

# An Evaluation of the Rotor-Router Mechanism

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# Research Background & Motivation

Looking Behind the Rotor-Router Mechanism

[ Research Background -> Simulation & Programming -> Results & Conclusion -> Questions ]

# What does the Rotor-Router Mechanism Apply to?

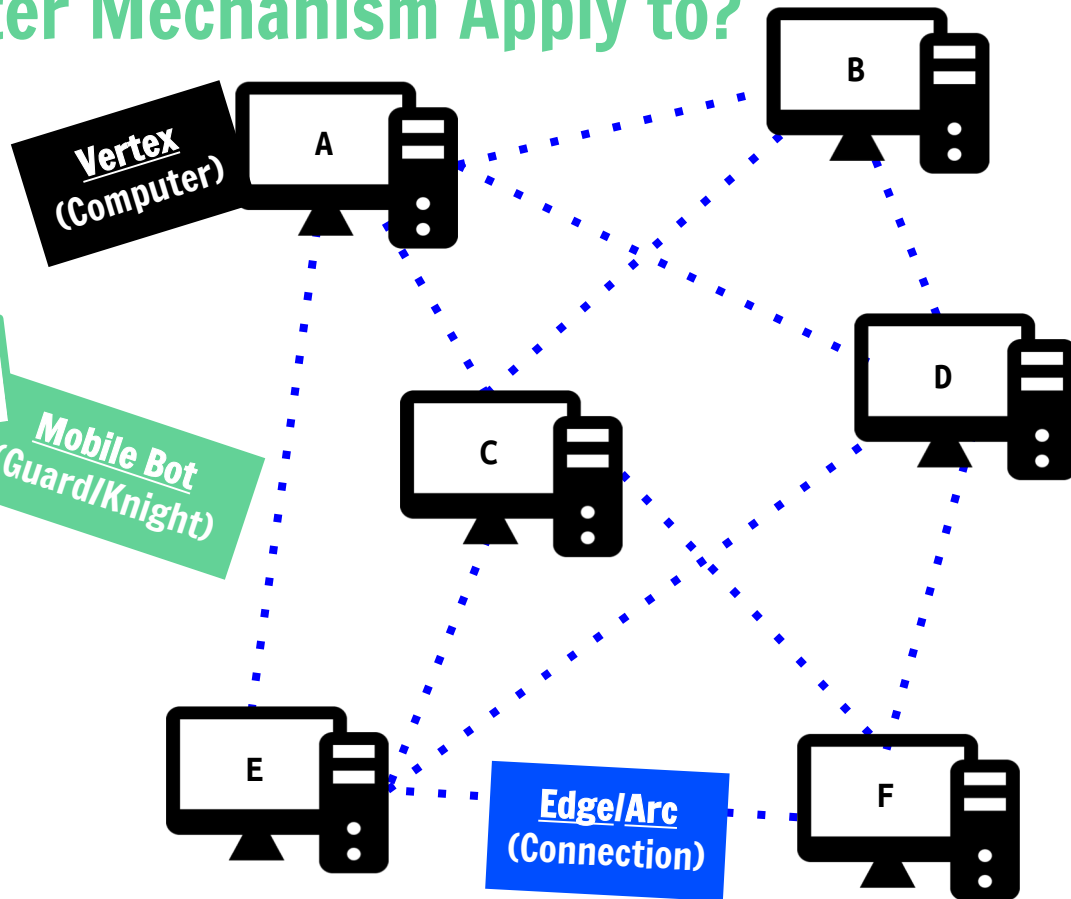
## I. Introduction

- ♞ Distributed Systems
- ♞ Patrolling Networks
- ♞ Mobile Bots
- ♞ Upgrade from Randomness!



