```
# installing catboost since it is not readily available in Google
Colab
!pip3 install catboost
Looking in indexes: https://pypi.org/simple, https://us-
python.pkg.dev/colab-wheels/public/simple/
Collecting catboost
  Downloading catboost-1.1.1-cp37-none-manylinux1 x86 64.whl (76.6 MB)
ent already satisfied: plotly in /usr/local/lib/python3.7/dist-
packages (from catboost) (5.5.0)
Requirement already satisfied: pandas>=0.24.0 in
/usr/local/lib/python3.7/dist-packages (from catboost) (1.3.5)
Requirement already satisfied: scipy in /usr/local/lib/python3.7/dist-
packages (from catboost) (1.7.3)
Requirement already satisfied: numpy>=1.16.0 in
/usr/local/lib/python3.7/dist-packages (from catboost) (1.21.6)
Requirement already satisfied: six in /usr/local/lib/python3.7/dist-
packages (from catboost) (1.15.0)
Requirement already satisfied: matplotlib in
/usr/local/lib/python3.7/dist-packages (from catboost) (3.2.2)
Requirement already satisfied: graphviz in
/usr/local/lib/python3.7/dist-packages (from catboost) (0.10.1)
Requirement already satisfied: pytz>=2017.3 in
/usr/local/lib/python3.7/dist-packages (from pandas>=0.24.0->catboost)
(2022.6)
Requirement already satisfied: python-dateutil>=2.7.3 in
/usr/local/lib/python3.7/dist-packages (from pandas>=0.24.0->catboost)
(2.8.2)
Requirement already satisfied: cycler>=0.10 in
/usr/local/lib/python3.7/dist-packages (from matplotlib->catboost)
(0.11.0)
Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!
=2.1.6,>=2.0.1 in /usr/local/lib/python3.7/dist-packages (from
matplotlib->catboost) (3.0.9)
Requirement already satisfied: kiwisolver>=1.0.1 in
/usr/local/lib/python3.7/dist-packages (from matplotlib->catboost)
(1.4.4)
Requirement already satisfied: typing-extensions in
/usr/local/lib/python3.7/dist-packages (from kiwisolver>=1.0.1-
>matplotlib->catboost) (4.1.1)
Requirement already satisfied: tenacity>=6.2.0 in
/usr/local/lib/python3.7/dist-packages (from plotly->catboost) (8.1.0)
Installing collected packages: catboost
Successfully installed catboost-1.1.1
! pip install xverse
! pip install --upgrade category encoders
Looking in indexes: https://pypi.org/simple, https://us-
python.pkg.dev/colab-wheels/public/simple/
Collecting xverse
```

```
Downloading xverse-1.0.5-py3-none-any.whl (21 kB)
Requirement already satisfied: scikit-learn>=0.19.0 in
/usr/local/lib/python3.7/dist-packages (from xverse) (1.0.2)
Requirement already satisfied: matplotlib>=3.0.3 in
/usr/local/lib/python3.7/dist-packages (from xverse) (3.2.2)
Requirement already satisfied: numpy>=1.11.3 in
/usr/local/lib/python3.7/dist-packages (from xverse) (1.21.6)
Requirement already satisfied: statsmodels>=0.6.1 in
/usr/local/lib/python3.7/dist-packages (from xverse) (0.12.2)
Requirement already satisfied: scipy>=0.19.0 in
/usr/local/lib/python3.7/dist-packages (from xverse) (1.7.3)
Requirement already satisfied: pandas>=0.21.1 in
/usr/local/lib/python3.7/dist-packages (from xverse) (1.3.5)
Requirement already satisfied: python-dateutil>=2.1 in
/usr/local/lib/python3.7/dist-packages (from matplotlib>=3.0.3-
>xverse) (2.8.2)
Requirement already satisfied: pyparsing!=2.0.4,!=2.1.2,!
=2.1.6,>=2.0.1 in /usr/local/lib/python3.7/dist-packages (from
matplotlib >= 3.0.3 - xverse) (3.0.9)
Requirement already satisfied: kiwisolver>=1.0.1 in
/usr/local/lib/python3.7/dist-packages (from matplotlib>=3.0.3-
>xverse) (1.4.4)
Requirement already satisfied: cycler>=0.10 in
/usr/local/lib/python3.7/dist-packages (from matplotlib>=3.0.3-
>xverse) (0.11.0)
Requirement already satisfied: typing-extensions in
/usr/local/lib/python3.7/dist-packages (from kiwisolver>=1.0.1-
>matplotlib>=3.0.3->xverse) (4.1.1)
Requirement already satisfied: pvtz>=2017.3 in
/usr/local/lib/python3.7/dist-packages (from pandas>=0.21.1->xverse)
(2022.6)
Requirement already satisfied: six>=1.5 in
/usr/local/lib/python3.7/dist-packages (from python-dateutil>=2.1-
>matplotlib>=3.0.3->xverse) (1.15.0)
Requirement already satisfied: threadpoolctl>=2.0.0 in
/usr/local/lib/python3.7/dist-packages (from scikit-learn>=0.19.0-
>xverse) (3.1.0)
Requirement already satisfied: joblib>=0.11 in
/usr/local/lib/python3.7/dist-packages (from scikit-learn>=0.19.0-
>xverse) (1.2.0)
Requirement already satisfied: patsy>=0.5 in
/usr/local/lib/python3.7/dist-packages (from statsmodels>=0.6.1-
>xverse) (0.5.3)
Installing collected packages: xverse
Successfully installed xverse-1.0.5
Looking in indexes: https://pypi.org/simple, https://us-
python.pkg.dev/colab-wheels/public/simple/
Collecting category encoders
  Downloading category encoders-2.5.1.post0-py2.py3-none-any.whl (72
kB)
```

```
ent already satisfied: patsy>=0.5.1 in /usr/local/lib/python3.7/dist-
packages (from category encoders) (0.5.3)
Requirement already satisfied: scipy>=1.0.0 in
/usr/local/lib/python3.7/dist-packages (from category encoders)
(1.7.3)
Requirement already satisfied: statsmodels>=0.9.0 in
/usr/local/lib/python3.7/dist-packages (from category encoders)
(0.12.2)
Requirement already satisfied: scikit-learn>=0.20.0 in
/usr/local/lib/python3.7/dist-packages (from category encoders)
Requirement already satisfied: pandas>=1.0.5 in
/usr/local/lib/python3.7/dist-packages (from category encoders)
(1.3.5)
Requirement already satisfied: numpy>=1.14.0 in
/usr/local/lib/python3.7/dist-packages (from category encoders)
(1.21.6)
Requirement already satisfied: pytz>=2017.3 in
/usr/local/lib/python3.7/dist-packages (from pandas>=1.0.5-
>category encoders) (2022.6)
Requirement already satisfied: python-dateutil>=2.7.3 in
/usr/local/lib/python3.7/dist-packages (from pandas>=1.0.5-
>category encoders) (2.8.2)
Requirement already satisfied: six in /usr/local/lib/python3.7/dist-
packages (from patsy>=0.5.1->category_encoders) (1.15.0)
Requirement already satisfied: joblib>=0.11 in
/usr/local/lib/python3.7/dist-packages (from scikit-learn>=0.20.0-
>category encoders) (1.2.0)
Requirement already satisfied: threadpoolctl>=2.0.0 in
/usr/local/lib/python3.7/dist-packages (from scikit-learn>=0.20.0-
>category encoders) (3.1.0)
Installing collected packages: category-encoders
Successfully installed category-encoders-2.5.1.post0
# to show the time taken by each cell
!pip install ipython-autotime
%load ext autotime
Looking in indexes: https://pypi.org/simple, https://us-
python.pkg.dev/colab-wheels/public/simple/
Collecting ipython-autotime
  Downloading ipython autotime-0.3.1-py2.py3-none-any.whl (6.8 kB)
Requirement already satisfied: ipython in
/usr/local/lib/python3.7/dist-packages (from ipython-autotime) (7.9.0)
Requirement already satisfied: pygments in
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (2.6.1)
Requirement already satisfied: traitlets>=4.2 in
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (5.1.1)
Requirement already satisfied: decorator in
```

```
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (4.4.2)
Collecting jedi>=0.10
  Downloading jedi-0.18.2-py2.py3-none-any.whl (1.6 MB)
ent already satisfied: prompt-toolkit<2.1.0,>=2.0.0 in
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (2.0.10)
Requirement already satisfied: setuptools>=18.5 in
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (57.4.0)
Requirement already satisfied: pickleshare in
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (0.7.5)
Requirement already satisfied: pexpect in
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (4.8.0)
Requirement already satisfied: backcall in
/usr/local/lib/python3.7/dist-packages (from ipython->ipython-
autotime) (0.2.0)
Requirement already satisfied: parso<0.9.0,>=0.8.0 in
/usr/local/lib/python3.7/dist-packages (from jedi>=0.10->ipython-
>ipython-autotime) (0.8.3)
Requirement already satisfied: wcwidth in
/usr/local/lib/python3.7/dist-packages (from prompt-
toolkit<2.1.0,>=2.0.0->ipython->ipython-autotime) (0.2.5)
Requirement already satisfied: six>=1.9.0 in
/usr/local/lib/python3.7/dist-packages (from prompt-
toolkit<2.1.0,>=2.0.0->ipython->ipython-autotime) (1.15.0)
Requirement already satisfied: ptyprocess>=0.5 in
/usr/local/lib/python3.7/dist-packages (from pexpect->ipython-
>ipython-autotime) (0.7.0)
Installing collected packages: jedi, ipython-autotime
Successfully installed ipython-autotime-0.3.1 jedi-0.18.2
time: 485 µs (started: 2022-11-23 16:27:14 +00:00)
import numpy as np
import pandas as pd
pd.set option('display.max rows', None)
pd.set option('display.max columns', None)
import matplotlib.pyplot as plt
import seaborn as sns
from xverse.transformer import WOE
from category encoders.cat boost import CatBoostEncoder
from category encoders.woe import WOEEncoder
from sklearn.model selection import train test split
```

```
from sklearn.pipeline import Pipeline
from catboost import CatBoostClassifier
from sklearn.ensemble import RandomForestClassifier
from xgboost import XGBClassifier
from lightgbm import LGBMClassifier
from sklearn.model selection import RandomizedSearchCV, GridSearchCV
from sklearn.metrics import classification report, fl score,
confusion matrix, ConfusionMatrixDisplay
from statsmodels.stats.outliers influence import
variance inflation factor
from scipy.stats import randint as sp randint
from scipy.stats import uniform as sp uniform
from sklearn.feature selection import RFE
time: 1.89 s (started: 2022-11-23 16:27:14 +00:00)
# importing required libraries
%matplotlib inline
import pandas as pd
from catboost import CatBoostClassifier
import numpy as np
import matplotlib.pyplot as plt
from sklearn.metrics import confusion matrix, roc_curve, auc,
ConfusionMatrixDisplay, f1_score, RocCurveDisplay, roc_auc_score,
accuracy score, classification report, recall score
from sklearn.model selection import train test split
time: 4.89 ms (started: 2022-11-23 16:28:08 +00:00)
```

