# Machine Learning

Lecture 7
Logistic Regression

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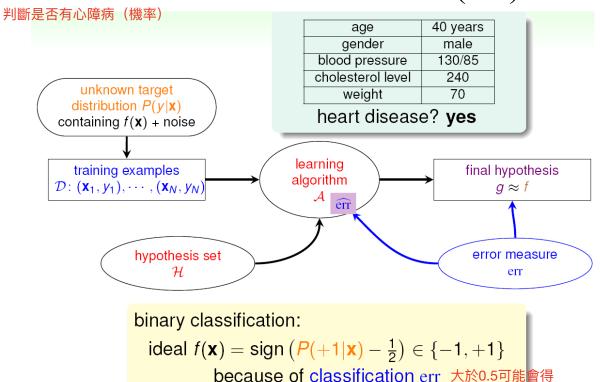
### The Storyline

**How Can Machines Learn?** 

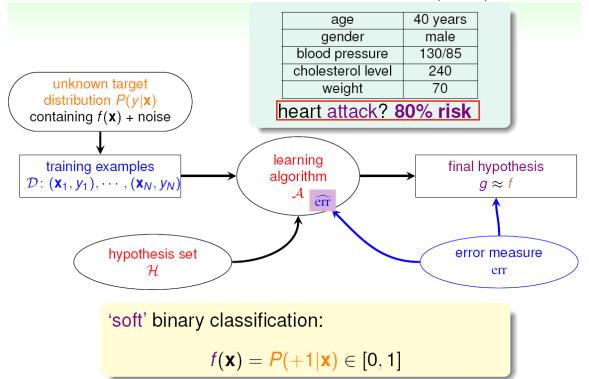
#### Logistic Regression

- Logistic Regression Problem
- Logistic Regression Error
- Gradient of Logistic Regression Error
- Gradient Descent

### Heart Attack Prediction Problem (1/2)



### Heart Attack Prediction Problem (2/2)



## Soft Binary Classification

target function  $f(\mathbf{x}) = P(+1|\mathbf{x}) \in [0,1]$  得到正一的機率多少

### ideal (noiseless) data

$$\begin{pmatrix} \mathbf{x}_{1}, y'_{1} &= 0.9 &= P(+1|\mathbf{x}_{1}) \\ (\mathbf{x}_{2}, y'_{2} &= 0.2 &= P(+1|\mathbf{x}_{2}) \\ \vdots \\ (\mathbf{x}_{N}, y'_{N} &= 0.6 &= P(+1|\mathbf{x}_{N}) \end{pmatrix}$$

### actual (noisy) data

$$\begin{pmatrix} \mathbf{x}_{1}, y_{1} &= \circ & \sim P(y|\mathbf{x}_{1}) \\ (\mathbf{x}_{2}, y_{2} &= \times & \sim P(y|\mathbf{x}_{2}) \end{pmatrix}$$

$$\vdots$$

$$\begin{pmatrix} \mathbf{x}_{N}, y_{N} &= \times & \sim P(y|\mathbf{x}_{N}) \end{pmatrix}$$

same data as hard binary classification, different target function

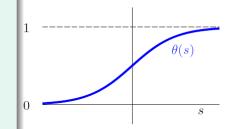
### Logistic Hypothesis

age	40 years	
gender	male	
blood pressure	130/85	
cholesterol level	240	

• For  $\mathbf{x} = (x_0, x_1, x_2, \dots, x_d)$  'features of patient', calculate a weighted 'risk score':

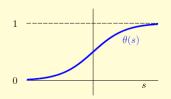
$$s = \sum_{i=0}^d w_i x_i$$

• convert the score to estimated probability by logistic function  $\theta(s)$ 



logistic hypothesis:  $h(\mathbf{x}) = \theta(\mathbf{w}^T \mathbf{x})$  帶到data裡

### Logistic Function



$$\theta(-\infty)=0$$
;

$$\theta(0) = \frac{1}{2}$$
;

$$\theta(\infty)=1$$

$$\theta(s) = \frac{e^s}{1 + e^s} = \frac{1}{1 + e^{-s}}$$

smooth, monotonic, sigmoid function of s

logistic regression: use

$$h(\mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{w}^T \mathbf{x})}$$

to approximate target function  $f(\mathbf{x}) = P(+1|\mathbf{x})$ 

#### Fun Time

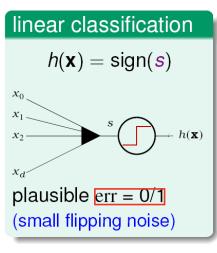
#### Logistic Regression and Binary Classification