**Mobile Bot**  
(Guard/Knight)

**Migration:** Allows a bot to move from one place to another.

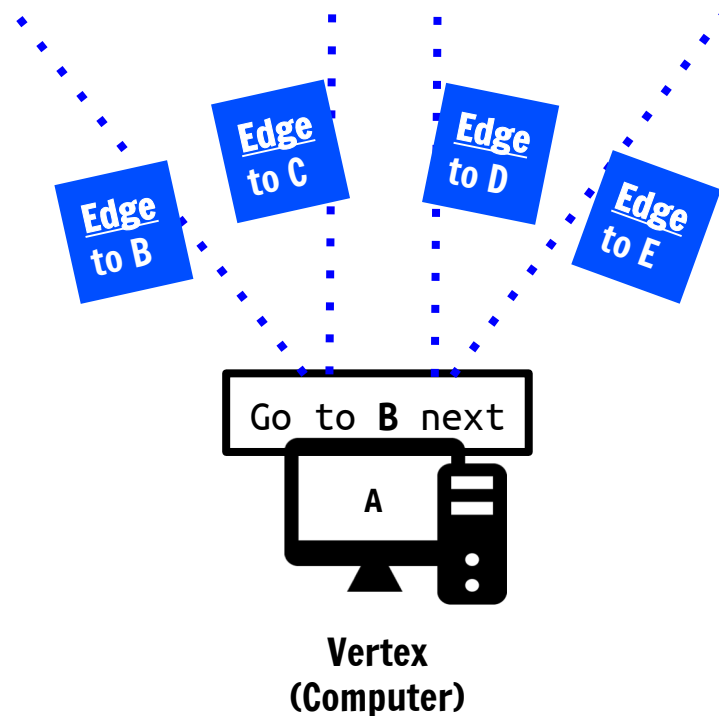


# Behind the Rotor-Router Mechanism

## II. Rotor-Router Mechanism

- Alternative to Random Walk
- Each Vertex Points to an Edge
  - ✓ **A (go to B, C, D, E, then B..)**
- Deterministic Algorithm
- Euler Cycle (Lock-In)

**Visiting:** When a bot arrives at a vertex **or** crosses an edge.



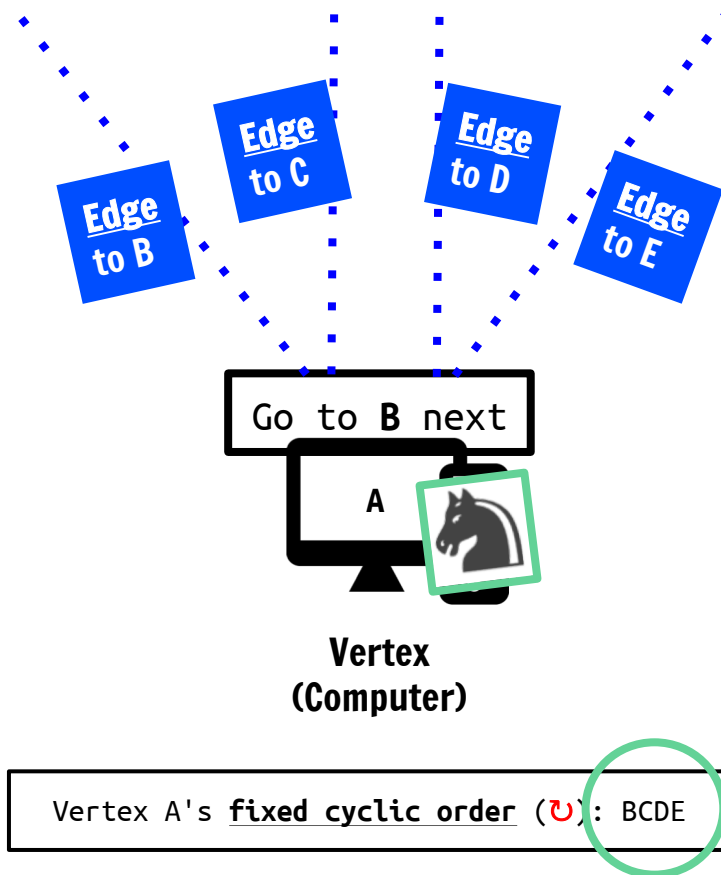
Vertex A's fixed cyclic order (↻): BCDE

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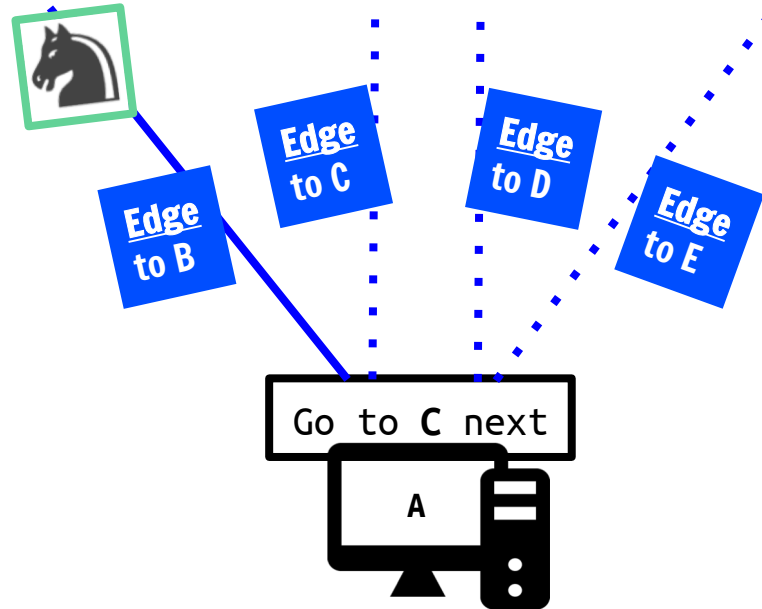