#### # About the Dataset

#### ## Insurance Claim Prediction

- 1. An insurance policy is an agreement between a company and a customer by which a company undertakes to provide a guarantee of compensation for specified loss, damage or illness in return for the payment of a specified premium. A premium is a sum of money that the customer needs to pay regularly to an insurance company for this guarantee.
- 2. For example, you pay a premium of Rs. 3000/- each year for car insurance with a coverage of Rs. 100,000/-. Unfortunately, in case of an accident, the car is severely damaged. In that case, the insurance provider company will bear the cost of damage etc. for up to Rs. 100,000.

- 3. Now if you are wondering how can a company bear such a high cost when it charges a premium of only Rs. 3000/- per year only i.e. where the concept of probability comes into the picture. For example, there might be thousands of customers who would be paying a premium of Rs. 3000 every year just like you, but only a few of them (say 2-3) would have had an accident that year and not everyone. This way everyone shares the risk of everyone else.
- 4. Our client is an Insurance company that provides insurance for cars to its customers. In this hackathon, you will be closely working with the insurer in understanding the behaviour of the policyholders.

```
# to display all the rows and columns
pd.set option('display.max rows', 100)
pd.set option('display.max columns', 100)
time: 1.07 ms (started: 2022-11-23 16:28:08 +00:00)
df = pd.read csv('train qWM28Yl.csv')
oot = pd.read csv('test_zo1G9sv.csv')
time: 557 ms (started: 2022-11-23 16:45:04 +00:00)
# checking for any duplicate policy IDs
df['policy id'].duplicated().sum()
0
time: 16.6 ms (started: 2022-11-23 16:28:08 +00:00)
df.head()
  policy id
             policy tenure age of car age of policyholder
area cluster \
    ID00001
                  0.515874
                                   0.05
                                                     0.644231
C1
1
    ID00002
                  0.672619
                                   0.02
                                                     0.375000
C2
2
    ID00003
                  0.841110
                                   0.02
                                                     0.384615
С3
                  0.900277
                                   0.11
3
    ID00004
                                                     0.432692
C4
    ID00005
                  0.596403
                                   0.11
4
                                                     0.634615
C5
   population density
                       make segment model fuel type
                                                          max torque
0
                 4990
                           1
                                        Μ1
                                                 CNG
                                                        60Nm@3500rpm
                                   Α
                                                        60Nm@3500rpm
1
                27003
                           1
                                   Α
                                        Μ1
                                                 CNG
2
                 4076
                           1
                                                 CNG
                                                        60Nm@3500rpm
                                   Α
                                        Μ1
3
                21622
                           1
                                  C1
                                        Μ2
                                              Petrol
                                                       113Nm@4400rpm
                34738
                           2
                                   Α
                                        М3
                                              Petrol
                                                        91Nm@4250rpm
```

```
engine type
                                           airbags is esc \
          max power
   40.36bhp@6000rpm
                       F8D Petrol Engine
                                                 2
                                                        No
                                                 2
                       F8D Petrol Engine
  40.36bhp@6000rpm
                                                        No
                                                 2
  40.36bhp@6000rpm
                       F8D Petrol Engine
                                                        No
                                                 2
  88.50bhp@6000rpm
                      1.2 L K12N Dualjet
                                                       Yes
                                                 2
4 67.06bhp@5500rpm
                                  1.0 SCe
                                                        No
  is adjustable steering is tpms is parking sensors is parking camera
0
                       No
                               No
                                                  Yes
                                                                       No
1
                       No
                               No
                                                  Yes
                                                                       No
2
                                                                       No
                       No
                               No
                                                  Yes
3
                      Yes
                               No
                                                  Yes
                                                                     Yes
4
                       No
                               No
                                                    No
                                                                     Yes
  rear brakes type displacement cylinder transmission type gear box
                              796
                                           3
                                                         Manual
                                                                         5
0
              Drum
1
              Drum
                              796
                                           3
                                                         Manual
                                                                         5
2
                                           3
                                                                         5
              Drum
                              796
                                                         Manual
3
              Drum
                                                      Automatic
                                                                         5
                             1197
                                           4
                                                     Automatic
                                                                         5
4
              Drum
                              999
                                           3
  steering_type turning_radius length
                                           width
                                                  height
gross weight
                             4.6
                                     3445
                                            1515
                                                     1475
          Power
                                                                    1185
1
                                                                    1185
          Power
                             4.6
                                     3445
                                            1515
                                                    1475
2
          Power
                             4.6
                                     3445
                                            1515
                                                     1475
                                                                    1185
3
       Electric
                             4.8
                                     3995
                                            1735
                                                    1515
                                                                    1335
4
       Electric
                             5.0
                                     3731
                                            1579
                                                     1490
                                                                    1155
```

is\_front\_fog\_lights is\_rear\_window\_wiper is\_rear\_window\_washer \

No

1 2 3 4	No No Yes No		No No No No	No No No No
0 1 2 3 4	is_rear_window_defogger is_bra No No No Yes No	_ N N N Ye	lo —· — lo lo	r_locks \ No No No Yes Yes
	<pre>is_central_locking is_power_s _driver_seat_height_adjustable</pre>			
	No Yes	Yes Yes		
	Yes	Yes		
is	<pre>is_day_night_rear_view_mirror   claim</pre>	is_ecw i	.s_speed_alert	ncap_rating
0 0	_ No	No	Yes	0
1	No	No	Yes	0
2	No	No	Yes	0
3	Yes	Yes	Yes	2
0 4 0	Yes	Yes	Yes	2

# time: 45.6 ms (started: 2022-11-23 16:28:08 +00:00)

## ## Description of each column:

Variable	Description
policy_id	Unique identifier of the policyholder
policy_tenure	Time period of the policy
age_of_car	Normalized age of the car in years
age_of_policyholder	Normalized age of policyholder in years
area_cluster	Area cluster of the policyholder

City)

make Encoded Manufacturer/company of the car

segment Segment of the car (A/B1/B2/C1/C2)

model Encoded name of the car

fuel\_type Type of fuel used by the car

max\_torque Maximum Torque generated by the car

(Nm@rpm)

max\_power Maximum Power generated by the car

(bhp@rpm)

engine\_type Type of engine used in the car engine\_type Type of engine used in the car

airbags Number of airbags installed in the car

is\_esc Boolean flag indicating whether Electronic

Stability Control (ESC) is present in the car

or not.

is\_adjustable\_steering Boolean flag indicating whether the

steering wheel of the car is adjustable or

not.