Consider any logistic hypothesis  $h(\mathbf{x}) = \frac{1}{1 + \exp(-\mathbf{w}^T \mathbf{x})}$  that approximates  $P(y|\mathbf{x})$ . 'Convert'  $h(\mathbf{x})$  to a binary classification prediction by taking sign  $(h(\mathbf{x}) - \frac{1}{2})$ . What is the equivalent formula for the binary classification prediction?

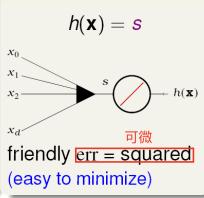
- **1** sign  $(\mathbf{w}^T \mathbf{x} \frac{1}{2})$
- $\mathbf{g}$ sign  $(\mathbf{w}^{\mathsf{T}}\mathbf{x})$
- 3 sign  $\left(\mathbf{w}^{\mathsf{T}}\mathbf{x} + \frac{1}{2}\right)$
- 4 none of the above

### Three Linear Models

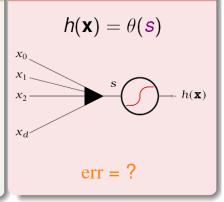
linear scoring function:  $s = \mathbf{w}^T \mathbf{x}$ 







#### logistic regression



how to define  $E_{in}(\mathbf{w})$  for logistic regression?

### Likelihood

target function 
$$f(\mathbf{x}) = P(+1|\mathbf{x})$$

$$\Leftrightarrow$$

$$P(y|\mathbf{x}) = \begin{cases} \frac{f(\mathbf{x}) & \text{for } y = +1}{1 - f(\mathbf{x}) & \text{for } y = -1} \end{cases}$$

consider 
$$\mathcal{D} = \{(\mathbf{x}_1, \circ), (\mathbf{x}_2, \times), \dots, (\mathbf{x}_N, \times)\}$$

#### probability that f generates $\mathcal{D}$

$$P(\mathbf{x}_1)P(\circ|\mathbf{x}_1) \times P(\mathbf{x}_2)P(\times|\mathbf{x}_2) \times \dots$$

$$P(\mathbf{x}_N)P(\times|\mathbf{x}_N)$$

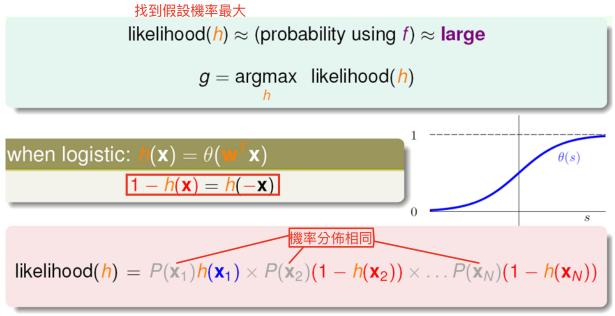
#### likelihood that h generates ${\cal D}$

$$P(\mathbf{x}_1)h(\mathbf{x}_1) \times P(\mathbf{x}_2)(1-h(\mathbf{x}_2)) \times \dots$$

$$P(\mathbf{x}_N)(1-h(\mathbf{x}_N))$$

- if  $h \approx f$ , then likelihood(h)  $\approx$  probability using f
- probability using f usually large 乘出來機率很大

