CYCLE-PART 2

- 1. Create a square matrix with random integer values(use randint()) and use appropriate functions to find:
 - i) inverse
 - ii) rank of matrix
 - iii) Determinant
 - iv) transform matrix into 1D array
 - v) eigen values and vectors

CODE

```
import numpy as np
from numpy import random
x=random.randint(100, size=(3,3))
inv = np.linalg.inv(x)
print("Matrix:\n",x)
print("Inverse:\n",inv)
rank=np.linalg.matrix_rank(x)
print("Rank:",rank)
print ("Determinant:",np.linalg.det(x))
arr = x.flatten()
print("Matrix to array:\n",arr)
w, v = np.linalg.eig(x)
print("Eigen value:\n",w)
print("Eigen Vector:\n",v)
```

```
Matrix:
 [[78 66 1]
 [65 21 10]
 [15 63 63]]
 [[-0.00342161 0.02021863 -0.00315499]
 [ 0.01947802 -0.02418829  0.00353024]
 [-0.01866335 0.01937433 0.01309397]]
Rank: 3
Determinant: -202536.00000000003
Matrix to array:
 [78 66 1 65 21 10 15 63 63]
Eigen value:
 [-25.92582736 125.85172975 62.07409761]
Eigen Vector:
 [[-0.47449916 0.64425209 -0.14036951]
  0.75404373 0.45781704 0.0188726 ]
 [-0.45416803 0.61265227 0.9899193
```

OR

```
import numpy as np
import numpy as nf
from numpy.linalg import eig
mat = np.random.randint(10, size=(3, 3))
array = nf.random.randint(10, size=(3, 3))
print(mat)
M inverse = np.linalg.inv(mat)
print("inverse of the array")
print(M inverse)
rank = np.linalq.matrix rank(mat)
print("Rank of the given Matrix ")
print(rank)
det= np.linalg.det(mat)
print("determinant of the given Matrix ")
print(det)
arr=mat.flatten()
print("transform matrix to array ")
print(arr)
w,v=eig(array)
print('E-value:', w)
print('E-vector', v)
```

```
[[3 1 9]
[4 2 8]
[2 2 8]]
[inverse of the array
[[0. 0.5 -0.5]
[-0.8 0.3 0.6]
[0.2 -0.2 0.1]]
Rank of the given Matrix
3
determinant of the given Matrix
19.999999999996
transform matrix to array
[[3 1 9 4 2 8 2 2 8]
E-value: [6. -2.244998 10.244998]
E-vector [[1. 0.02284217 -0.88453379]
[0. -0.87936938 -0.25394881]
[0. 0.47559198 -0.3912927]]
```

- 2. Create a matrix X with suitable rows and columns
- i) Display the cube of each element of the matrix using different methods

(use multiply(), *, power(),**)

- ii) Display identity matrix of the given square matrix.
- iii) Display each element of the matrix to different powers.
- iv) Create a matrix Y with same dimension as X and perform the operation X^2+2Y

```
import numpy as np
 arr1 = np.array([[1, 2, 3],[3,2,4],[2,2,1]])
 print(arr1)
 print("using power()")
 print(pow(arr1, 3))
 print("using multiply()")
 print(np.multiply(arr1,(arr1*arr1)))
 print("using *")
 print(arr1*arr1*arr1)
 print("using **")
 print(arr1**3)
 b = np.identity(3, dtype = int)
 print("Identity matrix:\n", b)
 out = np.power(arr1, arr1)
 print("each element of the matrix to different powers:\n",out)
 x = np.arange(1,10).reshape(3,3)
y = np.arange(11,20).reshape(3,3)
print("perform the operation X^2 + 2Y: \n",np.add((np.power(x,2)),
(np.multiply(y,2)))
```

```
[1 2 3]
[3 2 4]
 [2 2 1]]
using power()
[[ 1 8 27]
[27 8 64]
[ 8 8 1]]
using multiply()
[[ 1 8 27]
[27 8 64]
[ 8 8 1]]
using *
[[ 1 8 27]
[27 8 64]
[8 8 1]]
using **
[[ 1 8 27]
 [27 8 64]
 [8 8 1]]
Identity matrix:
 [[1 0 0]
 [0 1 0]
 [0 0 1]]
each element of the matrix to different powers:
[[ 1 4 27] perform the operation X^2 + 2Y:
 [[ 23 28 35]
 [ 44 55 68]
 [ 83 100 119]]
```

