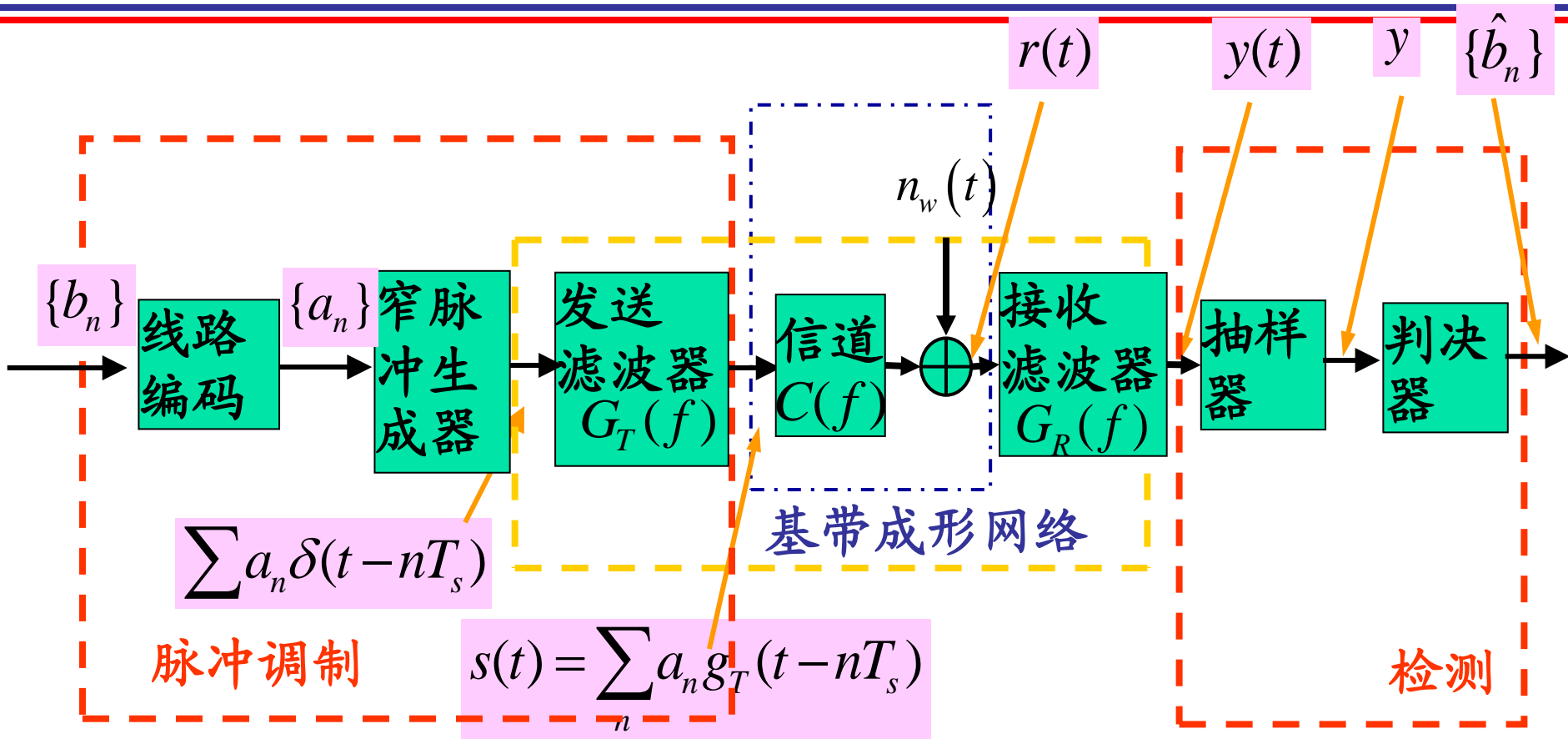


第15讲 二进制频带传输

数字基带传输系统



$$g(t) = g_T(t) * c(t) \xleftrightarrow{F.T.} G(f) = G_T(f) C(f)$$

$$h(t) = g(t) * g_R(t) \xleftrightarrow{F.T.} H(f) = G_T(f) C(f) G_R(f)$$

问题的引入

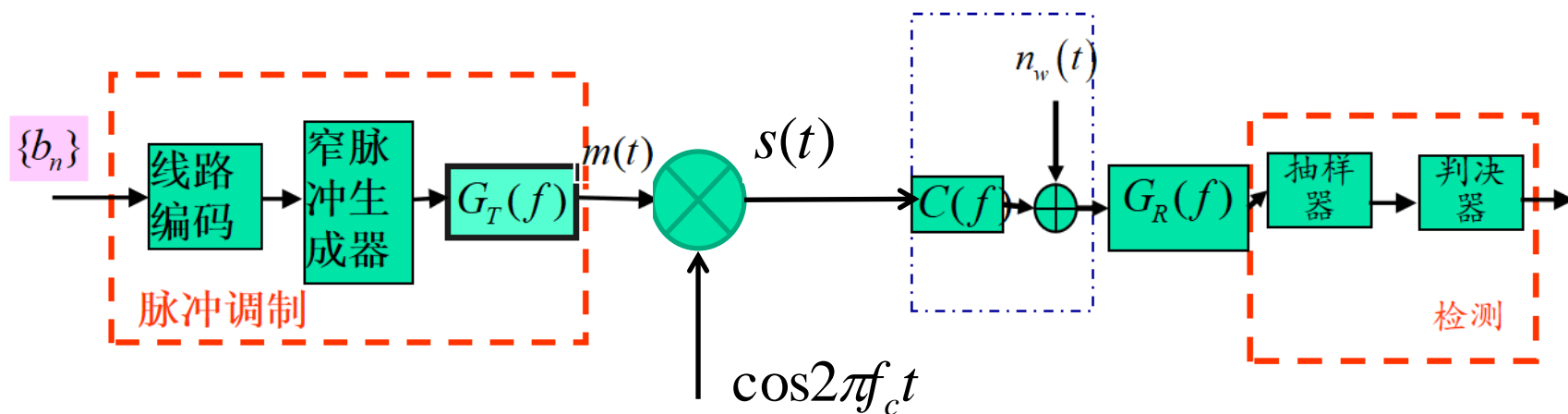
■ 模拟调制系统

- ✿ 调制原理与调制器模型
- ✿ 频谱分析
- ✿ 解调原理与解调器模型
- ✿ 抗噪声性能分析

■ 数字基带传输系统

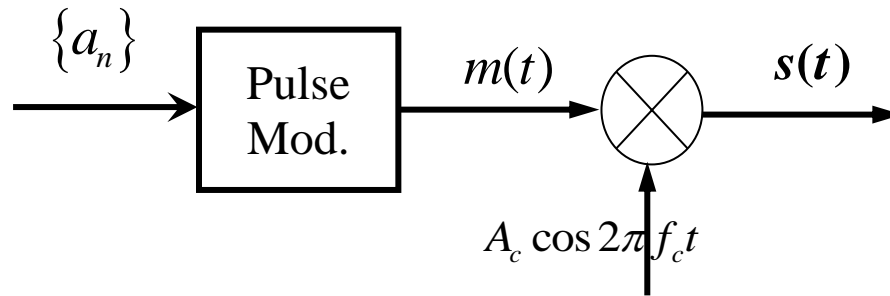
- ✿ 脉冲调制原理与脉冲调制器设计（线路编码、发送滤波器）
- ✿ 信号功率谱密度分析
- ✿ 检测原理与检测器模型
- ✿ 误码性能分析
- ✿ 频带无限与频带有限信号

数字频带传输系统

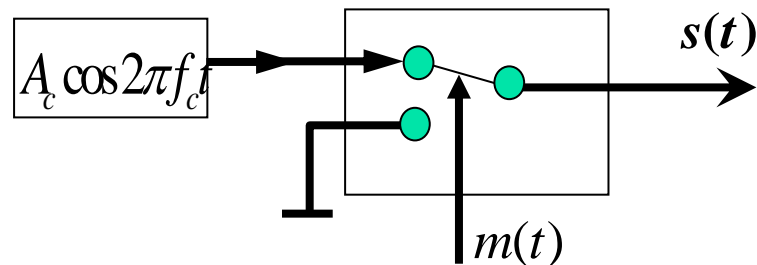


1、2ASK

1.1 两种2ASK调制器



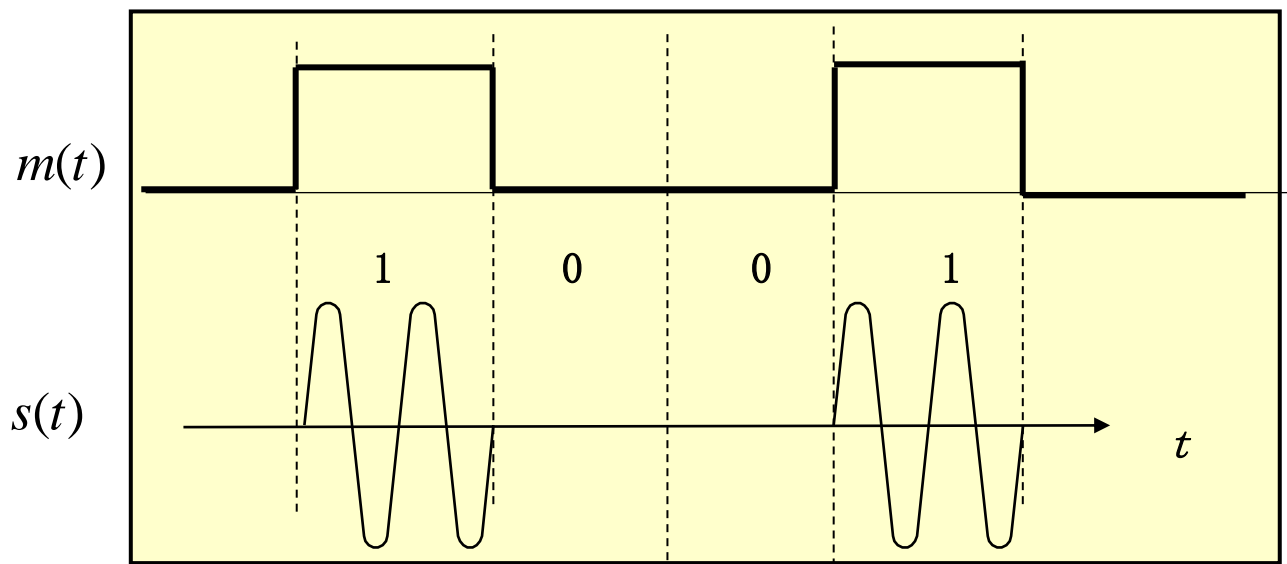
(a) DSB-SC Modulator



(b) Keying Modulator

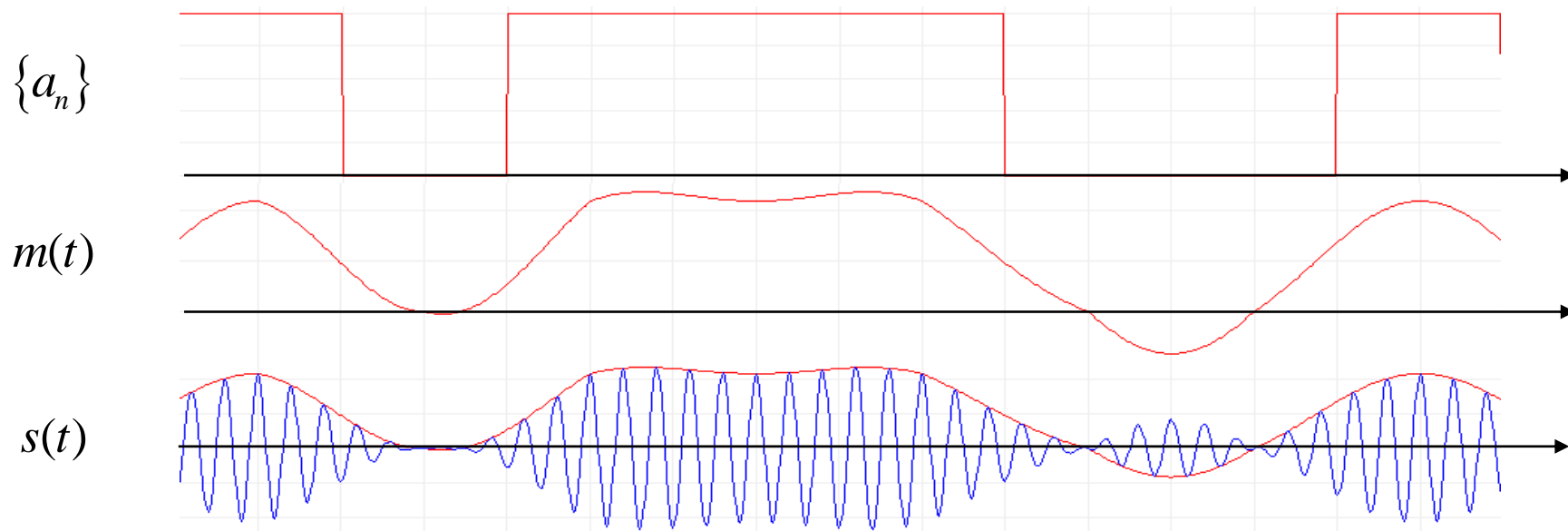
1.2 两种2ASK波形

(1) 无限带宽2ASK信号 (基带脉冲为方波)