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Vertex  
(Computer)

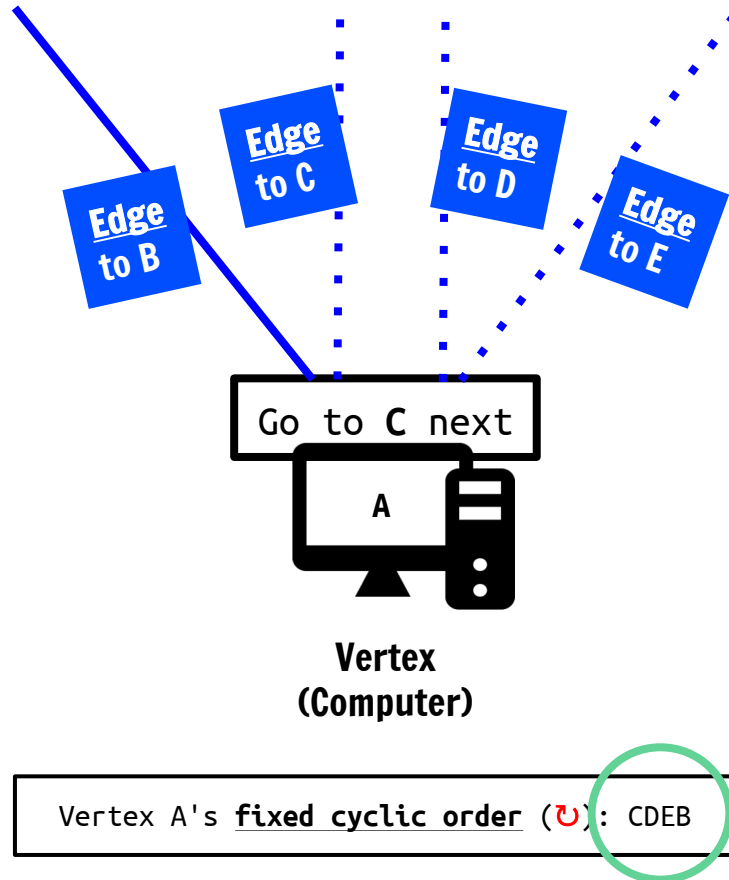
Vertex A's fixed cyclic order (CDEB): CDEB

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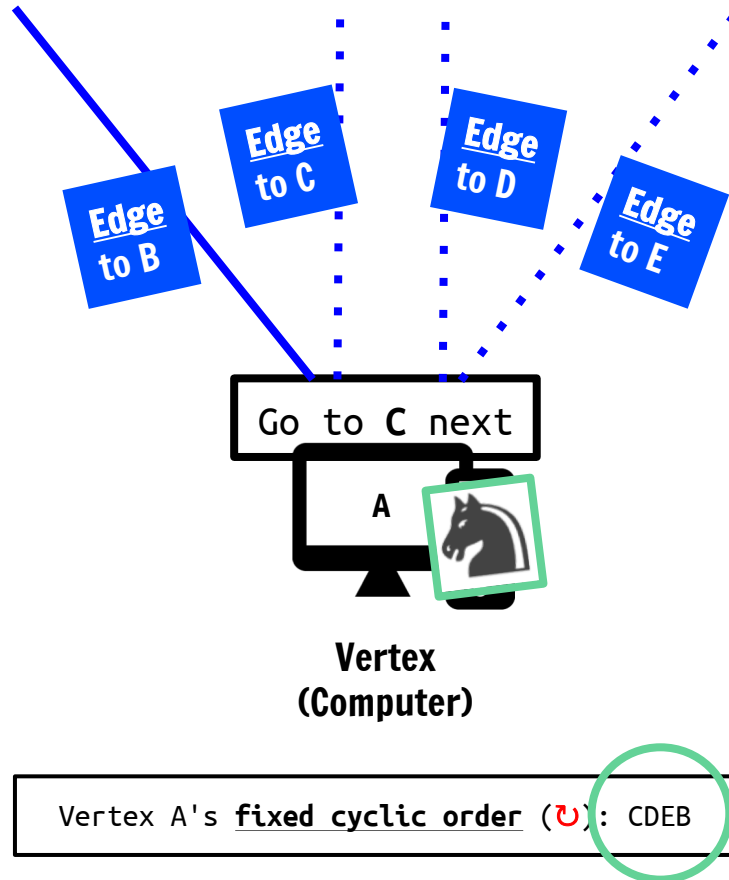


