0.0925 0.0805
                         0.00569
                                         0.00569
age_0
age_0.5
         0.0989 0.0712
                         0.00503
                                         0.00503
age_1
        -0.0163 0.0724
                         0.00512
                                         0.00656
         0.1007 0.0785
age_2
                         0.00555
                                         0.00641
age_3
         0.0532 0.3895
                        0.02754
                                         0.10919
```

2. Quantiles for each variable:

```
2.5% 25% 50% 75% 97.5%
```

```
-0.2346 -0.1487 -0.1011 -0.0392 0.0671
age 0
                 0.0560
                         0.1021
age_0.5
       -0.0484
                                  0.1446 0.2344
        -0.1555 -0.0591 -0.0162
                                  0.0310 0.1256
age_1
age_2
        -0.0447
                 0.0483
                          0.0988
                                  0.1494 0.2554
age 3
        -0.7295 -0.2035
                          0.1099
                                  0.3205 0.6948
```

Also, we may obtain trace plots and densities. For example try plot(mod_kr\$mod\$beta). The "kr" method is the default since version 2.0.0. We obtain results for method "lmer" as

```
R> fit_lmer <- brokenstick(hgt_z ~ age | id, data = smocc_200,</pre>
                           knots = c(0, 0.5, 1, 2), boundary = c(0, 3),
                           method = "lmer", control = ctl_lmer)
R> head(predict(fit_lmer, x = "knots", shape = "wide"), 3)
# A tibble: 3 x 6
     id
           0,
                 '0.5'
                             '1'
                                              '3'
  <dbl>
         <dbl>
                 <dbl>
                          <dbl>
                                   <dbl>
                                            <dbl>
1 10001
         0.778
                 0.272 -0.00986
                                  0.0757
                                          0.125
2 10002 -0.278 -0.206 -0.459
                                 -0.478
                                         -0.0827
3 10003
         1.68
                 1.97
                        1.28
                                  1.11
                                         -0.865
```

The broken stick estimates from the kr and lmer methods are similar, but not identical. In fact, substantial discrepancies may occur in areas where data are sparse, for example, at the right boundary knot. Apart from being faster for more complex models, the KR-sampler opens up interesting analytic options:

- 1. It is relatively easy to constrain the fitted covariance of random effects, Ω, to a matrix of simple structure. Informing the sampler of the time-dependent structure of the random effect leads to stabler estimates of Ω. The package currently implements two correlations models. These models express the correlation ρ(t₁, t₂) between two Z -scores Z₁ and Z₂ at successive ages t₁ and t₂ as a function of those ages. The Argyle model (Argyle, Seheult, and Wooff 2008) is ρ(t₁, t₂) = exp(-λ|T₁ T₂|), where T_i = log(τ + t_i) is a logarithmic rescaling of the time axis and ρ = exp(-λ). The Cole correlation model (Cole 1995) describes the Fisher-transformed correlation as a function of the average (t₁ + t₂)/2 and the difference (t₂ t₁), including two multiplicative terms. Note that both models were proposed in the context of child growth, so may fit less well for other types of time-dependent data.
- 2. The Kasim-Raudenbush sampler fits the slightly more general linear-mixed model with heterogeneous within-subject variances, i.e. with a residual variance σ_i^2 per subject i instead of the global residual σ^2 . This makes it easier to identify, study and weight subjects based on how well they fit the model.
- 3. A third option is to simulate imputations as an extra step to the sampler. For subject with large σ_i^2 , the random effect estimates are a too smooth representation of the data, leading to inappropriate variance estimates when those estimates are analysed as "just data". Section 11.3 of van Buuren (2018b) pioneered a solution that constructs

multiple trajectories by adding a proper amount of residual noise to random effect estimates. The variance estimation then proceeds according to the principles of multiple imputation. (Rubin 1987)

5. Functionality

5.1. Overview of brokenstick package

The **brokenstick** package contains functions to fit, predict and plot data. The main functions in the **brokenstick** package are:

Function name	Description
brokenstick() predict() plot()	Fit a broken stick model to irregular data Predict broken stick estimates Plot individual trajectories

The following functions are user-oriented helpers:

Function name	Description
coef()	Extract coefficients
fitted()	Calculate fitted values
<pre>get_knots()</pre>	Obtain the knots used by model
<pre>get_omega()</pre>	Extract the variance-covariance matrix
get_r2()	Obtain proportion of explained variance
<pre>model.frame()</pre>	Extract training data
<pre>model.matrix()</pre>	Extract design matrix
<pre>print()</pre>	Print object
residuals()	Extract residuals from model
<pre>summary()</pre>	Summarise object

The following functions implements the calculations:

Function name	Description
set_control()	Generic control function
<pre>control_kr()</pre>	Set controls for Kasim-Raudenbush sampler
kr()	Kasim-Raudenbush sampler for two-level model
EB()	Empirical Bayes predictor for random effects (internal)
make_basis()	Create linear splines basis (internal)

The package follows the standard R conventions for modelling objects. In some cases, the modeller does not wish to store the training data. Specify brokenstick(..., light = TRUE) to create a small object with just the parameter estimates. Of course, we cannot

extract the original data from a light object. However, we can still use it to calculate brokenstick estimates for new cases by predict(object, newdata = ...).

5.2. Data preparation

Before we can fit the model, the data need to be in shape. The brokenstick() function takes tidy data in the long-form, with every observed subject-time combination in a row. This section uses the built-in smocc_200 data, containing the heights of 200 children measured at ten visits up to two years.(Herngreen et al. 1994)

```
R> library(brokenstick)
R> head(smocc 200, 3)
# A tibble: 3 x 7
     id
           age sex
                                     hgt hgt_z
                          ga
                                bw
  <dbl> <dbl> <chr>
                      <dbl> <dbl> <dbl> <dbl>
1 10001 0
               female
                          40
                             3960
                                    52
                                         0.575
2 10001 0.0821 female
                          40
                             3960
                                    55.6 0.888
3 10001 0.159 female
                             3960 58.2 0.797
                          40
```

5.3. Calculate Z-scores

The broken stick model can fit observations in either the raw scale (cm, kg, and so on) or as a standard deviation score (SDS), or Z-score. The results from the analysis of the Z-score is preferable for several reasons:

- 1. For growth curves, a straight line assumption is more plausible in the Z-score scale;
- 2. Observations in the Z-score scale are closer to multivariate normality;
- 3. Analysis of Z-scores highlights the interesting variation within and between children;
- 4. Fitting Z-score data leads to fewer convergence issues.

It is easy to convert the measurements into the Z-score scale, fit the model, and convert back to the raw scale afterwards, if desired. There are several R packages that assist in the calculations: **AGD** (van Buuren 2018a), **anthro** (Schumacher, Borghi, and Polonsky 2020), **childsds** (Vogel 2020), **growthstandards** (Hafen 2021), **nlreferences** (van Buuren 2021) and **zscorer** (Myatt and Guevarra 2019).

The smocc_200 data contains the height measurement both in the original scale in cm (hgt) and the Z-score scale (hgt_z) relative to the height references from the Fourth Dutch Growth study (Fredriks, van Buuren, Burgmeijer, Meulmeester, Beuker, Brugman, Roede, Verloove-Vanhorick, and Wit 2000). For illustration, let us calculate and check height SDS using the AGD package.

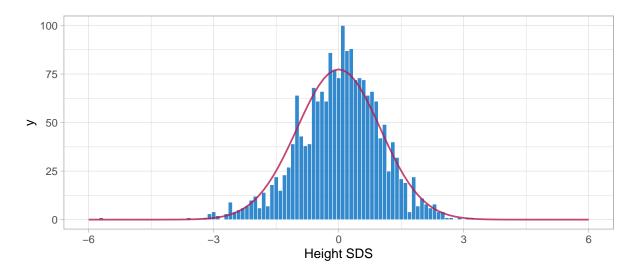


Figure 3: Distribution of height SDS for 200 Dutch children.

[1] TRUE

Figure 3 shows that, as expected, the empirical Z-score distribution is close to the standard normal. The few very extremely low heights correspond to pre-term born infants. The next section concentrate on modelling hgt_z. Function z2y() applies the inverse transformation of Z-scores to the original scale. The following snippet converts hgt_z into the cm scale.

[1] TRUE

We have used the Dutch 1997 height references here, but similar transforms could be made using other references. In practice we found that the model fit is often better when applied to Z-scores. Age-conditional references are common in child growth exists, but could be rare in other fields. An alternative is to apply the broken stick model to the standardized residuals of a preliminary non-linear regression of the outcome on time.

5.4. Model fitting

Figure 4 displays the growth curves of a subset of 52 children. The Z-score transformation takes away the major time trend, so all trajectories are more or less flat. This display allows us to see an extremely detailed assessment of individual growth. Note how the measurements cluster around ten ages: birth, 1, 2, 3, 6, 9, 12, 15, 18 and 24 months. While the data collectors rigorously followed the study design, variation in timing is inevitable because of weekends, holidays, sickness, and other events.

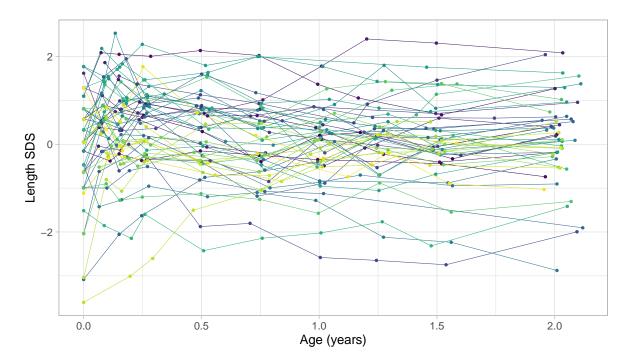


Figure 4: Length growth of 52 infants expressed in the Z-score scale.

Fit one line

As a start, let us fit a simple model with just one line anchored at the minimum and maximum age.

The what = "all" ensures that the right boundary is part of the plot. Figure 5 shows the observed (blue) and fitted (red) trajectories of three selected children. Note that this model can only capture the overall age trend. As a result, the approximation to the data is quite bad.

Fit two lines

We now extend to two connected lines. The first line should start at birth and end at the age of one year. The second line spans the period between one to two years. The lines must connect at the age of one year. We estimate and plot the model as follows:

The fit2 object holds the parameter estimates of the model:

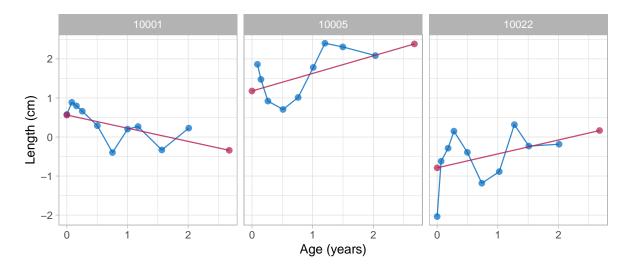


Figure 5: Simple linear model with one line anchored at the extremes.

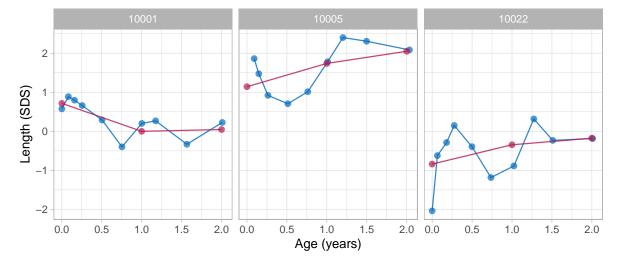


Figure 6: Broken stick model with two lines.

R> fit2