1.2 两种2ASK波形

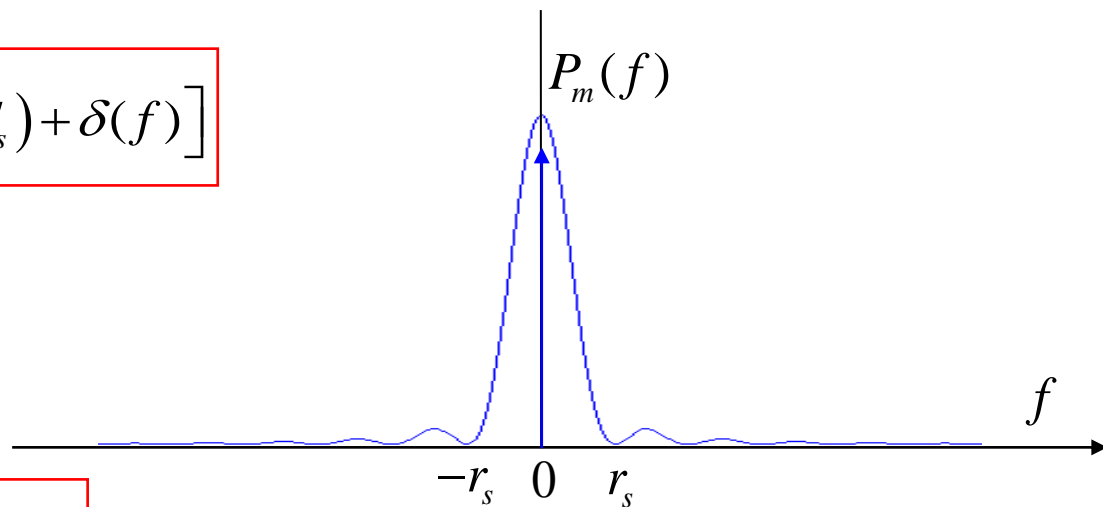
(2) 有限带宽2ASK信号 (基带脉冲为根升余弦波形)



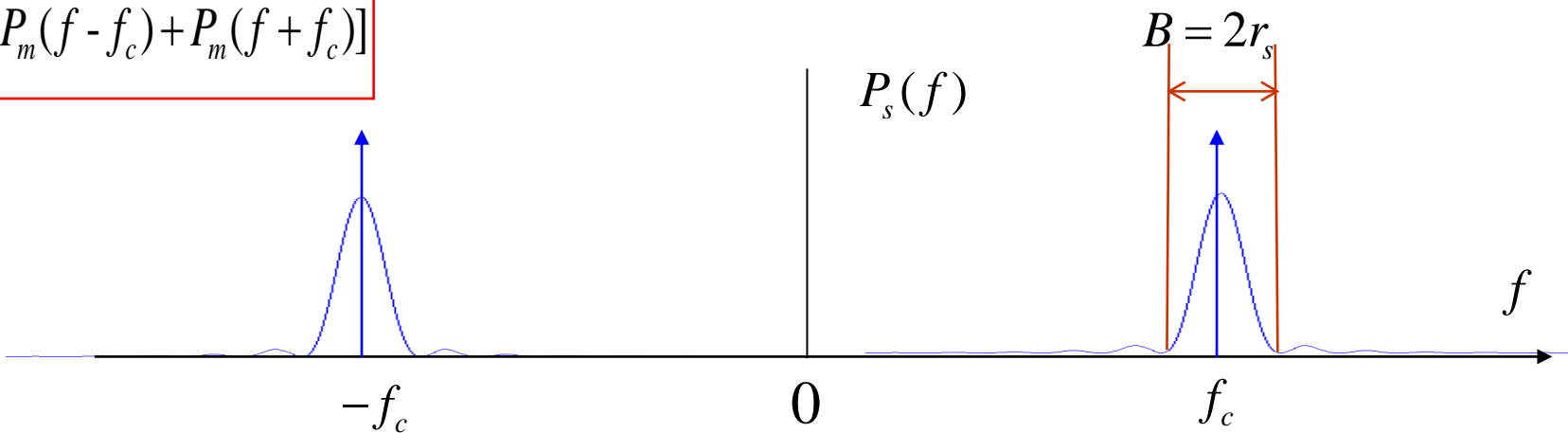
1.2 2ASK信号功率谱密度

(1) 无限带宽2ASK信号功率谱密度

$$P_m(f) = \frac{A_c^2}{2} [T_s \text{Sa}^2(\pi f T_s) + \delta(f)]$$



$$P_s(f) = \frac{1}{4} [P_m(f - f_c) + P_m(f + f_c)]$$



1.2 2ASK信号功率谱密度

(2) 带限2ASK信号功率谱密度

$$P_m(f) = \frac{1}{4T_s} |G_T(f)|^2 + \frac{1}{4T_s^2} |G_T(0)|^2 \delta(f)$$

$$|G_T(f)|^2 = |H_{RC}(f)|$$

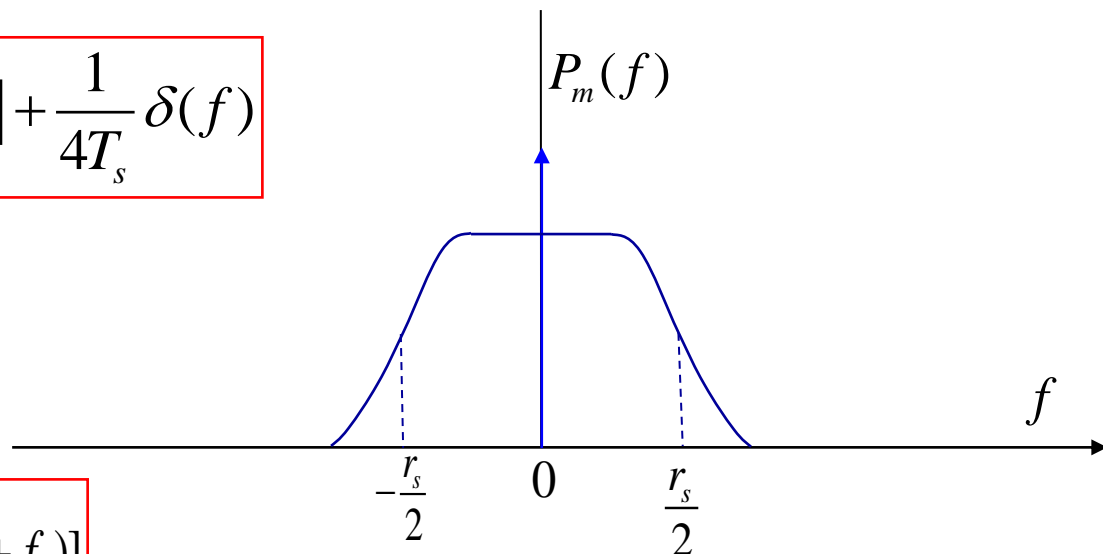
$$P_m(f) = \frac{1}{4T_s} |H_{RC}(f)| + \frac{1}{4T_s^2} |H_{RC}(0)| \delta(f) = \frac{1}{4T_s} |H_{RC}(f)| + \frac{1}{4T_s} \delta(f)$$

$$H_{RC}(f) = \begin{cases} T_s, & |f| < \frac{1}{2T_s} (1 - \alpha) \\ \frac{T_s}{2} \{1 - \sin[\frac{T_s}{\alpha} (f - \frac{1}{2T_s})]\}, & \frac{1}{2T_s} (1 - \alpha) \leq |f| \leq \frac{1}{2T_s} (1 + \alpha) \\ 0, & |f| > \frac{1}{2T_s} (1 + \alpha) \end{cases}$$

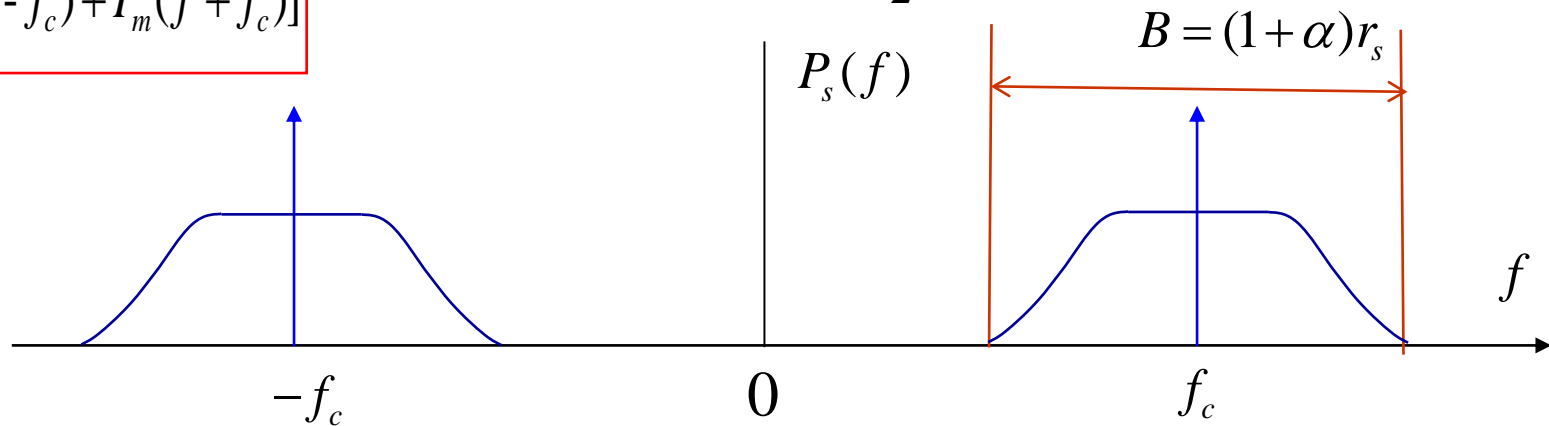
1.2 2ASK信号功率谱密度

(2) 带限2ASK信号功率谱密度

$$P_m(f) = \frac{1}{4T_s} |H_{RC}(f)| + \frac{1}{4T_s} \delta(f)$$



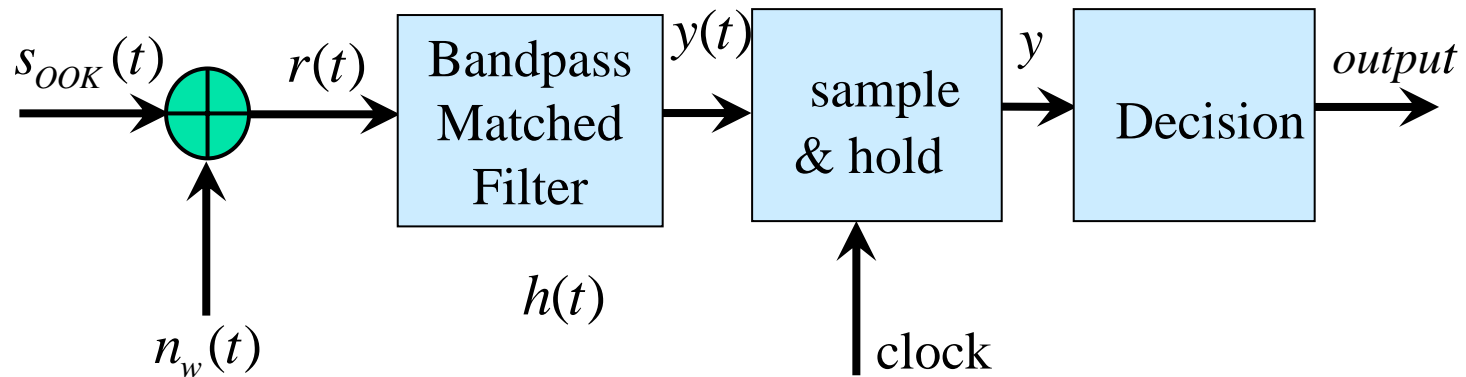
$$P_s(f) = \frac{1}{4} [P_m(f - f_c) + P_m(f + f_c)]$$



1.3 2ASK信号的解调

- (1) AWGN信道条件下OOK的最佳接收
- (2) 在理想限带及AWGN信道条件下OOK信号的最佳接收
- (3) OOK信号的非相干解调

(1) AWGN信道条件下OOK的最佳接收(1/4)



$$s(t) = \begin{cases} s_1(t) = A \cos 2\pi f_c t, & \text{"1"} \\ s_2(t) = 0, & \text{"0"} \end{cases}$$

$$h(t) = s_1(T_b - t), 0 \leq t \leq T_b$$

(1) AWGN信道条件下OOK的最佳接收 (2/4)

$$h(t) = s_1(t) = A \cos 2\pi f_c t \operatorname{Rect}\left(\frac{t}{T_b}\right)$$

$$\begin{aligned} H(f) &= AT_b \operatorname{Sa}(\pi f T_b) * \frac{1}{2} [\delta(f - f_c) + \delta(f + f_c)] \\ &= \frac{AT_b}{2} \{ \operatorname{Sa}[\pi T_b(f - f_c)] + \operatorname{Sa}[\pi T_b(f + f_c)] \} \end{aligned}$$

$$y(t) = r(t) * h(t) = \int_0^t r(\tau) h(t - \tau) d\tau$$

$$= \int_0^t r(\tau) s_1(T_b - t + \tau) d\tau = \int_0^t [s_1(\tau) + n_w(\tau)] s_1(T_b - t + \tau) d\tau$$

$$y \equiv y(T) = \int_0^{T_b} [s_1(\tau) + n_w(\tau)] s_1(\tau) d\tau = \int_0^{T_b} s_1^2(\tau) d\tau + \int_0^{T_b} s_1(\tau) n_w(\tau) d\tau = E_1 + Z$$

$$E_1 = \int_0^{T_b} s_1^2(\tau) d\tau = \frac{A^2}{2} T_b \quad E(Z | s_1) = 0 \quad D(Z | s_1) = \frac{N_0}{2} E_1$$