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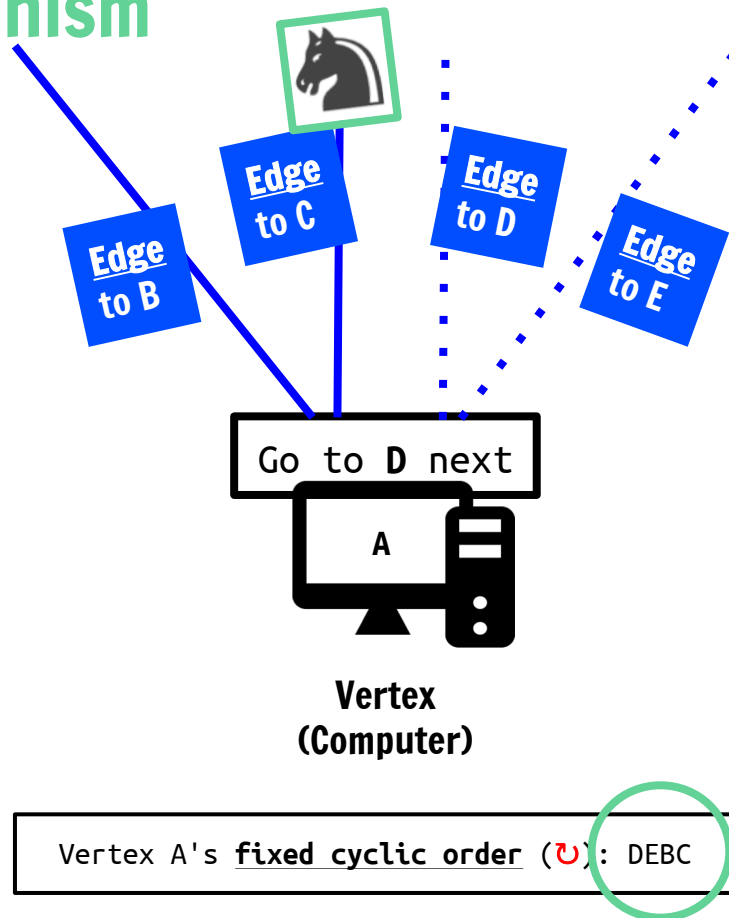


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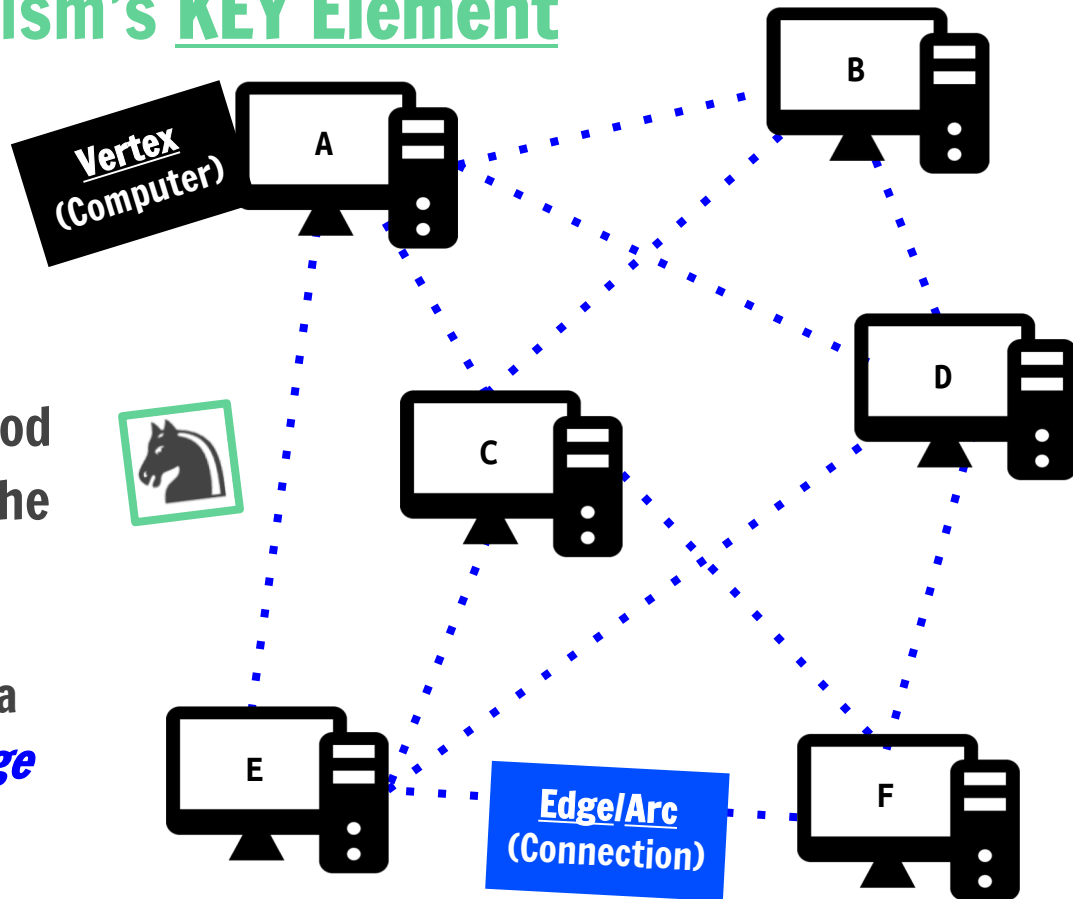