```
Class
             brokenstick (kr)
Variables
             hgt_z (outcome), age (predictor), id (group)
             1942 (n), 36 (nmis), 200 (groups)
Data
Parameters
             16 (total), 4 (fixed), 4 (variance), 6 (covariance), 2 (error)
Knots
             0 1 2 2.7
             -0.037 0.034 0.054 0.013
Means
Residuals
             0.12 0.15 0.17 0.2 0.39 (min, P25, P50, P75, max)
Mean resid
             0.18
R-squared
             0.87
Variance-covariance matrix
            age_0 age_1 age_2 age_2.6776
age_0
              1.2
            0.493 0.843
age_1
age_2
            0.475 0.797
                          0.905
age_2.6776 -0.027 0.203 -0.083
                                      1.45
```

The printed output lists the knots of the model at 0, 1, 2 and 2.6776 years. The left and right boundaries are located at 0 and 2.6776, respectively. The means entry lists the fixed effect estimates, which we interpret as the average SDS per time point. The time-to-time variance-covariance matrix cover four random effects (3 visits + 1 end knot). The residual variance measures the variability of the discrepancies between the model and the observed data. These three parameters (fixed, random, residual variance) are well interpretable and fully record the fitted broken stick model.

Fit nine lines

The two-line model does not fit well. We substantially refine the model by adding a knot for each scheduled visit. To make model specification independent of the data, we specify the right boundary as a constant of three years. We code and run the model as

```
R> knots <- round(c(0, 1, 2, 3, 6, 9, 12, 15, 18, 24)/12, 4)
R> fit9 <- brokenstick(hgt_z ~ age | id, data = smocc_200, knots = knots, boundary = c(0, 3), seed = 1)
```

This optimization problem is more complicated and time-consuming. As noted before, it is common for the optimization software to issue warnings, often related to the number of random effects relative to the number of observations. While these may be a little discomforting, we have found that the warnings are generally at the conservative side, and that the parameter estimates seem OK. With a small residual variance of 0.07, the nine-line broken stick model fits the observed data very well.

The training set includes all subjects. Depending on the study goals, we may wish to further improve the model fit by removing children from the data. For example, there might be children for which few observations are available, children with diseases, or children with

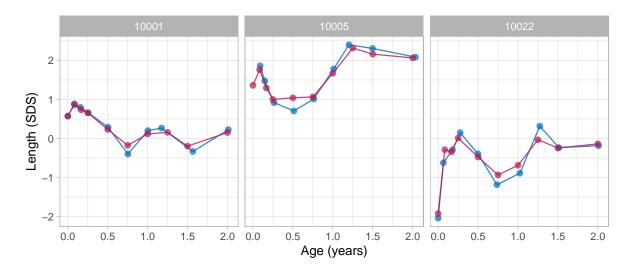


Figure 7: Broken stick model with nine lines.

trajectories that are very unusual or faulty. Use hist(fit9\$sigma2j) to spot the outlier. Of course, such removals may affect external generalisability.

5.5. Prediction

Once we have a fitted model, we may obtain predictions. The subject(s) could be part of the training sample, but could also consist of new children.

All subjects

The predict() function obtains predictions from the broken stick model. The function is flexible, and allows for prediction of new subjects at arbitrary ages in a variety of output formats. The simplest call

```
R> p1 <- predict(fit9)
R> head(p1, 3)
```

- .pred
- 1 0.57
- 2 0.86
- 3 0.75

produces the predicted value (in .pred) for each row in data.

The predicted values represent a compromise between the person's data values and the global mean. In general, the fewer and less extreme data points of a person are, the closer the compromise will be toward the global mean. The compromise is called the *conditional mean* of the posterior distribution, the sum of the fixed and random effects.

We can obtain the locations at which the lines connect by specifying the x = "knots" argument, e.g.

```
R> p2 <- predict(fit9, x = "knots")</pre>
R > head(p2, 3)
  .source
                  age sex ga bw hgt hgt_z .pred
             id
    added 10001 0.000 <NA> NA NA
                                   NA
                                         NA
                                             0.57
2
    added 10001 0.083 <NA> NA NA
                                   NA
                                         NA
                                             0.87
    added 10001 0.167 < NA NA
                                   NA
                                         NA
                                            0.73
```

This is case 1 in the help of predict.brokenstick(). The result p2 is a table with 2200 rows (= 11 knots \times 200 subjects). The rows include additional identifying information. Adding the shape = "wide" argument transforms the information into repeated measures, with 200 rows and 12 = 1 + 11 columns, that form supplemental variables for further analyses at the subject level.

We may also obtain both the conditional means as well as predictions at the observation ages for all children by

```
R> p3 <- predict(fit9, x = "knots", strip_data = FALSE)</pre>
R > head(p3, 3)
  .source
             id
                   age
                                   bw hgt hgt_z .pred
                          sex ga
1
     data 10001 0.000 female 40 3960
                                        52
                                            0.57
     data 10001 0.082 female 40 3960
2
                                        56
                                            0.89 0.86
3
     data 10001 0.159 female 40 3960
                                        58
                                           0.80 0.75
```

which contains 4140 rows (= 1940 data points + 2200 added points).

Now suppose that we desire to predict height SDS at other ages, e.g. at 0.42, 1.33 and 4 years. We can do so by (case 4, all groups)

```
R > head(predict(fit9, x = c(0.42, 1.33, 4), shape = "wide"), 3)
```

Thus, we have some flexibility to work with times that are not breakpoints. Remember though that the underlying model did not change. For example, we cannot magically predict outside the model at age 4.

Single subject

Obtaining predicted values per subject requires the group argument (case 3). For example