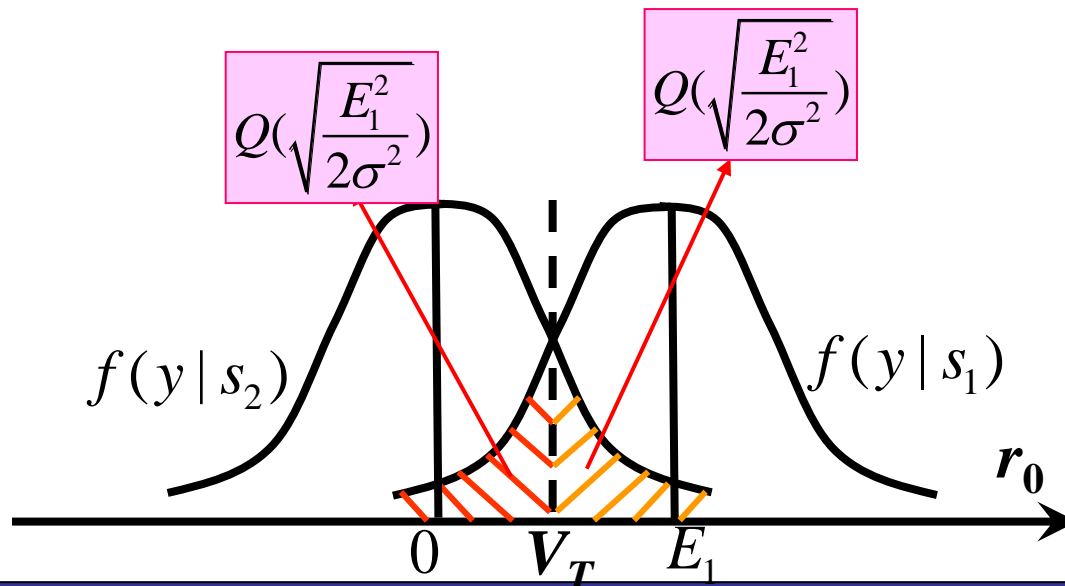
(1) AWGN信道条件下OOK的最佳接收(3/4)

$$p(y|s_1) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{(y-E_1)^2}{2\sigma^2}\right] \Rightarrow P_{e1} = Q\left(\sqrt{\frac{E_1^2}{4\sigma^2}}\right) = Q\left(\sqrt{\frac{E_1^2}{2E_1N_0}}\right) = Q\left(\sqrt{\frac{E_1}{2N_0}}\right)$$

发 “0” $\rightarrow s_2(t)$ $y \equiv y(T) = \int_0^T [s_2(\tau) + n_w(\tau)] s_1(\tau) d\tau = Z$

$$p(y|s_2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{y^2}{2\sigma^2}\right] \Rightarrow P_{e2} = Q\left(\sqrt{\frac{E_1^2}{4\sigma^2}}\right) = Q\left(\sqrt{\frac{E_1^2}{2E_1N_0}}\right) = Q\left(\sqrt{\frac{E_1}{2N_0}}\right)$$

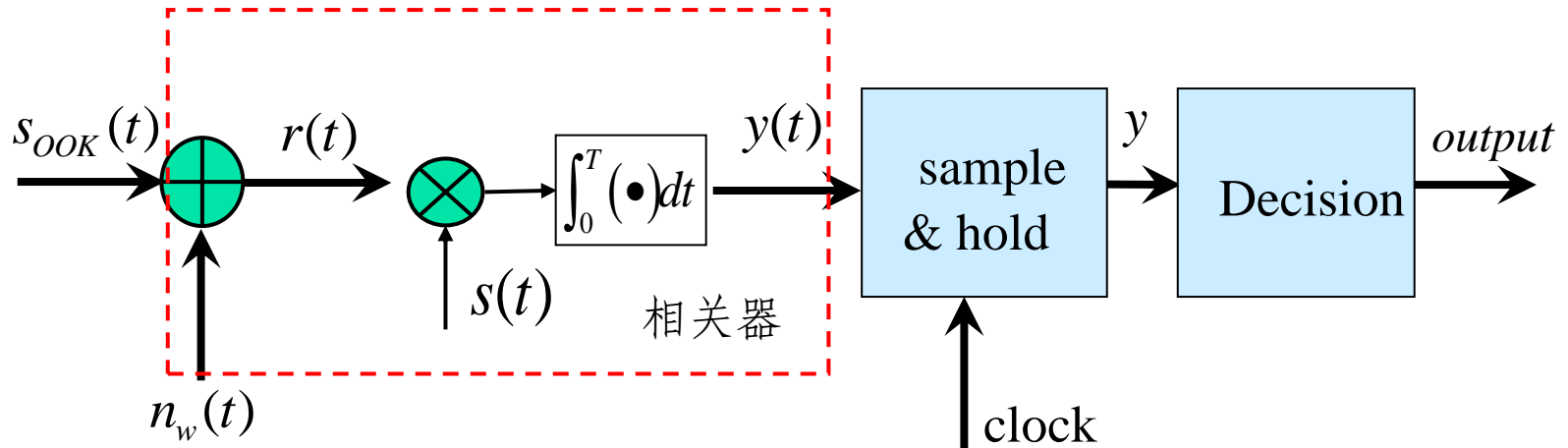
$$E_b = \frac{E_1}{2} = \frac{A^2}{4} T_b$$



$$P_b = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

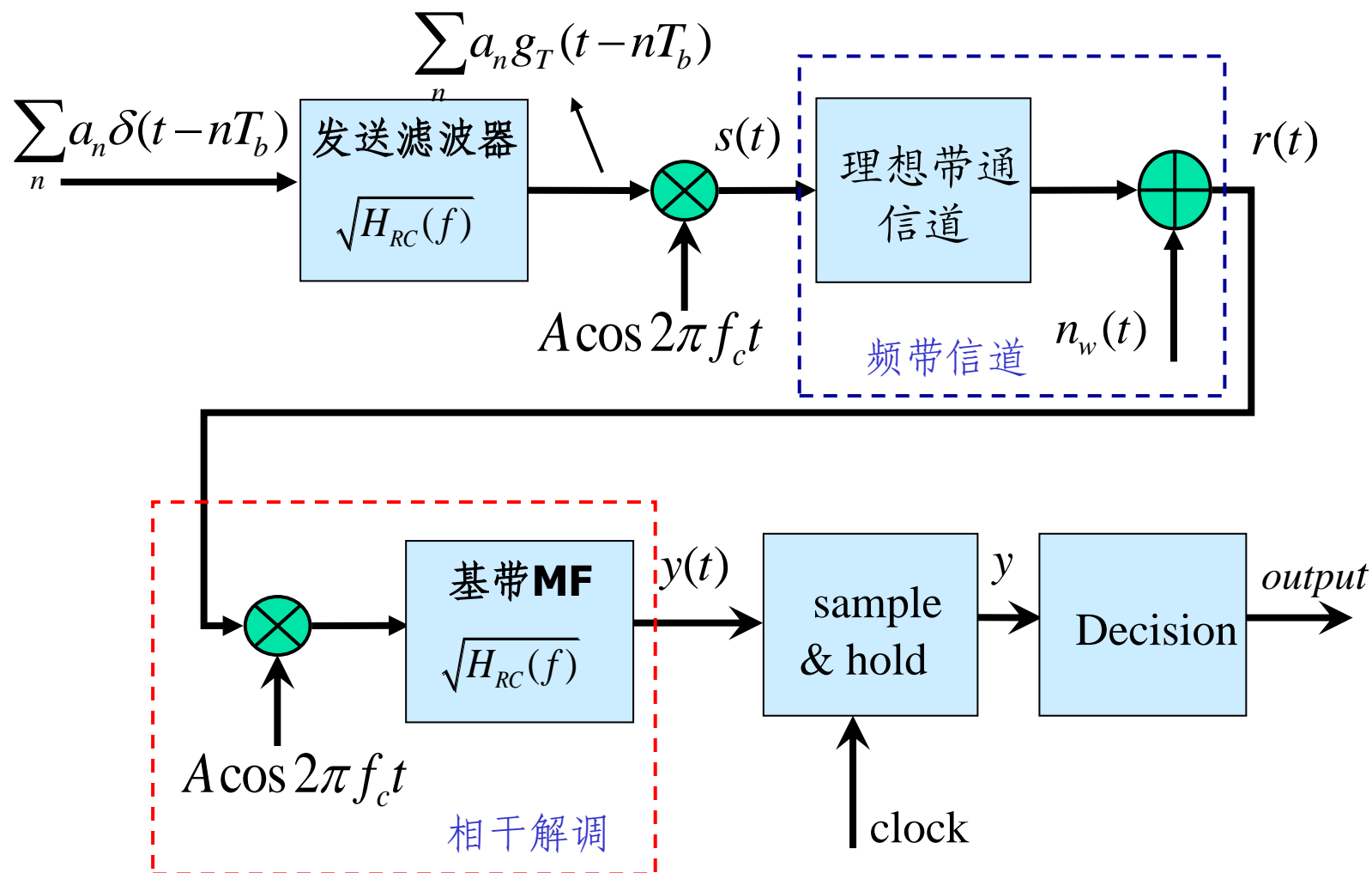
(1) AWGN信道条件下OOK的最佳接收(4/4)

匹配滤波器等效形式：相关接收机(Correlator)



$$y(t) = \int_0^{T_b} [s(t) + n_w(t)] s_1(t) dt$$

(2) 理想限带及AWGN信道OOK信号最佳接收 (1/2)



(2)理想限带及AWGN信道OOK信号最佳接收(2/2)

$$s(t) = \begin{cases} s_1(t) = Ag_T(t) \cos 2\pi f_c t, & "1" \\ s_2(t) = 0, & "0" \end{cases} \quad y = \begin{cases} E_1 + Z, & "1" \\ Z, & "0" \end{cases}$$

$$h(t) = s_1(t_0 - t) = s_1(t)$$

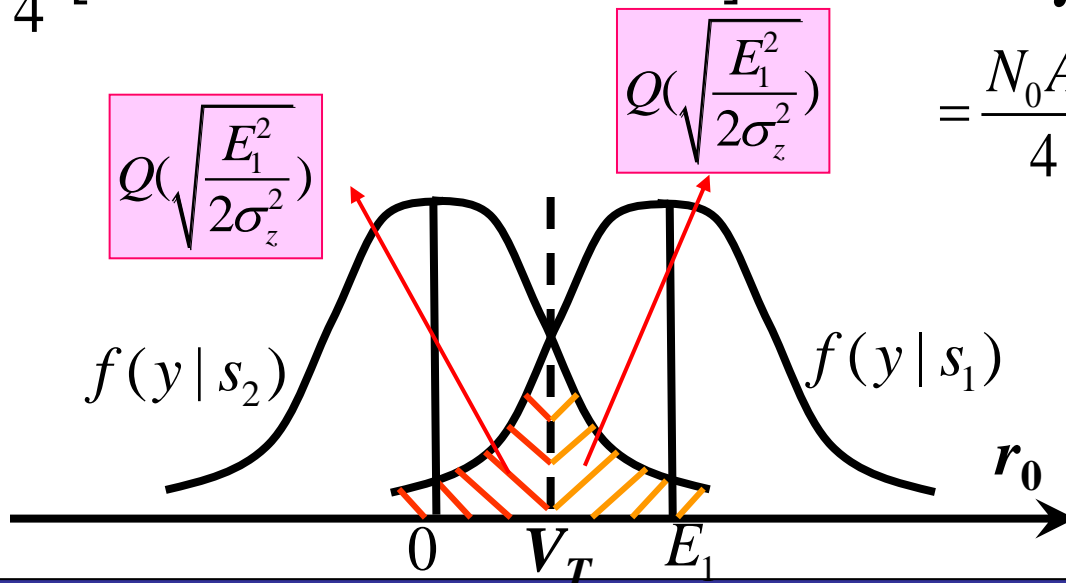
$$E_1 = \int_{-\infty}^{\infty} s_1^2(\tau) d\tau = \frac{A^2}{2} \int_{-\infty}^{\infty} g_T^2(\tau) d\tau = \frac{A^2}{2} \int_{-\infty}^{\infty} |G_T(f)|^2 df = \frac{A^2}{2} \int_{-\infty}^{\infty} |H_{RC}(f)| df$$

