

Fall 2025 Introduction to Algebra (I)

Preview Note

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0 Preliminaries

0.1 Basics

The subset of a given set A is

$$B = \{a \in A \mid \dots (\text{conditions on } a) \dots\}$$

The *order* (or *cardinality*) of a set A will be denoted by $|A|$. If A is a finite set, the order of A is simply the number of elements of A .

The *Cartesian product* of two sets A and B is the collection $A \times B = \{(a, b) \mid a \in A, b \in B\}$, of ordered pairs of elements from A and B .

The following notation for some common sets of numbers

1. **Integers:** $\mathbb{Z} = \{0, \pm 1, \pm 2, \dots\}$.
2. **Rational numbers:** $\mathbb{Q} = \{a/b \mid a, b \in \mathbb{Z}, b \neq 0\}$.
3. **Real numbers:** $\mathbb{R} = \{\text{all decimal expansions } \pm d_1 d_2 \dots d_n . a_1 a_2 a_3 \dots\}$.
4. **Complex numbers:** $\mathbb{C} = \{a + bi \mid a, b \in \mathbb{R}, i^2 = -1\}$.
5. \mathbb{Z}^+ , \mathbb{Q}^+ and \mathbb{R}^+ will denote the positive (nonzero) elements in \mathbb{Z} , \mathbb{Q} and \mathbb{R} , respectively.

The notation $f : A \rightarrow B$ or $A \xrightarrow{f} B$ to denote a *function* (or *map*) f from A to B , and the value of f at a is denoted by $f(a)$. The set A is called the *domain* of f and B is called the *codomain* of f .

The notation $f : a \mapsto b$ or $a \mapsto b$ if f is understood indicates that $f(a) = b$, i.e., the function is being specified on *elements*. If the function f is not specified on elements, it is important in general to check that f is *well defined*, i.e., is unambiguously determined.

The set

$$f(A) = \{b \in B \mid b = f(a), \text{ for some } a \in A\}$$

is a subset of B , called the *range* or *image* of f (or the *image* of A under f).

For each subset C of B , the set

$$f^{-1}(C) = \{a \in A \mid f(a) \in C\}$$

consisting of the elements of A mapping into C under f is called the *preimage* or *inverse image* of C under f . For each $b \in B$, the preimage of $\{b\}$ under f is called the *fiber* of f over b . Note that f^{-1} is not in general a function and that the fibers of f generally contain many elements since there may be many elements of A mapping to the element b .

If $f : A \rightarrow B$ and $g : B \rightarrow C$, then the composite map $g \circ f : A \rightarrow C$ is defined by

$$(g \circ f)(a) = g(f(a))$$

Definition 0.1-1 Let $f : A \rightarrow B$

1. f is *injective* or is an *injection* if whenever $a_1 \neq a_2$, then $f(a_1) \neq f(a_2)$.
2. f is *surjective* or is a *surjection* if for all $b \in B$, there is some $a \in A$ such that $f(a) = b$.
3. f is *bijective* or is a *bijection* if it is both injective and surjective. If such a bijection f exists from A to B , we say A and B are in *bijective correspondence*.
4. f has a *left inverse* if there is a function $g : B \rightarrow A$ such that $g \circ f : A \rightarrow A$ is the identity map on A , i.e., $(g \circ f)(a) = a$ for all $a \in A$.
5. f has a *right inverse* if there is a function $h : B \rightarrow A$ such that $f \circ h : B \rightarrow B$ is the identity map on B , i.e., $(f \circ h)(b) = b$ for all $b \in B$.

Proposition 0.1-1 Let $f : A \rightarrow B$

1. The map f is injective if and only if f has a left inverse.
2. The map f is surjective if and only if f has a right inverse.
3. The map f is a bijection if and only if there exists $g : B \rightarrow A$ such that $f \circ g$ is the identity map on B and $g \circ f$ is the identity map on A .
4. If A and B are finite sets with the same number of elements (i.e., $|A| = |B|$), then $f : A \rightarrow B$ is bijective if and only if f is injective if and only if f is surjective.

Proof.

1. (\Rightarrow) Suppose f is injective. Notice that if $b \in f(A)$ then there is a unique $a \in A$ such that $f(a) = b$. Choose any $a_0 \in A$, and define $g : B \rightarrow A$ by

$$g(b) = \begin{cases} a & \text{if } b \in f(A) \\ a_0 & \text{if } b \notin f(A) \end{cases}$$

Then $(g \circ f)(a) = a$ for all $a \in A$, so g is a left inverse of f .

(\Leftarrow) Suppose f has a left inverse g , and that $f(a) = f(b)$. Then $g(f(a)) = g(f(b))$, and since $g \circ f : A \rightarrow A$, we have $a = b$, which shows f is injective.