# The Rotor-Router Mechanism's KEY Element

**Euler Cycle:** A path where every edge is visited *exactly once*.

The bot will eventually end up entering a **Euler cycle** after a period of time (*exploring the network*), the **stabilization period**, passes.

**GOAL:** The overall goal is to lock into a **Euler cycle** and visit *each & every edge* as efficiently as possible.

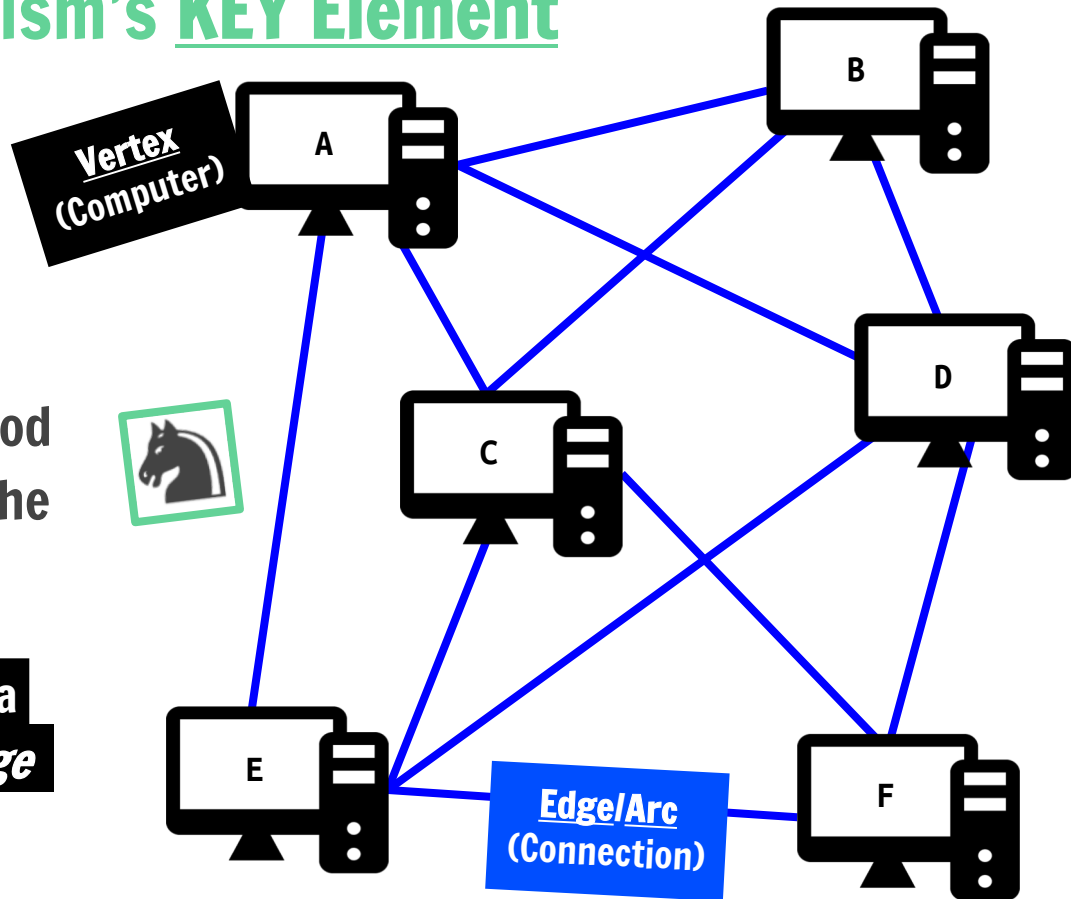


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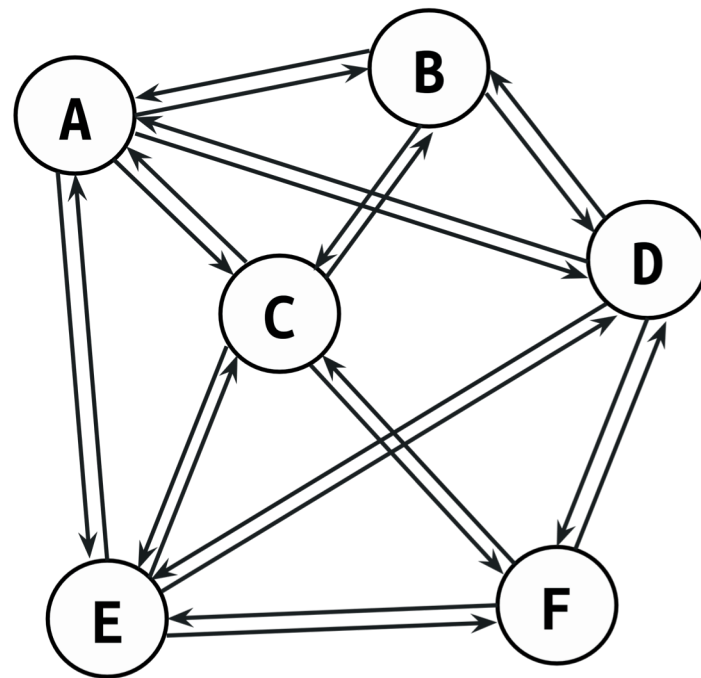


# Preparing to Observe the Rotor-Router Algorithm

I created a custom "network" with arrows (arcs, rather than edges) that start at one vertex and end at another.

The supposed limit is  $4 \cdot m \cdot D$ , or the **number of edges** ( $m = 11$ ) multiplied by the **diameter** of the graph ( $D = 2$ )  $\Rightarrow$  **44 steps**

What are the main questions that rise from this algorithm, and why perform a simulation?



*Simplified visual of the previous diagram*

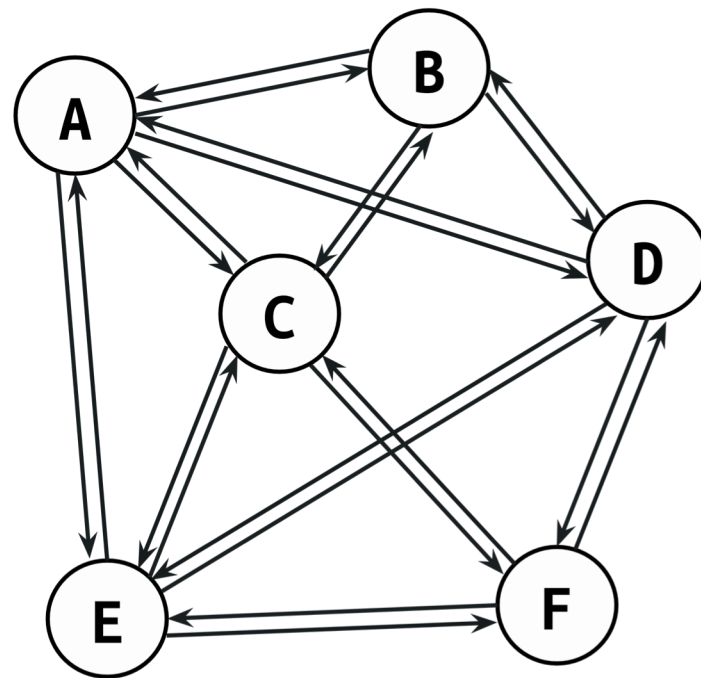
# Preparing to Observe the Rotor-Router Algorithm: Mysteries

The supposed limit is  $4 \cdot m \cdot D$ , or the **number of edges** ( $m = 22$ ) multiplied by the **diameter** of the graph ( $D = 2$ )  $\Rightarrow$  **44 steps**

