# Task1\_PEC-PMC\_Eigenmodes

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```
In [1]: import numpy as np
        import scipy as sp
        import scipy.sparse.linalg as linalg
        import matplotlib.pyplot as plt
        %matplotlib inline
```

# 1 Task 1: 1D PEC-PMC Cavity, Eigenmode formulation

## 1.1 Maxwell Equations (time domain)

$$\nabla \times E = -\mu \frac{\partial H}{\partial t} \tag{1}$$

$$\nabla \times H = \epsilon \frac{\partial E}{\partial t} \tag{2}$$

# 1.2 Time Domain $\rightarrow$ Frequency Domain

Using the Fourier transform we get:

$$E(r,t) \to E(r,\omega)$$
 (3)

$$\frac{\partial E}{\partial t} \to i\omega E \tag{4}$$

Thus our wave equation transforms into:

$$\nabla E = -i\omega\mu H \tag{5}$$

$$\nabla E = -i\omega \epsilon E \tag{6}$$

## 1.3 1D Coordinates

$$H_{y_i}, E_{z_{i+\frac{1}{2}}}, i \in \mathcal{N} \tag{7}$$

$$\frac{\partial E_z}{\partial x} = -i\omega \mu H_y \tag{8}$$

$$\frac{\partial H_y}{\partial x} = i\omega \epsilon E_z \tag{9}$$

## 1.4 Discretization

$$\frac{\partial E_{zi}}{\partial x} \approx \frac{E_{zi+1} - E_{zi-1}}{\Delta x} \tag{10}$$

Forward difference

$$-i\omega\mu E_{z_{i+\frac{1}{2}}} \approx \frac{H_{y_{i+1}} - H_{y_i}}{\Delta x} \tag{11}$$

Backward difference

$$-i\omega\epsilon H_{y_i} \approx \frac{E_{z_{i+\frac{1}{2}}} - E_{z_{i-\frac{1}{2}}}}{\Delta x} \tag{12}$$

## 1.5 Wave equation

$$H_y = \frac{i}{\omega \mu} \frac{\partial E_z}{\partial x} \tag{13}$$

$$E_z = \frac{-i}{\omega \epsilon} \frac{\partial H_y}{\partial x} \tag{14}$$

$$\frac{\partial}{\partial x} \frac{i}{\omega u} \frac{\partial}{\partial x} E_z = i\omega \epsilon E_z \tag{15}$$

$$\frac{1}{\epsilon} \frac{\partial}{\partial x} \frac{1}{\mu} \frac{\partial}{\partial x} E_z = \omega^2 E_z \tag{16}$$

or

$$\frac{1}{\mu} \frac{\partial}{\partial x} \frac{1}{\epsilon} \frac{\partial}{\partial x} H_y = \omega^2 H_y \tag{17}$$

## 1.6 Matrix form

$$H_y = \frac{i}{\omega\mu} \frac{\partial E_z}{\partial x} \approx \frac{i}{\omega\mu} \frac{E_{z_{i+\frac{1}{2}}} - E_{z_{i-\frac{1}{2}}}}{\Delta x}$$
 (18)

$$\begin{bmatrix} H_{y_0} \\ H_{y_1} \\ \vdots \\ H_{y_{n-1}} \\ H_{y_n} \end{bmatrix} = \frac{i}{\omega \mu \Delta x} \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & \vdots \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & -1 & 1 \end{bmatrix} \begin{bmatrix} E_{z_{0+\frac{1}{2}}} \\ E_{z_{1+\frac{1}{2}}} \\ \vdots \\ E_{z_{n-\frac{1}{2}}} \\ E_{z_{n+\frac{1}{2}}} \end{bmatrix}$$
(19)

$$E_z = \frac{-i}{\omega \epsilon} \frac{\partial H_y}{\partial x} \approx \frac{-i}{\omega \epsilon} \frac{H_{y_{i+1}} - H_{y_i}}{\Delta x}$$
 (20)

$$\begin{bmatrix} E_{z_{0+\frac{1}{2}}} \\ E_{z_{1+\frac{1}{2}}} \\ \vdots \\ E_{z_{n-\frac{1}{2}}} \\ E_{z_{n+\frac{1}{2}}} \end{bmatrix} = \frac{i}{\omega\mu\Delta x} \begin{bmatrix} -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & 0 \\ 0 & 0 & -1 & \dots & \vdots \\ \vdots & \vdots & \vdots & \ddots & 1 \\ 0 & 0 & \dots & 0 & -1 \end{bmatrix} \begin{bmatrix} H_{y_0} \\ H_{y_1} \\ \vdots \\ H_{y_{n-1}} \\ H_{y_n} \end{bmatrix}$$
(21)

$$\omega^2 E_z = \frac{1}{\epsilon} \frac{\partial}{\partial x} \frac{1}{\mu} \frac{\partial}{\partial x} E_z \tag{22}$$

$$\omega^{2} \begin{bmatrix} E_{z_{0+\frac{1}{2}}} \\ E_{z_{1+\frac{1}{2}}} \\ \vdots \\ E_{z_{n-\frac{1}{2}}} \\ E_{z_{n+\frac{1}{2}}} \end{bmatrix} = \frac{i}{\mu \Delta x} \begin{bmatrix} -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & 0 \\ 0 & 0 & -1 & \dots & \vdots \\ \vdots & \vdots & \vdots & \ddots & 1 \\ 0 & 0 & \dots & 0 & -1 \end{bmatrix} \frac{i}{\mu \Delta x} \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & \vdots \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & -1 & 1 \end{bmatrix} \begin{bmatrix} E_{z_{0+\frac{1}{2}}} \\ E_{z_{1+\frac{1}{2}}} \\ \vdots \\ E_{z_{n-\frac{1}{2}}} \\ E_{z_{n+\frac{1}{2}}} \end{bmatrix}$$
(23)

or, simplifying, and replacing  $i + \frac{1}{2}$  with i:

$$\omega^{2} \begin{bmatrix} E_{z0} \\ E_{z1} \\ \vdots \\ E_{zn-1} \\ E_{zn} \end{bmatrix} = -\frac{1}{\mu \epsilon \Delta x^{2}} \begin{bmatrix} -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & 0 \\ 0 & 0 & -1 & \dots & \vdots \\ \vdots & \vdots & \vdots & \ddots & 1 \\ 0 & 0 & \dots & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ -1 & 1 & 0 & \dots & 0 \\ 0 & -1 & 1 & \dots & \vdots \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & -1 & 1 \end{bmatrix} \begin{bmatrix} E_{z0} \\ E_{z1} \\ \vdots \\ E_{zn-1} \\ E_{zn} \end{bmatrix}$$
(24)

## 1.7 Boundary Conditions

#### 1.7.1 PEC

$$E_{zi} = 0 (25)$$

#### 1.7.2 PMC

$$H_{y_i} = 0 (26)$$

In our equations, they are automatically satisfied at the boundaries.

# 2 Implementation

## 2.1 Setup grid

#### 2.2 Build matrix