'is\_tpms' Boolean flag indicating whether Tyre

Pressure Monitoring System (TPMS) is

present in the car or not.

is\_parking\_sensors Boolean flag indicating whether parking

sensors are present in the car or not.

is\_parking\_camera Boolean flag indicating whether the

parking camera is present in the car or not.

rear\_brakes\_type Type of brakes used in the rear of the car

displacement Engine displacement of the car (cc)

cylinder Number of cylinders present in the engine

of the car

transmission\_type Transmission type of the car

gear\_box Number of gears in the car

steering\_type Type of the power steering present in the

car

turning\_radius The space a vehicle needs to make a certain

turn (Meters)

lemgth Length of the car (Millimetre)

width Width of the car (Millimetre)

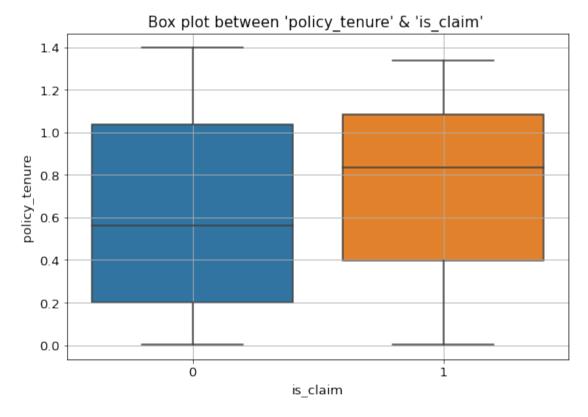
height Height of the car (Millimetre)

gross_weight	The maximum allowable weight of the fully-loaded car, including passengers, cargo and equipment (Kg)
is_front_fog_lights	Boolean flag indicating whether front fog lights are available in the car or not.
is_rear_window_wiper	Boolean flag indicating whether the rear window wiper is available in the car or not.
is_rear_window_washer	Boolean flag indicating whether the rear window washer is available in the car or not.
is_rear_window_defogger	Boolean flag indicating whether rear window defogger is available in the car or not.
is_brake_assist	Boolean flag indicating whether the brake assistance feature is available in the car or not.
is_power_door_lock	Boolean flag indicating whether a power door lock is available in the car or not.
is_central_locking	Boolean flag indicating whether the central locking feature is available in the car or not.
is_power_steering	Boolean flag indicating whether power steering is available in the car or not.
is_driver_seat_height_adjustable	Boolean flag indicating whether the height of the driver seat is adjustable or not.
is_day_night_rear_view_mirror	Boolean flag indicating whether day & night rearview mirror is present in the car or not.
is_ecw	Boolean flag indicating whether Engine Check Warning (ECW) is available in the car or not.
is_speed_alert	Boolean flag indicating whether the speed alert system is available in the car or not.
ncap_rating	Safety rating given by NCAP (out of 5)
is_claim	Outcome: Boolean flag indicating whether the policyholder file a claim in the next 6 months or not.

is\_claim: 0 -- not claimed & 1 -- claimed

## # Exploratory Data Analysis (EDA)

```
Plot between 'policy_tenure' & 'is_claim'
plt.figure(figsize=(9, 6))
ax = sns.boxplot(x = 'is_claim', y = 'policy_tenure', data = df)
#plt.legend(fontsize = 13)
# y-axis
plt.ylabel("policy_tenure ", fontdict = {'fontsize': 13})
plt.yticks(size=13)
#x-axis
plt.xlabel("is claim", fontdict = {'fontsize': 13})
plt.xticks(size=13)
# title
plt.title("Box plot between 'policy_tenure' & 'is_claim' ", fontdict =
{'fontsize': 15})
#plotting the graph
plt.grid()
plt.show()
```

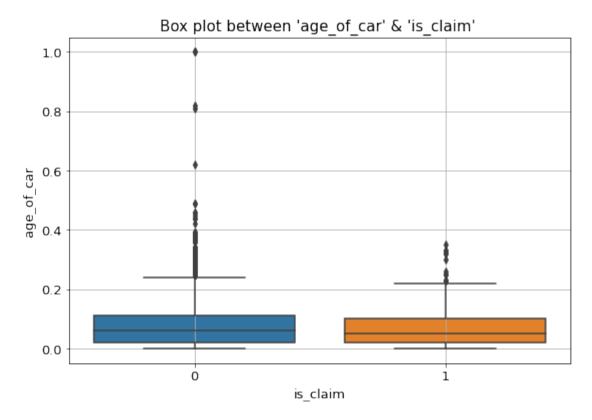


time: 172 ms (started: 2022-11-23 16:28:09 +00:00)

#### **Observations:**

- 1. Customers who has claimed the insurance are having more policty tenure when compared to the ones who didnot claim.
- 2. Nearly 50% of the customers who has claimed the insurance are having policy tenure = 0.8 which is only 0.55 for customers who has not claimed.

```
Box plot between 'age_of_car' & 'is_claim'
plt.figure(figsize=(9, 6))
# specifying x and y axis for our graph
ax = sns.boxplot(x = 'is claim', y = 'age of car', data = df);
#plt.legend(fontsize = 13)
# y-axis
plt.ylabel("age of car ", fontdict = {'fontsize': 13})
plt.yticks(size=13)
# x-axis
plt.xlabel("is_claim", fontdict = {'fontsize': 13})
plt.xticks(size=13)
# title
plt.title("Box plot between 'age_of_car' & 'is_claim' ", fontdict =
{'fontsize': 15})
# plotting the graph
plt.grid()
plt.show()
```



time: 157 ms (started: 2022-11-23 16:28:09 +00:00)

#### **Observations:**

1. age of the cars is very much high for the customers who has not claimed.

```
Box plot betwen 'age_of_policyholder' & 'is_claim'
plt.figure(figsize=(9, 6))

# specifying x and y axis for our graph
ax = sns.boxplot(x = 'is_claim', y = 'age_of_policyholder', data = df)

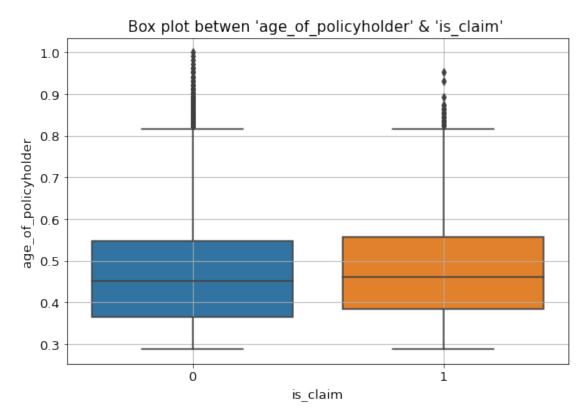
#plt.legend(fontsize = 13)

# y-axis
plt.ylabel("age_of_policyholder ", fontdict = {'fontsize': 13})
plt.yticks(size=13)

# x-axis
plt.xlabel("is_claim", fontdict = {'fontsize': 13})
plt.xticks(size=13)

# title
plt.title("Box plot betwen 'age_of_policyholder' & 'is_claim' ", fontdict = {'fontsize': 15})
```

```
# plotting the graph
plt.grid()
plt.show()
```



time: 195 ms (started: 2022-11-23 16:28:09 +00:00)

#### **Observations:**

1. Age of policy holders who not claimed is little high when compared to the customers who has claimed.

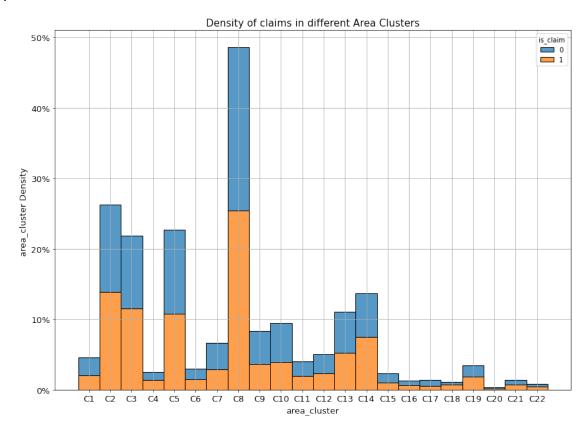
# Density of claims in different Area Clusters plt.figure(figsize=(14, 10))

```
# specifying x and y axis for our graph
ax = sns.histplot(x = 'area_cluster', hue = 'is_claim', data = df,
multiple = 'stack', stat = 'density', common_norm = False);

# y-axis
plt.ylabel("area_cluster Density ", fontdict = {'fontsize': 13})
plt.yticks(size=13)

# x-axis
plt.xlabel("area_cluster", fontdict = {'fontsize': 13})
plt.xticks(size=13)
# title
```

```
plt.title("Density of claims in different Area Clusters", fontdict =
{'fontsize': 15})
from matplotlib.ticker import PercentFormatter
plt.gca().yaxis.set_major_formatter(PercentFormatter(1))
# plotting the graph
plt.grid()
plt.show()
```



time: 429 ms (started: 2022-11-23 16:28:09 +00:00)