$$P_Z(f) = \frac{A^2}{4} [H_{RC}(f - f_c) + H_{RC}(f + f_c)]$$

$$\sigma_Z^2 = \int_{-\infty}^{\infty} P_z(f) df$$

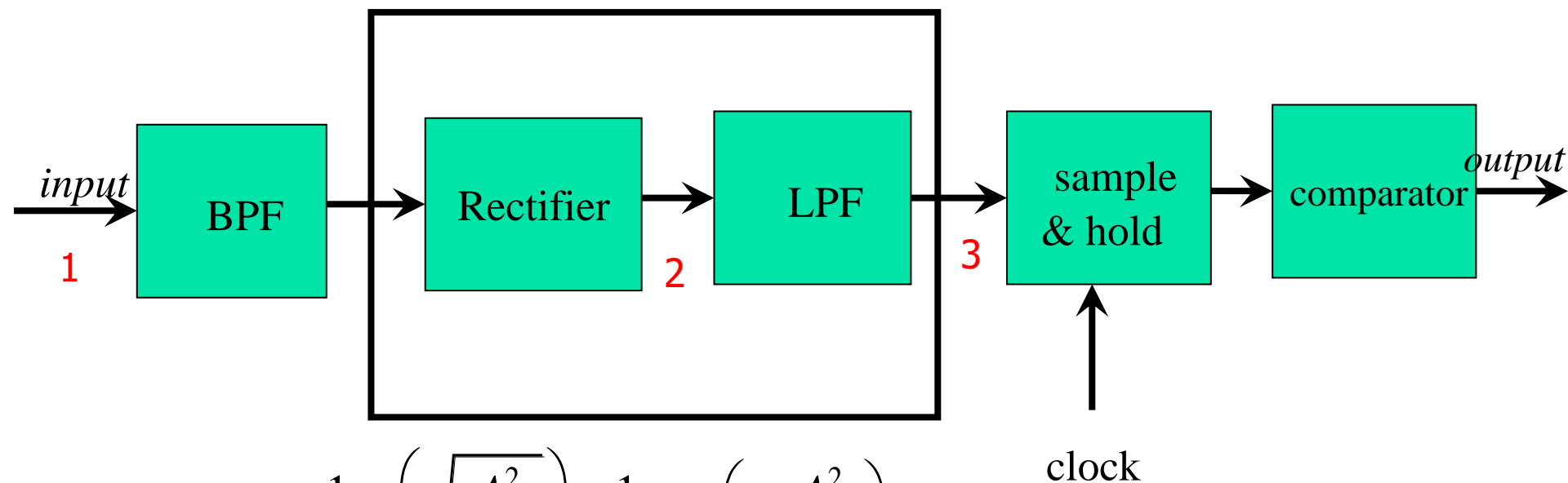
$$= \frac{N_0 A^2}{4} \int_{-\infty}^{\infty} |H_{RC}(f)| df = \frac{N_0 E_1}{2}$$

$$E_b = \frac{E_1}{2}$$



$$P_b = Q\left(\sqrt{\frac{E_b}{N_0}}\right)$$

(3) OOK信号的非相干解调



$$P_b \approx \frac{1}{2} Q\left(\sqrt{\frac{A^2}{4\sigma^2}}\right) + \frac{1}{2} \exp\left(-\frac{A^2}{8\sigma^2}\right)$$

$$P_b \approx \frac{1}{2} \exp\left(-\frac{A^2 T_b}{4} \frac{r_b}{2N_0 B}\right) = \frac{1}{2} \exp\left(-\frac{E_b}{2N_0} \cdot \frac{r_b}{B}\right)$$

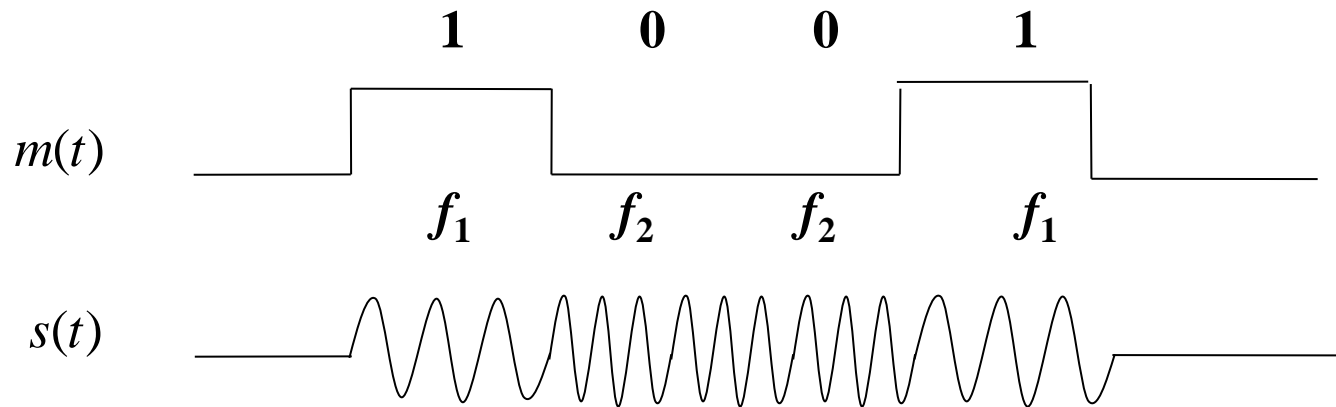
某2ASK传输系统，若符号传输速率为10kHz，则下列说法中正确的是

- ☒ A 该2ASK信号的最小带宽为10kHz
- ☐ B 该2ASK信号的最小带宽为20kHz
- ☐ C 若基带信号采用不归零方波，则该2ASK信号第一过零点带宽为10kHz
- ☒ D 若基带信号采用不归零方波，则该2ASK信号第一过零点带宽为20kHz

提交

2、2FSK

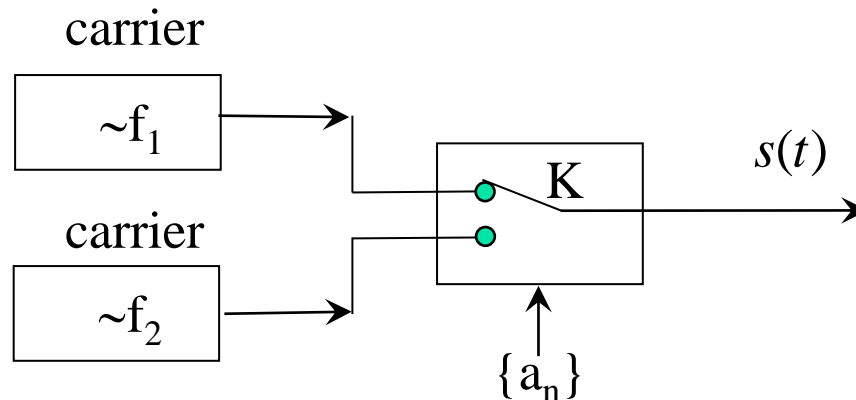
2.1 2FSK信号与两种调制器



$$s(t) = \begin{cases} A_c \cos(2\pi f_1 t + \varphi_1) & \text{'1'} \\ A_c \cos(2\pi f_2 t + \varphi_2) & \text{'0'} \end{cases} \quad 0 \leq t \leq T_b$$

2.1 2FSK信号与两种调制器

(1) 相位不连续2FSK信号

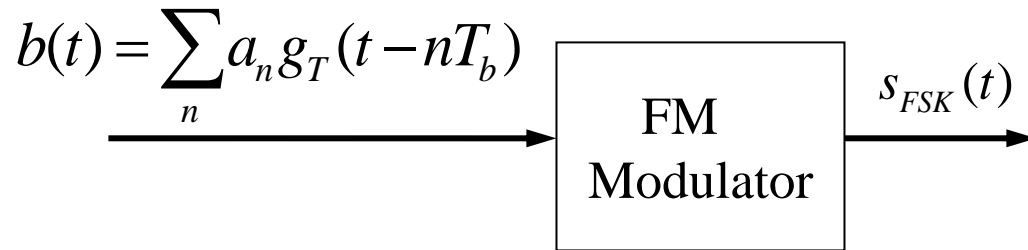


(a) FSK modulator with discontinuous phase

$$s_{FSK}(t) = \begin{cases} s_1(t) = A \cos 2\pi f_1 t, "1" \\ s_2(t) = A \cos 2\pi f_2 t, "0" \end{cases} \quad 0 \leq t \leq T_b$$

FSK modulator

(2) 相位连续2FSK信号



(b) FSK modulator with continuous phase

$$s_{FSK}(t) = A \cos \left[2\pi f_c t + 2\pi K_f \int_{-\infty}^t b(\tau) d\tau \right] = \text{Re} \left[v(t) e^{j2\pi f_c t} \right]$$

$$v(t) = A e^{j\theta(t)}$$

$$\theta(t) = 2\pi K_f \int_{-\infty}^t b(\tau) d\tau$$

2.2 2FSK信号之间的相关性

$$\rho_{12} = \frac{1}{E_b} \int_0^{T_b} s_1(t)s_2(t)dt \quad E_b = \frac{A^2}{2} T_b$$

$$s_{FSK}(t) = \begin{cases} s_1(t) = A \cos 2\pi(f_c + \Delta f)t, "1" \\ s_2(t) = A \cos 2\pi(f_c - \Delta f)t, "0" \end{cases} \quad 0 \leq t \leq T_b$$

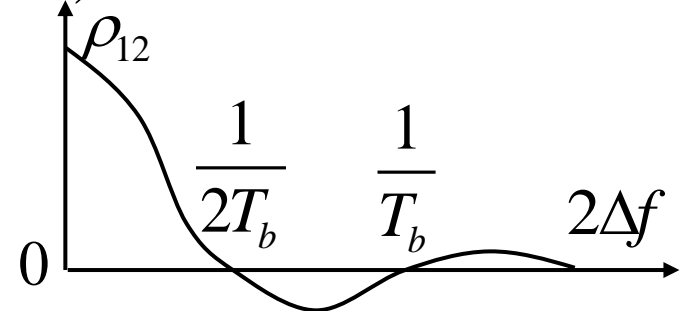
$$\rho_{12} = \frac{A^2}{E_b} \int_0^{T_b} [\cos 2\pi(f_c + \Delta f)t \times \cos 2\pi(f_c - \Delta f)t] dt$$

$$\rho_{12} = \frac{1}{T_b} \int_0^{T_b} [\cos 2\pi \cdot 2\Delta f \cdot t + \cos 2\pi \cdot 2f_c \cdot t] dt$$

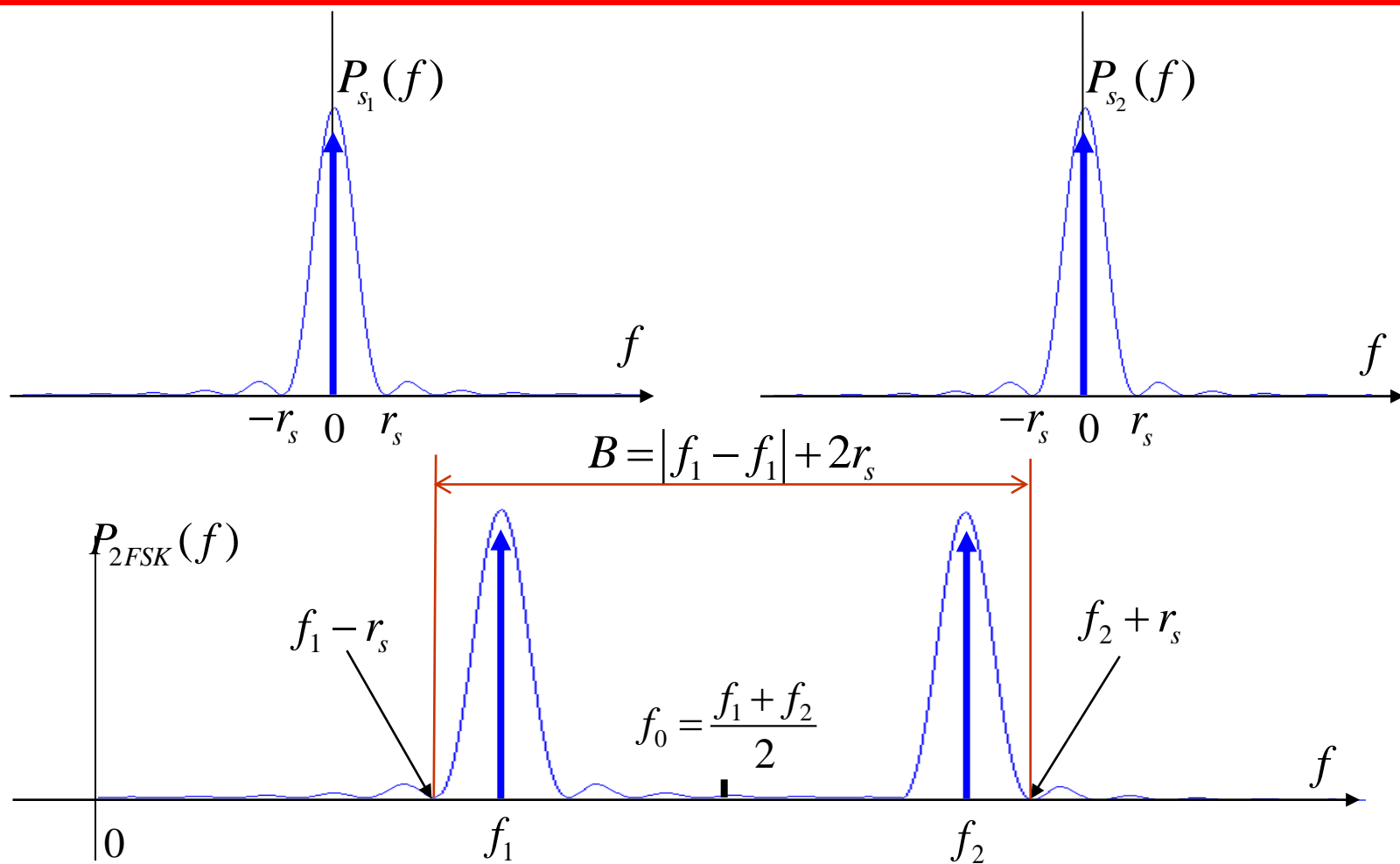
$$= \text{Sa}(2\pi \cdot 2\Delta f \cdot T_b) + \text{Sa}(2\pi \cdot 2f_c \cdot T_b)$$