```
R> predict(fit9, group = 10001, shape = "vector")
```

```
[1] 0.57 0.86 0.75 0.65 0.23 -0.17 0.12 0.15 -0.15 0.15
```

returns the vector of predictions for child 10001. Remove the **shape** argument to append the child's data. Also, here we can predict at other times using the x argument (case 4).

Now suppose that for subject 10001 we have additional height data at ages 0.42 and 1.33 years. Can we predict the child's trajectory with these new points included? The answer is yes. The command (case 5)

```
R > tail(predict(fit9, x = c(0.42, 1.33), y = c(-0.5, -1),
               group = c(10001, 10001), strip_data = FALSE), 3)
   .source
              id age
                         sex ga
                                   bw hgt hgt_z .pred
10
      data 10001 2.01 female 40 3960
                                       88
                                          0.23 0.06
     added 10001 0.42
                        <NA> NA
                                       NA -0.50 0.16
11
                                   NA
     added 10001 1.33
                                       NA -1.00 -0.30
12
                        <NA> NA
                                   NA
```

appends two new records to the data of child 10001, and recalculates the trajectory using all data.

New subject

Suppose we have measured two children, Fred and Alice. We wish to obtain predictions for both using the model fit9. The following snippet calculates predictions at both the observed ages and at the knot locations:

```
R> data <- data.frame(
+ age = c(0, 0.12, 0.32, 0.62, 1.1, 0.25, 0.46),
+ hgt_z = c(-1.2, -1.8, -1.7, -1.9, -2.1, -1.9, -1.5),
+ id = c(rep("Fred", 5), rep("Alice", 2)))
R> p <- predict(fit9, newdata = data, x = "knots", strip_data = FALSE)
```

We can plot the trajectories data by

```
R> plot(fit9, newdata = data, ylim = c(-2.5, 0),
+ xlab = "Age (years)", ylab = "Length (SDS)")
```

Alice contributes only two data points in the first half-year. The model expects that her height SDS will be around -1 SD at the age of two years. Using the data up to 1.1 years, the model predicts that Fred's growth curve remains around -2.0 SD until Fred is 1.5 years, and then increases to around -1.8 SD. While both predicted trajectories are extreme extrapolations, the example illustrates that it is possible to make informed predictions using just a handful of data points.

The brokenstick:::EB() function implements the empirical Bayes (EB) estimate, also known as BLUP (Skrondal and Rabe-Hesketh (2009), p. 683). The procedure is the workhorse underlying the predict() method.

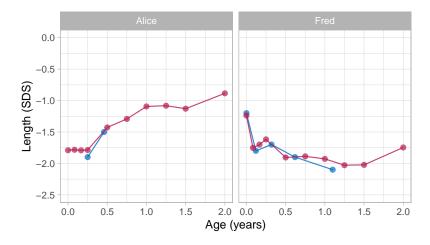


Figure 8: Alice and Fred - observed (blue) and fitted (red) trajectory.

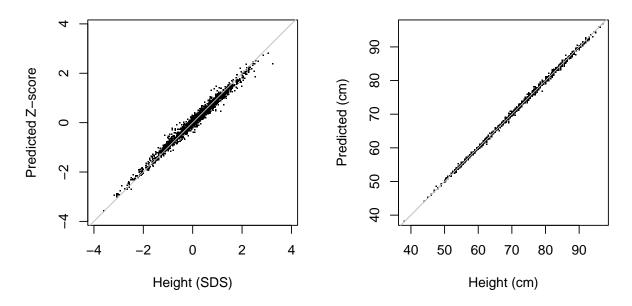


Figure 9: Predicted versus observed values.

5.6. Quality of prediction

Figure 9 is the scatterplot of the observed versus predicted values provides a visual representation of the accuracy of the prediction of the model in height SDS and cm scales. Both plots suggest an excellent fit between the observed and fitted data. The percentage of explained variance for the height SDS is high: 97.8%. The standard deviation of the residuals is equal to 0.152 SD, a small value in the Z-scale. When back-converted to centimetres, the scatterplot of the observed versus predicted values is even a little tighter. The proportion of explained variance is close to perfection: 99.9%. The standard deviation of the residuals is 4 mm, about the size of the technical error of measurement (TEM) for duplicate measurements in infants.(Ismail, Puglia, Ohuma, Ash, Bishop, Carew, Al Dhaheri, and Chumlea 2016, Table 2)

The model is as good as it can get. The uncertainties associated with the transformation from varying observation times to repeated measures will be small. For all practical purposes, the results from a linear mixed or multilevel model and a repeated measures model are likely to be same.

5.7. Knot placement strategies

Fitting the broken stick model requires a specification of the knots. The choice of the knots influences the quality and usefulness of the solution, so exercise some care in setting appropriate knot locations.

The brokenstick() function uses the same set of knots for all subjects. By default, the procedure places the boundary knots at the range of the data and no inner knots, resulting in a model that is linear in time without breakpoints. The k argument is a quick way to add k internal knots at equidense quantiles of the time variable. For example, specifying k=1 puts a knot at the 50th quantile (median), setting k=3 puts knots at the 25th, 50th and 75th quantiles, and so on. While convenient and quick, this option can result in suboptimal knot placement that is not adequate for the problem at hand. In general, it is best to specify explicit values for the knots and boundary arguments.

Here are some suggestions for knot placement:

- 1. Rule of thumb: Limit the number of knots to the (average) number of data points per subject;
- 2. If you want to predict at specific ages, then specify knots at those ages. For example, if the scientific interest includes prediction at the age of 1 and 2 years, then include these ages as knots;
- Setting knots at scheduled visits is a sensible strategy for obtaining predictions at precisely the scheduled times. Set equidistant knots if the analysis requires a fixed time interval;
- 4. Keep the number of knots low, for speed and simplicity. Having many (≥ 10) knots can improve the fit to the data. Still, it will also increase calculation time and may result in unstable solutions. For problems that require more than 10 knots, reduce calculation time by the setting method = "kr" method, and use control_kr() to improve stability by a correlation model:
- 5. Do not place knots in sparsely filled areas of the data, e.g. in-between two visits. Doing so may result in erratic joins;

- 6. Define a starting time common to all subjects (e.g. birth) and set the first breakpoint knots[1] equal to the left boundary knot boundary[1]. The brokenstick() is already cautions to ensure this;
- 7. Order knots in size;
- 8. Use the get knots() function to extract knots from a fitted model;
- 9. Set maximum value in knots to the highest time of scientific interest, but still within the data range. Set boundary knot boundary[2] larger than this value, e.g. equal to the maximum of the time variable. Broken stick estimates at the right boundary knot have no useful interpretation, so exclude those estimates from plots and ignore them in subsequent analyses:
- 10. Set knots to explicit values to support generalisation over the time variable in the training data.

6. Applications

6.1. Critical periods

The following question motivated the development of the broken stick model: At what ages do children become overweight? Knowing the answer to this question provides handles for preventive interventions to counter obesity. Dietz (1994) suggested the existence of three critical periods for obesity at adult age: the prenatal period, the period of adiposity rebound (roughly around the age of 5-6 years), and adolescence. Obesity formed in these periods is likely to increase the obesity risk at adult age and its complications.

A growth period, bounded by ages T_1 and T_2 , is critical for adult overweight if the following criteria hold: (de Kroon *et al.* 2010)

- a. there is a significant difference in mean gain score $Z_2 Z_1$ between subjects with and without adult overweight;
- b. the gain score $Z_2 Z_1$ has an independent contribution over Z_2 to the prediction of Z_{adult} . It not only matters where you were at T_2 but also how you got there;
- c. Z_2 correlates highly with Z_{adult} , so it is easier (i.e. with higher sensitivity and specificity) to identify children at risk for adult overweight.

de Kroon *et al.* (2010) found that the age interval 2-6 years met all criteria for a critical period. Our re-analysis tests the requirements for the following age intervals: birth-4 months, 4 months-1 year, 1-2 years, 2-4 years, 4-6 years, 6-10 years and 10-14 years. Hence, we define the following break ages:

```
R> knots <- round(c(0, 1/3, 1, 2, 4, 6, 10, 14, 24, 29), 3)
R> labels <- c("birth", "4m", "1y", "2y", "4y", "6y", "10y", "14y", "24y", "")
```

The Terneuzen Birth Cohort (de Kroon, Renders, Kuipers, van Wouwe, van Buuren, de Jonge, and Hirasing 2008) comprises of 2604 children born around the year 1980 in Terneuzen, The Netherlands. Figure 10 shows the BMI standard deviation scores (SDS) against age in a

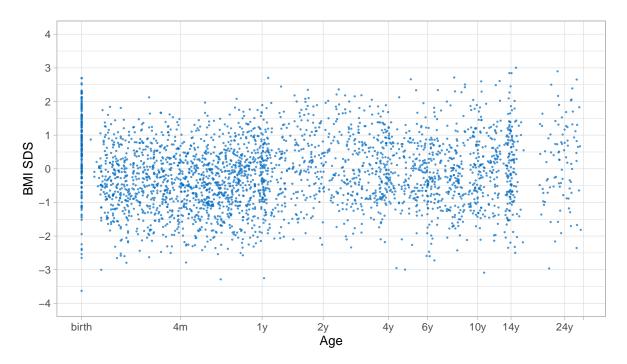


Figure 10: Body Mass Index (BMI) SDS by log(age + 0.2) (Terneuzen cohort)

random subset of 306 children. While we may easily recognise scheduled visits at birth, 1y and 14y, observations at other periods are less structured. Compared to the analysis in de Kroon *et al.* (2010), we removed the knots at 8 days and 18 years (because these appear in sparse data areas) and added knots at 4, 14 and 24 years. We set the right boundary knot to 29y, slightly higher than the maximum age in the data.

The control specification prevents warnings and messages that result from the over-parametrised nature of the model.

Figure 11 shows observed and fitted BMI SDS trajectories for six subjects using the lmer method. In general, the model fits the data well. The per cent explained variance of BMI SDS obtained by get_r2(fit_lmer) equals 84 per cent. Note that he fitted trajectory for subject 8 reveals a pretty rough estimate at the age of 24y. Persons 1259 and 7460 have very low (-2.5 SD) and high (+2.5 SD) BMI SDS at adult age, respectively. Note that the

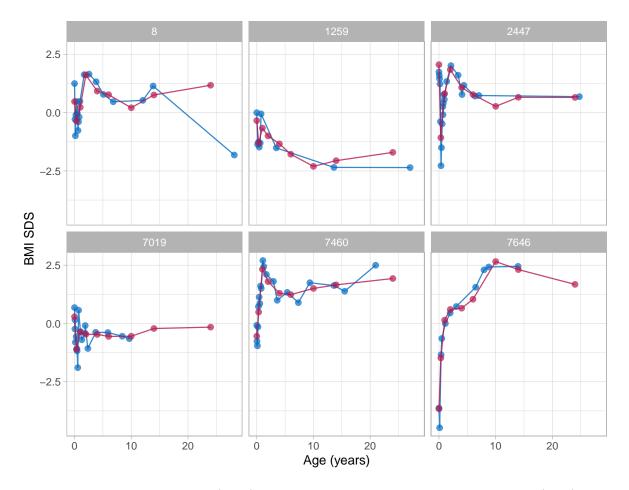


Figure 11: Body Mass Index (BMI) SDS trajectories of six subjects, observed (blue) and fitted (red). Imer method.

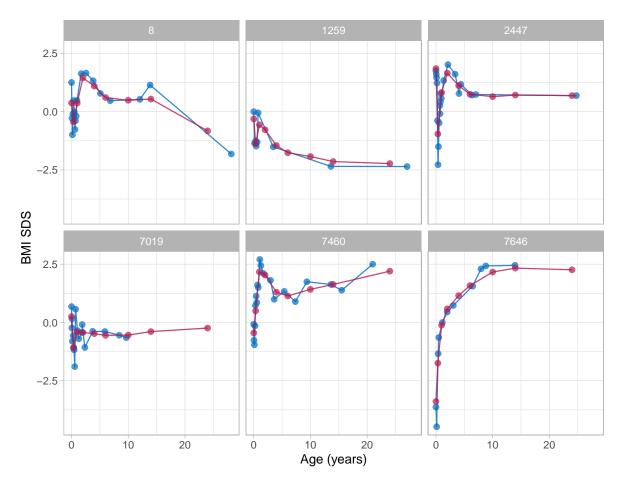


Figure 12: Body Mass Index (BMI) SDS trajectories of six subjects, observed (blue) and fitted (red). Argyle correlation model.

model pulls the adult BMI SDS estimates (in red) towards the global mean, due to the well-known bias-variance tradeoff. (Gelman and Hill 2007, pp. 394) Pulling is more vigorous at the extremes. The effect is negligible for more average trajectories, such as for subject 2447.

One may stabilise the model by constraining the variance-covariance matrix, for example by the Argyle correlation model. As a result, the fitted trajectories will be much stabler in regions with sparse data. The following snippet applies the Argyle model.

Figure 12 is the equivalent to Figure 11, but with the Argyle correlation model. The per cent explained variance is the same. Due to the constraint placed on the covariance matrix, the trajectories are slightly smoother and more stable in the adult ages with limited data. The rough estimate for subject 8 has gone. There is still some gravity towards to global mean at knot 24y for persons 1259 and 7460, but it is of lesser magnitude. All fitted trajectories are well behaved. We, therefore, select the kr solution for further analysis.

To identify critical periods, we need to predict adult overweight. In Figure 12, only three out of six subjects had a BMI measurement at adult age. Since we do not want the results to overly depend on fitted extrapolations, we restrict the analysis sample to persons with an adult measurement. The following lines extract the repeated measures for 92 (out of 306) individuals for whom we observed adult BMI.

```
R> tbc1 <- mice::tbc %>%
    filter(!is.na(ao) & first) %>%
    select(id, nocc, sex)
R> tbc2 <- mice::tbc.target %>%
    filter(id %in% tbc1$id)
R> prd <- predict(fit_kr, mice::tbc, x = "knots",</pre>
                 shape = "wide", group = tbc1$id)
R> data <- bind_cols(prd,
                     select(tbc1, -id),
                     select(tbc2, -id))
R> head(data, 3)
# A tibble: 3 x 15
          '0' '0.333'
                                                       10'
     id
  <dbl> <dbl>
                <dbl>
                         <dbl>
                                <dbl>
                                       <dbl>
                                               <dbl>
                                                      <dbl>
                                                              <dbl>
                                                                     <dbl>
                                                                            <dbl>
      8 0.371 -0.439
                      0.366
                                1.45
                                        1.10
                                               0.606
                                                      0.489 \quad 0.542 \quad -0.825 \quad -1.18
     60 0.159 -0.372 -0.0443 -0.360 -0.595 -0.819 -1.03 -1.16 -1.46 -1.39
     97 1.68
                0.569 0.948
                                1.90
                                        1.28
                                               0.838 0.444 0.239
                                                                     0.397 0.708
# ... with 4 more variables: nocc <dbl>, sex <dbl>, ao <dbl>, bmi.z.jv <dbl>
```

Figure 13 shows the 92 fitted trajectories coloured by adult overweight status (BMI SDS > 1.3). It is evident that BMI SDS at ages of 14y or 10y is highly predictive of adult overweight, but does that also hold in early childhood? Also, does a change in specific periods predict later overweight? To answer such questions, we fit simple linear models to predict observed (not fitted!) BMI SDS at adult age from the fitted BMI SDS trajectories. The following code block fits two models for the period 4y-6y.

```
R> m1 <- lm(bmi.z.jv ~ '6', data)
R> m2 <- lm(bmi.z.jv ~ '6' + I('6'-'4'), data)
R> anova(m1, m2)

Analysis of Variance Table

Model 1: bmi.z.jv ~ '6'
Model 2: bmi.z.jv ~ '6' + I('6' - '4')
   Res.Df RSS Df Sum of Sq F Pr(>F)
1   90 74.3
2   89 63.4 1   10.8 15.2 0.00019 ***
---
Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
```

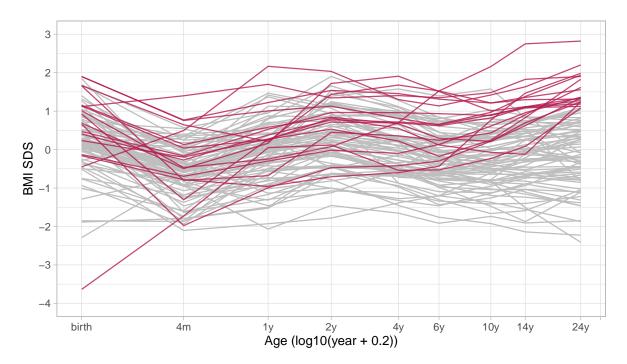


Figure 13: Body Mass Index (BMI) SDS trajectories for 92 subjects, coloured by adult overweight status.

Model m1 predicts adult BMI SDS from BMI SDS 6y, and explains 45.3 per cent of the variance. Model m2 extends the model with the pre-gain between 4y and 6y. If the pre-gain improves the prediction, then it matters how much you gained between 4y and 6y. In that case, we would call the interval 4y-6y a critical period. Here we found that model 2 explain 53.6 per cent variance, thus 8.3 per cent more. The anova statement performs the formal test. In this case, the pre-gain is significant over the last predictor at 6y. Thus, interval 4y-6y classifies as a critical period. We can repeat these analyses for other age intervals, similar to Table 3 in Kenward (1987).

6.2. Time-to-time correlations

The conditional gain score is defined as (Cole 1995)

conditional
$$Z_{\text{gain}} = \frac{Z_2 - rZ_1}{\sqrt{1 - r^2}},$$

where Z_1 and Z_2 are the standard deviation scores at times T_1 and T_2 , with $T_2 > T_1$, and where r is the correlation between Z_1 and Z_2 . The conditional gain corrects for regression to the mean, which is its selling point over traditional velocity measures and is less sensitive to measurement error. (van Buuren 2007) A practical difficulty is to obtain r for a given T_1 and T_2 . The time-to-time correlation matrix needs to be known. Also, we need to interpolate r if T_1 or T_2 differs from the tabulated ages.

The broken stick model provides an estimate of the time-to-time correlation matrix. The brokenstick object stores the variance-covariance matrix Ω of the random effects. For a perfectly fitting model (with $\sigma^2 = 0$) Ω equals the time-to-time covariance matrix, so then

get_omega(fit, what = "cor") gives the desired time-to-time correlation matrix. If $\sigma^2 > 0$ then Ω overestimates the covariances between the observed data. In general, we need to add the within-residual variance estimate to the diagonal, thus $\Omega + \hat{\sigma}^2 I(n_i)$ to estimate the time-to-time covariance matrix.