#### **Observation:**

1. We can observer that most of the policy holders are the area\_cluster C8 and least are from C20 area cluster.

```
Box plot between 'is_claim' and 'population_density'
plt.figure(figsize=(9, 6))

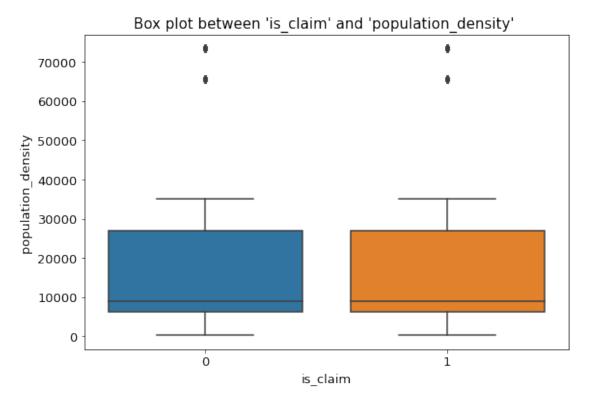
# specifying x and y axis for our graph
ax = sns.boxplot(x = 'is_claim', y = 'population_density', data = df);

# y-axis
plt.ylabel("population_density ", fontdict = {'fontsize': 13})
plt.yticks(size=13)
```

```
# x-axis
plt.xlabel("is_claim", fontdict = {'fontsize': 13})
plt.xticks(size=13)

# title
plt.title("Box plot between 'is_claim' and 'population_density' ",
fontdict = {'fontsize': 15})

# plotting the graph
plt.show()
```



time: 165 ms (started: 2022-11-23 16:28:10 +00:00)

#### **Observation:**

1. population density is almost same in both the categories.
df.make.value\_counts().sort\_values(ascending = False)

```
1 38126

3 14018

2 2373

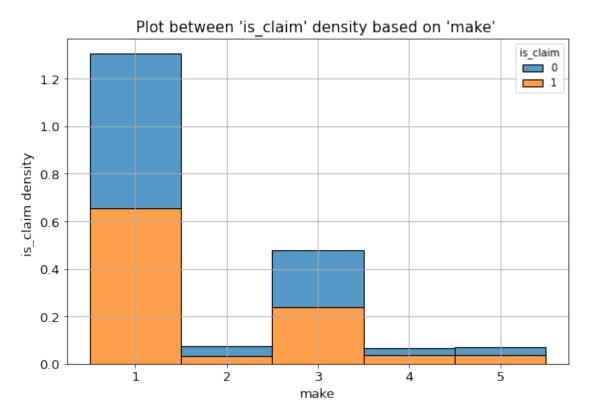
5 2114

4 1961

Name: make, dtype: int64

time: 9.51 ms (started: 2022-11-23 16:28:10 +00:00)
```

```
Plot between 'is claim' density based on 'make'
df['make'] = df['make'].astype('category')
plt.figure(figsize=(9, 6))
# specifying x and y axis for our graph
ax = sns.histplot(x = 'make', hue = 'is claim', data = df, multiple =
'stack', stat = 'density', common norm=False);
# y-axis
plt.ylabel("is claim density ", fontdict = {'fontsize': 13})
plt.yticks(size=13)
# x-axis
plt.xlabel("make", fontdict = {'fontsize': 13})
plt.xticks(size=13)
# title
plt.title("Plot between 'is claim' density based on 'make' ", fontdict
= {'fontsize': 15})
# plotting the graph
plt.grid()
plt.show()
```

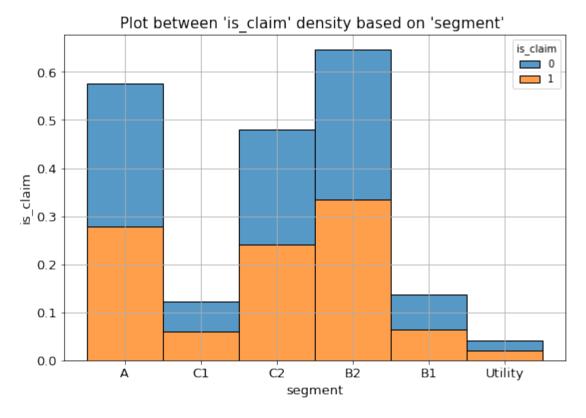


time: 422 ms (started: 2022-11-23 16:28:10 +00:00)

#### **Observation:**

1. We can observe that most of the policy holders are from make = 1 cateogory and claimed, not claimed ration is alomost same in the same type.

```
Plot between 'is claim' density based on 'segment'
plt.figure(figsize=(9, 6))
# specifying x and y axis for our graph
ax = sns.histplot(x = 'segment', hue = 'is claim', data = df, multiple
= 'stack', stat = 'density', common_norm=False);
# y-axis
plt.ylabel("is claim", fontdict = {'fontsize': 13})
plt.yticks(size=13)
# x-axis
plt.xlabel("segment", fontdict = {'fontsize': 13})
plt.xticks(size=13)
# title
plt.title("Plot between 'is claim' density based on 'segment' ",
fontdict = {'fontsize': 15})
# plotting the graph
plt.grid()
plt.show()
```



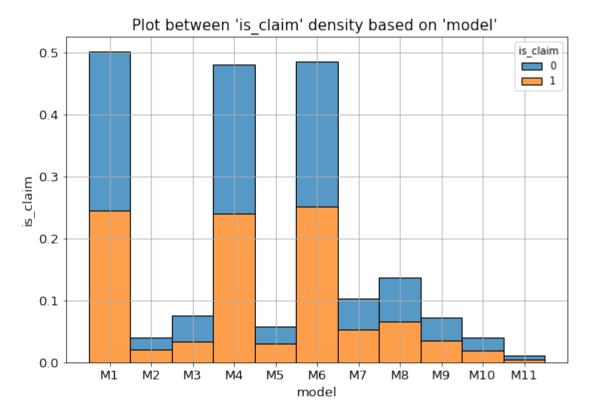
time: 273 ms (started: 2022-11-23 16:28:10 +00:00)

## Plot between 'is\_claim' density based on 'model' of the Car

a = df.groupby(['is\_claim']).model.value\_counts(normalize = False)
print(a)

is_claim	model	
0 _	M1	14030
	M4	13117
	M6	12837
	M8	3929
	M7	2739
	M3	2245
	M9	1981
	M5	1482
	M10	1136
	M2	1000
	M11	348
1	M6	939
	M1	918
	M4	901
	M8	244
	M7	201
	M9	133
	M3	128
	M5	116

```
M2
                      80
          M10
                      73
          M11
                      15
Name: model, dtype: int64
time: 19.2 ms (started: 2022-11-23 16:28:10 +00:00)
plt.figure(figsize=(9, 6))
# specifying x and y axis for our graph
ax = sns.histplot(x = 'model', hue = 'is claim', data = df, multiple =
'stack', stat = 'density', common_norm=False);
# y-axis
plt.ylabel("is claim", fontdict = {'fontsize': 13})
plt.yticks(size=13)
# x-axis
plt.xlabel("model", fontdict = {'fontsize': 13})
plt.xticks(size=13)
# title
plt.title("Plot between 'is claim' density based on 'model' ",
fontdict = {'fontsize': 15})
# plotting the graph
plt.grid()
plt.show()
```



time: 315 ms (started: 2022-11-23 16:28:10 +00:00)

#### **Observations:**

1. We can observe that most of the claims are done by the model M6 which is around 939 and least number of claims i.e, 15 are made by M11 model.

```
Plot between 'is_claim' density based on 'fuel_type'
plt.figure(figsize=(9, 6))

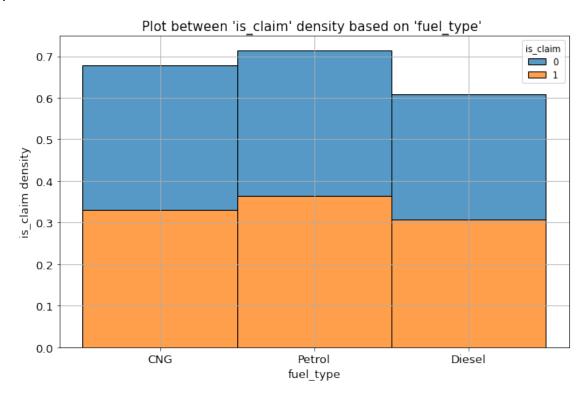
# specifying x and y axis for our graph
ax = sns.histplot(x = 'fuel_type', hue = 'is_claim', data = df,
multiple = 'stack', stat = 'density', common_norm=False);

# y-axis
plt.ylabel("is_claim density", fontdict = {'fontsize': 13})
plt.yticks(size=13)

# x-axis
plt.xlabel("fuel_type", fontdict = {'fontsize': 13})
plt.xticks(size=13)

# title
plt.title("Plot between 'is_claim' density based on 'fuel_type' ",
fontdict = {'fontsize': 15})
```

```
# plotting the graph
plt.grid()
plt.tight_layout()
plt.show()
```



time: 317 ms (started: 2022-11-23 16:28:11 +00:00)

