07/10/24 week-2 5

03) Solve 8 puzzle problem using DFS and BFS.

Algorithm:

BFS Algorithm:

step1: start at a chosen node (source node)

step2: Mark the node as visited.

~~steps:~~

=>

1. Input the ~~user~~ puzzle.

prompt the user to input the initial state and the goal state of the puzzle.

(eg [1, 2, 3, 0, 4, 5, 6, 7, 8]) where '0' represent the blank tile.

2. Choose Algorithm:

BFS: Generate the shortest solution path but can consume more memory.

DFS: Can be more memory-efficient but might not generate the shortest path.

3. Initialization:

BFS: use queue (FIFO) to store the current state and the path taken to reach it.

DFS: use a recursion to explore deeper branches first.

use a visited list to avoid cycles and ~~also~~ revisiting state.

4. BFS procedure:

- while the queue is not empty
- Dequeue the first state from the queue.
- If the dequeued state is the goal state, return the sequence of moves. (up, down, left, right).
- for each valid move; ~~Recursively~~ create a new state ~~not been visited~~ by swapping the blank tile with the adjacent tile.

5. DFS procedure:

- use the recursive function to explore the current state.
- If the current state is the goal state, return the solution path.
- Mark the current state as ~~the~~ visited,
- Get the position of the blank tile and generate all possible moves (up, down, left, right).

6. Move Generation:

- find the position of the blank tile ~~the 3×3 [or any square matrix] grid.~~
- for each valid direction (up, down, left, right), calculate the new position of the blank tile.

7. check for goal state:

- After every move, compare the sequence of moves ~~with~~ current state with the goal state.
- If they match, the puzzle is solved.

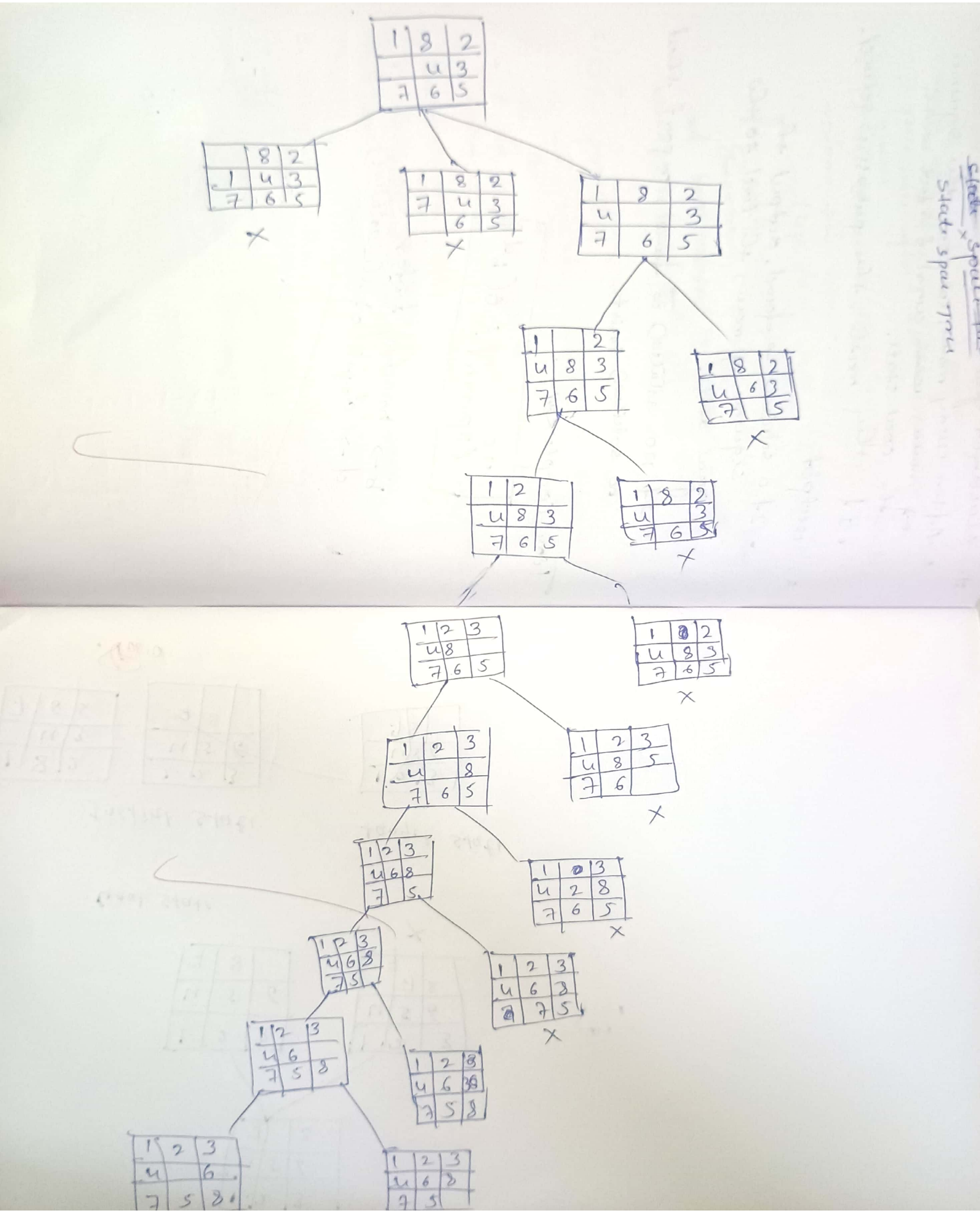
8. output.