## Mysteries (Why, Why, Why?)

**[1]** No matter where the bot starts, it will always end up in a forever lasting loop.

**[2]** The worst case is **44 steps** (for this example), but what is the **average case**? Is it **close to 44**, **close to 0**, or **in the middle**?



*Simplified visual of the previous diagram*

# Simulations & Programming

What simulations did I run to get the data I needed?

[ ~~Research Background~~ -> **Simulation & Programming** -> Results & Conclusion -> Questions ]

# Simulation Program (C++)

*Files: Edge.h, Vertex.h, Graph.h, StatList.h, Functions.h, Edge.cpp, Vertex.cpp, Graph.cpp, StatList.cpp, Functions.cpp, main.cpp*

```

41 int mobileAgent(Graph graph, Vertex* start, int iterations, string& temp) {
42     Vertex* destination = NULL;
43     for (int i = 0; i < iterations; i++) {
44         int currentIndex = start->getIndex();
45         start->edgeToCross(start, currentIndex)->incrementVi;
46         Edge* cross = start->edgeToCross(start, currentIndex);
47         destination = cross->getEndVertex();
48     }
49
50     cout << "[Step " << i+1 << "] Agent crosses the EDGE
51     << cross->getStartVertex()->getName() << cross->getEi
52     << " and is now at VERTEX " << cross->getEndVertex();
53
54     graph.insertEdgeToOverall(cross); //New
55     destination->incrementVisited();
56     start->changeIndex();
57     start = destination;
58 }