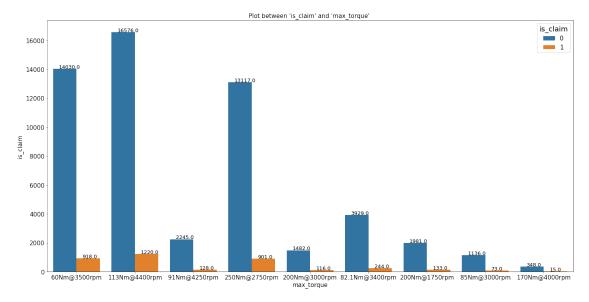
#### **Observation:**

1. Most of the Claims are made by the cars which are having fuel\_type as Petrol and next to this almost equal number of claims are made by the cars which are having fuel type of Diesel and CNG.

a = df.groupby(['is\_claim']).max\_torque.value\_counts(normalize = True)
print(a)

```
is claim
          max torque
          113Nm@4400rpm
                             0.302239
          60Nm@3500rpm
                             0.255816
          250Nm@2750rpm
                             0.239169
          82.1Nm@3400rpm
                             0.071640
          91Nm@4250rpm
                             0.040934
          200Nm@1750rpm
                             0.036121
          200Nm@3000rpm
                             0.027022
          85Nm@3000rpm
                             0.020713
          170Nm@4000rpm
                             0.006345
1
          113Nm@4400rpm
                             0.325507
          60Nm@3500rpm
                             0.244931
          250Nm@2750rpm
                             0.240395
```

```
82.1Nm@3400rpm
                            0.065101
          200Nm@1750rpm
                            0.035486
          91Nm@4250rpm
                            0.034152
          200Nm@3000rpm
                            0.030950
          85Nm@3000rpm
                            0.019477
          170Nm@4000rpm
                            0.004002
Name: max_torque, dtype: float64
time: 19.7 ms (started: 2022-11-23 16:28:11 +00:00)
Plot between 'is claim' density based on 'max torque'
plt.figure(figsize=(20, 10))
ax = sns.countplot(data = df, x='max torque', hue='is claim')
# adding legend with title
plt.legend(title = 'is claim', title fontsize = 18, fontsize = 15)
# x-axis
plt.xlabel("max_torque", fontdict = {'fontsize': 15})
plt.xticks(size = 15)
# y-axis
plt.ylabel("is claim ", fontdict = {'fontsize': 15})
plt.yticks(size = 15)
# adding title
plt.title("Plot between 'is claim' and 'max torque' ", fontdict =
{'fontsize': 15})
# annotating the bars
for p in ax.patches:
        ax.annotate('\{:.1f\}'.format(p.get height()), (p.get x()+0.1,
p.get height()+25), ha='left', va='baseline', fontsize = 13)
# plotting the graph
#plt.grid()
plt.tight_layout()
plt.show()
```



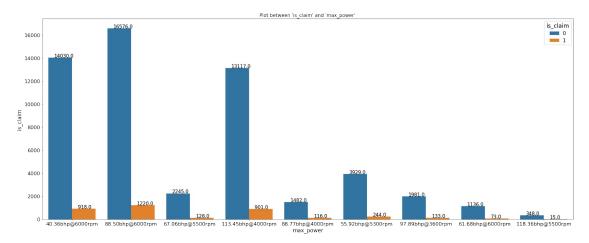
time: 508 ms (started: 2022-11-23 16:28:11 +00:00)

#### **Observation:**

1. 1220 claims are made by the cars which are having max\_torque as 113Nm@440rpm and least of them which is 15 claims were made by cars having max\_torque as 170Nm@4000 rpm.

```
Plot between 'is claim' and 'max power'
plt.figure(figsize=(25, 10))
ax = sns.countplot(data = df, x='max power', hue='is claim')
# adding legend with title
plt.legend(title = 'is claim', title fontsize = 18, fontsize = 15)
# x-axis
plt.xlabel("max power", fontdict = {'fontsize': 17})
plt.xticks(size = 16)
# y-axis
plt.ylabel("is_claim ", fontdict = {'fontsize': 17})
plt.yticks(size = 16)
# adding title
plt.title("Plot between 'is claim' and 'max power' ", fontdict =
{'fontsize': 15})
# annotating the bars
for p in ax.patches:
        ax.annotate('{:.1f}'.format(p.get_height()), (p.get_x()+0.1,
p.get height()+25), ha='left', va='baseline', fontsize = 15)
# plotting the graph
```

```
#plt.grid()
plt.tight_layout()
plt.show()
```

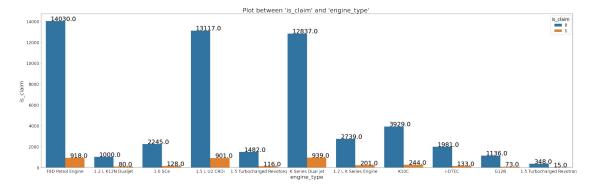


#### **Observation:**

1. We can observe that the cars which are having max\_power of 88.50bhp@6000rpm has made as highest of 1220 claims and least numbers of claims are made by the cars that have max\_power of 118.36bhp@5500rpm which is 15 claims.

```
Plot between 'is_claim' and 'engine_type'
plt.figure(figsize=(32, 10))
ax = sns.countplot(data = df, x='engine type', hue='is claim')
# adding legend with title
plt.legend(title = 'is claim', title fontsize = 18, fontsize = 15)
# x-axis
plt.xlabel("engine type", fontdict = {'fontsize': 22})
plt.xticks(size = 17)
# v-axis
plt.ylabel("is_claim ", fontdict = {'fontsize': 22})
plt.yticks(size = 17)
# adding title
plt.title("Plot between 'is claim' and 'engine type' ", fontdict =
{'fontsize': 25})
# annotating the bars
for p in ax.patches:
        ax.annotate('{:.1f}'.format(p.get_height()), (p.get_x()+0.1,
p.get height()+25), ha='left', va='baseline', fontsize = 25)
# plotting the graph
# plt.grid()
```

```
plt.tight_layout()
plt.show()
```

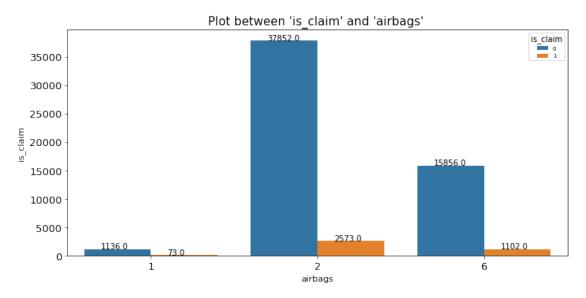


time: 1.21 s (started: 2022-11-23 16:29:32 +00:00)

#### **Observation:**

1. Most number of claims are made by the cars that have engine type as F&D Petrol engine and least number by the ones which have engine type as 1.5 Turbocharged Revotron

```
Plot between 'is_claim' and 'airbags'
plt.figure(figsize=(10, 5))
ax = sns.countplot(data = df, x='airbags', hue='is claim')
# adding legend with title
plt.legend(title = 'is claim', title fontsize = 10, fontsize = 7)
# x-axis
plt.xlabel("airbags", fontdict = {'fontsize': 11})
plt.xticks(size = 13)
# v-axis
plt.ylabel("is_claim ", fontdict = {'fontsize': 11})
plt.yticks(size = 13)
# adding title
plt.title("Plot between 'is claim' and 'airbags' ", fontdict =
{'fontsize': 15})
# annotating the bars
for p in ax.patches:
        ax.annotate('\{:.1f\}'.format(p.get_height()), (p.get x()+0.1,
p.get height()+25), ha='left', va='baseline', fontsize = 10)
# plotting the graph
#plt.grid()
plt.tight_layout()
plt.show()
```



time: 264 ms (started: 2022-11-23 16:28:13 +00:00)

