CS/B.TECH/EE/EVEN/SEM-6/EE-605A/2015-16



MAULANA ABUL KALAM AZAD UNIVERSITY OF TECHNOLOGY, WEST BENGAL Paper Code: EE-605A DIGITAL SIGNAL PROCESSING

Time Allotted: 3 Hours

Full Marks: 70

The figures in the margin indicate full marks.

Candidates are required to give their answers in their own words as far as practicable.

GROUP - A

(Multiple Choice Type Questions)

- Choose the correct alternatives for any ten of the following: $10 \times 1 = 10$
 - The sampling frequency of the following analog signal $x(t) = 3\sin(150t) + 5\cos(200t)$ should be
 - a) greater than or equal to 150 Hz
 - b) greater than or equal to 200 Hz
 - c) greater than or equal to 600 Hz
 - d) less than or equal to 200 Hz.

CS/B.TECH/EE/EVEN/SEM-6/EE-605A/2015-16

- A discrete-time system is said to be causal if and only if its impulse response h[n] is
 - a) zero for n < 0
- b) zero for n > 0
- c) zero at n = 0
- d) zero at n0.
- iii) If x[n] and h[n] are two finite length sequences with length 6 and 5 respectively then their convolution has length
 - a) 8

b) 9

c) 10

- d) 11.
- iv) The value of the twiddle factor W_{16}^2 is given by
 - a) 0+j

b) 0.707 - j0.707

c) 0 – j

- d) -0.707 + j0.707.
- v) The first three points of a 4-point DFT of a real valued sequence are $\{6,-2+j2,-2\}$. The remaining point in the DFT is
 - a) 2 j2

b) 2 + j2

6-2j

d) -2-j2.

Turn over

6/60511

6/60511

2

CS/B.TECH/EE/EVEN/SEM-6/EE-605A/2015-16

- vi) An increase in the length of the rectangular window function
 - a) increases the main lobe width and computational burden
 - b) increases the main lobe width and decreases computational burden
 - c) decreases the main lobe width and computational burden
 - d) decreases the main lobe width and increase computational burden.
- vii) If $x[n] \leftrightarrow X(z)$, then
 - a) $x[-n] \leftrightarrow X(-z)$ b) $x[-n] \leftrightarrow zX(z)$
 - c) $x(-n) \leftrightarrow X(z)/z$ d) $x(-n) \leftrightarrow X(1/z)$.
- viii) The digital system is $y(n) = x(n^2)$ is
 - a) linear and causal
 - b) non-linear and causal
 - c) linear and non-causal
 - d) non-linear and non-causal.

CS/B.TECH/EE/EVEN/SEM-6/EE-605A/2015-16

- ix) Zero padding of a signal
 - a) reduces aliasing
 - b) increases frequency
 - c) increases time resolution
 - d) has no effect.
- x) The convolution of u(n) with u(n-4) at n=5 is
 - a) 5

b) 2

c) 1

- d) 0.
- xi) Stability criteria for discrete time LTI system is
 - a) h(n) > 1

b) h(n) < 1

c) h(n) = 1

- d) h(n) = 0.
- xii) The ROC of the z-transform causal sequence is
 - a) the interior of circle b) the exterior of circle
 - c) a rectangle
- d) an annular region.
- xiii) For a 32 point sequence, radix 2 FFT algorithm involves
 - a) 160 complex additions and 160 complex multiplications
 - b) 80 complex additions and 80 complex multiplications
 - c) 160 complex additions and 80 complex multiplications
 - d) 80 complex additions and 160 complex multiplications.

3

CS/B TECH/EE/EVEN/SEM-6/EE-605A/2015-16

GROUP - B

(Short Answer Type Questions)

Answer any three of the following. $3 \times 5 = 15$

Determine the z-transform of the following sequence and find its ROC:

$$\boldsymbol{x(n)} = (n+0\cdot5) \left(\frac{1}{3}\right)^n u(n)$$

Determine the Fourier transform of the signal $x(n) = 2^n u(-n) - 2^{-n} u(n).$

Determine the convolution of the given sequences by ...transform to the input signal

$$h(n) = (0.5)^n u(n)$$

 $x(n) = 3^n u(-n).$

$$x(n) = 3^n u(-n).$$

If $x(n) = \{1, 3, 2\}$ and $y(n) = \{1, 2\}$, find the linear convolution $x(n)^*y(n)$ using DFT based approach.

For the sequence $x(n) = \{1,1,0,-1,-1,0,0\}$, determine the 8-point DFT.

CS/B.TECH/EE/EVEN/SEM-6/EE-605A/2015-16

GROUP - C

(Long Answer Type Questions)

Answer any three of the following. $3 \times 15 = 45$

- Find the 8-point DFT using decimation in time FFT 7. algorithm for a sequence $x(n) = \{1, 3, 5, 7, 2, 4, 6, 8\}$.
 - What do you mean by zero padding?
 - Using linear convolution find $y(n) = x(n)^* h(n)$ for c) $x(n) = \{1, 2, -1, -2, 0, 1, 3, -1\}.$ the Compare the result by solving the problem using
 - overlap save method
 - overlap add method.

- 5 + 2 + 8
- Explain impulse invariant method of designing IIR 8. digital filter.
 - Design and realize a digital LPF using bilinear transformation method to satisfy the following specifications:
 - Monotonic stop and pass band
 - -3dB cutoff frequency at 0.5π
 - Magnitude down to at least 15 dB at 0.75π .

5 + 10

CS/B.TECH/EE/EVEN/SEM-6/EE-605A/2015-16

- 9. a) Distinguish between FIR and IIR filters.
 - b) What is warping effect in bilinear transformation?

 How can you remove this effect?
 - c) The output and input of a recursive DTLTI system are related by the equation

$$y(n) = -0 \cdot 1y(n-1) + 0 \cdot 2y(n-2) + 3x(n)$$

$$+3\cdot6x(n-1)+0\cdot6x(n-2)$$
.

Derive and draw the direct form II structure of realizing the system.

d) Check the stability of the system defined by y(n) = x(n) + x(n-1)/2 + x(n-2)/4.

$$3+(2+2)+5+3$$

- 10. a) Find out inverse z-transform of $X(z) = \log(1 0.5z^1)$; |z| > 0 5 using differential property.
 - b) Determine whether the system is (i) causal, (ii) stable.
 - i) $h(n) = 2^n u(-n)$
 - ii) $h(n) = 8(n) + \sin nn.$

4 + 4

c) Define discrete Fourier series.

2

CS/BTECH/EE/EVEN/SEM-6/EE-605A/2015-16

- 1. a) State and prove the time shifting property and differentiation property of z-transform.
 - b) Find the z-transform and ROC of the sequence $x(n) = -(0.8)^n u(-n-1) (1.3)^n u(-n-1).$

4 + 4 + 7

- 12. Write short notes on any three of the following: 3×5
 - a) Radix-2 DIF algorithm
 - Mapping of s-plane into z-plane
 - c) BIBO stability
 - d) Causal and non-causal systems
 - e) TMS320C 6713 architecture
 - Odd & Even signal.