```

**Input:** # of **steps** (for the agent)

# of **tests** (for accuracy)

**Output:** Average visit count (edge)  
Average visit count (vertex)  
Stabilization period  
(average, min, max, distr)  
Euler cycle (repeated forever)

**Line Count:** 673 (11 files)

**RESULTS**

Number of STEPS per TEST: 30  
Number of TESTS: 1

Average Visited Count for Vertices

A: 6  
B: 3  
C: 5  
D: 6  
E: 6  
F: 4

Average Visited Count for Edges

AB: 3  
AC: 2  
AD: 3  
AE: 3  
BC: 2  
BD: 2  
CE: 4  
CF: 2

**Stabilization Period Data**

Worst Case: 12

Average Case: 1.24542

Best Case: 0

**All Euler Cycles**

Cycle 1: AE->EC->CE->ED->DF->FD->DA->AB->BC->CF->FE->EF->FC->CA->AC->CB->BD->DB->BA->AD->DE->EA->

# Results & Conclusion

What results did I get from running 1,000,000 tests on a graph?

[ ~~Research Background~~ -> ~~Simulation & Programming~~ -> **Results & Conclusion** -> Questions ]



# Results: What did I find out?

## II. Stabilization Period & Euler Cycle

**\*\*Data that applies to only one graph\*\***

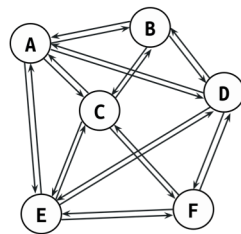
### (Stabilization Period)

- ♠ Way lower than **44 step** limit.
- ♠ Often instantly locks in (49%)
- ♠ Random initialization

### (Euler Cycle)

- ♠ Always different (each test)

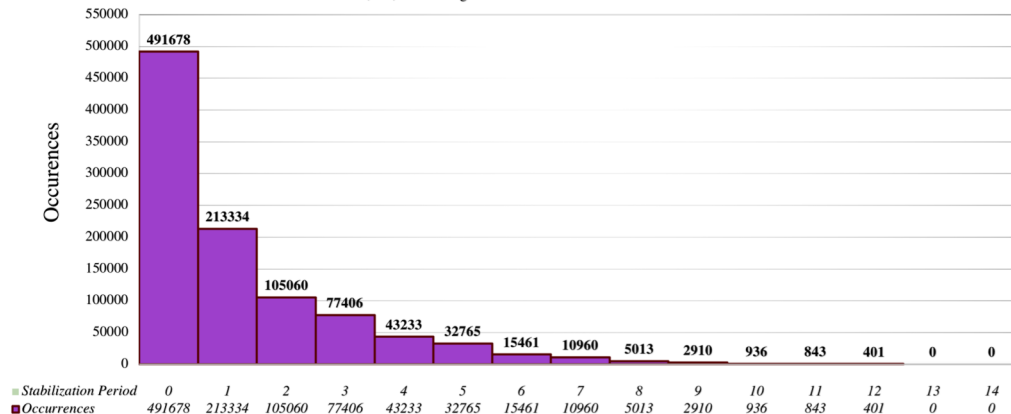
**Important:** There is no way to predict what the stabilization period average by simply looking at a network. My simulation brought these hidden statistics to light.



***Stabilization Period Statistics***  
 Locking in 2 or fewer steps => 81.01%  
 Locking in 5 or fewer steps => 96.35%  
 Locking in 10 or fewer steps => 99.88%  
 Average Lock-in Time => 1.25 steps