#### **Observations:**

1. Cars that have only 2 air bags have claimed more times when compared to the ones have 1 and 6 air bags.

```
cols = ['is esc', 'is adjustable steering', 'is tpms',
'is parking sensors', 'is parking camera',
         'is front fog lights', 'is rear window wiper',
'is rear window washer',
        ____
'is rear window defogger', 'is brake assist',
'is power_door_locks', 'is_central_locking', 'is_power_steering',
'is_driver_seat_height_adjustable',
'is_day_night_rear_view_mirror', 'is_ecw', 'is_speed_alert']
for col in cols:
    df[col] = np.where(df[col] == 'Yes', 1, 0)
for col in cols:
    oot[col] = np.where(oot[col] == 'Yes', 1, 0)
time: 357 ms (started: 2022-11-23 16:45:20 +00:00)
# Modelling - LGBM
Train and Validation Split
X = df.drop(columns = ['policy id', 'is claim'])
y = df['is_claim']
time: 22.9 ms (started: 2022-11-23 16:45:26 +00:00)
# using 10% of the given data in testing
x train, x test, y train, y test = train test split(X, y, test size =
0.1, stratify = y, random state = 1)
```

```
time: 44.6 ms (started: 2022-11-23 16:45:28 +00:00)
print("Number of points available in Training data for each claim type
are:")
y train.value counts()
Number of points available in Training data for each claim type are:
0
     49359
1
      3373
Name: is claim, dtype: int64
time: 8.87 ms (started: 2022-11-23 16:45:31 +00:00)
val = (y train.value counts(normalize = True)) * 100
print("Percentage of points available in Training data for each claim
type are:")
print(val)
# we can observe that nearly 93% percent of the values are having
is claim status as '0' and other 6% have as status '1'
Percentage of points available in Training data for each claim type
are:
0
     93.603505
      6.396495
1
Name: is claim, dtype: float64
time: 3.89 ms (started: 2022-11-23 16:45:33 +00:00)
print("Number of points available in Test data for each claim type
are:")
y test.value counts()
Number of points available in Test data for each claim type are:
0
     5485
      375
1
Name: is claim, dtype: int64
time: 8.43 ms (started: 2022-11-23 16:45:37 +00:00)
val = (y test.value counts(normalize = True)) * 100
print("Percentage of points available in Test data for each claim type
are:")
print(val)
Percentage of points available in Test data for each claim type are:
     93,600683
      6.399317
Name: is claim, dtype: float64
time: 5.68 ms (started: 2022-11-23 16:45:39 +00:00)
```

### References for WOEEncoder( Weight of Evidence):

max power

 $0.\overline{0}83521$ 

42769

engine\_type

 $0.0\overline{7}6777$ 

- 1. https://www.listendata.com/2015/03/weight-of-evidence-woe-and-information.html
- 2. https://towardsdatascience.com/an-easier-way-to-encode-categorical-features-d840ff6b3900
- **3.** https://www.analyticsvidhya.com/blog/2021/06/understand-weight-of-evidence-and-information-value/

```
# implementing Weight of Evidence Encoding
woe = W0EEncoder()
time: 723 µs (started: 2022-11-23 16:45:44 +00:00)
# listing down all the categorical features in our Data
feature_list = ['area_cluster', 'make', 'segment', 'model',
'fuel_type', 'max_torque', 'max_power', 'engine_type',
                  'rear_brakes_type', 'transmission_type',
'steering type']
time: 976 µs (started: 2022-11-23 16:45:46 +00:00)
# applying WOEEncoder on Train and Test data sets
train woe = woe.fit transform(x train[feature list], y train)
test woe = woe.transform(x test[feature list])
oot woe = woe.transform(oot[feature list])
time: 1.01 s (started: 2022-11-23 16:45:48 +00:00)
train woe.shape
(52732, 11)
time: 3.89 ms (started: 2022-11-23 16:45:54 +00:00)
train woe.head()
       area cluster
                      make
                              segment
                                          model
                                                  fuel type
max torque \
42769
           0.104014
                            0.090258
                                                                0.083521
                         1
                                       0.076777
                                                   0.043882
                         1 -0.060953 -0.037514
35051
           0.104014
                                                  -0.053764
                                                               -0.037514
12127
           0.116440
                         1 -0.060953 -0.037514
                                                  -0.053764
                                                               -0.037514
17456
           0.127955
                         1 0.090258 0.076777
                                                   0.043882
                                                                0.083521
          -0.087772
                         3 -0.007887 -0.007887
                                                   0.009051
                                                               -0.007887
17734
```