2. (\Rightarrow) Suppose f is surjective. Then every $b \in B$ is in the image of f , so for each $b \in B$ pick an element $g(b) \in A$ such that $f(g(b)) = b$. Then g is a right inverse of f .

(\Leftarrow) Suppose f has a right inverse g and let $b \in B$. Then $f(g(b)) = b$ as $f \circ g : B \rightarrow B$. This shows $b \in f(A)$, so $f(A) = B$ and f is surjective.

3. (\Rightarrow) Suppose f is a bijection, then f is injective and surjective by definition. By part 1. there exists a left inverse $g : B \rightarrow A$ such that $g \circ f : A \rightarrow A$, and by part 2. there exists a right inverse $g : B \rightarrow A$ such that $f \circ g : B \rightarrow B$.

(\Leftarrow) Suppose there exists $g : B \rightarrow A$ such that $f \circ g : B \rightarrow B$ and $g \circ f : A \rightarrow A$. Then by part 1., f is surjective, and by part 2., f is injective. Then f is a bijection.

4. **Claim:**

- (1) If $f : A \rightarrow B$ is injective, then $|A| \leq |B|$.
- (2) If $f : A \rightarrow B$ is surjective, then $|A| \geq |B|$.
- (3) If $f : A \rightarrow B$ is a bijection, then $|A| = |B|$.

proof. Let $A = \{a_1, a_2, \dots, a_m\}$ has m elements.

- (1) $\{f(a_1), f(a_2), \dots, f(a_m)\}$ is a subset of B , because f is injective, $|A| = m \leq |B|$.
- (2) $\{f(a_1), f(a_2), \dots, f(a_m)\} = B$ has at most m different elements because f is surjective, $|A| = m \geq |B|$.
- (3) This follows from (1) and (2), since $|A| \leq |B|$ and $|A| \geq |B|$, we have $|A| = |B|$.

The situation of part 3. of **Proposition 0.1-1**, the map g is necessarily unique and we shall say g is the *2-sided inverse* (or *inverse*) of f .

A *permutation* of a set A is simply a bijection from A to itself.

If $A \subseteq B$ and $f : B \rightarrow C$, we denote the *restriction* of f to A by $f|_A$.

If $A \subseteq B$ and $g : A \rightarrow C$ and there is a function $f : B \rightarrow C$ such that $f|_A = g$, we shall say f is an *extension* of g to B .

Definition 0.1-2 Let A be a nonempty set.

- 1. A *binary relation* on a set A is a subset R of $A \times A$ and we write $a \sim b$ if $(a, b) \in R$.
- 2. The relation \sim on A is said to be:
 - (a) *reflexive* if $a \sim a$, for all $a \in A$
 - (b) *symmetric* if $a \sim b$ implies $b \sim a$ for all $a, b \in A$
 - (c) *transitive* if $a \sim b$ and $b \sim c$ implies $a \sim c$ for all $a, b, c \in A$

A relation is an *equivalence relation* if it is reflexive, symmetric and transitive.

- 3. If \sim defines an equivalence relation on A , then the *equivalence class* of $a \in A$ is defined to be $\{x \in A \mid x \sim a\}$. Elements of the equivalence class of a are said to be *equivalent* to a . If C is an equivalence class, any element of C is called a *representative* of the class C .
- 4. A *partition* of A is any collection $\{A_i \mid i \in I\}$ of nonempty subsets of A (I some indexing set) such that
 - (a) $A = \cup_{i \in I} A_i$
 - (b) $A_i \cap A_j = \emptyset$ for all $i, j \in I$ with $i \neq j$, i.e., A is the disjoint union of the sets in the partition.

Proposition 0.1-2 Let A be a nonempty set.

1. If \sim defines an equivalence relation on A , then the set of equivalence classes of \sim form a partition of A .
2. If $\{A_i \mid i \in I\}$ is a partition of A , then there is an equivalence relation on A whose equivalence classes are precisely the sets A_i , $i \in I$.

Proof. [Link](#)

0.2 Properties of the integers

0.2.1 Well Ordering of \mathbb{Z}

If A is any nonempty subset of \mathbb{Z}^+ , there is some element $m \in A$ such that $m \leq a$, for all $a \in A$ (m is call a *minimal element* of A).

0.2.2 Divides

If $a, b \in \mathbb{Z}$ with $a \neq 0$, we say a *divides* b if there is an element $c \in \mathbb{Z}$ such that $b = ac$. In this case, we write $a \mid b$; if a does not divide b , we write $a \nmid b$.