```
R> fit <- brokenstick(hgt_z ~ age | id, data = smocc_200,
                      knots = 1:4/2, boundary = c(0, 3))
R> omega <- get_omega(fit)</pre>
R> t2t <- omega + diag(fit$sigma2, ncol(omega))
R> round(cov2cor(t2t), 2)
        age_0 age_0.5 age_1 age_1.5 age_2
                       0.45
                                0.45
                                      0.36
age_0
         1.00
                  0.57
         0.57
                  1.00 0.83
                                0.79 0.74
age_0.5
age_1
         0.45
                  0.83
                        1.00
                                0.88 0.85
         0.45
                  0.79
                        0.88
                                1.00
                                      0.89
age_1.5
age_2
         0.36
                  0.74 0.85
                                0.89
                                      1.00
```

In child growth, we expect that the correlation tapers off as the difference between T_1 and T_2 grows. Also, for a fixed interval $T_2 - T_1$ we expect the correlation to increase with age. Ignoring the uninteresting estimate for age_3, we find that both expectations hold. Altering the number and location of the knots may change this. It is often useful to scan the time-to-time correlation matrix for gross deviations of the expectations. If such happens, one could simplify the model, for example, by subjecting Ω to a correlation model.

The above code fits a model with 22 equidistant breakpoints, which is likely large enough for most purposes. It works because it restricts the covariance-matrix by the Argyle correlation model, which summarises the information by just two parameters. We may extract or reestimate these parameters and create a one-liner for calculating r.

We cannot indefinitely add breakpoints. Suppose we double the number of knots by setting knots = seq(0, 2, 0.05). Then even kr is not able to cope and will abort with Error: Sigma is symmetric but not positive. Thus, as always, be sensible in what you ask the software to do for you.

6.3. Profile analysis

Profile analysis (Morrison 1976; Johnson and Wichern 1988) refers linear multivariate linear methods to test for differences in population means or treatment effects, typically by

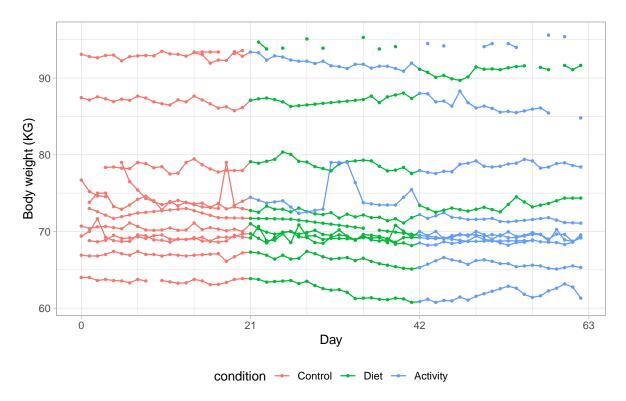


Figure 14: Daily body weight (KG) for 12 subjects under three conditions.

regression analysis or multivariate analysis of variance (MANOVA). These methods assume independence of subjects, organise the data at the subject level, and express parameters of interest by linear combinations of outcomes, like change scores, means or other derived quantities.

Krone, Boessen, Bijlsma, van Stokkum, Clabbers, and Pasman (2020) report a statistical analyses using the linear mixed model with time-varying individual subject data. This section re-analyses the data from Figure 4 using the broken stick model. The data are available as the brokenstick::weightloss object.

Figure 14 charts daily body weight measurements of twelve individuals who were followed for nine weeks. The investigators subdivided the total duration into three periods of three weeks. Period one (week 1-3) acted as a control period. During period 2 (week 4-6), the investigators stimulated participants to restrict food intake, and during period 3 (week 7-9) the experimenters promoted physical activity. Subjects 4 and 12 received the interventions in the opposite order. See Krone *et al.* (2020) for more detail.

Most of these subjects adhere quite well to the data collection design. Some trajectories show gaps due to missed measurements. The most extreme example is the trajectory at the top, which has only scant measures. Other curves display stretches of lines, suggesting that missed measurements were linearly interpolated. One of the series shows some surprising spikes, likely to be measurement errors. All in all, these data perfectly illustrate the inescapable imperfections of real data.

The remainder of the section discusses two ways to estimate the effect of diet and physical activity on body weight.

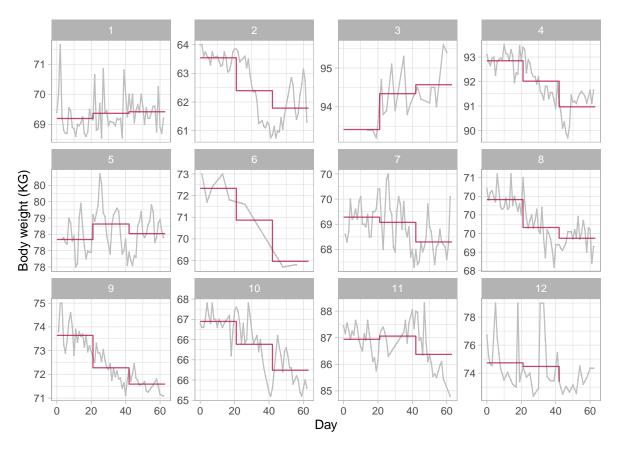


Figure 15: Constant model. Observed and fitted trajectories for a model that summarises each experimental period by a constant.

Constant model

```
R> fit0 <- brokenstick(body_weight ~ day | subject, data,

knots = c(0, 21, 42, 63), degree = 0)

R> plot(fit0, size_y = 0, color_y = rep("grey", 2), what = "all",

+ scales = "free_y", xlab = "Day", ylab = "Body weight (KG)",

+ n_plot = 12, ncol = 4)
```

The model underlying Figure 15 summarises the trajectory within a period by a constant, the mean. We obtain an estimate of these mean by setting the degree = 0 argument. This model gives a fair representation of the trajectory of subjects 9 (a persistent downward trend), 1 and 5 (no trend). On the other hand, the model fails to capture patterns for subjects 2, 4 and 8 (rebound in period 3) or 11 (inverse rebound).

It is straightforward quantify the effects of Diet and Activity relative to Control. The next code snippet calculates these effects per person, accounting for the intervention order reversal for subjects 4 and 12.

```
R> prd <- data.frame(predict(fit0, data, x = "knots", shape = "wide"))
R> control <- prd[, 2]</pre>
```

```
R> diet <- prd[, 3]</pre>
R > diet[c(4, 12)] < -prd[c(4, 12), 4]
R> activity <- prd[, 4]</pre>
R > activity[c(4, 12)] < -prd[c(4, 12), 3]
R> round(data.frame(diet control = diet - control,
                     activity_control = activity - control,
+
                     activity_diet = activity - diet), 1)
   diet_control activity_control activity_diet
1
             0.2
                                0.2
2
            -1.1
                               -1.8
                                              -0.6
3
             0.9
                                1.2
                                               0.2
4
            -1.9
                               -0.8
                                               1.0
5
             0.5
                                0.2
                                              -0.3
6
            -1.5
                               -3.4
                                              -1.9
7
            -0.1
                               -0.5
                                              -0.4
8
            -0.8
                               -1.0
                                              -0.3
9
            -1.4
                               -2.1
                                              -0.7
10
            -0.6
                               -1.2
                                              -0.6
11
             0.1
                               -0.6
                                              -0.7
12
            -1.3
                               -0.3
                                               1.1
```

The average weight under caloric restriction is 0.6 KG lower than control. In contrast, we find a 0.8 KG lower body weight when we stimulate physical activity. We could be tempted to believe that exercise reduces weight more than a diet. However, except for subjects 4 and 12, the investigators administered the activity treatment after the diet treatment, so the difference relative to control represents the *combined effect* of diet and activity on body weight. It might be more relevant to study the difference between training and diet (third column). The average difference of -0.3 KG suggests that diet is more effective than physical activity. Realise that also this estimate is not entirely satisfactory. First, subjects 4 and 12 had a reversed administration, so the difference does not make sense for them. Second, as anyone who has tried to lose weight can attest, "quick wins" are more likely in period 2 than in period 3. Although it is possible to account for these sequence effects, there is a more intuitive analysis of the data.

Broken stick model