rear\_brakes\_type transmission\_type \

 $0.0\overline{0}3574$ 

 $0.0\overline{0}2479$ 

```
35051
       -0.037514
                    -0.037514
                                        0.002479
                                                           0.003574
12127 -0.037514
                    -0.037514
                                        0.002479
                                                           0.003574
                     0.076777
17456
       0.083521
                                       0.002479
                                                           0.003574
17734
      -0.007887
                    -0.007887
                                       -0.007887
                                                          -0.006683
       steering type
42769
            0.054712
           -0.040718
35051
12127
           -0.040718
17456
            0.054712
17734
           -0.040718
time: 18.2 ms (started: 2022-11-23 16:45:55 +00:00)
x train.drop(columns = feature list, inplace = True)
x test.drop(columns = feature list, inplace = True)
oot.drop(columns = feature list, inplace = True)
time: 19.5 ms (started: 2022-11-23 16:46:01 +00:00)
x_train_final = pd.concat([x_train, train_woe], axis = 1)
x test final = pd.concat([x test, test woe], axis = 1)
oot final = pd.concat([oot, oot woe], axis = 1)
time: 21.2 ms (started: 2022-11-23 16:46:07 +00:00)
x train final.head()
       policy tenure age of car age of policyholder
population density \
            0.868744
                            0.08
42769
                                              0.346154
8794
            0.383458
35051
                            0.00
                                              0.509615
8794
12127
            0.869126
                            0.00
                                              0.423077
4076
17456
            0.766596
                            0.01
                                              0.307692
27742
                            0.06
17734
            0.031597
                                              0.298077
5410
       airbags is esc
                        is adjustable steering
                                                 is tpms
is parking sensors \
42769
             2
                     0
                                              1
                                                       0
1
35051
             2
                     0
                                              0
                                                       0
1
             2
12127
                     0
                                              0
                                                       0
17456
             2
                     0
                                              1
                                                       0
1
```

```
17734
              6
                      1
                                                1
                                                          1
1
       is parking camera displacement cylinder gear box
turning radius \
42769
                         0
                                     1197
                                                   4
                                                              5
4.8
35051
                         0
                                      796
                                                   3
                                                              5
4.6
12127
                         0
                                      796
                                                   3
                                                              5
4.6
17456
                         0
                                     1197
                                                   4
                                                              5
4.8
17734
                         1
                                     1493
                                                   4
                                                              6
5.2
       length width height
                                gross weight is front fog lights
42769
         3845
                 1735
                          1530
                                         1335
                                                                   1
35051
         3445
                 1515
                          1475
                                         1185
                                                                   0
                                                                   0
12127
         3445
                 1515
                          1475
                                         1185
                                                                   1
17456
         3845
                 1735
                          1530
                                         1335
17734
                 1790
                          1635
                                                                   1
         4300
                                         1720
       is rear window wiper is rear window washer
is rear window defogger
42769
                            0
                                                     0
35051
                            0
                                                     0
12127
                            0
                                                     0
0
17456
                            0
                                                     0
0
17734
                            1
                                                     1
       is_brake_assist
                          is_power_door_locks
                                                is_central_locking
42769
                      1
35051
                      0
                                             0
                                                                   0
                                             0
12127
                      0
                                                                   0
17456
                      1
                                             1
                                                                   1
17734
                      1
                                             1
                                                                   1
       is power steering
                            is driver seat height adjustable
42769
                         1
                                                              1
                         1
35051
                                                              0
                         1
                                                              0
12127
                         1
17456
                                                              1
17734
                         1
                                                              1
```

```
is day night rear view mirror is ecw
                                                is speed alert
ncap_rating \(\bar{\}\)
42769
                                     1
                                             1
                                                              1
2
35051
                                     0
                                             0
                                                              1
                                             0
12127
                                     0
                                                              1
17456
                                     1
                                             1
                                                              1
2
17734
                                     0
                                             1
                                                              1
3
                             segment
       area cluster
                      make
                                          model
                                                 fuel type
max torque \
           0.104014
42769
                                       0.076777
                                                               0.083521
                         1
                            0.090258
                                                  0.043882
35051
           0.104014
                         1 -0.060953 -0.037514
                                                 -0.053764
                                                              -0.037514
12127
           0.116440
                         1 -0.060953 -0.037514
                                                 -0.053764
                                                              -0.037514
17456
           0.127955
                            0.090258 0.076777
                                                  0.043882
                                                               0.083521
17734
          -0.087772
                         3 -0.007887 -0.007887
                                                  0.009051
                                                              -0.007887
       max power
                  engine type
                                rear brakes type transmission type \
                      0.0\overline{7}6777
42769
        0.083521
                                         0.002479
                                                             0.003574
35051
       -0.037514
                     -0.037514
                                         0.002479
                                                             0.003574
12127
       -0.037514
                     -0.037514
                                         0.002479
                                                             0.003574
17456
        0.083521
                      0.076777
                                         0.002479
                                                             0.003574
17734
      -0.007887
                     -0.007887
                                        -0.007887
                                                            -0.006683
       steering type
            0.0\overline{5}4712
42769
35051
           -0.040718
12127
           -0.040718
17456
            0.054712
17734
           -0.040718
time: 31 ms (started: 2022-11-23 16:46:07 +00:00)
x test final.head()
       policy_tenure age_of_car age_of_policyholder
population density \
24307
            0.867852
                             0.02
                                               0.653846
4076
57327
            1.090563
                             0.17
                                               0.451923
8794
```

```
24703
            1.088634
                             0.18
                                               0.423077
8794
                                               0.605769
                             0.01
40585
            0.913375
4076
                             0.04
17527
            0.745566
                                               0.576923
6108
       airbags is esc is adjustable steering is tpms
is parking sensors
24307
                      0
                                               0
                                                         0
             2
1
57327
             2
                      0
                                               1
                                                         0
1
             2
24703
                      0
                                               1
                                                         0
1
40585
             6
                      1
                                               1
                                                         1
17527
             2
                      0
                                               0
                                                         0
1
       is parking camera displacement cylinder gear box
turning radius \
24307
                        0
                                     796
                                                 3
                                                            5
4.6
57327
                                    1498
                                                            5
                        1
                                                  4
4.9
24703
                        0
                                    1197
                                                 4
                                                            5
4.8
40585
                        1
                                    1493
                                                 4
                                                            6
5.2
                                                            5
17527
                        0
                                     796
                                                  3
4.6
       length width
                       height gross_weight is_front_fog_lights
         3445
                1515
                         1475
24307
                                        1185
57327
         3995
                                        1051
                                                                 1
                1695
                         1501
                                                                 1
24703
         3845
                1735
                         1530
                                        1335
40585
         4300
                1790
                         1635
                                        1720
                                                                 1
17527
                                                                 0
         3445
                1515
                         1475
                                        1185
       is rear window wiper is rear window washer
is rear window defogger
24307
                           0
                                                    0
0
57327
                           0
                                                    0
1
24703
                           0
                                                    0
40585
                           1
                                                    1
1
```

```
17527
                            0
                                                     0
0
                          is power door locks
                                                is central locking
       is brake assist
24307
                      0
57327
                      0
                                             1
                                                                   1
                      1
                                             1
                                                                   1
24703
                      1
                                             1
                                                                   1
40585
                      0
                                             0
                                                                   0
17527
                            is_driver_seat_height_adjustable
       is_power_steering
24307
                         1
                                                              1
57327
24703
                         1
                                                              1
                         1
40585
                                                              1
17527
                         1
                                                              0
       is day night rear view mirror
                                         is ecw
                                                  is speed alert
ncap_rating \
24307
                                              0
                                      0
                                                                1
57327
                                      1
                                              1
                                                                1
4
24703
                                      1
                                              1
                                                                1
40585
                                      0
                                              1
                                                                1
3
17527
                                      0
                                              0
                                                                1
0
       area cluster
                      make
                              segment
                                           model
                                                   fuel type
max_torque \
24307
                          1 -0.060953 -0.037514
           0.116440
                                                   -0.053764
                                                                -0.037514
57327
           0.104014
                          5 -0.010470 -0.029199
                                                    0.009051
                                                                -0.029199
24703
           0.104014
                             0.090258
                                        0.076777
                                                    0.043882
                                                                 0.083521
40585
           0.116440
                          3 -0.007887 -0.007887
                                                    0.009051
                                                                -0.007887
17527
           -0.105572
                          1 -0.060953 -0.037514
                                                   -0.053764
                                                                -0.037514
                   engine type
                                 rear brakes type
                                                     transmission type
       max power
24307
       -0.037514
                     -0.037514
                                          0.002479
                                                               0.003574
57327
       -0.029199
                     -0.029199
                                          0.002479
                                                               0.003574
24703
        0.083521
                      0.076777
                                          0.002479
                                                               0.003574
40585
       -0.007887
                     -0.007887
                                         -0.007887
                                                              -0.006683
17527
       -0.037514
                     -0.037514
                                          0.002479
                                                               0.003574
```

```
steering_type
24307
            -0.040718
57327
             0.054712
24703
             0.054712
40585
            -0.040718
17527
            -0.040718
time: 32.1 ms (started: 2022-11-23 16:46:18 +00:00)
oot final.head()
  policy_id
             policy_tenure age_of_car
                                          age of policyholder
    ID58593
                   0.341732
                                    \overline{0}, 00
0
                                                       0.586538
                                    0.13
1
    ID58594
                   0.307241
                                                       0.442308
2
    ID58595
                   0.327924
                                    0.12
                                                       0.451923
3
                                    0.01
    ID58596
                   0.782654
                                                       0.461538
4
    ID58597
                   1.233404
                                    0.02
                                                       0.634615
   population density airbags is esc is adjustable steering
is_tpms \
                  4076
                               2
                                                                 0
0
                                       0
0
1
                               2
                  8794
                                       0
                                                                 1
0
2
                               2
                  8794
                                       0
                                                                 0
0
3
                 34738
                               2
                                       0
                                                                 0
0
4
                               2
                                       0
                                                                 0
                 34738
0
                                                            cylinder
   is_parking_sensors is_parking_camera displacement
gear_box \
                     1
                                          0
                                                       796
                                                                   3
0
5
1
                     1
                                          0
                                                      1197
                                                                   4
5
2
                     0
                                          1
                                                      999
                                                                   3
5
3
                     1
                                          0
                                                       796
                                                                   3
5
4
                                                       796
                                                                   3
                     1
                                          0
5
   turning radius length width height gross weight
is front fog lights
                      3445
0
               4.6
                              1515
                                      1475
                                                     1185
0
1
               4.8
                      3845
                              1735
                                      1530
                                                     1335
```

```
1
2
                5.0
                        3731
                                1579
                                         1490
                                                         1155
0
3
                4.6
                        3445
                                1515
                                         1475
                                                         1185
0
4
                4.6
                                                         1185
                        3445
                                1515
                                         1475
0
                            is rear window washer
   is_rear_window_wiper
is_rear_window_defogger
                                                   0
0
1
                         0
                                                   0
0
2
                         0
                                                   0
0
3
                                                   0
                         0
0
4
                         0
                                                   0
0
                                              is_central_locking
   is_brake_assist
                      is_power_door_locks
0
1
                   1
                                           1
                                                                  1
2
                   0
                                           1
                                                                  1
3
                   0
                                           0
                                                                  0
4
                   0
                                           0
                                                                  0
                         is_driver_seat_height_adjustable
   is_power_steering
0
                                                            10
1
                     1
2
                     1
3
                     1
                                                            0
4
                                                            0
   is_day_night_rear_view_mirror
                                     is_ecw is_speed_alert ncap_rating
\
0
                                   0
                                            0
                                                               1
                                                                              0
1
                                   1
                                                               1
                                                                              2
                                            1
2
                                                                              2
                                   1
                                            1
                                                               1
3
                                   0
                                            0
                                                               1
                                                                              0
4
                                   0
                                            0
                                                               1
                                                                              0
```