$$\approx \text{Sa}(2\pi \cdot 2\Delta f \cdot T_b)$$

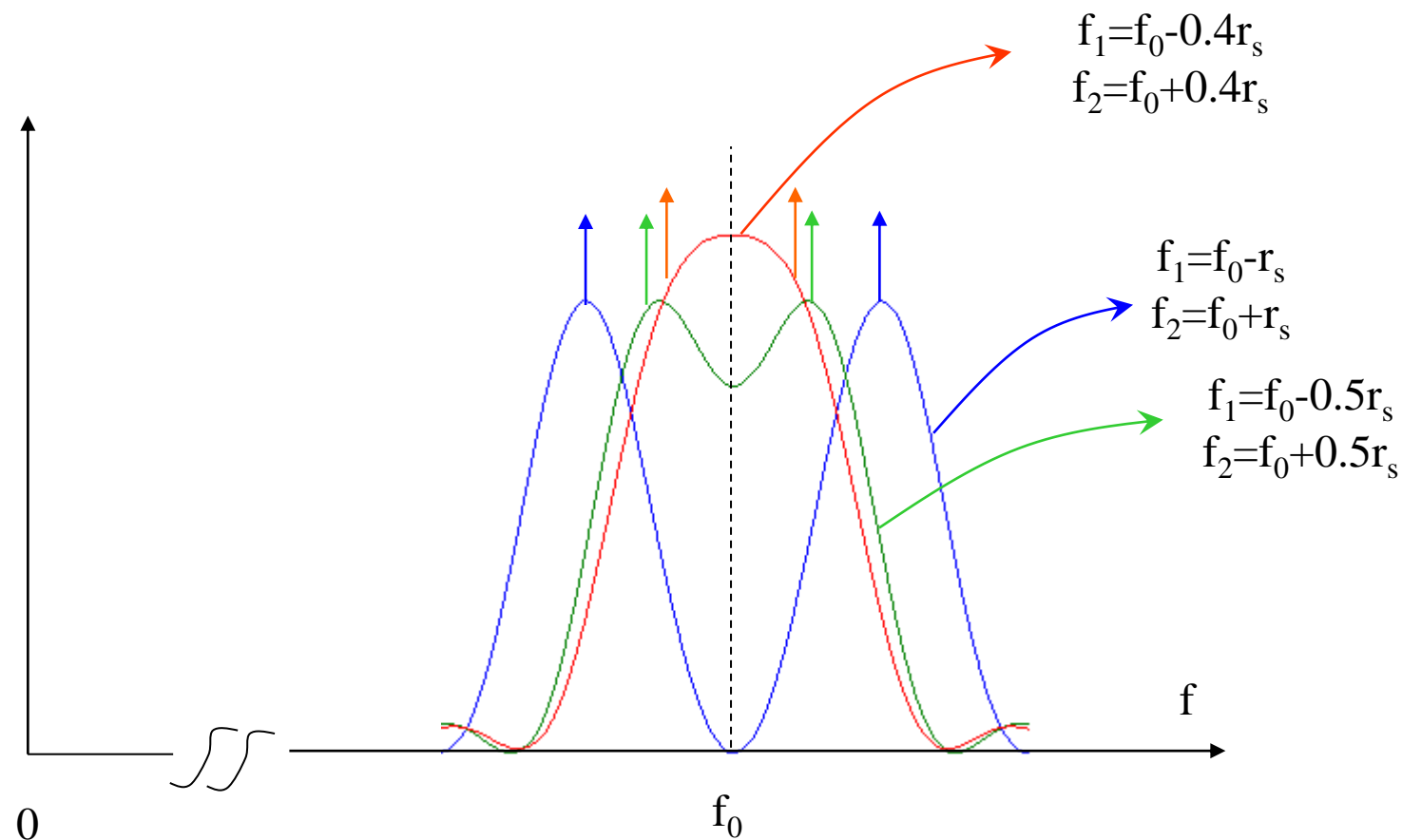
$$2\Delta f = \frac{1}{2T_b}, \text{orthogonal FSK}$$



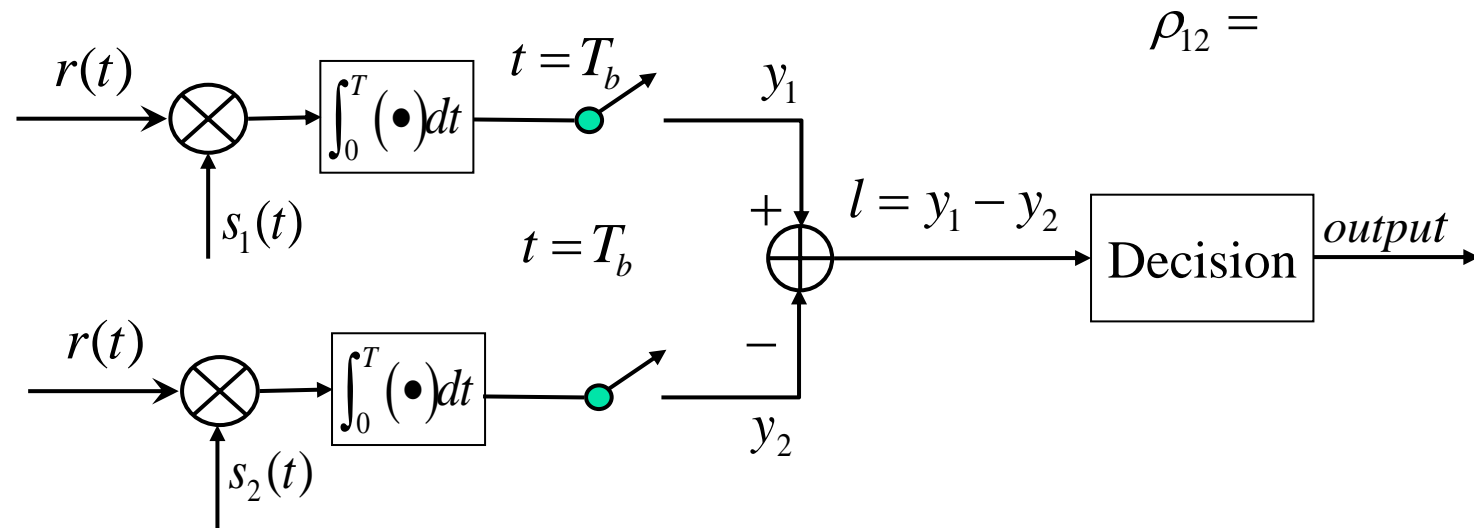
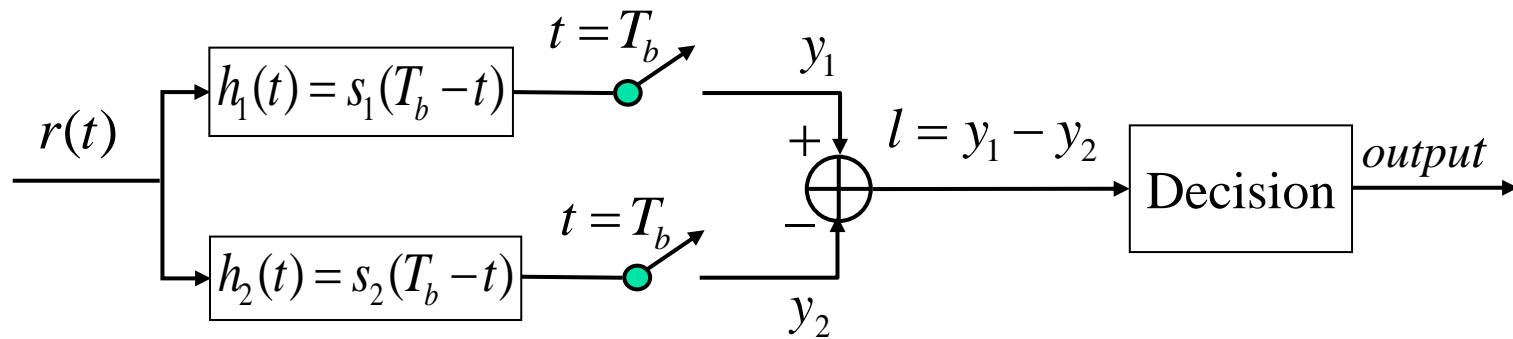
2.3 2FSK信号功率谱密度



$$P_{2FSK}(f) = \frac{1}{4} [P_{s_1}(f - f_1) + P_{s_1}(f + f_1)] + \frac{1}{4} [P_{s_2}(f - f_2) + P_{s_2}(f + f_2)]$$



2.4 AWGN信道正交2FSK最佳接收(1/2)



2.4 AWGN信道正交2FSK最佳接收(2/2)

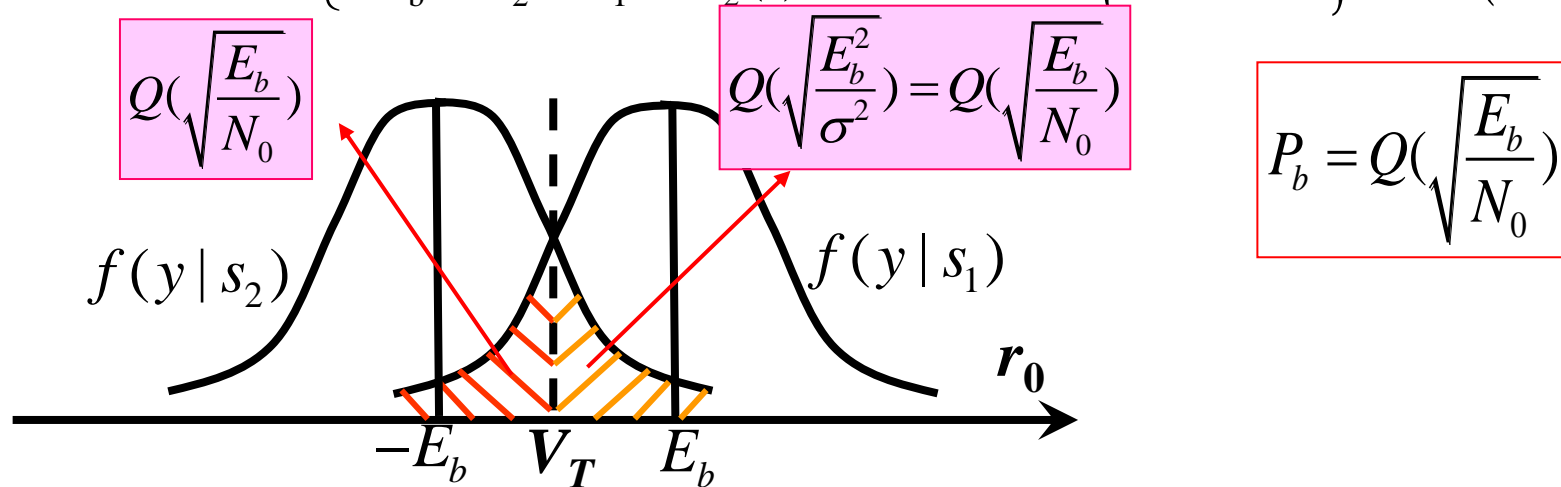
发 $s_1(t)$

$$\begin{aligned} y_1 &= y_1(T_b) = E_b + Z_1 & Z_1 &= \int_0^{T_b} n_w(t) s_1(t) dt \\ y_2 &= y_2(T_b) = Z_2 & Z_2 &= \int_0^{T_b} n_w(t) s_2(t) dt \end{aligned}$$

发 $s_2(t)$

$$\begin{aligned} y_1 &= y_1(T_b) = Z_1 & Z_1 &= \int_0^{T_b} n_w(t) s_1(t) dt \\ y_2 &= y_2(T_b) = E_b + Z_2 & Z_2 &= \int_0^{T_b} n_w(t) s_2(t) dt \end{aligned}$$

$$l = y_1 - y_2 = \begin{cases} E_b + Z_1 - Z_2, & \text{发 } s_1(t) \\ -E_b + Z_2 - Z_1, & \text{发 } s_2(t) \end{cases} \quad \begin{aligned} E(l | s_1) &= E(y_1 | s_1) - E(y_2 | s_2) = E_b \\ D(l | s_1) &= E\{[Z_1 - Z_2]^2\} = 2E(Z_1^2) = N_0 E_b \end{aligned}$$



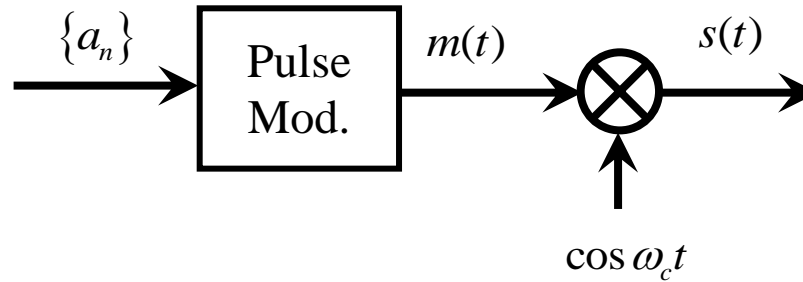
某2FSK传输系统，若符号传输速率为10kHz，载波频率为900kHz和1MHz，若基带波形为方波，则下列说法中正确的是