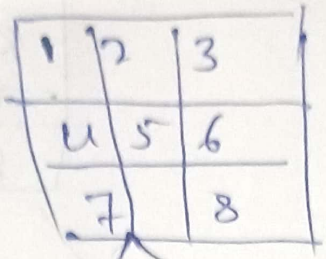
- If a solution is found, output the sequence of moves the lead to the goal state.
- If no solution is found, report that no solution exists.

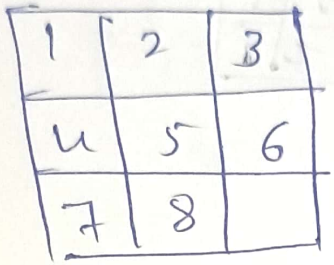
Time complexity:

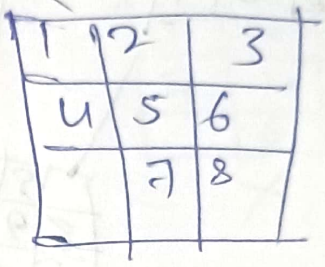
$$TC(8\text{puzzle}) : O(b^d)$$

b -> branching factor
d -> depth of the solution





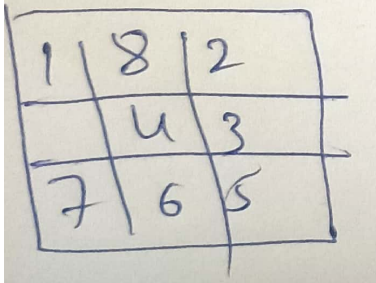


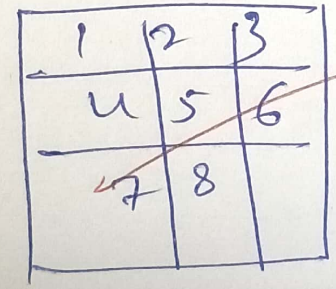


X

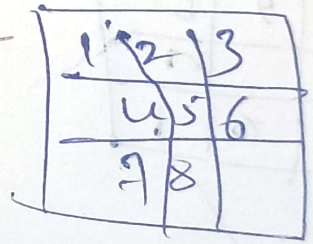
Goal state.

Initial state





target state



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