### Likelihood of Logistic Hypothesis

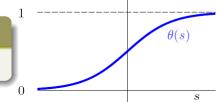


### Likelihood of Logistic Hypothesis

likelihood(
$$h$$
)  $pprox$  (probability using  $f$ )  $pprox$  large 
$$g = \underset{h}{\operatorname{argmax}} \quad \text{likelihood}(h)$$

when logistic:  $h(\mathbf{x}) = \theta(\mathbf{w}^\mathsf{T}\mathbf{x})$ 

$$1 - h(\mathbf{x}) = h(-\mathbf{x})$$



likelihood(
$$h$$
) =  $P(\mathbf{x}_1)h(+\mathbf{x}_1) \times P(\mathbf{x}_2)h(-\mathbf{x}_2) \times \dots P(\mathbf{x}_N)h(-\mathbf{x}_N)$ 

likelihood(logistic 
$$h$$
)  $\propto \prod_{n=1}^{N} h(y_n \mathbf{x}_n)$ 

### **Cross-Entropy Error**

$$\max_{h} \quad \text{likelihood(logistic } h) \propto \prod_{n=1}^{N} h(y_n \mathbf{x}_n)$$

$$\max_{\mathbf{w}} \quad \text{likelihood(} \mathbf{w}) \propto \prod_{n=1}^{N} \theta \left( \underbrace{y_n \mathbf{w}}_{n} \mathbf{x}_n \right)$$

$$\max_{\mathbf{w}} \quad \ln \prod_{n=1}^{N} \theta \left( y_n \mathbf{w}^T \mathbf{x}_n \right)$$

### Cross-Entropy Error

$$\theta(s) = \frac{1}{1 + \exp(-s)}$$
 :  $\min_{\mathbf{w}} \frac{1}{N} \sum_{n=1}^{N} \ln\left(1 + \exp(-y_n \mathbf{w}^T \mathbf{x}_n)\right)$  最大值
$$\implies \min_{\mathbf{w}} \frac{1}{N} \sum_{n=1}^{N} \operatorname{err}(\mathbf{w}, \mathbf{x}_n, y_n)$$
 最小誤差

$$err(\mathbf{w}, \mathbf{x}, y) = ln(1 + exp(-y\mathbf{w}\mathbf{x}))$$
: **cross-entropy error**

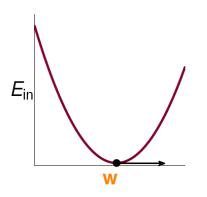
#### Fun Time

The four statements below help us understand more about the cross-entropy error  $err(\mathbf{w}, \mathbf{x}, y) = ln(1 + exp(-y\mathbf{w}^T\mathbf{x}))$ . Consider  $\mathbf{w}^T\mathbf{x} \neq 0$ . Which statement is not true?

- 1 For any  $\mathbf{w}$ ,  $\mathbf{x}$ , and y,  $err(\mathbf{w}, \mathbf{x}, y) > 0$ .
- 2 For any  $\mathbf{w}$ ,  $\mathbf{x}$ , and  $\mathbf{y}$ ,  $\operatorname{err}(\mathbf{w}, \mathbf{x}, \mathbf{y}) < 1126$ .
- **3** When  $y = \text{sign}(\mathbf{w}^T\mathbf{x})$ ,  $\text{err}(\mathbf{w}, \mathbf{x}, y) < \text{ln 2. 相同}$
- 4 When  $y \neq \text{sign}(\mathbf{w}^T\mathbf{x})$ ,  $\text{err}(\mathbf{w}, \mathbf{x}, y) \geq \ln 2$ .

## Minimizing $E_{in}(\mathbf{w})$

$$\min_{\mathbf{w}} \quad E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \ln \left( 1 + \exp(-y_n \mathbf{w}^T \mathbf{x}_n) \right)$$



- E<sub>in</sub>(w): continuous, differentiable, twice-differentiable, convex
- how to minimize? locate valley

微分為0的解 want 
$$\nabla E_{\text{in}}(\mathbf{w}) = \mathbf{0}$$

first: derive  $\nabla E_{in}(\mathbf{w})$ 

#### The Gradient $\nabla E_{in}(\mathbf{w})$

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \ln \left( \underbrace{1 + \exp(-y_n \mathbf{w}^T \mathbf{x}_n)}_{\square} \right)$$