```
R> fit1 <- brokenstick(body_weight ~ day | subject, data,

+ knots = c(0, 21, 42, 63))

R> plot(fit1, size_y = 0, color_y = rep("grey", 2), what = "all",

+ size_yhat = 1.5, scales = "free_y", , xlab = "Day", ylab = "Body weight (KG)",

+ n_plot = 12, ncol = 4)
```

Figure 16 shows the same data as in Figure 15 but now fitted by the broken stick model. This model also suggests a persistent downward trend for subject 9 and an absence of for participants 1 and 5. Also, the model now correctly identifies the prominent zig-zag patterns for persons 2, 4, 8 and 11 across the three experimental periods.

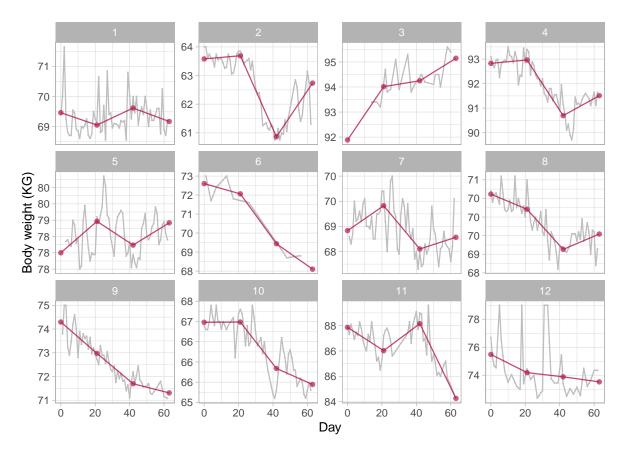


Figure 16: Broken stick model. Observed and fitted trajectories for a model that summarises each experimental period by a line.

A natural way to quantify the effect of the intervention is to calculate the before-after estimate per period. For example, for person 2 the effect of diet is 60.9 - 63.6 = -2.7 KG, of activity is 62.6 - 60.9 = +1.7 KG. The following code accounts for the alternate treatment ordering of subjects 4 and 12.

```
R> prd <- data.frame(predict(fit1, data, x = "knots", shape = "wide"))
R> control <- prd[, 3] - prd[, 2]</pre>
R> diet <- prd[, 4] - prd[, 3]</pre>
R > diet[c(4, 12)] < -prd[c(4, 12), 5] - prd[c(4, 12), 4]
R> activity <- prd[, 5] - prd[, 4]</pre>
R > activity[c(4, 12)] \leftarrow prd[c(4, 12), 4] - prd[c(4, 12), 3]
R> round(data.frame(control = control,
                     diet = diet,
+
                     activity = activity), 1)
   control diet activity
      -0.4 0.6
1
                      -0.4
2
       0.1 - 2.8
                       1.9
3
       2.1 0.2
                       0.9
4
       0.1 0.8
                      -2.3
5
       1.0 - 0.7
                       0.7
      -0.5 -2.6
                      -1.3
6
       0.5 - 0.9
                       0.2
7
      -0.4 -1.1
                       0.4
8
9
      -1.3 -1.3
                      -0.4
10
       0.0 - 1.1
                      -0.4
      -0.9 1.1
11
                      -2.9
12
      -1.3 -0.4
                      -0.3
```

The average effects are -0.2 KG (control), -0.7 KG (diet) and -0.3 KG (activity). Although not statistically significant, the slight decrease of -0.2 KG during the control period suggests that weight monitoring by itself may motivate the participant to lose weight. The effect estimates for diet and activity are of similar magnitude as before. Still, they can be sizeable discrepancies at the individual level, e.g. for subjects 2 or 11.

We may obtain a simple estimate of the sequence effect by linear regression as

```
(Intercept) act per2
-0.706 0.353 0.025
```

The result is a little surprising. When applied in period 2, the intervention leads to higher body weight (+123 grammes) as compared to administration in period 3. Of course, bear in mind that we calculated these results on very few individuals. Hence, they are sensitive to substantial estimation error.

This application demonstrates that the broken stick model can effectively capture rapid linear changes in experiments. Even though the actual timing of the observations may be erratic, it is easy to define, interpret and calculate intuitive effect estimates at the individual level. Note that the analysis here assumed an instantaneous effect of the interventions. If we expect a delay, then we may right-shift the knots by a few days and re-estimate the broken stick model. By varying the number of days, we may be able to detect the optimal delay factor.

6.4. Curve interpolation

Problem

A growth chart visualises the individual trajectory relative to a set of centile lines. We may store a centile line as a set of coordinates with a relatively dense age grid. If we connect the adjacent vertices by a straight line, the centile will appear as smooth in time. However, this plotting method runs into trouble when ages are wide apart. This section shows how we can create a realistic interpolation with sparse time data.

Interpolation in measurement scale

Suppose we measured the length of a boy at the ages of 1 month (52.6 cm) and 14 months (81.7 cm). The following code block uses the AGD::y2z() function to convert the measurements to standard deviation scores (SDS) relative to the reference of the Fourth Dutch Growth Study.

```
R> boy <- data.frame(x = c(1/12, 14/12), y = c(52.6, 81.7))
R> ref <- AGD::n14.hgt
R> boy$z <- AGD::y2z(y = boy$y, x = boy$x, sex = "M", ref = ref)
R> boy$z
```

During the period the boy grows from moderately short (about -1.0 SD at month 1) to relatively tall (about +1.0 SD at month 14). Figure 17 shows the usual representation of the growth chart with a straight line drawn between the two values. Due to the convex shape of the centile lines, the straight line that connects the two measurements starts at -1.0 SD, then touches the -2.0 SD centile around 0.3 yr, is back at -1.0 SD around 0.7 yr, crosses the 0.0 SD line at 1 yr, and ends at +1.0 SD at 1.2 yr. The graph on the right-hand side portrays the interpolated growth curve in the Z-score scale. Since length growth during infancy is not linear in time, finding a real growth curve like this is extremely unlikely. Since we have just two data points smoothing the data does not help either.

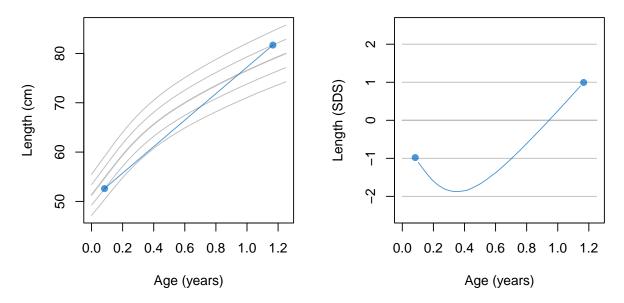


Figure 17: Linear interpolation in the cm scale results in an unrealistic trajectory at intermediate ages.

Interpolation in the Z-score scale

A first alternative is to apply the linear interpolation in the Z-score scale. This option is attractive because convexity of centile lines is absent on this scale.

Figure 18 illustrates the interpolation in the Z-scale. By definition, the line that connects the measurements is straight in the Z-score scale. In the cm scale, the representation is more realistic and more pleasing to the eye. The curve crosses the 0 SD line about halfway, at about 0.6 yr.

While this approach is a considerable improvement over interpolation in the Y-scale, it is still not ideal. The assumption underlying this interpolation is that the Z-score increment is constant across time. This assumption is false, however. Since length growth is more variable during the first half-year than in the second half-year, we expect that the larger share of the increment to occur during the earlier months. In other words, the cross-over point at 0.6 yr is too late.

Interpolation by the broken stick model

The second alternative is a model-based interpolation. Assuming the availability of a fitted broken stick model, we specify a dense time grid, say every week, and predict the length at these times given the data from the observed trajectory. The expected curve represents the most likely values under the model at the intermediate ages. The following code calculates the relevant estimates from the fit_200 fitted model:

```
R> # prepare data input
R> age <- round(seq(2/24, 28/24, 1/24), 3)
R> z <- rep(NA, length(age))
R> z[1] <- boy$z[1]; z[length(z)] <- boy$z[2]
R>
```

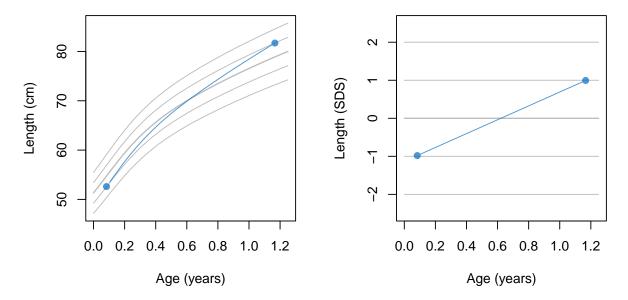


Figure 18: Linear interpolation in the Z-score scale results in a more realistic trajectory at intermediate ages.

```
R> # predict with broken stick model
R> zout <- predict(fit_200, x = age, y = z, shape = "vector")
R>
R> # convert predicted values to Y-scale
R> yout <- AGD::z2y(x = age, z = zout, ref = ref)</pre>
```

Figure 19 shows the results of the broken stick model. The predicted curve in the Y-scale represents the most likely course according to the broken stick model. Because growth is more variable during early infancy, the child realises the larger share of the change during the first part of the period. As a result, the cross-over point where the predicted value intersects the 0 SD line is now at 0.4 yr, considerably earlier than obtained by the two other interpolation methods. The plot on the right-hand side confirms the steeper slope in the first part. Note that this method treats rising and declining curves alike. For example, if the boy's length would be 57 cm at month 1 (+1.0 SD) and 76 cm at month 14 (-1.0 SD), the cross-over point would also be at 0.4 yr.

Observe that we left the world of pure interpolation and moved to an approximation of the data by a model. The observed and predicted lengths are not exactly equal. The difference is so small that we may hardly notice the discrepancy when plotted in the Y-scale, but it is more conspicuous in the Z-score scale. Of the three approaches considered here, the broken stick model provides the most realistic expected trajectory at the intermediate ages.

6.5. Multiple imputation

Remember from section 2 that the broken stick estimates are conditional means. We may be tempted to analyse these estimates as if they were "just data", but they do not have the same variability as the real data. For example, suppose we calculate the correlation matrix of the broken stick estimates. We know that the values in this matrix will exceed those from

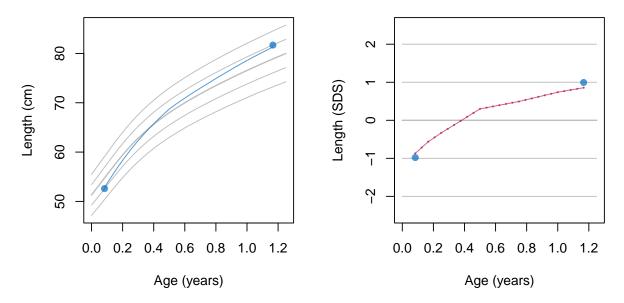


Figure 19: Broken stick model fitted in the SDS scale results in a most realistic expected trajectory at intermediate ages.

the underlying observed data. Not accounting for this fact leads to overconfident predictions and results that are too good to be true.

Multiple imputation (Rubin 1987; van Buuren 2018b) restores variability by adding noise. We may fit standard complete-data software to the imputed data, and obtain valid regression weights, confidence intervals and *P*-values under a wide range of conditions.

By default, method kr executes 200 iterations of the Kasim-Raudenbush sampler. The imp_skip argument to the control_kr() function specifies the interval at which the method adds noise to the broken stick estimates. The following code block appends the break ages to the input data and sets imp_skip = 10. The call to the brokenstick() function thus creates 20 imputations for each missing outcome (hgt_z here).

Figure 20 displays the observed data from three persons plotted on top of 20 imputed trajectories. The within-person within-time average over the grey trajectories approximates to the broken stick estimate (not shown here). The observed curve in each panel occasionally strays towards the boundaries of the grey bundle. This behaviour is as expected and indicates that the blue curve performs like a grey curve.

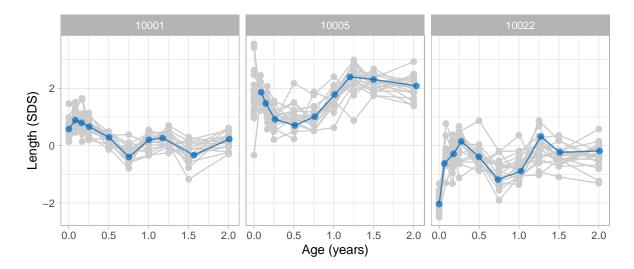


Figure 20: Observed data plotted on top of 20 imputed trajectories.

Section 5.2 showed how we can estimate the time-to-time correlation matrix. An alternative way is to calculate it from the imputed data, as follows:

```
R> expand.grid(id = unique(smocc_200$id), age = knots) %>%
    bind_cols(as.data.frame(fit_kr$imp)) %>%
   pivot_longer(cols = num_range("", 1:fit_kr$control$nimp), names_to = "imp") %>%
   pivot_wider(id_cols = c("id", "imp"), names_from = "age") %>%
   select(-id, -imp) %>%
    cor() %>%
   round(2)
          0 0.0833 0.1667 0.25 0.5 0.75
                                             1 1.25
                                                     1.5
0
       1.00
              0.66
                     0.64 0.56 0.42 0.40 0.35 0.32 0.34 0.27
0.0833 0.66
              1.00
                     0.79 0.78 0.68 0.58 0.52 0.53 0.53 0.41
0.1667 0.64
              0.79
                     1.00 0.80 0.72 0.60 0.52 0.52 0.56 0.46
0.25
                     0.80 1.00 0.76 0.67 0.58 0.57 0.57 0.50
       0.56
              0.78
0.5
       0.42
              0.68
                     0.72 0.76 1.00 0.86 0.82 0.77 0.77 0.69
0.75
       0.40
              0.58
                     0.60 0.67 0.86 1.00 0.85 0.80 0.79 0.72
1
       0.35
              0.52
                     0.52 0.58 0.82 0.85 1.00 0.85 0.81 0.77
1.25
       0.32
                     0.52 0.57 0.77 0.80 0.85 1.00 0.86 0.83
              0.53
1.5
       0.34
              0.53
                     0.56 0.57 0.77 0.79 0.81 0.86 1.00 0.83
2
       0.27
              0.41
                     0.46 0.50 0.69 0.72 0.77 0.83 0.83 1.00
```

Another important application of the multiply-imputed curves is to obtain correct confidence intervals and P-values for estimates of scientific interest. The most convenient way to do this is to convert the **brokenstick** object into an object of class **mids**, as defined by the **mice** package. The **brokenstick** package currently has no features that perform the conversion.

6.6. Curve matching

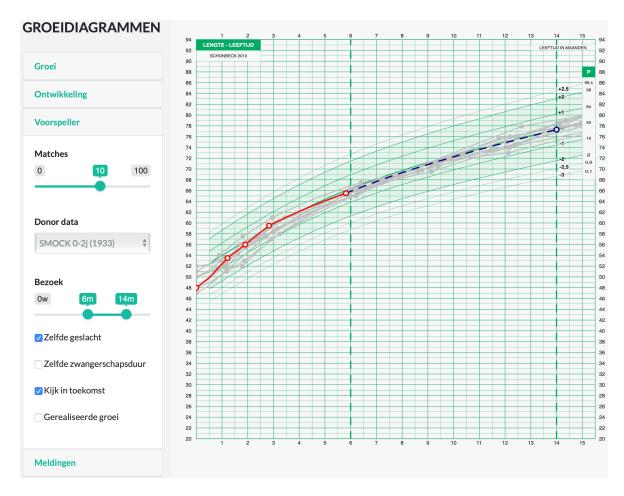


Figure 21: Curve matching. Predict infant length at 14 months given length data up to 6 months using 10 matches.

Curve matching (van Buuren 2014) is a tool to assist in the interpretation and prediction of individual growth curves. The idea is as follows. Suppose we measure the growth of the target child up to half a year and plot the measurements onto his or her growth chart. Curve matching is a nearest-neighbour technique that relies on historical growth data. It finds, say, ten other children who are similar to the target child, and add the curves of those matches to the child's chart. If the matching is done right, then the bundle of historic growth curves suggests how the target child will develop in the future.

Figure 21 demonstrates curve matching for infant length. The red curve corresponds to five measurements of the target child made during the first six months. The ten grey curves are historic growth curves from the ten matched children. We may define similarity in many ways. Here we use a linear model to predict length at the age of 14m from previous length data. The distance between the target child and another child is equal to the difference between their predicted values. The procedure lifts the data of the matches from the database, and plots the observed growth curves onto the chart as grey curves. This method for finding nearest neighbours is known as predictive mean matching and has grown into a powerful technique for missing data. (van Buuren 2018b) The bundle of grey curves indicates some possible future trajectories of the target child. The mean of the bundle is the most likely path. Graphically

it is the dotted blue curve between the last measurement and the age of the outcome.

Let's look at a numerical example. We split the data into one target child and 199 donor children, and fit a broken stick model to the donor set.