0.2.3 Greatest Common Divisor (g.c.d.)

If $a, b \in \mathbb{Z} \setminus \{0\}$, there is a unique positive integer d , called the *greatest common divisor* of a and b (or g.c.d. of a and b), satisfying:

- (1) $d \mid a$ and $d \mid b$ (d is a common divisor of a and b)
- (2) If $e \mid a$ and $e \mid b$, then $e \leq d$ (d is the greatest such divisor)

The g.c.d. of a and b will be denoted by (a, b) (or $\gcd(a, b)$). If $(a, b) = 1$, we say that a and b are *relatively prime*.

0.2.4 Least Common Multiple (l.c.m.)

If $a, b \in \mathbb{Z} \setminus \{0\}$, there is a unique positive integer l , called the *least common multiple* of a and b (or l.c.m. of a and b), satisfying:

- (1) $a \mid l$ and $b \mid l$ (l is a common multiple of a and b)
- (2) If $a \mid m$ and $b \mid m$, then $l \leq m$ (l is the least such multiple)

The l.c.m. of a and b will be denoted by $[a, b]$ (or $\text{lcm}(a, b)$). The connection between the g.c.d. d and the l.c.m. l of two integers a and b is given by $dl = ab$.

0.2.5 The Division Algorithm

If $a, b \in \mathbb{Z} \setminus \{0\}$, then there exist unique $q, r \in \mathbb{Z}$ such that

$$a = qb + r \quad \text{and} \quad 0 \leq r < |b|$$

where q is the *quotient* and r is the *remainder*.

0.2.6 The Euclidean Algorithm

If $a, b \in \mathbb{Z} \setminus \{0\}$, then we obtain a sequence of quotients and remainders

$$a = q_0b + r_0 \quad (0)$$

$$b = q_1r_0 + r_1 \quad (1)$$

$$r_0 = q_2r_1 + r_2 \quad (2)$$

$$r_1 = q_3r_2 + r_3 \quad (3)$$

$$\vdots$$

$$r_{n-2} = q_nr_{n-1} + r_n \quad (n)$$

$$r_{n-1} = q_{n+1}r_n \quad (n+1)$$

where r_n is the last nonzero remainder. Such an r_n exists since $|b| > |r_0| > |r_1| > \cdots > |r_n|$ is a decreasing sequence of strictly positive integers if the remainders are nonzero and such a sequence cannot continue indefinitely. Then r_n is the g.c.d. (a, b) of a and b .

Example 0.2.6-1 Find the g.c.d. of $a = 57970$ and $b = 10353$.

Sol. Applying the Euclidean algorithm, we have

$$57970 = (5)10353 + 6205$$

$$10353 = (1)6205 + 4148$$

$$6205 = (1)4148 + 2057$$

$$4148 = (2)2057 + 34$$

$$2057 = (60)34 + 17$$

$$34 = (2)17$$

Thus, the g.c.d. of 57970 and 10353 is $(57970, 10353) = 17$.

0.2.7 \mathbb{Z} -linear Combinations

One consequence of the Euclidean Algorithm which we shall use regularly is the following: if $a, b \in \mathbb{Z} \setminus \{0\}$, then there exist $x, y \in \mathbb{Z}$ such that

$$(a, b) = ax + by$$

that is, *the g.c.d. of a and b is a \mathbb{Z} -linear combination of a and b* . This follows by recursively writing the element r_n in the Euclidean Algorithm in terms of the previous remainders (namely, use equation (n) above to solve for $r_n = r_{n-2} - q_nr_{n-1}$ in terms of the remainders r_{n-1} and r_{n-2} , then use equation $(n-1)$ to write r_n in terms of the remainders r_{n-2} and r_{n-3} , etc., eventually writing r_n in terms of a and b).

Example 0.2.7-1 Use the Euclidean Algorithm to find integers x, y such that

$$(57970, 10353) = 57970x + 10353y$$

Sol. Based on **Example 0.2.6-1** we know that $(57970, 10353) = 17$. Start from the fifth equation in the Euclidean Algorithm,

$$\begin{aligned} 17 &= 2057 - 60 \cdot 34 \\ &= 2057 - 60 \cdot (4148 - (2)2057) = 121 \cdot 2057 - 60 \cdot 4148 \\ &= 121 \cdot (6205 - (1)4148) - 60 \cdot 4148 = 121 \cdot 6205 - 181 \cdot 4148 \\ &= 121 \cdot 6205 - 181 \cdot (10353 - (1)6205) = 302 \cdot 6205 - 181 \cdot 10353 \\ &= 302 \cdot (57970 - (5)10353) - 181 \cdot 10353 \\ &= 302 \cdot 57970 + (-1691) \cdot 10353 \end{aligned}$$

Thus, $x = 302$ and $y = -1691$ is a solution of $(57970, 10353) = 57970x + 10353y$.

0.2.8 Prime and Composite Numbers

An element p of \mathbb{Z}^+ is called a *prime* if $p > 1$ and the only positive divisors of p are 1 and p . An integer $n > 1$ which is not prime is called *composite*.

0.2.9 The Fundamental Theorem of Arithmetic

If $n \in \mathbb{Z}$, $n > 1$, then n can be factored uniquely into the product of primes, i.e., there are distinct primes p_1, p_2, \dots, p_s and positive integers $\alpha_1, \alpha_2, \dots, \alpha_s$ such that

$$n = p_1^{\alpha_1} p_2^{\alpha_2} \dots p_s^{\alpha_s}$$

This factorization is unique in the sense that if q_1, q_2, \dots, q_t are any distinct primes and positive integers $\beta_1, \beta_2, \dots, \beta_t$ such that

$$n = q_1^{\beta_1} q_2^{\beta_2} \dots q_t^{\beta_t}$$

then $s = t$ and if we arrange the two sets of primes in increasing order, then $q_i = p_i$ and $\alpha_i = \beta_i$ $1 \leq i \leq s$.

Suppose the positive integers a and b are expressed as products of prime powers:

$$a = p_1^{\alpha_1} p_2^{\alpha_2} \dots p_s^{\alpha_s} \quad b = p_1^{\beta_1} p_2^{\beta_2} \dots p_s^{\beta_s}$$

where p_1, p_2, \dots, p_s are distinct and the exponents are ≥ 0 (we allow the exponents to be 0 here, so that the products are taken over the same set of primes – the exponent will be 0 if that prime is not actually a divisor). Then the g.c.d. of a and b is

$$(a, b) = p_1^{\min\{\alpha_1, \beta_1\}} p_2^{\min\{\alpha_2, \beta_2\}} \dots p_s^{\min\{\alpha_s, \beta_s\}}$$

and the l.c.m. of a and b is

$$[a, b] = p_1^{\max\{\alpha_1, \beta_1\}} p_2^{\max\{\alpha_2, \beta_2\}} \dots p_s^{\max\{\alpha_s, \beta_s\}}$$

0.2.10 Euler φ -function

For $n \in \mathbb{Z}^+$, let $\varphi(n)$ be the number of positive integers $a \leq n$ with a relatively prime to n , i.e., $(a, n) = 1$. For example, $\varphi(12) = 4$ since the positive integers 1, 5, 7, 11 are the only positive integers less than or equal to 12 which have no factors in common with 12. For prime p , $\varphi(p) = p - 1$, and more generally, for all $a \geq 1$ we have the formula

$$\varphi(p^a) = p^a - p^{a-1} = p^{a-1}(p - 1)$$

The function φ is *multiplicative* in the sense that

$$\varphi(ab) = \varphi(a)\varphi(b) \quad \text{if } (a, b) = 1$$

(note that it is important here that a and b be relatively prime). Together with the formula above this gives a general formula for the values of φ : if $n = p_1^{\alpha_1} p_2^{\alpha_2} \dots p_s^{\alpha_s}$, then

$$\begin{aligned} \varphi(n) &= \varphi(p_1^{\alpha_1})\varphi(p_2^{\alpha_2}) \dots \varphi(p_s^{\alpha_s}) \\ &= p_1^{\alpha_1-1}(p_1 - 1)p_2^{\alpha_2-1}(p_2 - 1) \dots p_s^{\alpha_s-1}(p_s - 1) \end{aligned}$$

Example 0.2.10-1 Find the value of $\varphi(36)$.

Sol. The prime factorization of 36 is $36 = 2^2 \cdot 3^2$, therefore

$$\begin{aligned} \varphi(36) &= \varphi(2^2)\varphi(3^2) \\ &= 2^{2-1}(2 - 1)3^{2-1}(3 - 1) \\ &= 2 \cdot 1 \cdot 3 \cdot 2 = 12 \end{aligned}$$

0.3 $\mathbb{Z}/n\mathbb{Z}$: The integers modulo n

Let n be a fixed positive integer. Define a relation on \mathbb{Z} by

$$a \sim b \quad \text{if and only if} \quad n \mid (a - b)$$

Clearly $a \sim a$, and $a \sim b$ implies $b \sim a$ for any integers a and b , so this relation is trivially reflexive and symmetric. If $a \sim b$ and $b \sim c$, then n divides $a - b$ and n divides $b - c$, so n also divides the sum of these two integers, i.e., n divides $(a - b) + (b - c) = a - c$, so $a \sim c$ and the relation is transitive. Hence, this is an equivalence relation. Write $a \equiv b \pmod{n}$ (read: a is *congruent* to b mod n) if $a \sim b$. For any $k \in \mathbb{Z}$ we shall denote the equivalence class of a by \bar{a} – this is called the *congruent class* or *residue class* of a mod n and consists of the integers which differ from a by an integral multiple of n , i.e.,

$$\begin{aligned} \bar{a} &= \{a + kn \mid k \in \mathbb{Z}\} \\ &= \{a, a \pm n, a \pm 2n, a \pm 3n, \dots\} \end{aligned}$$

There are precisely n distinct equivalence classes mod n , namely

$$\bar{0}, \bar{1}, \bar{2}, \dots, \overline{n-1}$$

determined by the possible remainders after division by n , and this residue classes partition the integers \mathbb{Z} . the set of equivalence classes under this equivalence relation will be denoted by $\mathbb{Z}/n\mathbb{Z}$, and called the *integers modulo n* (or the *integers mod n*).

The process of finding the equivalence class mod n of some integer a is often referred to as *reducing a mod n* . This terminology also frequently refers to finding the smallest nonnegative integer congruent to a mod n (the *least residue* of a mod n).

Definition 0.3-1 We can define an addition and a multiplication for the elements of $\mathbb{Z}/n\mathbb{Z}$, defining *modular arithmetic* as follows: for $\bar{a}, \bar{b} \in \mathbb{Z}/n\mathbb{Z}$, define their sum and product by

$$\bar{a} + \bar{b} = \overline{a + b} \quad \text{and} \quad \bar{a} \cdot \bar{b} = \overline{ab}$$

Given any two elements \bar{a} and \bar{b} in $\mathbb{Z}/n\mathbb{Z}$, to compute their sum (respectively, their product) take *any representative* integer a in the *class* \bar{a} and *any representative* integer b in the *class* \bar{b} , and add (respectively, multiply) the integers a and b as usual in \mathbb{Z} , and then take the equivalence class containing the result.

Theorem 0.3-1 The operations of addition and multiplication on $\mathbb{Z}/n\mathbb{Z}$ defined in **Definition 0.3-1** are both well defined, that is, they do not depend on the choices of representatives for the classes involved. More precisely, if $a_1, a_2 \in \mathbb{Z}$ and $b_1, b_2 \in \mathbb{Z}$ with $\bar{a}_1 = \bar{b}_1$ and $\bar{a}_2 = \bar{b}_2$, then $\overline{a_1 + a_2} = \overline{b_1 + b_2}$ and $\overline{a_1 a_2} = \overline{b_1 b_2}$, i.e., if

$$a_1 \equiv b_1 \pmod{n} \quad \text{and} \quad a_2 \equiv b_2 \pmod{n}$$

then

$$a_1 + a_2 \equiv b_1 + b_2 \pmod{n} \quad \text{and} \quad a_1 a_2 \equiv b_1 b_2 \pmod{n}$$

Proof. Suppose $a_1 \equiv b_1 \pmod{n}$, i.e., $a_1 - b_1$ is divisible by n . Then $a_1 = b_1 + sn$ for some integer s . Similarly, $a_2 \equiv b_2 \pmod{n}$ means $a_2 = b_2 + tn$ for some integer t . Then $a_1 + a_2 = (b_1 + b_2) + (s + t)n$, so $a_1 + a_2 \equiv b_1 + b_2 \pmod{n}$, which shows that the sum of the residue classes is independent of the representatives chosen.

Similarly, $a_1 a_2 = (b_1 + sn)(b_2 + tn) = b_1 b_2 + (b_1 t + b_2 s + stn)n$, so $a_1 a_2 \equiv b_1 b_2 \pmod{n}$, and so the product of the residue classes is also independent of the representatives chosen.

Example 0.3-1 Find the last two digits in the number 2^{1000} .

Sol. First observe that the last two digits give the remainder of 2^{1000} after we divided by 100, so we are interested in the residue class mod 100 containing 2^{1000} . We compute $2^{10} = 1024 \equiv 24 \pmod{100}$, so then $2^{20} = (2^{10})^2 \equiv 24^2 = 576 \equiv 76 \pmod{100}$. Then $2^{40} = (2^{20})^2 \equiv 76^2 = 5776 \equiv 76 \pmod{100}$. Similarly, $2^{80} \equiv 2^{160} \equiv 2^{320} \equiv 2^{640} \equiv 76 \pmod{100}$. Finally, $2^{1000} = 2^{640} \cdot 2^{320} \cdot 2^{40} \equiv 76 \cdot 76 \cdot 76 \equiv 76 \pmod{100}$. Thus, the last two digits of 2^{1000} are 76.

An important subset of $\mathbb{Z}/n\mathbb{Z}$ consists of the collection of residue classes which have a multiplicative inverse in $\mathbb{Z}/n\mathbb{Z}$:

$$(\mathbb{Z}/n\mathbb{Z})^\times = \{\bar{a} \in \mathbb{Z}/n\mathbb{Z} \mid \text{there exists } \bar{c} \in \mathbb{Z}/n\mathbb{Z} \text{ with } \bar{a} \cdot \bar{c} = \bar{1}\}$$

Proposition 0.3-1

$$(\mathbb{Z}/n\mathbb{Z})^\times = \{\bar{a} \in \mathbb{Z}/n\mathbb{Z} \mid (a, n) = 1\}$$

Proof. It is easy to see that if any representative of \bar{a} is relatively prime to n , then all representatives are relatively prime to n , so that the set on the right in the proposition is well defined.

If a is an integer relatively prime to n , then the Euclidean Algorithm produces integers x and y satisfying $ax + ny = 1$, hence $ax \equiv 1 \pmod{n}$, so that \bar{x} is the multiplicative inverse of \bar{a} in $\mathbb{Z}/n\mathbb{Z}$. This gives an efficient method for computing multiplicative inverses in $\mathbb{Z}/n\mathbb{Z}$.

Example 0.3-2 Find the multiplicative inverse of $\overline{17}$ in $\mathbb{Z}/60\mathbb{Z}$.

Sol. Suppose $n = 60$ and $a = 17$. Applying the Euclidean Algorithm, we obtain

$$60 = (3)17 + 9$$

$$17 = (1)9 + 8$$

$$9 = (1)8 + 1$$

$$8 = (8)1$$

so that a and n are relatively prime, and $(-7)17 + 2 \cdot 60 = 1$. Hence, $\overline{-7} = \overline{53}$ is the multiplicative inverse of $\overline{17}$ in $\mathbb{Z}/60\mathbb{Z}$.

Part I

Group Theory

1 Introduction to Groups

1.1 Basic Axioms and Examples

Definition 1.1-1

1. A *binary operation* \star on a set G is a function $\star : G \times G \rightarrow G$. For any $a, b \in G$, we shall write $a \star b$ for $\star(a, b)$.
2. A binary operation \star on a set G is *associative* if for all $a, b, c \in G$, we have $a \star (b \star c) = (a \star b) \star c$.
3. If \star is a binary operation on a set G , we say elements a and b of G *commute* if $a \star b = b \star a$. We say \star (or G) is *commutative* if for all $a, b \in G$, we have $a \star b = b \star a$.

Example 1.1-1

1. $+$ (usual addition) is a commutative binary operation on \mathbb{Z} (or on $\mathbb{Q}, \mathbb{R}, \mathbb{C}$ respectively).
2. \times (usual multiplication) is a commutative binary operation on \mathbb{Z} (or on $\mathbb{Q}, \mathbb{R}, \mathbb{C}$ respectively).
3. $-$ (usual subtraction) is noncommutative binary operation on \mathbb{Z} , where $-(a, b) = a - b$. It is not a binary operation on \mathbb{Z}^+ (nor $\mathbb{Q}^+, \mathbb{R}^+$) (e.g. $-(1, 2) = 1 - 2 = -1 \notin \mathbb{Z}^+$).
4. Taking the vector cross-product of two vectors in \mathbb{R}^3 is a binary operation which is not associative and not commutative. For example,
 - (1) $\mathbf{u} = (1, 2, 3), \mathbf{v} = (4, 5, 6) \in \mathbb{R}^3, \mathbf{u} \times \mathbf{v} = (-3, 6, -3)$
 $\Rightarrow \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}^3$
 - (2) $\mathbf{u} = (1, 2, 3), \mathbf{v} = (4, 5, 6) \in \mathbb{R}^3, \mathbf{u} \times \mathbf{v} = (-3, 6, -3), \mathbf{v} \times \mathbf{u} = (3, -6, 3)$
 \Rightarrow it is not commutative.
 - (3) $\mathbf{u} = (1, 2, 3), \mathbf{v} = (4, 5, 6), \mathbf{w} = (7, 8, 9) \in \mathbb{R}^3,$
 $(\mathbf{u} \times \mathbf{v}) \times \mathbf{w} = (-3, 6, -3) \times (7, 8, 9) = (78, 6, -66)$
 $\mathbf{u} \times (\mathbf{v} \times \mathbf{w}) = (1, 2, 3) \times (-3, 6, -3) = (-24, -6, 12)$

Suppose that \star is a binary operation on a set G , and H is a subset of G . If the restriction of \star to H is a binary operation on H ($\forall a, b \in H, a \star b \in H$), we say that H is *closed* under \star .

Observe that if \star is an associative (respectively, commutative) binary operation on a set G , and \star restricted to some subset H of G is a binary operation on H , then \star is automatically associative (respectively, commutative) on H as well.

Definition 1.1-2

1. A *group* is an ordered pair (G, \star) where G is a set and \star is a binary operation on G satisfying the following axioms:
 - (i) **Associative:** $(a \star b) \star c = a \star (b \star c)$, for all $a, b, c \in G$.
 - (ii) **Identity:** There exists an element $e \in G$ such that $e \star a = a \star e = a$ for all $a \in G$.
 - (iii) **Inverses:** For each $a \in G$, there exists $a^{-1} \in G$ such that $a \star a^{-1} = a^{-1} \star a = e$.
2. The group (G, \star) is called *abelian* (or *commutative*) if $a \star b = b \star a$ for all $a, b \in G$.

We say G is a *finite group* if in addition G is a finite set.

Note that the axiom (ii) ensures that a group is always nonempty.

Example 1.1-2

1. $\mathbb{Z}, \mathbb{Q}, \mathbb{R}$ and \mathbb{C} are groups under $+$ with $e = 0$ and $a^{-1} = -a$ for all a .
2. $\mathbb{Q} \setminus \{0\}, \mathbb{R} \setminus \{0\}, \mathbb{C} \setminus \{0\}, \mathbb{Q}^+, \mathbb{R}^+$ are groups under \times with $e = 1$ and $a^{-1} = \frac{1}{a}$.
3. The axioms for a vector space V which specify that $(V, +)$ is an abelian group.
4. For $n \in \mathbb{Z}^+$, $\mathbb{Z}/n\mathbb{Z}$ is an abelian group under the operation $+$ with the identity element $\bar{0}$ and the inverse of \bar{a} is $\overline{-a}$.
5. For $n \in \mathbb{Z}^+$, the set $(\mathbb{Z}/n\mathbb{Z})^\times$ of equivalence classes \bar{a} which have multiplicative inverses mod n is an abelian group under multiplication with the identity element $\bar{1}$.

If (A, \star) and (B, \diamond) are groups, we can find a new group $A \times B$, called the *direct product*, whose elements are those in the Cartesian product

$$A \times B = \{(a, b) \mid a \in A, b \in B\}$$

and whose operation is defined componentwise:

$$(a_1, b_1)(a_2, b_2) = (a_1 \star a_2, b_1 \diamond b_2)$$

Proposition 1.1-1 If G is a group under the operation \star , then

1. The identity of G is unique.
2. For each $a \in G$, a^{-1} is uniquely determined.
3. $(a^{-1})^{-1} = a$ for all $a \in G$.
4. $(a \star b)^{-1} = (b)^{-1} \star (a)^{-1}$
5. **Generalized Associative Law:** For any $a_1, a_2, \dots, a_n \in G$, the value of $a_1 \star a_2 \star \dots \star a_n$ is independent of how the expression is bracketed.

Proof.

1. If f and g are both identities, then by axiom (ii) of the **Definition 1.1-2**, we have $f \star g = f$ and $g \star f = g$. Thus $f = g$, and the identity is unique.

2. Assume b and c are both inverses of a , and let e be the identity of G . By axiom (iii) of the **Definition 1.1-2**, $a \star b = e$ and $c \star a = e$. Thus

$$\begin{aligned}
 c &= c \star e && \text{(Axiom (ii))} \\
 &= c \star (a \star b) && \text{(Since } e = a \star b) \\
 &= (c \star a) \star b && \text{(Axiom (i))} \\
 &= e \star b && \text{(Since } e = c \star a) \\
 &= b && \text{(Axiom (ii))}
 \end{aligned}$$

3. The inverse of a is a^{-1} , and the inverse of a^{-1} is $(a^{-1})^{-1}$, by part 2., we know $a = (a^{-1})^{-1}$.
4. Let $c = (a \star b)^{-1}$, so by definition of c , $(a \star b) \star c = e$. By the associative law, we have

$$a \star (b \star c) = e$$

Multiply both sides on the left by a^{-1} to get

$$a^{-1} \star (a \star (b \star c)) = a^{-1} \star e$$

The associative law on the LHS and the definition of e on the RHS give

$$\begin{aligned}
 (a^{-1} \star a) \star (b \star c) &= a^{-1} \\
 e \star (b \star c) &= a^{-1} \\
 b \star c &= a^{-1}
 \end{aligned}$$

Now, multiply both sides on the left by b^{-1} to get

$$\begin{aligned}
 b^{-1} \star (b \star c) &= b^{-1} \star a^{-1} \\
 (b^{-1} \star b) \star c &= b^{-1} \star a^{-1} \\
 e \star c &= b^{-1} \star a^{-1} \\
 c &= b^{-1} \star a^{-1}
 \end{aligned}$$

Thus $(a \star b)^{-1} = b^{-1} \star a^{-1}$.

5. First show the result is true for $n = 1, 2$ and 3. Next, assume for any $k < n$ that any bracketing of a product of k elements, $b_1 \star b_2 \star \cdots \star b_k$ can be reduced (without altering the value of the product) to an expression of the form

$$b_1 \star (b_2 \star (b_3 \star (\cdots \star b_k))) \cdots$$

Now argue that an bracketing of the product $a_1 \star a_2 \star \cdots \star a_n$ must break into 2 subproducts, say $(a_1 \star a_2 \star \cdots \star a_k) \star (a_{k+1} \star a_{k+2} \star \cdots \star a_n)$, where each subproduct is bracketed in some fashion. Apply the induction assumption to each of these two subproducts and finally reduce the result to the form $a_1 \star (a_2 \star (a_3 \star (\cdots \star a_n))) \cdots$ to complete the induction.

For any group G (operation \cdot implied) and $x \in G$ and $n \in \mathbb{Z}^+$ since the product $xx \dots x$ (n terms) does not depend on how it is bracketed, we shall denote it by x^n . Denote $x^{-1}x^{-1} \dots x^{-1}$ (n terms) by x^{-n} . Let $x^0 = 1$, the identity of G .

When we are dealing with specific groups, we shall use the natural (given) operation. For example, when the operation is $+$, the identity will be denoted by 0 and for any element a , the inverse a^{-1} will be written $-a$, and $a + a + \dots + a$ ($n > 0$ terms) will be written na ; $-a - a - \dots - a$ (n terms) will be written $-na$, and $0a = 0$.

Proposition 1.1-2 Let G be a group and let $a, b \in G$. The equations $ax = b$ and $ya = b$ have unique solutions for $x, y \in G$. In particular, the left and right cancellation laws hold in G , i.e.,

1. If $au = av$, then $u = v$.
2. If $ub = vb$, then $u = v$.

Proof. We can solve $ax = b$ by multiplying both sides on the left by a^{-1} and simplifying to get $x = a^{-1}b$. The uniqueness of x follows because a^{-1} is unique. Similarly, we can solve $ya = b$ by multiplying both sides on the right by a^{-1} and simplifying to get $y = ba^{-1}$. The uniqueness of y follows because a^{-1} is unique.

If $au = av$, multiply both sides on the left by a^{-1} , and simplify to get $u = v$. Similarly, if $ub = vb$, multiply both sides on the right by b^{-1} , and simplify to get $u = v$.

Definition 1.1-3 For G a group and $x \in G$ define the *order* of x to be the smallest positive integer n such that $x^n = 1$, and denote this integer by $|x|$. In this case x is said to be of order n . If no positive power of x is the identity, the order of x is defined to be infinity and x is said to be of infinite order.

Example 1.1-3

1. An element of a group has order 1 if and only if it is the identity.
2. In the additive groups \mathbb{Z} , \mathbb{Q} , \mathbb{R} or \mathbb{C} every nonzero element has infinite order.
3. In the multiplicative groups $\mathbb{R} \setminus \{0\}$ or $\mathbb{Q} \setminus \{0\}$ the element -1 has order 2 and all other nonidentity elements have infinite order.
4. In the additive group $\mathbb{Z}/9\mathbb{Z}$, the element $\bar{6}$ has order 3 since $\bar{6} \neq \bar{0}$, $\bar{6} + \bar{6} = \bar{12} = \bar{3} \neq \bar{0}$, but $\bar{6} + \bar{6} + \bar{6} = \bar{18} = \bar{0}$, the identity in this group.
5. In the multiplicative group $(\mathbb{Z}/7\mathbb{Z})^\times$, the element $\bar{2}$ has order 3 since $\bar{2} \neq \bar{1}$, $\bar{2} \times \bar{2} = \bar{4} \neq \bar{1}$, but $\bar{2} \times \bar{2} \times \bar{2} = \bar{8} = \bar{1}$, the identity in this group.

Definition 1.1-4 Let $G = \{g_1, g_2, \dots, g_n\}$ be a finite group with $g_1 = 1$. The *multiplication table* or *group table* of G is the $n \times n$ matrix whose i, j entry is the group element $g_i g_j$.

More about the group table:

1. [Group Multiplication Tables | Cayley Tables \(Abstract Algebra\)](#)
2. [Group Theory Step-by-Step: 1 - 7](#)

1.2 Dihedral Groups

For each $n \in \mathbb{Z}^+$, $n \geq 3$ let D_{2n} be the set of symmetries of a regular n -gon, where a symmetry is any rigid motion of the n -gon which can be effected by taking a copy of the n -gon, moving this copy in any fashion in 3-space, and then placing the copy back on the original n -gon so it exactly covers it.

1.3 Symmetric Groups

1.4 Matrix Groups

1.5 The Quaternion Group

1.6 Homomorphisms and Isomorphisms

1.7 Group Actions

2 Subgroups