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Abstract

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Chapter 1

Introduction

1.1 Background and Recent Research

1.1.1 ;any sub section here;

1.1.2 Literature Survey

1.2 Layout of Paper

;Sub-subsection title;

some text^[1], some more text

;Sub-subsection title;

even more text¹, and even more.

1.3 Motivation

¹;footnote here;

Chapter 2

Technical Background

2.1 Isogenies

2.1.1 ¶Sub-section title¶

2.1.2 ¶Sub-section title¶

some text[2], some more text

2.1.3 ¶Sub-section title¶

2.1.4 ¶Sub-section title¶

Refer figure 4.1.

2.2 SIDH

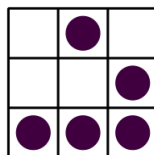


Figure 2.1: ¶Caption here¶

2.2.1 ¶Sub-section title¶

2.3 Fiat-Shamir

2.4 Isogeny Based Signatures

Chapter 3

Batching Operations for Isogenies

3.1 Batching Procedure in Detail

This section will outline one of the two main procedures implemented in our work. The algorithm in question reduces arbitrarily many unrelated/potentially parallel \mathbb{F}_{p^2} inversions to a sequence of \mathbb{F}_p multiplications & additions, as well as one \mathbb{F}_p inversion.

The procedure is as follows:

Algorithm 1 Batched Partial-Inversion

```
1: procedure PARTIAL_BATCHED_INV( $\mathbb{F}_{p^2}[\ ]$  VEC,  $\mathbb{F}_{p^2}[\ ]$  DEST, INT N)
2:   initialize  $\mathbb{F}_p$  den[n]
3:   for i = 0..(n-1) do
4:     den[i]  $\leftarrow a[i][0]^2 + a[i][1]^2$ 
5:   a[0]  $\leftarrow$  den[0]
6:   for i = 1..(n-1) do
7:     a[i]  $\leftarrow$  a[i-1]*den[i]
8:   ainv  $\leftarrow$  inv(a[n-1])
9:   for i = n-1..1 do
10:    a[i]  $\leftarrow$  ainv * dest[i - 1]
11:    ainv  $\leftarrow$  ainv * den[i]
12:   dest[0]  $\leftarrow$  ainv
13:   for i = 0..(n-1) do
14:     dest[i][0]  $\leftarrow$  a[i] * vec[i][0]
15:     vec[i][1]  $\leftarrow$  -1 * vec[i][1]
16:     dest[i][1]  $\leftarrow$  a[i] * vec[i][1]
```

3.1.1 Projective Space

Because the work of Yoo et al. was built on top of the original Microsoft SIDH library, all underlying field operations (and isogeny arithmetic) are performed in projective space. Doing field arithmetic in projective space allows us to avoid many inversion operations. The downside of this (for our work) is that the number opportunities for implementing

the batched inversion algorithm becomes greatly limited.

3.1.2 Remaining Opportunities

There are two functions called in the isogeny signature system that perform a \mathbb{F}_{p^2} inversion: `j_inv` and `inv_4_way`. These functions are called once in `SecretAgreement` and `KeyGeneration` operations respectively. `SecretAgreement` and `KeyGeneration` are in turn called from each signing and verification thread.

This means that in the signing procedure there are 2 opportunities for implementing batched partial-inversion with a batch size of 248 elements. In the verify procedure, however, there are 3 opportunities for implementing batched inversion with a batch size of roughly 124 elements.

3.2 Implementation

3.3 Results

Two different machines were used for benchmarking. System A denotes a single-core, 1.70 GHz Intel Celeron CPU. System B denotes a quad-core, 3.1 GHz AMD A8-7600.

The two figures below provide benchmarks for `KeyGen`, `Sign`, and `Verify` procedures with both batched partial inversion implemented (in the previously mentioned locations) and not implemented. All benchmarks are averages computed from 100 randomized sample runs. All results are measured in clock cycles.

Procedure	System A Without Batching	System A With Batching
KeyGen	68,881,331	68,881,331
Signature Sign	15,744,477,032	15,565,738,003
Signature Verify	11,183,112,648	10,800,158,871
Procedure	System B Without Batching	System B With Batching
KeyGen	84,499,270	84,499,270
Signature Sign	10,227,466,210	10,134,441,024
Signature Verify	7,268,804,442	7,106,663,106

System A: With inversion batching turned on we notice a 1.1 % performance increase for key signing and a 3.5 % performance increase for key verification.

System B: With inversion batching turned on we observe a 0.9 % performance increase for key signing and a 2.3 % performance increase for key verification.

3.3.1 Analysis

It should first be noted that, because our benchmarks are measured in terms of clock cycles, the difference between our two system clock speeds should be essentially ineffective.

In the following table, "Batched Inversion" signifies running the batched partial-inversion procedure on 248 \mathbb{F}_{p^2} elements. The procedure uses the binary GCD \mathbb{F}_p inversion function which, unlike regular \mathbb{F}_{p^2} montgomery inversion, is not constant time.

Procedure	Performance
Batched Inversion	1721718
\mathbb{F}_{p^2} Montgomery Inversion	874178

Do performance increases observed make sense?

Chapter 4

Compressed Signatures

4.1 Compression of Public Keys

4.1.1 ;Sub-section title;

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4.1.3 ;Sub-section title;

4.1.4 ;Sub-section title;

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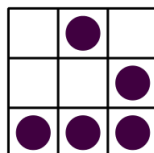


Figure 4.1: ;Caption here;

4.1.5 ;Sub-section title;

4.2 Implementation

4.3 Results

Chapter 5

Discussion & Conclusion

5.1 Results & Comparisons

5.2 Additional Opportunities for Batching

5.3 Future Work

¡Conclusion here¿

Acknowledgments

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References

[1] iName of the reference here_i, <urlhere>

[2] iName of the reference here_i, <urlhere>