- ☒ A 信号带宽为无穷大
- ☒ B 信号第一过零点带宽为120kHz
- ☐ C 信号为带限信号
- ☐ D 信号第一过零点带宽为110kHz

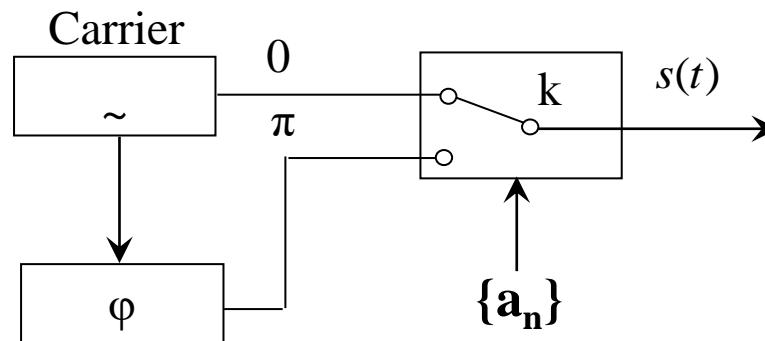
提交

3、2PSK

3.1 两种调制器



(a) DSB-SC modulator



(b) Shifting keying modulator

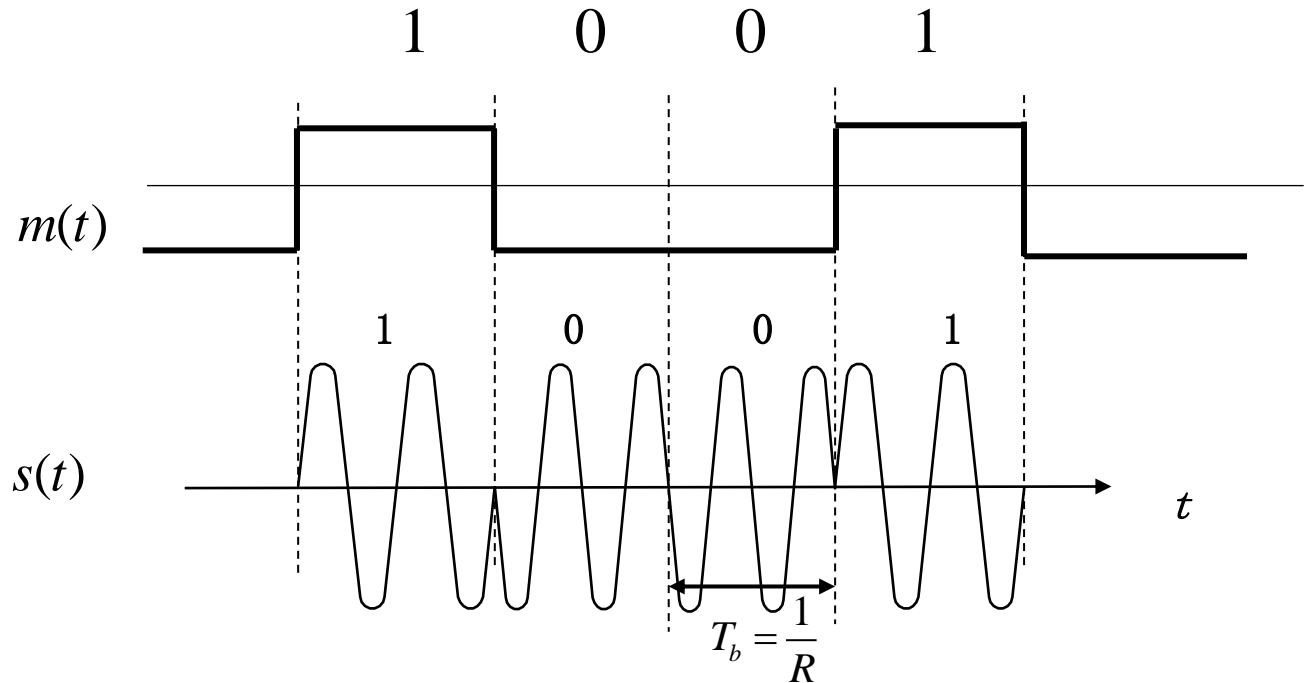
3.2 两种信号波形



BPSK

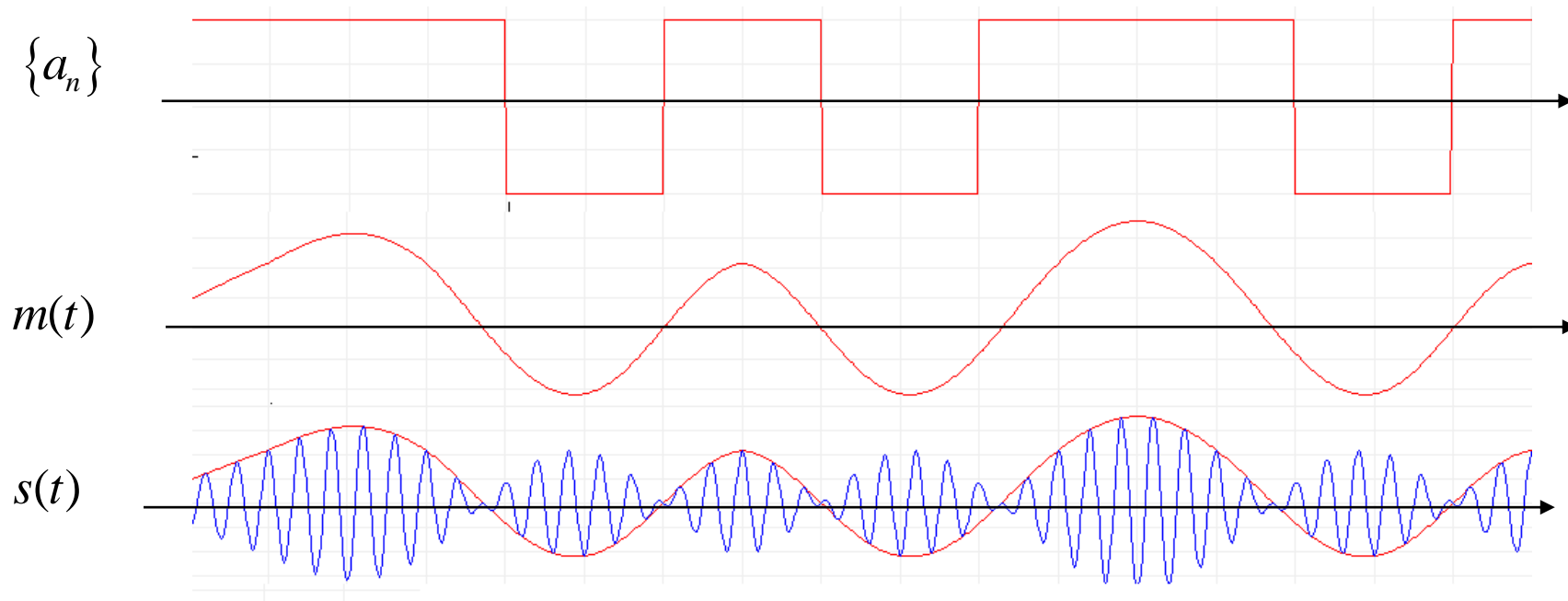
Polar modulation

BPSK signal



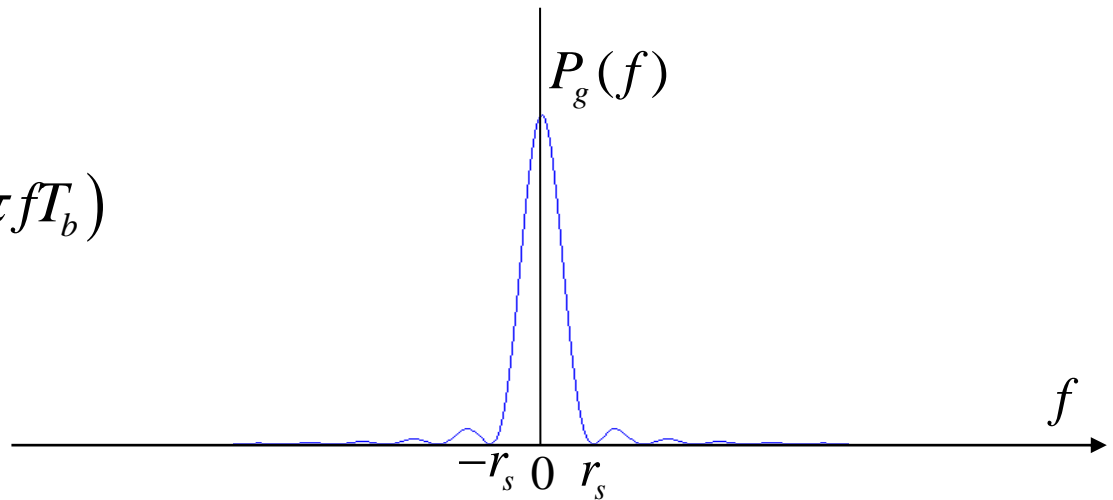
3.2 两种信号波形

DSB-SC with pulse shaping

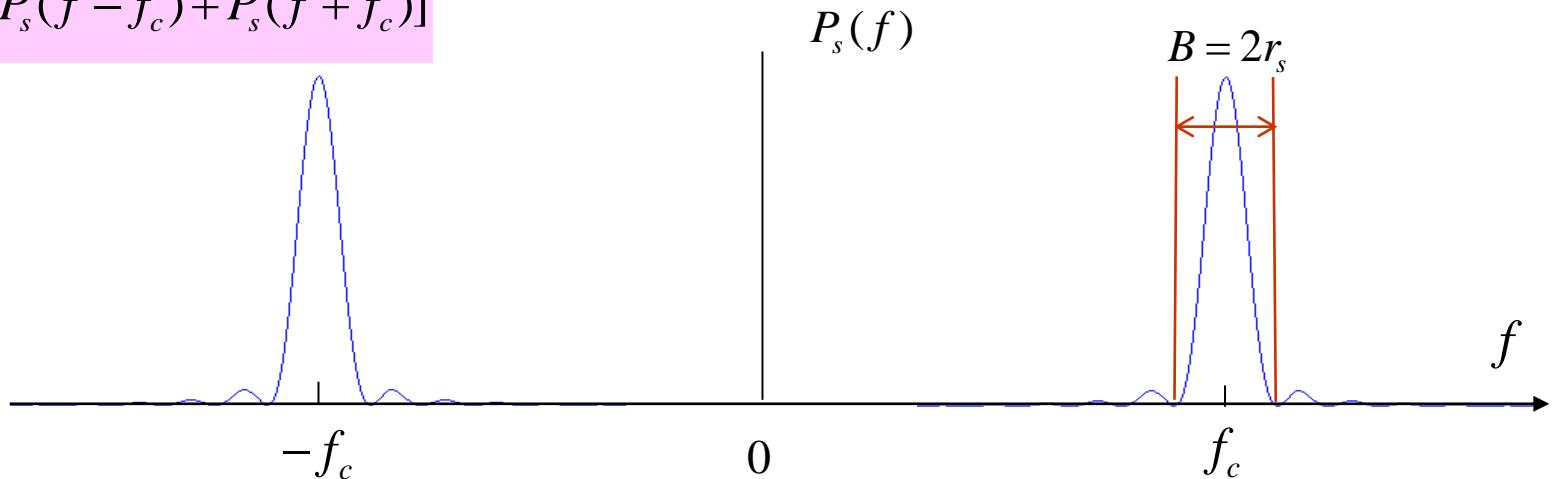


3.3 BPSK信号功率谱密度

$$P_g(f) = A_c^2 T_b S a^2 (\pi f T_b)$$



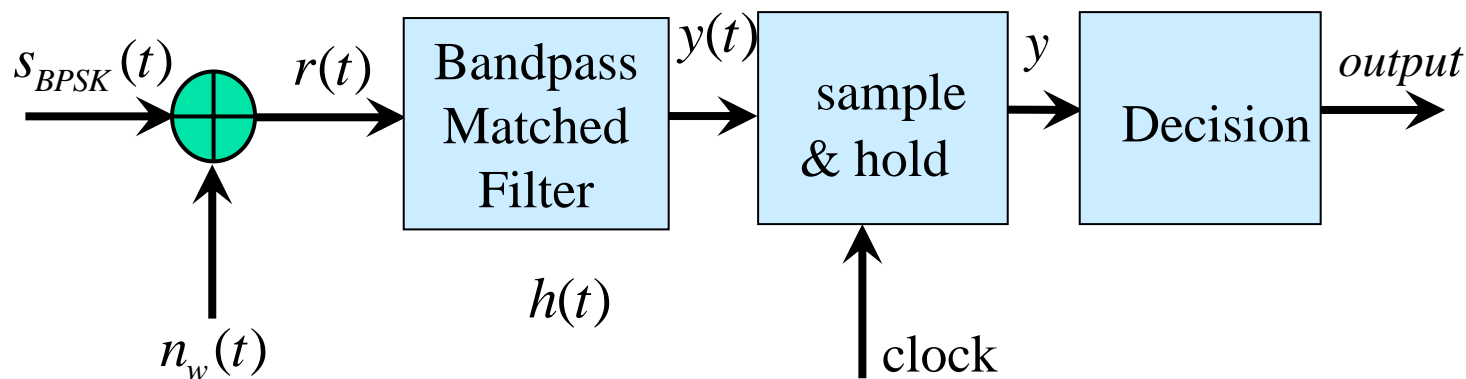
$$P_s(f) = \frac{1}{4} [P_s(f - f_c) + P_s(f + f_c)]$$



3.4 BPSK信号解调

- (1) AWGN信道条件下BPSK的最佳接收
- (2) 在理想限带及AWGN信道条件下BPSK信号的最佳接收

(1) AWGN信道条件下BPSK的最佳接收(1/3)



$$s(t) = \begin{cases} s_1(t) = A \cos 2\pi f_c t, "1" \\ s_2(t) = -A \cos 2\pi f_c t, "0" \end{cases}$$