OR

```
import numpy as np

matrix=np.random.randint(0,10,4).reshape(2,2)
print("Display the cube of each element of the matrix using different
methods (use multiply(), *, power(),**)")
x=np.power(matrix,3)
print("power()",x)

y=np.multiply(matrix,(matrix*matrix))
print("multiply()")
print(y)

z=matrix*matrix*matrix
print("**")
print(z)

cube=matrix*3
```

```
print("*")
print(cube)

print("Display identity matrix of the given square matrix.")
identity=np.identity(2,dtype=int)
print(identity)

print("Display each element of the matrix to different powers.")
dpow=np.power(matrix,matrix)
print(dpow)

print("Create a matrix Y with same dimension as X and perform the operation X^2 +2Y")
a=np.add((np.power(x,2)),(np.multiply(y,2)))
print(a)
```

3. Multiply a matrix with a submatrix of another matrix and replace the same in larger matrix.

```
\begin{bmatrix} a_{00} a_{01} & a_{02} & a_{03} & a_{04} & a_{05} \\ a_{10} & a_{11} & a_{12} & a_{13} & a_{14} & a_{15} \\ a_{20} & a_{21} & a_{22} & a_{23} & a_{24} & a_{25} \\ a_{30} & a_{31} & a_{32} & a_{33} & a_{34} & a_{35} \\ a_{40} & a_{41} & a_{42} & a_{43} & a_{44} & a_{45} \end{bmatrix} \begin{bmatrix} b_{00} & b_{01} & b_{02} \\ b_{10} & b_{11} & b_{12} \\ b_{20} & b_{21} & b_{22} \end{bmatrix}
```

CODE

```
import numpy as np
A = \text{np.array}([[6, 1, 1, 6, 3],
               [4, -2, 5, 1, 3],
               [2, 8, 7, 7, 8],
               [6, 1, 1,6,3],
               [2, 8, 7, 7, 8]]
B=np.array([[2, 1, -2],
               [3, 0, 1],
               [1, 1, -1]]
print("Mat A=\ln",A)
print("Mat B=\ln",B)
C=A[:3, :3]
res = np.dot(B,C)
print("Multiplication Result\n",res)
A[:3,:3]=res[:3,:3]
print("Resultant Matrix:\n",A)
```

```
[[6 1 1 6 3]
  4 -2 5 1 3]
  2 8 7 7 8]
    1 1 6 3]
 [[2 1 -2]
  3 0 1]
Multiplication Result
 [[ 12 -16 -7]
  20 11 10]
  8 -9 -1]]
Resultant Matrix:
 [[ 12 -16 -7 6
                 3]
8]
3]
8]]
  20 11 10
             1
   8
```

4. Given 3 Matrices A, B and C. Write a program to perform matrix multiplication of the 3 matrices.

```
import numpy as np
m1 = np.random.randint(20, size=(2, 2))
print("1 st matrix \n",m1)
m2 = np.random.randint(20, size=(2, 2))
print("2nd matrix \n",m2)
```

```
m3 = np.random.randint(20, size=(2, 2))
print("3rd matrix \n",m3)
print("multiplication of the 3 matrices")
m4 = np.dot(m1,m2,m3)
print(m4)
```

```
1 st matrix
[[12 0]
[17 12]]
2nd matrix
[[ 7 5]
[13 11]]
3rd matrix
[[ 1 5]
[ 7 12]]
multiplication of the 3 matrices
[[ 84 60]
[275 217]]
```