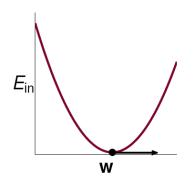
$$\frac{\partial E_{\text{in}}(\mathbf{w})}{\partial w_{i}} = \frac{1}{N} \sum_{n=1}^{N} \left( \frac{\partial \ln(\square)}{\partial \square} \right) \left( \frac{\partial (1 + \exp(\bigcirc))}{\partial \bigcirc} \right) \left( \frac{\partial - y_{n} \mathbf{w}^{T} \mathbf{x}_{n}}{\partial w_{i}} \right) \\
= \frac{1}{N} \sum_{n=1}^{N} \left( \frac{1}{\square} \right) \left( \exp(\bigcirc) \right) \left( -y_{n} x_{n,i} \right) \\
= \frac{1}{N} \sum_{n=1}^{N} \left( \frac{\exp(\bigcirc)}{1 + \exp(\bigcirc)} \right) \left( -y_{n} x_{n,i} \right) \\
= \frac{1}{N} \sum_{n=1}^{N} \theta(\bigcirc) \left( -y_{n} x_{n,i} \right) \\
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= \frac{1}{N} \sum_{n=1}^{N} \left( -y_{n} x_{n,i} \right) \\
= \frac{1}{N} \sum_{n=1}$$

$$\nabla E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \theta \left( -y_n \mathbf{w}^T \mathbf{x}_n \right) \left( -y_n \mathbf{x}_n \right)$$

## Minimizing $E_{in}(\mathbf{w})$

$$\min_{\mathbf{w}} E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \ln \left( 1 + \exp(-y_n \mathbf{w}^T \mathbf{x}_n) \right)$$

want 
$$\nabla E_{\text{in}}(\mathbf{w}) = \left| \frac{1}{N} \sum_{n=1}^{N} \theta \left( -y_n \mathbf{w}^T \mathbf{x}_n \right) \left( -y_n \mathbf{x}_n \right) \right| = \mathbf{0}$$



#### scaled $\theta$ -weighted sum of $-y_n \mathbf{x}_n$

- all  $\theta(\cdot) = 0$ : only if  $y_n \mathbf{w}^T \mathbf{x}_n \gg 0$ —linear separable  $\mathcal{D}$
- weighted sum = 0:
   non-linear equation of w

closed-form solution? no :-(

### PLA Revisited: Iterative Optimization

PLA: start from some  $\mathbf{w}_0$  (say,  $\mathbf{0}$ ), and 'correct' its mistakes on  $\mathcal{D}$ 

For t = 0, 1, ...

1 find a mistake of  $\mathbf{w}_t$  called  $(\mathbf{x}_{n(t)}, y_{n(t)})$ 

$$sign\left(\mathbf{w}_{t}^{\mathsf{T}}\mathbf{x}_{n(t)}\right) \neq y_{n(t)}$$

(try to) correct the mistake by

$$\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t + y_{n(t)} \mathbf{x}_{n(t)}$$

 $\bigcirc$  (equivalently) pick some n, and update  $\mathbf{w}_t$  by

$$\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t + \left[ \operatorname{sign} \left( \mathbf{w}_t^\mathsf{T} \mathbf{x}_n \right) \neq y_n \right] y_n \mathbf{x}_n$$

when stop, return last  $\mathbf{w}$  as g

### PLA Revisited: Iterative Optimization

PLA: start from some  $\mathbf{w}_0$  (say,  $\mathbf{0}$ ), and 'correct' its mistakes on  $\mathcal{D}$ 

For 
$$t = 0, 1, ...$$

 $\bullet$  (equivalently) pick some n, and update  $\mathbf{w}_t$  by

$$\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t + \underbrace{\mathbf{1}}_{\eta} \cdot \underbrace{\left( \left[ \operatorname{sign} \left( \mathbf{w}_t^\mathsf{T} \mathbf{x}_n \right) \neq y_n \right] \cdot y_n \mathbf{x}_n \right)}_{\mathbf{v} = \frac{1}{2} - \hat{n} = \hat{p} \hat{p} \hat{p}}$$

when stop, return last w as g

choice of  $(\eta, \mathbf{v})$  and stopping condition defines iterative optimization approach

#### Fun Time

Consider the gradient  $\nabla E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} \theta \left( -y_n \mathbf{w}^T \mathbf{x}_n \right) \left( -y_n \mathbf{x}_n \right)$ . That is, each example  $(\mathbf{x}_n, y_n)$  contributes to the gradient by an amount of  $\theta \left( -y_n \mathbf{w}^T \mathbf{x}_n \right)$ . For any given  $\mathbf{w}$ , which example contributes the most amount to the gradient?

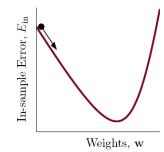
- 1 the example with the smallest  $y_n \mathbf{w}^T \mathbf{x}_n$  value
- 2 the example with the largest  $y_n \mathbf{w}^T \mathbf{x}_n$  value
- 3 the example with the smallest  $\mathbf{w}^T \mathbf{x}_n$  value
- 4 the example with the largest  $\mathbf{w}^T \mathbf{x}_n$  value

### Iterative Optimization

```
For t=0,1,\dots \mathbf{W}_{t+1} \leftarrow \mathbf{W}_t + \boxed{\eta \mathbf{V}} 純量\mathbf{x}向量方向
```

when stop, return last  $\mathbf{w}$  as g

- PLA: v comes from mistake correction
- smooth E<sub>in</sub>(w) for logistic regression: choose v to get the ball roll 'downhill'?
  - direction v: (assumed) of unit length
  - step size η:
     (assumed) positive



a greedy approach for some given  $\eta > 0$ :

讓向量最小
$$\min_{\|\mathbf{v}\|=1} E_{\mathrm{in}}(\underbrace{\mathbf{w}_t + \eta \mathbf{v}}_{\mathbf{w}_{t+1}})$$

### Linear Approximation

a greedy approach for some given  $\eta > 0$ :

沒有辦法一次到位

$$\min_{\|\mathbf{v}\|=1} \quad E_{in}(\mathbf{w}_t + \mathbf{\eta v})$$

- still non-linear optimization, now with constraints
   —not any easier than min<sub>w</sub> E<sub>in</sub>(w)
- local approximation by linear formula makes problem easier

$$E_{\text{in}}(\mathbf{w}_t + \frac{\eta \mathbf{v}}{\mathbf{v}}) \approx E_{\text{in}}(\mathbf{w}_t) + \frac{\eta \mathbf{v}}{\mathbf{v}}^T \nabla E_{\text{in}}(\mathbf{w}_t)$$

if  $\eta$  really small (Taylor expansion)

an approximate greedy approach for some given small  $\eta$ :

$$\min_{\|\mathbf{v}\|=1} \quad \underbrace{E_{\text{in}}(\mathbf{w}_t)}_{\text{known}} + \underbrace{\eta}_{\text{given positive}} \mathbf{v}^{\mathsf{T}} \underbrace{\nabla E_{\text{in}}(\mathbf{w}_t)}_{\text{known}}$$

### Gradient Descent

an approximate greedy approach for some given small  $\eta$ :

$$\min_{\|\mathbf{v}\|=1} \underbrace{E_{\text{in}}(\mathbf{w}_t)}_{\text{known}} + \underbrace{\eta}_{\text{given positive}} \underbrace{\nabla E_{\text{in}}(\mathbf{w}_t)}_{\text{known}}$$

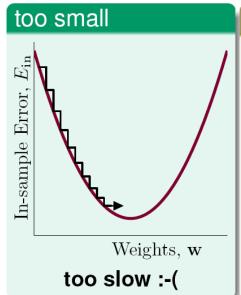
• optimal **v**: opposite direction of  $\nabla E_{in}(\mathbf{w}_t)$ 

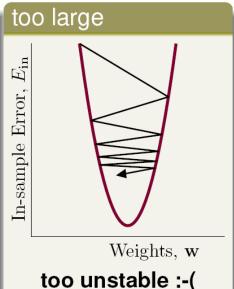
$$\mathbf{v} = egin{array}{c} -rac{
abla E_{\mathsf{in}}(\mathbf{w}_t)}{\|
abla E_{\mathsf{in}}(\mathbf{w}_t)\|} \end{array}$$
單位向量