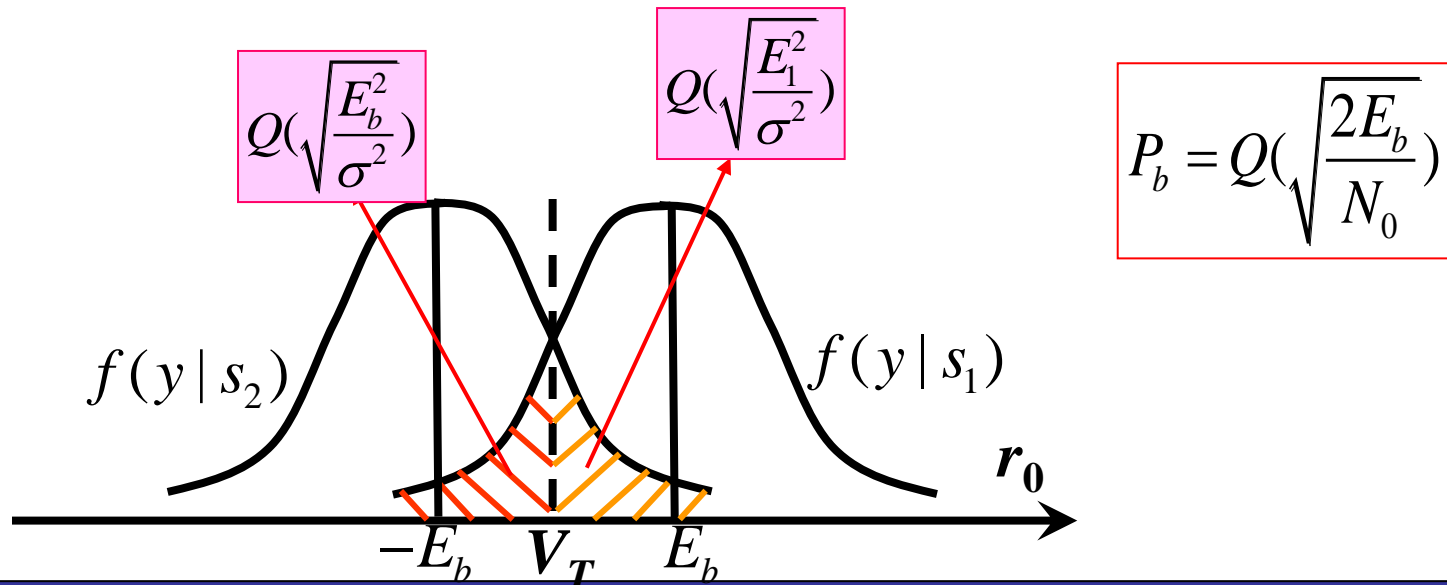
$$h(t) = s_1(T_b - t), 0 \leq t \leq T_b$$

(1)AWGN信道条件下BPSK的最佳接收(2/3)

$$y = \begin{cases} E_b + Z, "1" \\ -E_b + Z, "0" \end{cases} \quad D(Z) = \sigma^2 = \frac{E_b N_0}{2}$$

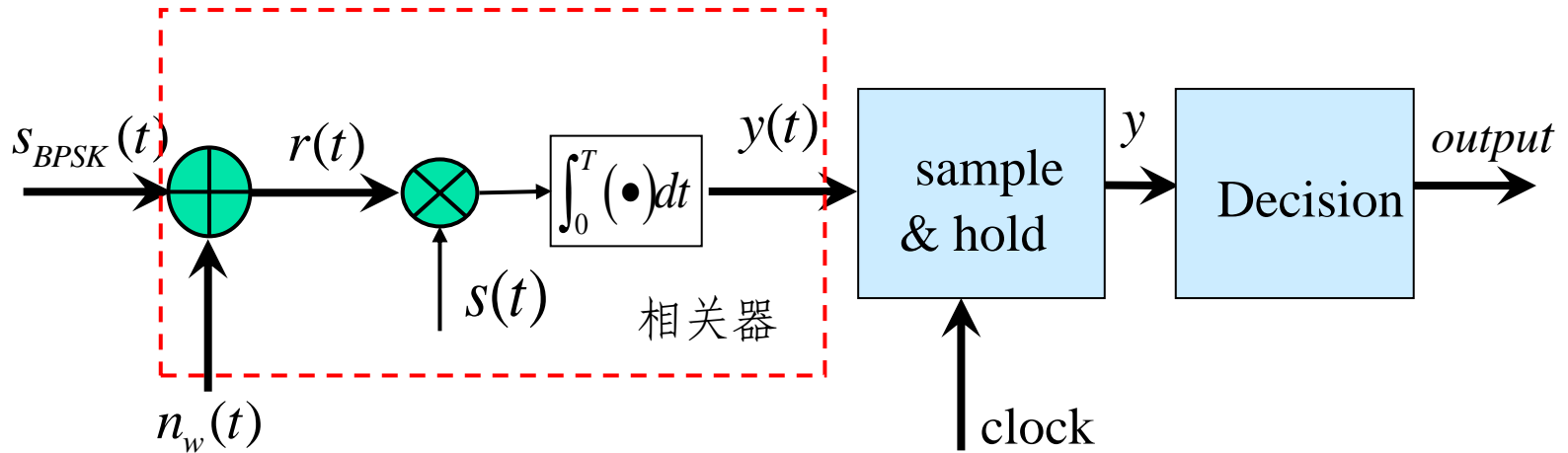
$$p(y|s_1) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{(y-E_b)^2}{\sigma^2}\right] \Rightarrow P_{e1} = Q\left(\sqrt{\frac{E_b^2}{\sigma^2}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

$$p(y|s_2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{(y+E_b)^2}{\sigma^2}\right] \Rightarrow P_{e2} = Q\left(\sqrt{\frac{E_b^2}{\sigma^2}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$



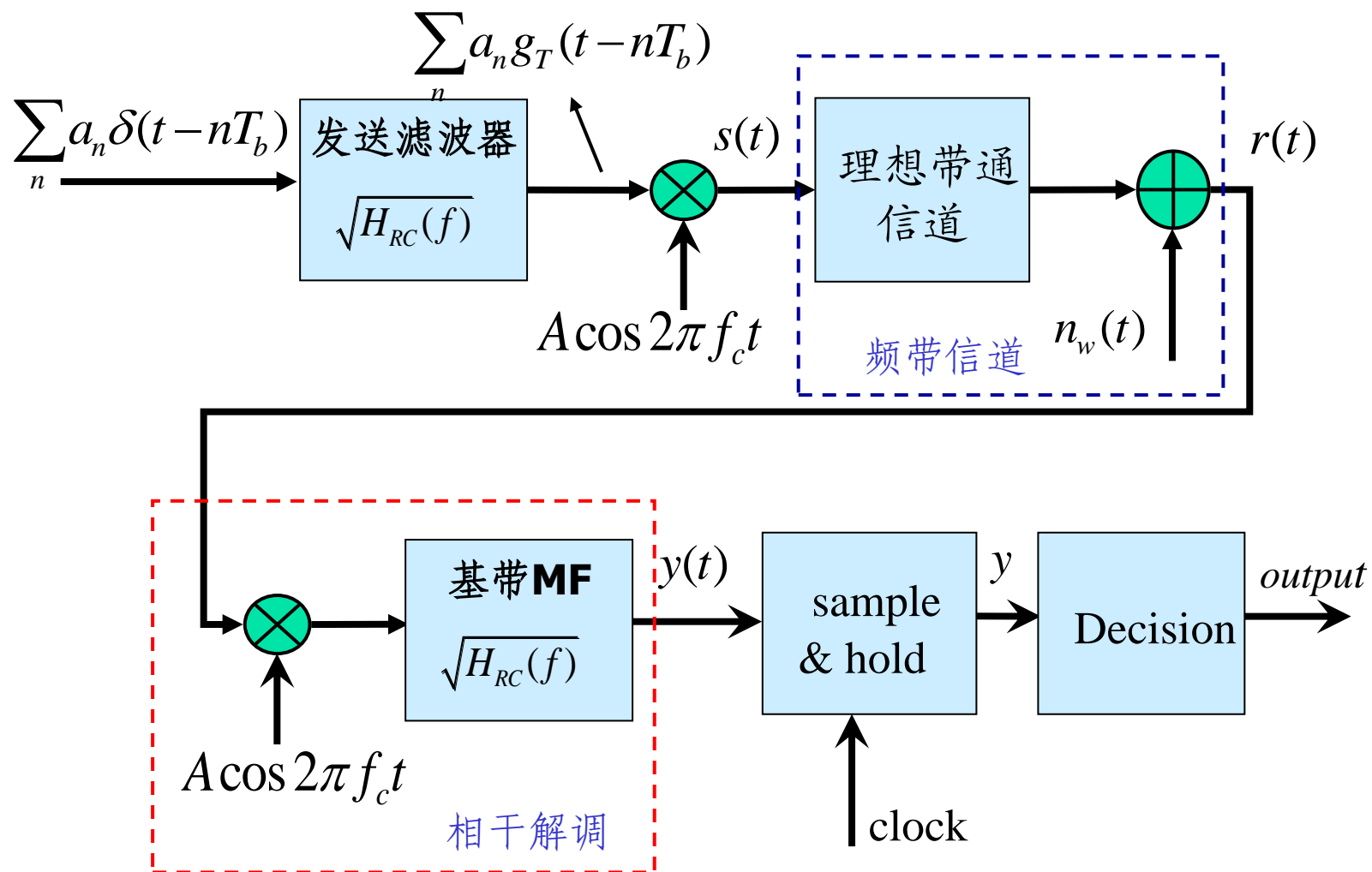
(1)AWGN信道条件下BPSK的最佳接收(3/3)

匹配滤波器等效形式：相关接收机(Correlator)



$$y(t) = \int_0^{T_b} [s(t) + n_w(t)] s_1(t) dt$$

(2)理想限带及AWGN信道BPSK信号最佳接收(1/2)

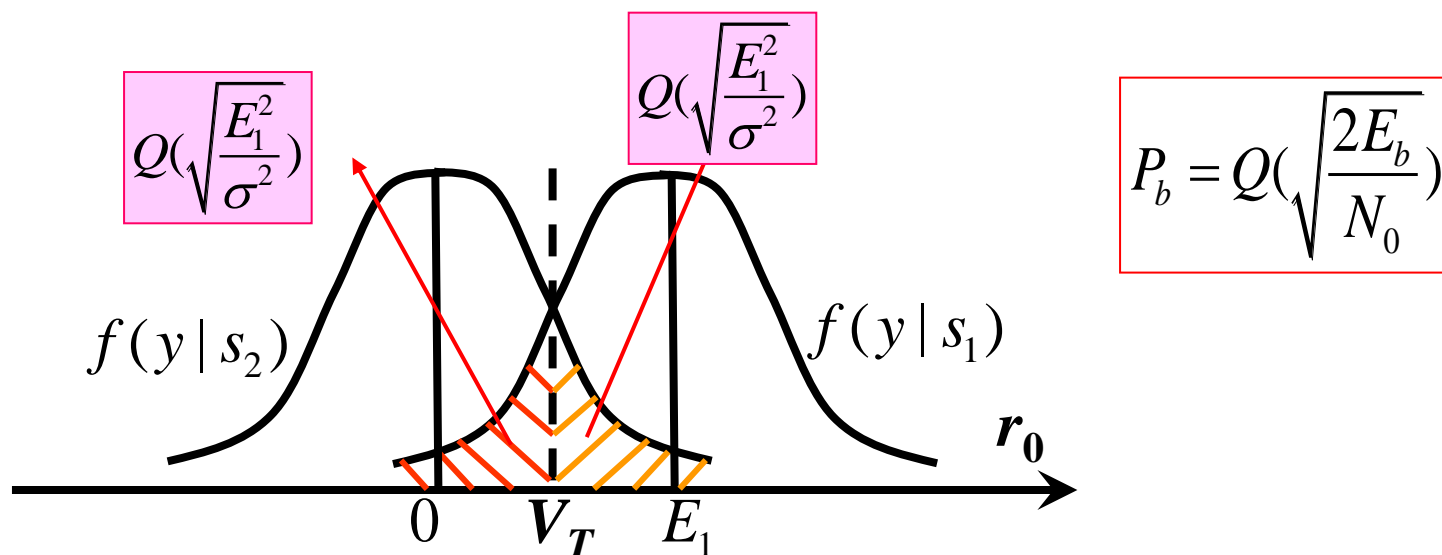


(2)理想限带及AWGN信道BPSK信号最佳接收(2/2)