```
In [3]: # Forward

    diag = np.ones(n) * -A
        up_diag = np.ones(n) * A

    M_1 = sp.sparse.dia_matrix(([up_diag, diag], [1, 0]), [n,n])

# Backward

    diag = np.ones(n) * 1
        up_diag = np.ones(n) * -1

    M_2 = sp.sparse.dia_matrix(([up_diag, diag], [-1, 0]), [n,n])

    M = M_1.dot(M_2)
```

## 2.3 Solve for eigenmodes

```
In [4]: kt = 2*sp.pi*1  # wave vector target to some num_eigs = 6
   k2, V = linalg.eigs(M, k=num_eigs, M=None, sigma=kt**2) # solve for eigent

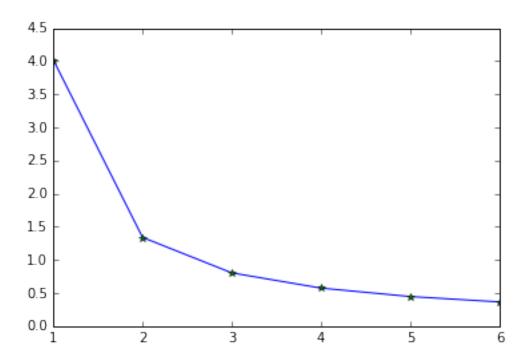
V_indicies = np.linspace(0,num_eigs-1, num_eigs, dtype=np.int)
   k, V_indicies = (list(t) for t in zip(*sorted(zip(np.sqrt(k2), V_indicies)))