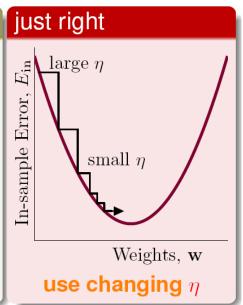
• gradient descent: for small  $\eta$ ,  $\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t - \eta \frac{\nabla E_{\text{in}}(\mathbf{w}_t)}{\|\nabla E_{\text{in}}(\mathbf{w}_t)\|}$ 

gradient descent:
a simple & popular optimization tool

### Choice of $\eta$







 $\eta$  better be **monotonic of**  $\|\nabla E_{in}(\mathbf{w}_t)\|$ 

## Simple Heuristic for **Changing** η

 $\eta$  better be monotonic of  $\|\nabla E_{in}(\mathbf{w}_t)\|$ 

• if red  $\eta \propto \|\nabla E_{in}(\mathbf{w}_t)\|$  by ratio purple  $\eta$ 

$$\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t - \eta \frac{\nabla E_{\mathsf{in}}(\mathbf{w}_t)}{\|\nabla E_{\mathsf{in}}(\mathbf{w}_t)\|}$$
 $\parallel$ 
 $\mathbf{w}_t - \eta \nabla E_{\mathsf{in}}(\mathbf{w}_t)$ 

• call purple  $\eta$  the fixed learning rate

fixed learning rate gradient descent:

$$\mathbf{W}_{t+1} \leftarrow \mathbf{W}_t - \eta \nabla E_{\text{in}}(\mathbf{W}_t)$$

### Putting Everything Together

#### Logistic Regression Algorithm

initialize  $\mathbf{w}_0$ For  $t = 0, 1, \cdots$ 

1 compute

$$\nabla E_{\text{in}}(\mathbf{w}_t) = \frac{1}{N} \sum_{n=1}^{N} \theta \left( -y_n \mathbf{w}_t^T \mathbf{x}_n \right) \left( -y_n \mathbf{x}_n \right)$$

2 update by

$$\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t - \eta \nabla \mathbf{\mathcal{E}}_{in}(\mathbf{w}_t)$$
 更新

微分等於0

...until  $\nabla E_{in}(\mathbf{w}_{t+1}) = 0$  or enough iterations return last  $\mathbf{w}_{t+1}$  as g

similar time complexity to **pocket** per iteration

### Fun Time

If  $\mathbf{w}_0 = \mathbf{0}$ , and take  $\eta = 0.1$ . What is  $\mathbf{w}_1$  in the logistic regression algorithm?

$$\bullet$$
 +0.1 ·  $\frac{1}{N} \sum_{n=1}^{N} y_n \mathbf{x}_n$ 

2 
$$-0.1 \cdot \frac{1}{N} \sum_{n=1}^{N} y_n \mathbf{x}_n$$

3 +0.05 
$$\cdot \frac{1}{N} \sum_{n=1}^{N} y_n \mathbf{x}_n$$

**4** 
$$-0.05 \cdot \frac{1}{N} \sum_{n=1}^{N} y_n \mathbf{x}_n$$

$$\nabla E_{\text{in}}(\mathbf{w}_t) = \frac{1}{N} \sum_{n=1}^{N} \theta \left( -y_n \mathbf{w}_t^T \mathbf{x}_n \right) \left( -y_n \mathbf{x}_n \right)$$
$$\mathbf{w}_{t+1} \leftarrow \mathbf{w}_t - \eta \nabla E_{\text{in}}(\mathbf{w}_t)$$

### Summary

#### **How Can Machines Learn?**

### Linear Regression Logistic Regression Logistic Regression Problem $P(+1|\mathbf{x})$ as target and $\theta(\mathbf{w}^T\mathbf{x})$ as hypotheses Logistic Regression Error cross-entropy (negative log likelihood) Gradient of Logistic Regression Error $\theta$ -weighted sum of data vectors Gradient Descent roll downhill by $-\nabla E_{in}(\mathbf{w})$