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Software Design

Requirements Specification Introduction:

The purpose of this program is to navigate the finch robot using a computer. The program provides a simple and easy to use graphical user interface with a variety of commands to direct the finch.

Functional Requirements:

- 1) The system should have an introductory message at the start, which informs the user of the implemented commands that the program can execute and how to properly enter a command.
- 2) The system shall successfully implement these commands:
 - *F (for Forward movement)*
 - B (for Backward movement)
 - R (for Right turn)
 - *L* (for Left turn)
 - *T (for retracing previous movement(s))*
 - *W (for Writing the log of the commands to a text file)*
 - *X* (for executing commands from a text file)
 - *Q* (to Quit the program)
- 3) The system shall present the user with an error if any other letter that does not correspond to a command is entered and ask them to re-enter their command.
- 4) No movement should last more than 6 seconds, the speed should not exceed 200 neither should accept a negative value for speed and duration.
- 5) The system shall ensure that the input values are within the set valid range; for example, duration should be entered having a value between 1 to 6 seconds and speed should be entered having a value between 0 to 200, thus an input of 10 seconds or 250 (for speed) will result in an error message requesting the user to re-enter their command.
- 6) The system shall only accept two integer values as inputs for the commands forward('F') and backward("B"). The first value should set the duration of the command (in seconds) and the second value should set the speed of the finch; at which it should execute the command. For example, 'F 3 150' should be interpreted as a command to move the finch forward for 3 seconds at a speed of 150.
- 7) The system shall only accept two integer values for the commands right('R') and left('L'). The first value sets the duration of the turn in seconds and the second value should set the speed of the finch after the turn is made.
 - a) Each turn should not last more than 6 seconds and speed should not exceed 200.
 - b) The turns should always be orthogonal to the current course and finch shall continue moving forward at the given duration and speed after the turn is made.
- 8) The system shall only accept one integer value for the command retrace('T'). This value should determine how many previous movements the finch needs to retrace. For example,

- if the finch has executed the following commands 'L', 'R', B', 'F', 'B', 'R', thus when 'T4' is entered, the finch should execute again 'R', then 'B' then 'F' and lastly 'B' (i.e. the previous 4 movements starting from the last one).
- a) If the number of movements to retrace exceeds the number of movements the finch has executed then the system must display an error message and request the user to reenter their command.
- b) The system shall retrace only previous movement commands and not any previous 'T' commands.
- 9) For the command 'W', the program should write the current local time in HH: MM: SS format and all the commands (including the 'T' commands) that the finch has executed to a text file.
 - a) If no text file is found then a new text file shall be created and written to.
- 10) For command 'X', the program should open and read an existing file that must contain at least three commands (i.e. 'B 1 100', 'F 3 200', 'L 4 150', 'R 6 170') and have the finch execute them one by one.
 - a) Either if no text file is found or the text consists of fewer than three commands then, the system shall display an error message informing the user should check a file exist in the specified directory and that the file consists of at least 3 executable commands.
 - b) The system shall also execute any 'T' commands found in the text file.
- 11) The system shall terminate the program if the command 'Q' is entered.

Non-functional Requirements:

- 1) The system should provide a simple and easy to use graphical user interface for the user to interact (GUI) with the program (usability).
- 2) The program should be reliable and maintainable. Furthermore, it should aim to have low coupling and high cohesion between methods.
- 3) The system should attempt to implement object-oriented (00) methods such as encapsulation to ensure that the program is as secure as possible.
- 4) The system may have an additional log display in the graphical user interface (GUI), where it displays previously executed commands and error messages that do occur during the execution of commands.

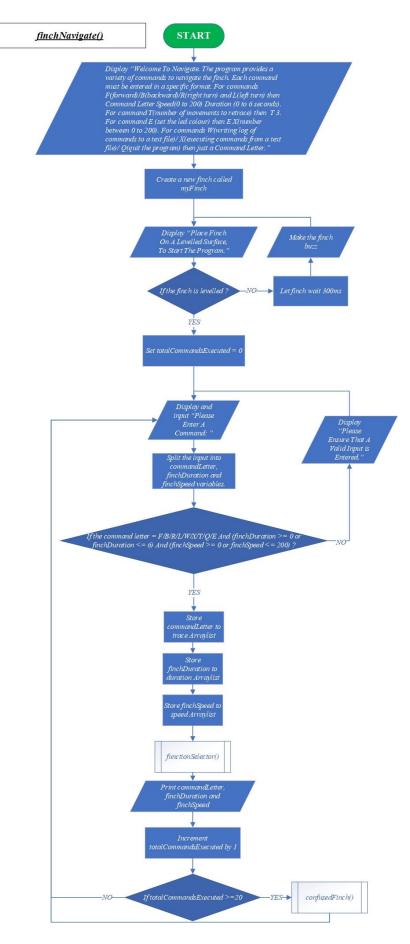
Additional Requirements:

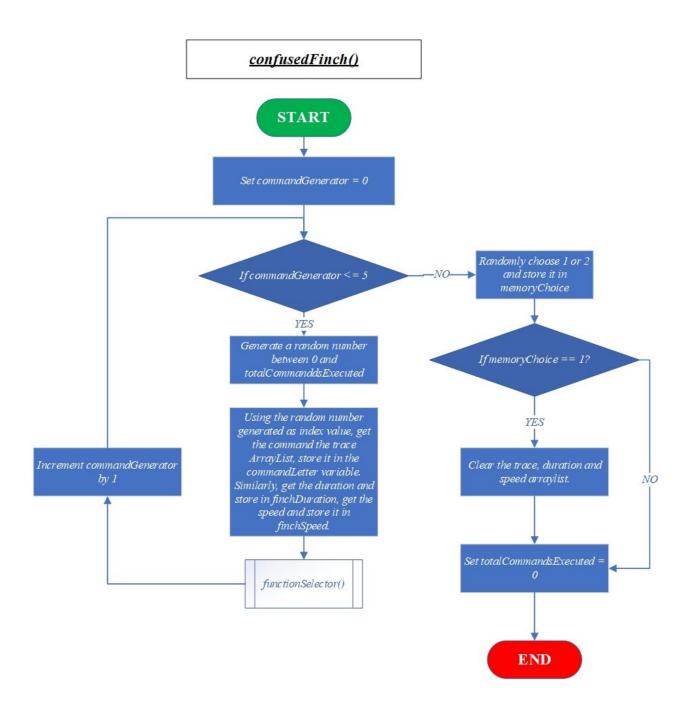
- 1) The system may have an additional mode ("Confused Finch") where if twenty or more commands are executed then it results in the finch randomly executing 5 previously executed commands from the trace array. Furthermore, the finch may choose to forget any previous commands executed (each ArrayList is cleared) if the confused finch mode occurs.
- 2) The system may have an additional function that checks the level of the finch relative to the ground. If the finch is on a levelled ground, then the program will continue else, the system shall display an error message and request the user to place the finch on a levelled surface. Furthermore, the system shall make the finch wait 300ms and make a buzz sound.

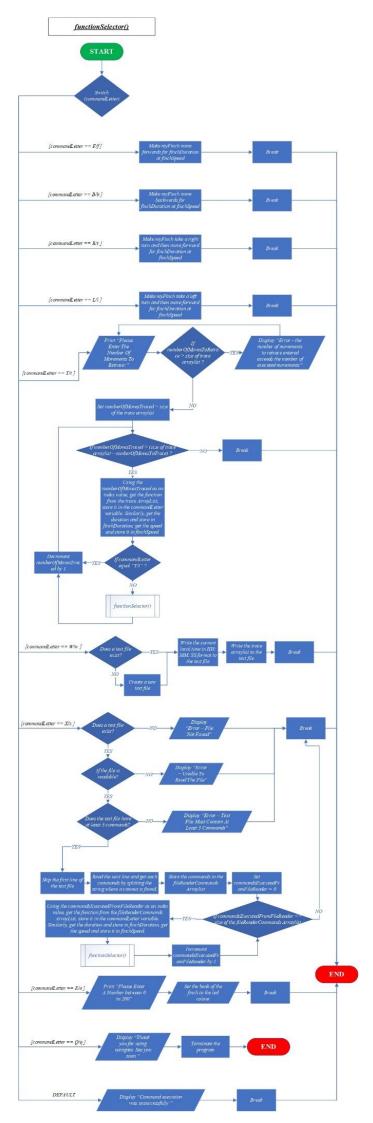
3) An additional command, 'E (for Led colour)' may be implemented, where the system shall only accept one integer value between 0 and 200. This value sets the beak of the finch to a random colour for 3 seconds. If a value greater less than 0 or than 200 is entered, then the user must be informed using an error message and request the user to re-enter their command.

Conclusion: The design of the algorithm includes all the required functionalities, the non-functional requirements and the additional requirements. Many of the additional functionalities are added, provide a variety and commands for the user to execute and also the confusedFinch mode, makes the program more interesting and complete.

Flowchart:







Pseudocode

Algorithm 1: finchNavigate (myFinch, User Input)

/* This algorithm takes in commands from the graphical user interface (GUI), validates if the command (function, duration and speed) entered are within the set valid range and finally stores the executed commands to an ArrayLists. */

Input: User inputs are string based which includes the function, duration and the speed. myFinch is a finch. Finch also provides an internal input to check if its levelled – where it returns a Boolean value.

Set finchDuration = 0, finchSpeed = 0, totalCommandsExecuted = 0

Initialise inputCommand, commandLetter

Create an ArrayList called trace

Create an ArrayList called duration

Create an ArrayList called speed

Print "Welcome To Navigate. The program provides a variety of commands to navigate the finch. Each command must be entered in a specific format. For commands F(forward)/B(backward)/R(right turn) and L(left turn) then Command Letter Speed(0 to 200) Duration (0 to 6 seconds)..."

/* Prints out an introductory message informing the user about the program. Creates a new finch and it make finch wait for 300ms, make the finch buzzes to inform the user to place finch on levelled surface. */

Create a new finch

Repeat

Let myFinch wait for 300ms

myFinch buzz

Print "Place Finch On A Levelled Surface, To Start The Program."

Until myFinch is on a levelled surface

/* This while loop ensure repeats itself until the user enters a valid command which satisfies all conditions in the if statement. Furthermore, it stores function into the trace ArrayList, finchDuration in the duration ArrayLists and finchSpeed into the speed ArrayList. Then the functionSelector method is called. If the totalCommandsExecuted is greater than 20 then it calls the confusedFinch method. */

While true

Set inputCommand = **Input**("Please Enter A Command:"")

Split the inputCommand into commandLetter, finchDuration and finchSpeed

If the commandLetter is equal to (F or B or R or L or W or X or T or Q or E) And (finchDuration >= 0 or finchDuration <= 6) And (finchSpeed >= 0 or finchSpeed <= 200) then

Add commandLetter to the trace ArrayList

Add finchDuration to the duration ArrayList

Add finchSpeed to the speed ArrayList

Call functionSelector()

Print "commandLetter, finchDuration and finchSpeed"

Increment totalCommandsExecuted by 1

If totalCommandsExecuted >= 20 then

Call confusedFinch()

Break

End If

Else

Print "Please Ensure That A Valid Input is Entered."

End If

End While

Output: Buzz sound from the finch, totalCommandsExecuted, commandLetter, finchDuration, finchSpeed, trace, duration and speed.

<u>Algorithm 2: confusedFinch (myFinch, totalCommandsExecuted, commandLetter, finchDuration, finchSpeed, trace, duration and speed)</u>

/* This algorithm makes the finch randomly select 5 previously executed commands and adds a random option which can clear any previously stored commands. */

Input: totalCommandsExecuted is an integer, which indicates the total number of commands so far. commandLetter is a character where it stores the function. finchDuration and finchSpeed are integer values. Trace is a character ArrayList consisting commandLetters. Both duration and speed are integer based ArrayList.

/* When curiousFinch method is called, it randomly selects 5 previously executed commands from the 3 ArrayLists and executes using the functionSelector method. Lastly, towards the end it randomly picks a number, which decides if the previous command log remain or not. If 1 is chosen then all 3 ArrayLists are cleared. */

```
Set commandGenerator = 0
```

Initialise index Value, memory Choice

If commandGenerator <= 5 **then**

indexValue = Generate a random number between 0 and totalCommandsExecuted

Set commandLetter = **Get** trace[indexValue]

Set finchDuration = **Get** duration[indexValue]

Set finchSpeed = **Get** speed[indexValue]

Call functionSelector()

Increment commandGenerator by 1

Else

Set memoryChoice = generate a random number (1, 2)

If memoryChoice is equal to 1 then

Clear trace ArrayList

Clear duration ArrayList

Clear speed ArrayList

Set totalCommandsExecuted = 0

Else

Set totalCommandsExecuted = 0

End If

End If

Output: totalCommandsExecuted, commandLetter, finchDuration, finchSpeed, trace, duration and speed

<u>Algorithm 3: functionSelector (myFinch, text file, commandLetter, finchDuration, finchSpeed, trace, duration and speed)</u>

/* This algorithm is a switch case, which takes in the commandLetter as input and compared it against each individual case. */

Input: The text file consists of string commands separated by commas. commandLetter is a type of string variable which stores the function. finchDuration and finchSpeed are integer values. Trace, duration and speed are types of arrays. myFinch is a finch.

Initialise numberOfMovesToRetrace, commandsExecutedFromFileReader

Create a new ArrayList called fileReaderCommands

Switch, based on commandLetter

/* The following cases; f/b/r/l, use the commandLetter to select the appropriate case. Each case then uses the finchDuration and finchSpeed values to make the finch move. */

Case commandLetter equals F/f

Move myFinch forward for finchDuration at finchSpeed

Break

End Case

Case commandLetter equals B/b

Move myFinch backward for finchDuration at finchSpeed

Break

End Case

Case commandLetter equals R/r

Move myFinch to take a right turn

Move myFinch forward for finchDuration at finchSpeed

Break

End Case

Case commandLetter equals L/l

Move myFinch to take a left turn

Move myFinch forward for finchDuration at finchSpeed

Break

End Case

/* This case retrieves the previously executed commands and using a for and if loops, it reads the array backwards and if T is found as commandLetter than the command is skipped. Each command is then executed one by one by calling the functionSelector method. */

Case commandLetter equals T/t

While True

Set numberOfMovesToRetrace = **Input**("Please Enter The Number Of Movements To Retrace:"")

If numberOfMovesToRetrace > size of trace ArrayList **then**

Print "Error - the number of movements to retrace entered exceeds the number of executed movements"

Else

Set numberOfMovesTraced = size of the trace arraylist

OUTER_LOOP

If numberOfMovesTraced > (size of trace arraylist – nunberOfMovesToTrace) **then**

Set commandLetter = **Get** trace[numberOfMovesTrraced]

Set finchDuration = **Get** duration[numberOfMovesTraced]

Set finchSpeed = **Get** speed[numberOfMovesTraced]

If commandLetter is equal to T or t **then**

Decrement numberOfMovesTraced by 1

Break OUTER_LOOP

Else

Call functionSelector()

Decrement numberOfMovesTraced by 1

Break OUTER_LOOP

End If

Else

Break

End If

End If

End While

End Case

/* This case writes down the local time on a text along with all the previously executed commands (including the 'T' commands) to a text file. If no text file is found the a new text file is created. */

