Computer Architecture Lab 3 Report

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The task of this lab is to extend Ramulator to evaluate two memory scheduling policies: ATLAS and BLISS. Before the actual implementation of the new policies, the scheduler was refactored using the strategy design pattern to make the code easier to extend. The refactoring removes many nested if-statements and moves fields, that were only relevant to certain policies, to the respective policy class.

Task 1: Implementing ATLAS

For implementing ATLAS, we need to track for each thread the attained service (AS) in the current quantum and the overall AS (TotalAS) up to the current quantum. Ramulator executes only one thread per core, so coreid is used to identify a thread.

Each memory controller (see Controller.h) tracks the AS of a thread during a quantum in the vector attained_service. When a request is issued, the corresponding vector entry is incremented. The counter is enclosed in a ifstatement so the counter is only incremented on the first command of a request (see line 417).

ATLAS requires a meta-controller to coordinate multiple memory controllers. The meta-controller is implemented in the Memory class because the class holds references to all memory controllers. At the end of a quantum, the meta-controller fetches and accumulates the AS values for each thread (see line 295-302 in Memory.h). Then, the meta-controller recalculates the TotalAS for each thread and passes the new value to all memory-controllers (see line 304-313).

The actual policy is implemented in Scheduler.h by overriding the compare() function. The scheduler compares the arrival time of a request to the clock count of the memory controller to figure out if the request has been outstanding for more than T cycles (see line 229-233). If both requests are below the threshold T, the scheduler queries the TotalAS value for each request from the memory controller and picks the request with the lowest value (see line 235-241). If both AS values are the same, the scheduler prioritizes row hits and then oldest requests first.

Task 2: Implementing BLISS

BLISS requires even less machinery than ATLAS and is implemented in Controller.h. The vector blacklisted keeps track of the blacklisted threads. Two variables

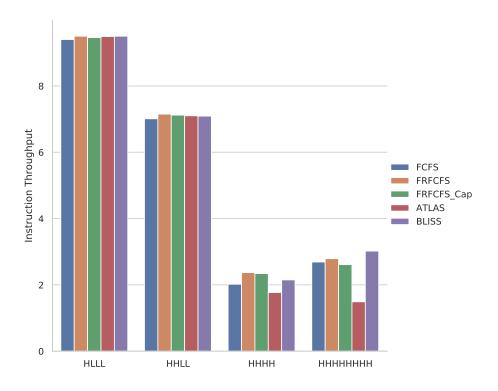


Figure 1: Instruction Throughput

 $({\tt last_request_coreid}$ and ${\tt request_served_counter})$ are used to identify malicious threads.

Similar to ATLAS the compare() function is used to pick the best request. The scheduler returns the request whose thread is not blacklisted or defaults to row hits/oldest first if a decision based on the blacklist is not possible.

Task 3: Evaluation

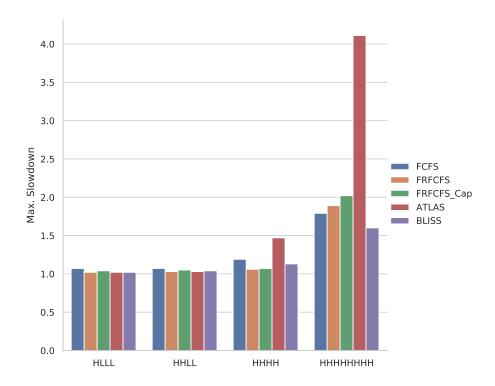


Figure 2: Max. Slowdown