### Stabilization Period Distribution

T = 1,000,000 | Average: 1.251651 | Standard Deviation: 1.783



#### Sample Euler Cycles (T = 1,000,000)

C1: CB->BA->AB->BC->CE->EA->AC->CF->FD->DF->FE->EC->CA->AD->DA->AE->ED->DB->BD->DE->EF->FC

C2: FC->CA->AD->DA->AE->ED->DB->BD->DE->EF->FD->DF->FE->EA->AB->BA->AC->CB->BC->CE->EC->CF

C3: DA->AC->CE->EA->AD->DB->BA->AE->EC->CF->FE->ED->DE->EF->FC->CA->AB->BC->CB->BD->DF->FD

C4: AE->ED->DE->EF->FC->CB->BC->CE->EA->AB->BD->DF->FD->DA->AC->CF->FE->EC->CA->AD->DB->BA

# Upgrading the Rotor-Router Mechanism

## Enhancing the RR Mechanism

### (Initialization of a Graph)

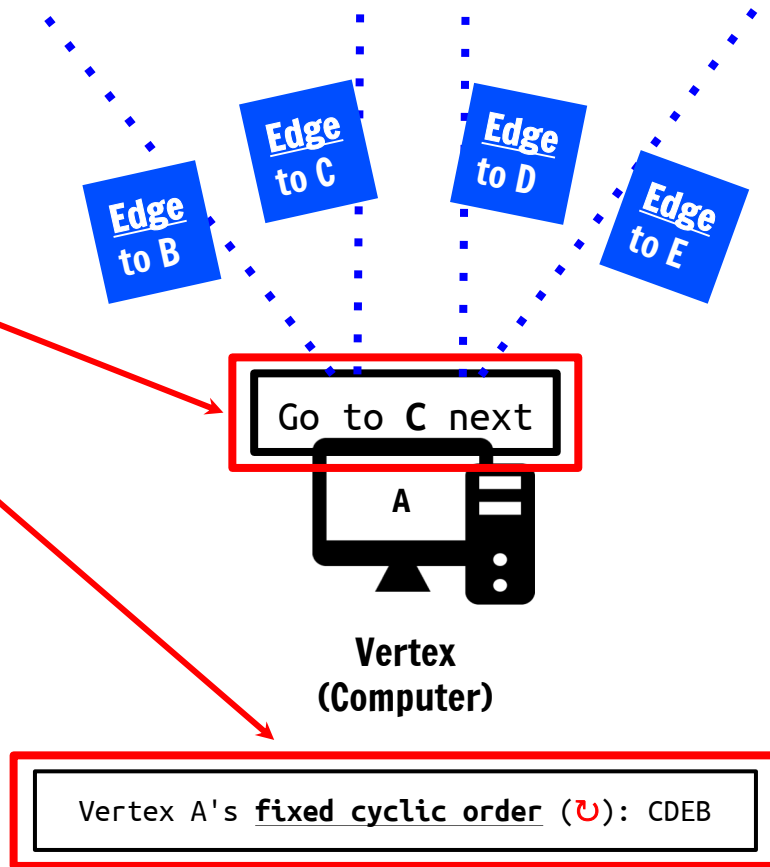
- ♞ Customizing the starting value
- ♞ Customizing the fixed order

### (Extra Additions to the Agent)

- ♞ Making the agents smarter
- ♞ Giving agents a mind (memory)

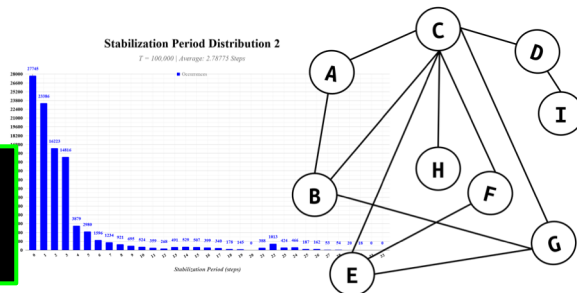
### (Increasing the Quantity)

- ♞ Multiple Agents in a Graph



# Conclusion

Stabilization Period Data  
Worst Case: 30  
Average Case: 2.78775  
Best Case: 0

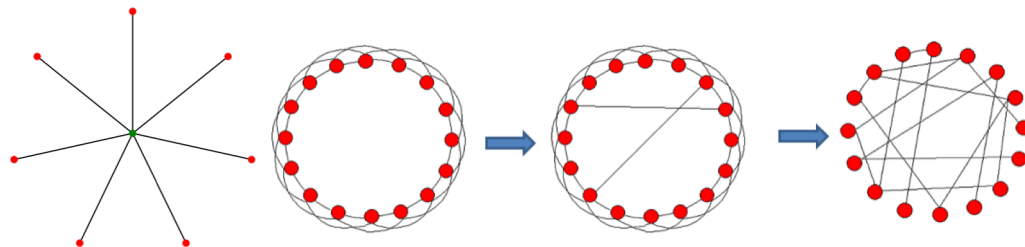


## (Thoughts & the Good Parts)

- ♞ Seeing the Rotor-Router Mechanism in action = !!
- ♞ Writing the simulation from the ground up to obtain data
- ♞ Creating animations, figures to understand the algorithm = !!
- ♞ Understanding the reliability behind RR, and the details behind mobile agents, networks

## (The Further-Research Part)

- ♞ Simulations on a variety of graphs (stars, small world, etc)
- ♞ Designing a random graph generator that works (!!)
- ♞ Investigating stabilization period & more with *multiple agents*.
- ♞ Creating a simulation program for newly proposed versions of the Rotor-Router mechanism (!!!!)



# (Some) References

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**Total:** ~140 pages

# Questions (?)

From the mechanism itself to how I ran simulations, please feel free to ask me anything!

[ ~~Research Background~~ -> ~~Simulation & Programming~~ -> ~~Results & Conclusion~~ -> **Questions** ]