# k = np.sort(np.sqrt(k2)) # sort

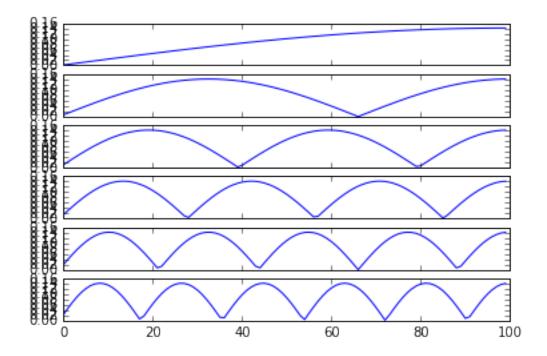
lam = 2*sp.pi/np.real(k) # wavelength # quality factor
```

## 2.4 Plot eigenmodes

## 2.4.1 Wavelengths



# 2.4.2 Field distribution



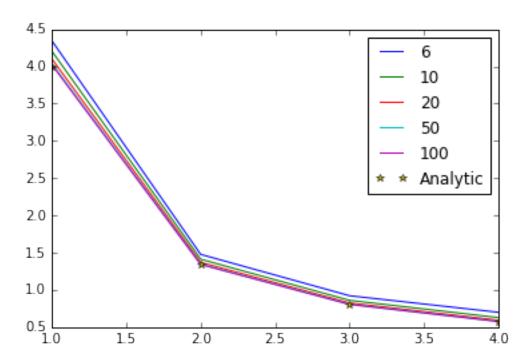
#### 2.5 Discretization artefacts

#### 2.5.1 Solve

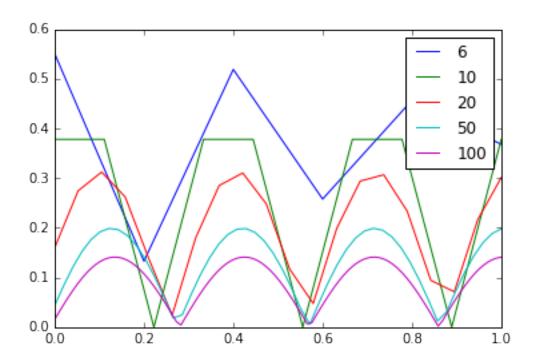
```
In [7]: discret = [6, 10, 20, 50, 100]
        eigs = []
        field = []
        num_eigs = 4
        for num in discret:
            # Grid
                        # Num grid nodes
            dx = 1. / num # Step size for overall size of 1
            eps = 1. # Vacuum
            mu = 1.
                         # Vacuum
              = -1. / (dx **2 * mu * eps)
            # Matrix
            # Forward
            diag = np.ones(n) * -A
            up_diag = np.ones(n) * A
            M_1 = \text{sp.sparse.dia\_matrix}(([up\_diag, diag], [1, 0]), [n,n])
            # Backward
            diag = np.ones(n) * 1
            up\_diag = np.ones(n) * -1
            M_2 = sp.sparse.dia_matrix(([up_diag, diag], [-1, 0]), [n,n])
            M = M 1.dot(M 2)
            # Solve
            kt = 2*sp.pi*1
                                                               # wave vector target
            k2, V = linalg.eigs(M, k=num_eigs, M=None, sigma=kt**2) # solve for el
            V_indicies = np.linspace(0,num_eigs-1, num_eigs, dtype=np.int)
            k, V_indicies = (list(t) for t in zip(*sorted(zip(np.sqrt(k2), V_indic:
            lam = 2*sp.pi/np.real(k)
                                                               # wavelength
            eigs.append(lam)
            field.append(V[:, V_indicies])
```

## 2.5.2 Wavelength

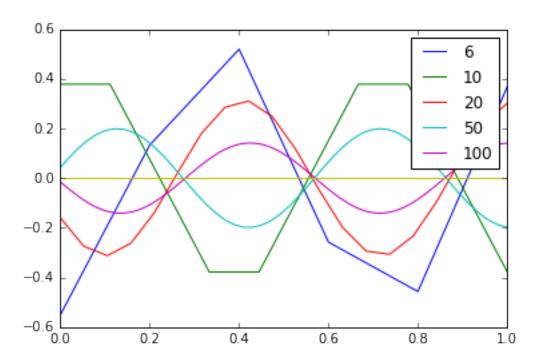
Out[8]: <matplotlib.legend.Legend at 0x7faade06e0b8>



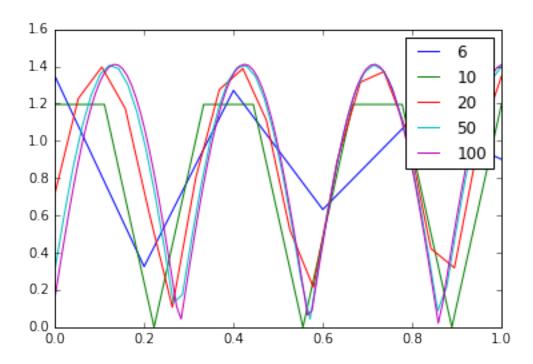
## 2.5.3 No normalization, amplitude changes



# 2.5.4 No normalization, phase changes



## 2.5.5 Normalization



In [ ]: