Name:	v	er. Orașină	1	
Roll No. :		•		
Invigilator's Signature :		6.7		

#### **CONTROL SYSTEMS**

Time Allotted: 3 Hours

Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

Semi log paper and Graph Sheet/(s) will be provided by the institution

#### GROUP -- A ( Multiple Choice Type Questions )

- 1. Choose the correct alternatives for any ten of the following:
  - $10\times1=10$
  - i) A system having transfer function  $G(s) = \frac{1}{2(s+0.5)}$  is subjected to a unit step input, the steady value of the output is
    - a) 1

b)

c)  $\frac{1}{2}$ 

- d)  $\frac{1}{10}$ .
- ii) The natural frequency of oscillations of the output for the equation  $\frac{d^2x}{dt^2} + 1.5 \frac{dx}{dt} + 4x = 1$  is
  - a) 0 rad/sec
- b) 1.5 rad/sec
- c) 2 rad/sec
- d) 4 rad/sec.

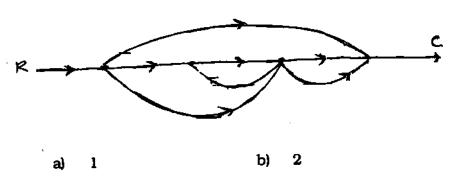
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- xi) State variable approach converts an nth order system into
  - a) n 2nd order differential equations
  - b) 2 differential equations
  - c) n 1st order differential equations
  - d) a low order system.
- xii) The number of forward paths in the signal flow graph shown below is



c) 3 d) 5.

# GROUP - B ( Short Answer Type Questions )

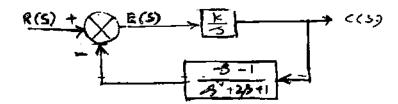
Answer any three of the following.  $3 \times 5 = 15$ 

2. A unity feedback heat treatment system has open loop transfer function

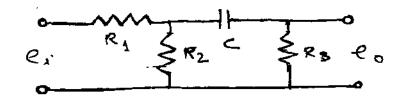
$$G(s) = \frac{10000}{(1+s)(1+0.5s)(1+0.02s)}$$
. The output set point is 500°C. What is the steady state temperature?

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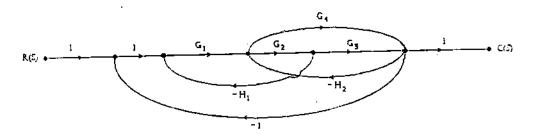
3. Find the range of k to keep the system shown in figure to be stable.



4. Determine the transfer function of the network shown in figure relating  $E_o(s) \& E_i(s)$ 



5. Find the transfer function from the following signal flow graph using Mason's gain farmula.



6. Construct the state model for a system characterized by the differential equation

$$\ddot{Y} + 5\dot{y} + 6y = 4.$$

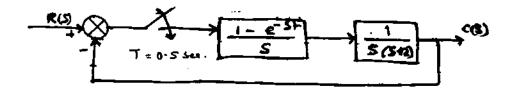
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- 10. a) Find Z transform of cos wt.
  - b) Obtian Z transer function for the block diagram shown in the figure.



5 + 10

- 11. a) Explain with an example the steps to find the phase trajectory of a second order system using method of isoclines.
  - b) Write a note on PID controller.

10 + 5

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