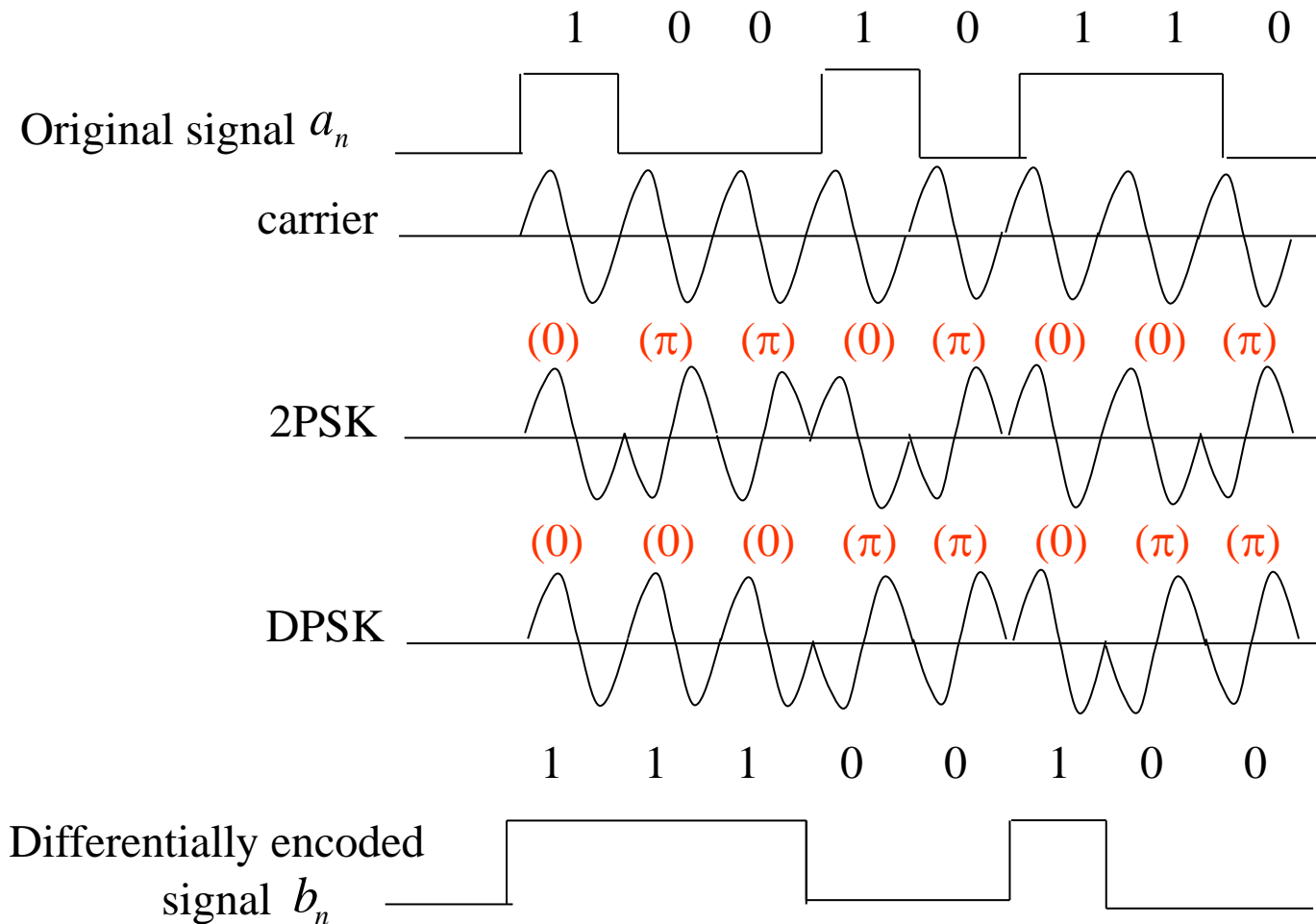
$$s(t) = \begin{cases} s_1(t) = Ag_T(t) \cos 2\pi f_c t, "1" \\ s_2(t) = -Ag_T(t) \cos 2\pi f_c t, "0" \end{cases} \quad y = \begin{cases} E_b + Z, "1" \\ -E_b + Z, "0" \end{cases}$$

$$h(t) = s_1(t_0 - t) = s_1(t), 0 \leq t \leq t_0$$

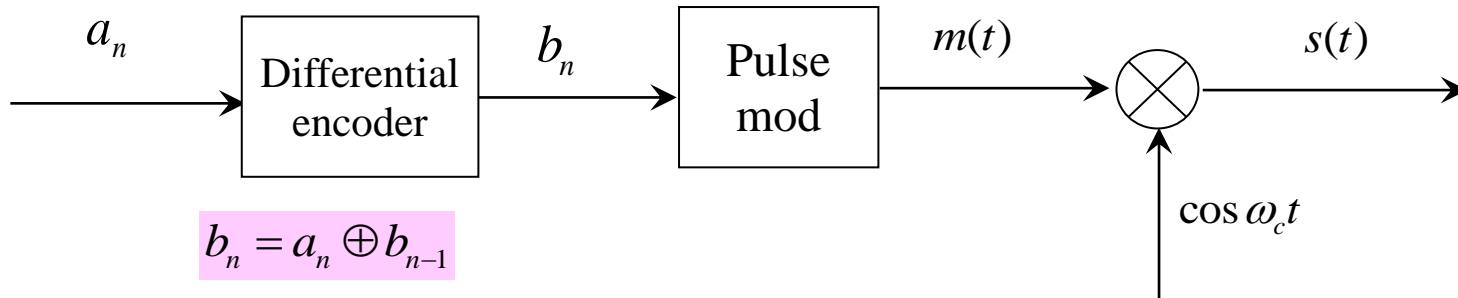
$$E_b = \frac{A^2}{2} \int_{-\infty}^{\infty} |H_{RC}(f)|^2 df \quad D(z) = \sigma^2 = \frac{N_0 E_b}{2}$$



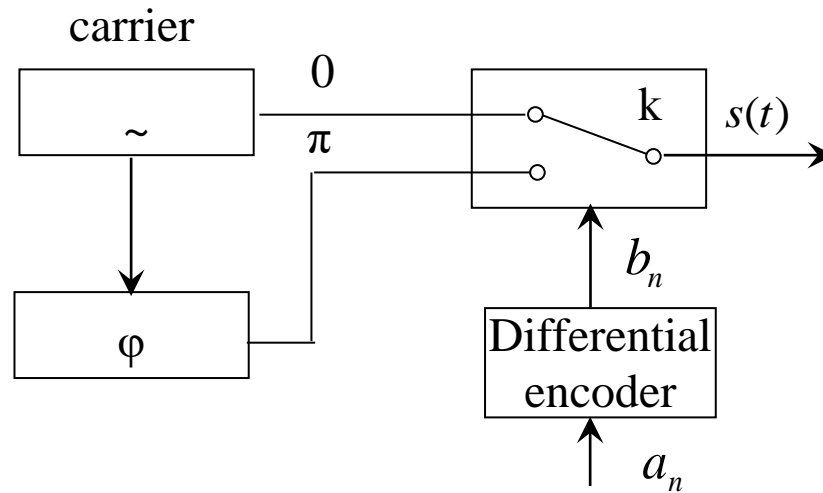
3.5 Differential phase-shift keying (DPSK)



DPSK modulator

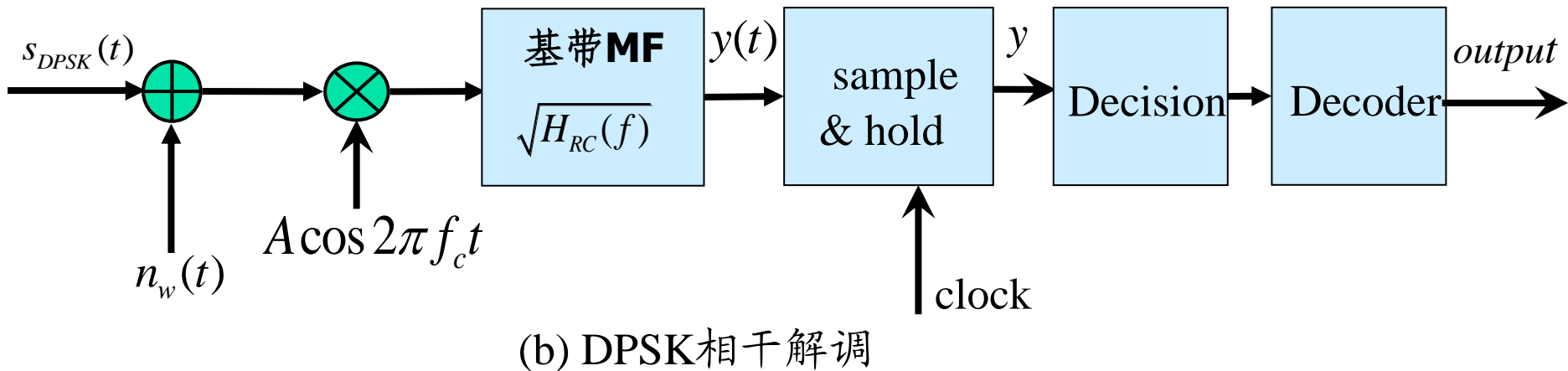
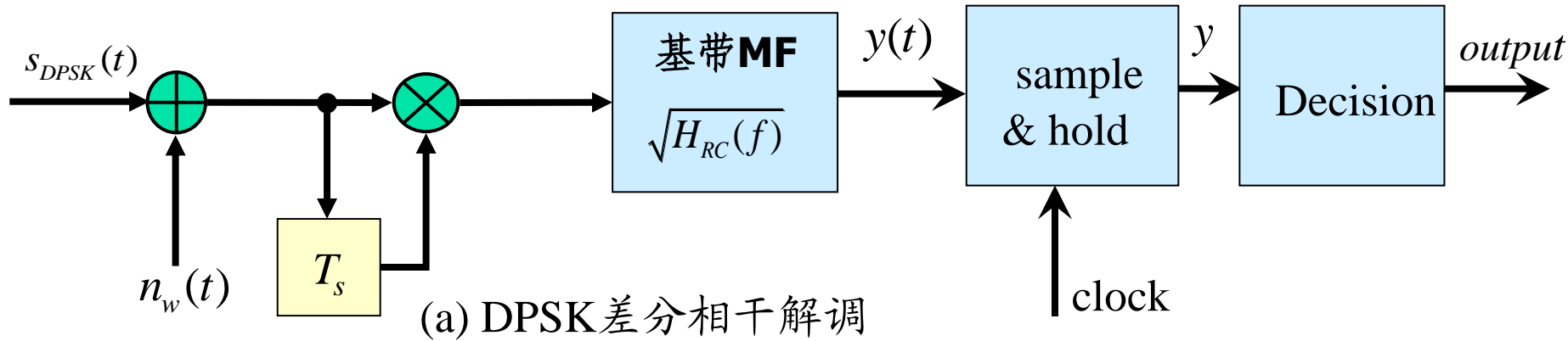


(a) DSB-SC modulator

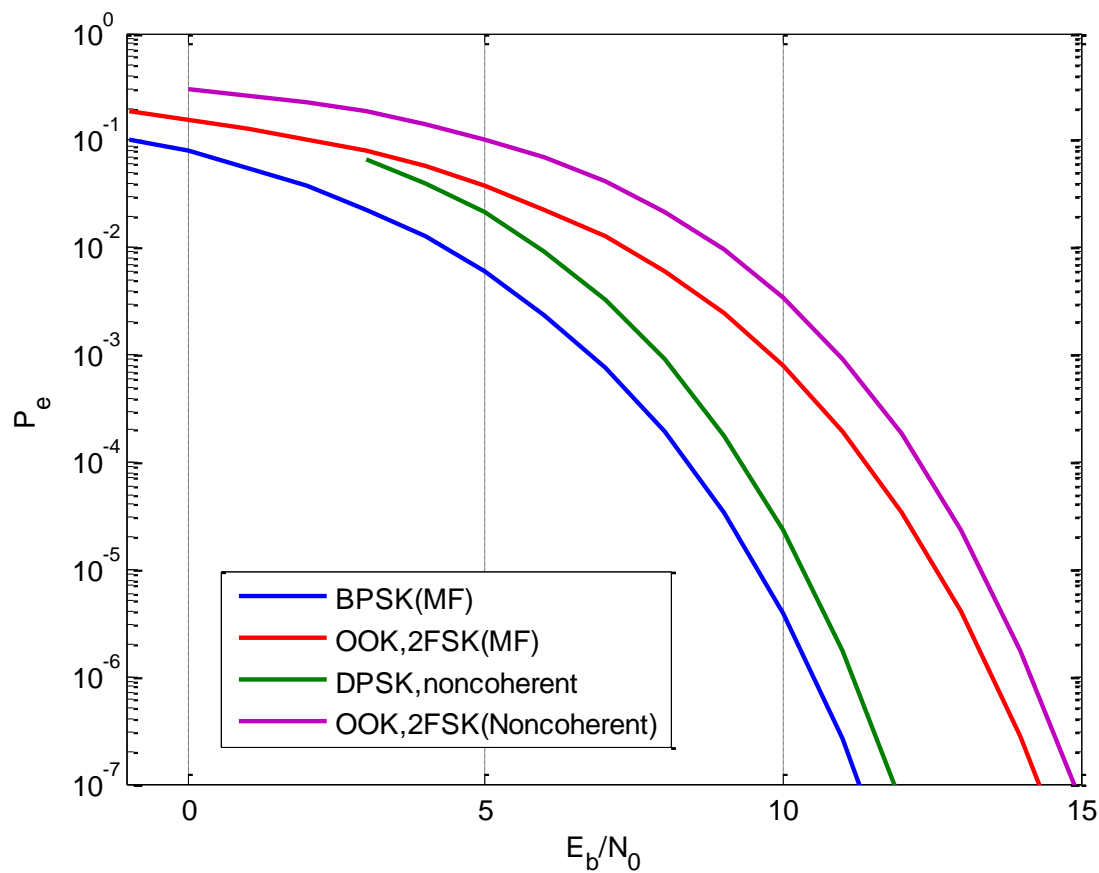


(b) Shift keying modulator

DPSK demodulator



误码率结果比较



此题未设答案

下列二进制频带传输系统中，误码性能最好的是

- ☐ A 2ASK非相干解调
- ☐ B 2PSK相干解调
- ☐ C 2FSK相干解调
- ☐ D 2DPSK非相干解调

提交