OR

CODE

```
import numpy as np
M1 = np.array([[3, 6], [4, 2]])
M2 = np.array([[9, 2], [1, 2]])
M3=np.array([[2,4],[3,1]])
Mul = M1.dot(M2)
mul1=M3.dot(Mul)
print("Matrix1:\n",M1)
print("Matrix2:\n",M2)
print("Matrix3:\n",M3)
print("multiplication of 3 matrices")
print(mul1)
```

```
Matrix1:
[[3 6]
[4 2]]
Matrix2:
[[9 2]
[1 2]]
Matrix3:
[[2 4]
[3 1]]
multiplication of 3 matrices
[[218 84]
[137 66]]
```

```
5. Write a program to check whether given matrix is symmetric or
     Skew Symmetric.
CODE
import numpy as np
A = np.array([[6, 1, 1],
        [4, -2, 5],
        [2, 8, 7]]
inv=np.transpose(A)
print (inv)
neg=np.negative(A)
comparison = A == inv
comparison1 = inv = neg
equal arrays = comparison.all()
skew=comparison1.all()
if equal arrays:
  print("Symmetric")
else:
  print("not Symmetric")
```

if skew:

print("Skew Symmetric")

else:

print("Not Skew Symmetric")

OUTPUT

```
[[ 6 4 2]
 [ 1 -2 8]
 [ 1 5 7]]
not Symmetric
Not Skew Symmetric
```

Solving systems of equations with numpy

One of the more common problems in linear algebra is solving a matrix-vector equation.

Here is an example. We seek the vector x that solves the equation

$$AX = b$$

$$A = \begin{bmatrix} 2 & 1 & -2 \\ 3 & 0 & 1 \\ 1 & 1 & -1 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} -3 \\ 5 \\ -2 \end{bmatrix}$$

Where

And
$$X=A^{-1}b$$
.

Numpy provides a function called solve for solving such eauations.

6. Write a program to find out the value of X using **solve()**, given **A** and **b** as above

```
[-2]])
inv=np.linalg.inv(A)
x=np.linalg.solve(inv,b)
print(x)
```

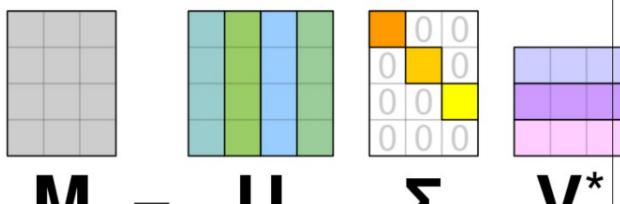
```
[[15.]
[7.]
[10.]]
```

Singular value Decomposition

Matrix decomposition, also known as matrix factorization, involves describing a given matrix using its constituent elements.

The Singular-Value Decomposition, or SVD for short, is a matrix decomposition method for reducing a matrix to its constituent parts in order to make certain subsequent matrix calculations simpler. This approach is commonly used in reducing the no: of attributes in the given data set.

M= U ∑V^T



$\mathbf{M} = \mathbf{U} \quad \mathbf{\Sigma} \quad \mathbf{V}^*$ $m \times n \quad m \times n \quad n \times n$

- **M**-is original matrix we want to decompose
- U-is left singular matrix (columns are left singular vectors). U
 columns contain eigenvectors of matrix MM^t
- Σ-is a diagonal matrix containing singular (eigen) values.
- V-is right singular matrix (columns are right singular vectors).
 V columns contain eigenvectors of matrix M^tM

Numpy provides a function for performing svd, which decomposes the given matrix into 3 matrices.

 Write a program to perform the SVD of a given matrix. Also reconstruct the given matrix from the 3 matrices obtained after performing SVD.

```
from numpy import array
from scipy.linalg import svd
from numpy import diag
from numpy import dot
from numpy import zeros
# define a matrix
A = array([[1, 2], [3, 4], [5, 6]])
print(A)
# SVD
U, s, VT = svd(A)
print("first" ,U)
print("second",s)
print("3rd", VT)
Sigma = zeros((A.shape[0], A.shape[1]))
# populate Sigma with n x n diagonal matrix
Sigma[:A.shape[1], :A.shape[1]] = diag(s)
```

```
# reconstruct matrix
B = U.dot(Sigma.dot(VT))
print(B)
```

```
[[1 2]
  [3 4]
  [5 6]]
  first [[-0.2298477   0.88346102   0.40824829]
   [-0.52474482   0.24078249  -0.81649658]
   [-0.81964194  -0.40189603   0.40824829]]
  second [9.52551809   0.51430058]
  3rd [[-0.61962948  -0.78489445]
  [-0.78489445   0.61962948]]
  [[1. 2.]
  [3. 4.]
  [5. 6.]]
```