Case commandLetter equals W/w

While True

If a text file exists then

Write the current local time in HH: MM: SS format to the text file

Write the trace ArrayList to the text file

Break

Else

Create a new text file

Write the current local time in HH: MM: SS format to the text file

Write the trace ArrayList to the text file

Break

End If

End While

End Case

/* This case makes few checks such as if a text file exists, if the text file is readable and if the text file has at least 3 commands. Then the commands are read and broken down when a comma is found. Each command is stored in a fileReaderCommands ArrayList and then executed one by one using the functionSelection(). If any of the conditions are not meet, then an error message is displayed. */

Case commandLetter equals X/x

If a text file exists then

If the text file is readable then

If he texts file has at least 3 commands then

Skip the first line of the text file

Read the next line and **split** when a comma is found

Store the commands in the fileReaderCommands ArrayList

Set commandsExecutedFromFileReader = 0

Second_Outer_Loop

If commandsExecutedFromFileReader <= size of the fileReaderCommands Arraylist **then**

Set commandLetter = **Get**

fileReaderCommands[commandsExecutedFromFileReader]

Set finchDuration = **Get**

duration[commandsExecutedFromFileReader]

Set finchSpeed = **Get** speed[num

commandsExecutedFromFileReader berOfMovesTraced]

Call functionSelector()

Increment commandsExecutedFromFileReader by 1

Break Second_Outer_Loop

Else

Break

End If

Else

Print "Error – Text File Must Contain At Least 3 Commands"

Break

End If

```
Print "Error – Unable To Read The File"
Break
End If
Else
Print "Display "Error – File Not Found"
Break
```

End Case

End If

/* The E/e case take in an integer input and set the beak of the finch to its led colour. Case Q causes the program to terminate and lastly, the default case prints out a print message and breaks out of the switch statement. */

Case commandLetter equals E/e

Print "Please Enter A Number between 0 to 200"

Set the beak of the finch to the led colour using the input from the user

Break

End Case

Case commandLetter equals Q/q

Print "Thank you for using navigate. See you soon."

Terminate the program

Exit

End Case

Case DEFAULT

Print "Thank you for using navigate. See you soon."

Break

End Case

Outputs: Text file with commands written to it, trace, duration, speed, commandLetter, finchDuration, finchSpeed, Led Colour shown on the beak of the finch and termination of the program.

Graphical User Interface (GUI) – Prototype Design

Starting Screen:

FINCH NAVIGATE	- D x
<u>Commands LOG</u>	
Enter Command: Command Latter (F/D/D/L/T/W/V/O/F) Duration (C.t., C.c., J.) Second	(0 to 200) i o "F 4 400"
Enter Command: Command Letter (F/B/R/L/T/W/X/Q/E) Duration (0 to 6 Seconds) Speed (
	ENTER

Program in use

rogram in use:		
FINCH NAVIGATE	- D x	
Commands LOG		
F-Forward, $Duration = 5$ $Second(s)$, $Speed 100$		
B-Backward, Duration = 6 Second(s), Speed 150		
B-Backward, $Duration = 1$ Second(s), $Speed 170$		
R-Right, $Duration = 2 Second(s)$, $Speed 100$		
Error – incorrect command!! Please ensure command entered as Command Letter(F/. Duration (0 to 6 seconds) Speed (0 to 200). i.e. F 1 100 OR B 5 170.	B/R/L/W/T/X/E/Q)	
L-Left, $Duration = 3 Second(s)$, $Speed 90$		
T – Trace, 2 Previous Movements		
L-Left, $Duration = 3 Second(s)$, $Speed 90$		
R-Right, Duration = 2 Second(s), Speed 100		
W – Writing command log to the text file.		
5-to-6-man d. 6-man d. the (5/0/0/1/17/14/1/0/15) Devetion (0.to-6-man) (0.to-6-man) (0.to-6-man)		
Enter Command: Command Letter (F/B/R/L/T/W/X/Q/E) Duration (0 to 6 Seconds) Speed (0 to 200) i.e. "F 1 100"	
B 3 170	ENTER	