```
R> donor_data <- smocc_200 %>%
+ filter(id != "10001")
R> target_data <- smocc_200 %>%
+ filter(id == "10001" & age < 0.51)
R>
R> # fit brokenstick model at time level
R> knots <- round(c(0, 1, 2, 3, 6, 9, 12, 15, 18, 24)/12, 4)
R> fit <- brokenstick(hgt_z ~ age | id, data = donor_data, knots = knots, boundary = c(0, 3), seed = 15244)</pre>
```

All timepoints from the donor data enter the broken stick model. Note that the target_data contains only observations from the first five visits.

We now fit the prediction model on the child-level donor data. The prediction model contains the broken stick estimates for length SDS up to 6 months, as well as sex, gestational age and birth weight as covariates.

```
R> # predict with matching model at child level
R> covariates <- donor_data %>%
    group_by(id) %>%
    slice(1)
R> bse <- predict(fit, donor_data, x = "knots", shape = "wide")</pre>
R> donors <- bind_cols(covariates, select(bse, -id))</pre>
R> model <- lm('1.25' ~ '0' + '0.0833' + '0.1667' + '0.25' + '0.5'
              + sex + ga + bw, data = donors)
R> summary(model)
Call:
lm(formula = '1.25' \sim '0' + '0.0833' + '0.1667' + '0.25' + '0.5' +
    sex + ga + bw, data = donors)
Residuals:
                                     Max
             1Q Median
                              3Q
-1.3361 -0.2704 -0.0133 0.2643 1.4164
Coefficients:
             Estimate Std. Error t value Pr(>|t|)
(Intercept) -1.70e-01
                        7.19e-01
                                    -0.24
                                             0.813
°0°
             9.75e-02 4.87e-02
                                     2.00
                                             0.047 *
'0.0833'
             2.58e-02 8.27e-02
                                     0.31
                                             0.755
```

0.044 *

-2.10e-01 1.04e-01 -2.03

°0.1667°

```
'0.25'
            -2.49e-01
                                   -2.19
                                            0.030 *
                        1.14e-01
0.5
             1.22e+00
                        7.45e-02
                                            <2e-16 ***
                                   16.32
sexmale
             9.71e-02
                        6.28e-02
                                    1.55
                                            0.124
             1.30e-02
                        2.18e-02
                                    0.59
                                            0.553
ga
bw
            -1.18e-04
                        9.45e-05
                                   -1.25
                                            0.212
Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' ' 1
Residual standard error: 0.43 on 190 degrees of freedom
Multiple R-squared: 0.785, Adjusted R-squared: 0.776
F-statistic: 86.6 on 8 and 190 DF, p-value: <2e-16
```

The next step is to extract model predictions for both donors and target and find the ten closest donors.

Finally, let us study the observed and fitted trajectories of the ten matches.

The ten trajectories are all are close to the prediction (0.101 SD) for the target child at the age of 1.25y. Note that this does not guarantee that the histories are identical. Most matches have relatively flat curves, but a few (10051, 11023, 11086) show striking rising patterns. Nevertheless, these candidates are the best in terms of the model prediction.

If we wish the curves of the matches during the first six months to be closer to the target case, we could consider alternative metrics. A simple measure is the sum of squares differences of the broken stick estimates. Such a selection may be visually more pleasing, at the expense of prediction accuracy. On the other hand, we are less tied to setting one particular future time point, so other measures may work better when "future" is more vaguely defined as

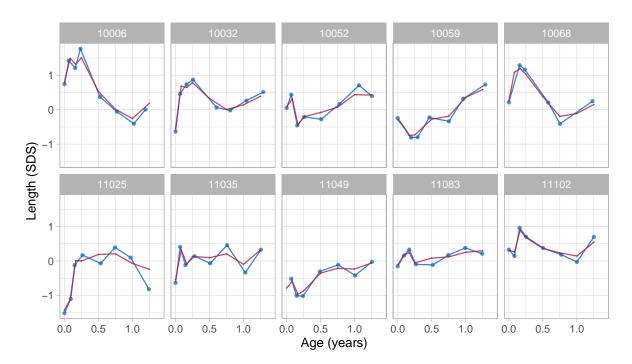


Figure 22: Curve matching. Observed and fitted trajectories of 10 matches for subject 10001.

a time interval. It is still an open research question where we strike a balance. Whatever the objectives of preferences from the user might be, the curve matching methodology, as illustrated here, has tremendous flexibility and is easy to adapt.

7. Conclusion

Overview

This paper introduces a new approach to solve the problem of irregular longitudinal data. The method absorbs the time-dependent information into a set of broken stick estimates at the subject level. The primary advantage is that it simplifies the analysis by splitting the modelling problem into two steps. First, solve the timing problem, and then solve the substantive/scientific problem. The method is mathematically simple, using a linear B-spline, conceptually simple, yet principled.

Distinctive features

The assumptions of the model cover many cases of practical interest: a straight line between breakpoints, a multivariate normal distribution for the random effects, and the MAR assumption including future data. Despite the relatively low number of model parameters, it is possible to obtain a close fit to the data, sometimes almost up to perfect reconstruction (c.f. Figure 9). There is no need to specify equidistant breakpoints. Applications in human growth and development are often more natural using non-uniformly spaced knots, which is very easy to model. Many people find it easier to understand the raw data values than the summaries. The broken stick model invites visualisation of the actual data points against time

and makes it is easy to portray uncertainty as a bundle of curves. Such direct visualisation options contribute to the explainable and responsible personalised analyses that appeal to a broad user group.

Current limitations

The broken stick model, as presented here, uses just three variables: time, measurement and group. This design choice simplifies interpretation and estimation. The lack of covariates in the model implies that the transformation from irregular data to repeated measures is identical for every subject. As long as the residual error is small, the relations with not-in-the-model variables thus remain intact. The possibility to include covariate in a second-round enhances modular modern analytic pipelines. Yet, some will prefer the direct estimation of all effects in one more extensive analysis. The current package does not support covariates. However, an experienced R user will have no difficulty in extending the formula in section 3.5 to include the covariates of interest.

The method that requires that all subject share the same time axis and breakpoints. In our applications, synchronisation at the start was most natural (e.g. birth, start of experiment), which is easy to do. In some cases, one might wish to anchor in the middle, e.g. at menarche, which occurs at different ages for different individuals.(Naumova, Must, and Laird 2001) It could also make sense to fasten the end, e.g. at death. However, it will be hard to do meaningful predictive analysis as we cannot anchor alive subjects. The choice of the anchor may matter less for cyclic processes. The broken stick model is not suited for applications where breakpoints vary between individuals. In those cases, it is better to use the linear mixed model directly.

Software

The Kasim-Raudenbush sampler (Kasim and Raudenbush 1998) is both fast and flexible. It produces estimates of the residual error variance per subject, can accommodate for correlation models and supports multiple imputation out-of-the-box. More research needed to establish its statistical properties especially compared to lmer() and other established methods. It would also be interesting to study the suitability of the correlation models implemented in the lme4qtl package (Ziyatdinov, Vázquez-Santiago, Brunel, Martinez-Perez, Aschard, and Soria 2018). As no training data are stored, instances of the brokenstick model class are tiny, often 15–20k.

Features not implemented, but that could be useful in future versions include a separate impute() function that inputs class brokenstick and returns class mids, a Trelliscope (Hafen and Schloerke 2020) viewer to quickly peruse hundreds of individuals model fits, an extension to multivariate time-varying and child-level data, and a generalisation to degree > 1 to support quadratic and cubic splines.

Methodological advances

The primary modelling task for the user is to set the proper knot locations. One might envision scenarios where we want to search for the "best" places. It is not yet clear how we should do this, and how far we could automate knot placement strategies.

We need more insight into the statistical properties of procedures that execute the analysis

as a sequence of steps. The relative pro's and con's of choices between multiple imputation versus random effects are not yet fully understood.

The current procedure assumes that the within-person error is constant across all time points. However, we might expect that observing more data close to the breakpoint will reduce the uncertainty of its estimate. In some applications, we might require that the estimate should equal the observed data value when the observation time coincides with the breakpoints. While models for such scenarios are considerably more complicated, they could also increase efficiency.

Conclusion

This paper highlighted various applications of the broken stick model: critical periods, time-to-time correlation, profile analysis, curve interpolation, multiple imputation and personalised prediction. These applications certainly do not exhaust the potential of the model. My hope is that the availability of the software will stimulate creative uses, ideas and experiments.

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