area\_cluster make segment model fuel\_type max\_torque

```
max power \
                    1 -0.060953 -0.037514
       0.116440
                                           -0.053764
                                                        -0.037514 -
0.037514
       0.104014
                    1 0.090258 0.076777
                                            0.043882
                                                        0.083521
0.083521
       0.104014
                    2 -0.060953 -0.212061
                                            0.043882
                                                        -0.212061
0.212061
                    1 -0.060953 -0.037514
                                           -0.053764
                                                        -0.037514
      -0.095075
0.037514
      -0.095075
                    1 -0.060953 -0.037514
                                           -0.053764
                                                        -0.037514 -
0.037514
                rear brakes type transmission type
   engine type
                                                     steering type
0
     -0.037514
                        0.002479
                                           0.003574
                                                          -0.040718
1
      0.076777
                        0.002479
                                           0.003574
                                                          0.054712
2
     -0.212061
                        0.002479
                                          -0.006683
                                                          0.054712
3
     -0.037514
                        0.002479
                                           0.003574
                                                          -0.040718
4
     -0.037514
                        0.002479
                                           0.003574
                                                          -0.040718
time: 29 ms (started: 2022-11-23 16:46:23 +00:00)
Hyperparameter tuning
# parameters that will be used for Random Seacrh CV
params = {'num leaves': [8, 12, 16, 20, 25],
           'subsample': [0.5, 0.7, 0.9],
           'colsample bytree': [0.4, 0.5, 0.6, 0.7, 0.8],
           'reg_alpha': [0, 1e-1, 1, 5, 7, 10, 50],
           'reg lambda': [0, 1e-1, 1, 5, 10, 50],
           'learning rate': [0.015, 0.02, 0.03, 0.05, 0.07, 0.1, 0.2,
0.3],
           'n estimators': [100, 120, 140, 150]}
time: 1.95 ms (started: 2022-11-23 16:46:28 +00:00)
lgbm = LGBMClassifier(objective = 'binary', is unbalance = True,
random state = 1)
time: 1.04 ms (started: 2022-11-23 16:46:32 +00:00)
# performing Random Search on the above mentioned hyperparameters with
'f1' score as a metric
model lgbm = RandomizedSearchCV(estimator = lgbm,
                            param distributions = params,
                            n iter = 30,
                            scoring = 'f1',
                            cv = 3,
                            random state = 1,
                            verbose = 1)
model lgbm.fit(x train final, y train)
```

```
Fitting 3 folds for each of 30 candidates, totalling 90 fits
RandomizedSearchCV(cv=3,
                   estimator=LGBMClassifier(is unbalance=True,
                                             objective='binary',
                                             random state=1),
                   n iter=30,
                   param distributions={'colsample bytree': [0.4, 0.5,
0.6, 0.7,
                                                              0.8],
                                         'learning rate': [0.015, 0.02,
0.03,
                                                           0.05, 0.07,
0.1, 0.2,
                                                            0.3],
                                         'n estimators': [100, 120,
140, 150],
                                         'num leaves': [8, 12, 16, 20,
25],
                                         'reg alpha': [0, 0.1, 1, 5, 7,
10, 50],
                                         'reg_lambda': [0, 0.1, 1, 5,
10, 50],
                                         'subsample': [0.5, 0.7, 0.9]},
                   random state=1, scoring='f1', verbose=1)
time: 1min 14s (started: 2022-11-23 16:46:32 +00:00)
# best score using our LGBM Model
model lgbm.best score
0.1696347022813929
time: 4.18 ms (started: 2022-11-23 16:48:12 +00:00)
# best Parameteres for our LGBM Model
model_lgbm.best_params_
{'subsample': 0.9,
 'reg lambda': 0,
 'reg alpha': 0.1,
 'num leaves': 8,
 'n estimators': 140,
 'learning rate': 0.015,
 'colsample bytree': 0.5}
time: 3.81 ms (started: 2022-11-23 16:48:15 +00:00)
# defining LGBM Model based on Best parameters
lgbm_best = LGBMClassifier(objective = 'binary',
                           colsample by tree = 0.5,
                           subsample = 0.9,
```

```
is unbalance = True,
                       learning rate = 0.015,
                       num leaves = 8,
                       \max depth = 5,
                       reg lambda = 0,
                       reg alpha = 0.1,
                       n = 140,
                       random state = 1)
time: 1.51 ms (started: 2022-11-23 16:48:38 +00:00)
# fitting on Train data
y pred train lgbm = lgbm best.fit(x train final, y train)
time: 1.16 s (started: 2022-11-23 16:48:41 +00:00)
# predicting on the Test data
y pred test lgbm = lgbm best.predict(x test final)
time: 37.5 ms (started: 2022-11-23 16:48:48 +00:00)
''' function to evaluate our model using different metrics '''
# values to be passed :
# model name = Our Model name, model = classifier used used to
predict, y train pred, y test pred, x train, x test
def evaluate_model(model_name, model, y_train_pred, y_test_pred,
x train, x test):
   print('Printing various Evaluation metrics for our
'+str(model_name)+' model.....')
   print('\n')
# Printing Train & Test Accuracy scores
   print("Train Accuracy :", accuracy_score(y_train,
model.predict(x train)))
   print("Test Accuracy :", accuracy_score(y_test,
model.predict(x test)))
   print('\n')
   print("="*60)
   print('\n')
********************************
```

```
# Printing Confusion Matrix for Train & Test data
   print("Train Confusion Matrix:")
   print(confusion_matrix(y_train, model.predict(x_train)))
   print("Test Confusion Matrix:")
   print(confusion matrix(y test, model.predict(x test)))
   print('\n')
   print("="*60)
   print('\n')
# Printing classification reports
   # For Train Data
   print("Classification report for our Model's Training data:")
   print("-"*52)
   print(classification_report(y_train, model.predict(x train)))
   print('\n')
   print("="*60)
   print('\n')
   # For Train Data
   print("Classification report for our Model's Test data:")
   print(classification report(y test, model.predict(x test)))
   print('\n')
   print("="*60)
   print('\n')
# Calculating AUC ROC scores
   auc train data = roc auc score(y train, model.predict(x train))
   auc_test_data = roc_auc_score(y_test, model.predict(x_test))
   print("AUC scores for \nTrain data is :", auc train data," & \
nTest data is :", auc_test_data)
   print('\n')
   print("="*60)
   print('\n')
   # Plotting AUC ROC scores for Train & Test data
   # ROC Curve using predict proba method
```

```
print("Plotting AUC ROC curves for Train and Test Data")
   tr fpr, tr tpr, tr thresh = roc curve(y train,
model.predict(x_train))
   te fpr, te tpr, te thresh = roc curve(y test,
model.predict(x test))
   plt.style.use('seaborn')
   # plot roc curves
   plt.plot(tr_fpr, tr_tpr, linestyle='--', color='orange',
label='Train AUC ='+str(auc(tr fpr, tr tpr).round(3)))
   plt.plot(te_fpr, te_tpr, linestyle='--', color='green',
label='Test AUC ='+str(auc(te fpr, te tpr).round(3)))
   # title
   plt.title('ROC curve using '+str(model_name)+' model')
   # x label
   plt.xlabel('False Positive Rate')
   # y label
   plt.ylabel('True Positive rate')
   plt.legend(loc='best')
   plt.show();
   print('\n')
# https://www.quantinsti.com/blog/creating-heatmap-using-python-
seaborn
   # Plotting Train & Test Confusion matrices
   print("Plotting Train and Test Confusion matrices")
   sns.set()
   con m train = confusion matrix(y train, model.predict(x train))
   con m test = confusion matrix(y test, model.predict(x test))
   key = (np.asarray([['TN','FP'], ['FN', 'TP']]))
   fig, ax = plt.subplots(1,2, figsize=(12,5))
   labels train = (np.asarray(["{0}] = {1:.2f}]" .format(key, value)
for key, value in zip(key.flatten(),
con m train.flatten())])).reshape(2,2)
   labels_test = (np.asarray(["{0}] = {1:.2f}]" .format(key, value) for
key, value in zip(key.flatten(), con m test.flatten())])).reshape(2,2)
```

```
sns.heatmap(con m train, linewidths=.5, xticklabels=['PREDICTED :
0', 'PREDICTED: 1'], yticklabels=['ACTUAL: 0', 'ACTUAL: 1'], annot
= labels_train, fmt = '', ax=ax[0], cmap='Blues')
   sns.heatmap(con_m_test, linewidths=.5, xticklabels=['PREDICTED :
0', 'PREDICTED: 1'], yticklabels=['ACTUAL: 0', 'ACTUAL: 1'], annot
= labels test, fmt = '', ax=ax[1], cmap='Blues')
   ax[0].set title('Train Data')
   ax[1].set title('Test Data')
   plt.show()
   print('\n')
*******
   # printing F1-score for Train and Test Datasets
   print('Printing F1-scores for our '+str(model name)+' model')
   print("="*60)
   print('\n')
   # for Train Data
   f1_score_train = f1_score(y_train, model.predict(x_train))
   print('For Train data: \n ', f1_score_train )
   # for test data
   f1_score_test = f1_score(y_test, model.predict(x_test))
   print('For Test data: \n ', f1_score_test )
   print('\n')
*****************
time: 44.3 ms (started: 2022-11-23 17:36:32 +00:00)
Evaluation Metrics
# function to evaluate our model using different metrics
# values to be passed :
# model name = Our Model name, model = classifier used used to
predict, y train pred, y test pred, x train, x test
model name = 'LGBM'
evaluate model(model name, lgbm best, y pred train lgbm,
y_pred_test_lgbm, x_train_final, x_test_final);
```

Printing various Evaluation metrics for our LGBM model.....

Train Accuracy : 0.7122240764621103 Test Accuracy : 0.7136518771331058

\_\_\_\_\_

Train Confusion Matrix:
[[35909 13450]
 [ 1725 1648]]
Test Confusion Matrix:
[[4000 1485]
 [ 193 182]]

\_\_\_\_\_

# Classification report for our Model's Training data:

	precision	recall	f1-score	support
0 1	0.95 0.11	0.73 0.49	0.83 0.18	49359 3373
accuracy macro avg weighted avg	0.53 0.90	0.61 0.71	0.71 0.50 0.78	52732 52732 52732

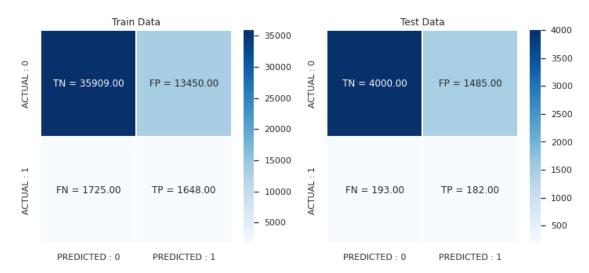
\_\_\_\_\_\_

## Classification report for our Model's Test data:

	precision	recall	f1-score	support
0 1	0.95 0.11	0.73 0.49	0.83 0.18	5485 375
accuracy macro avg weighted avg	0.53 0.90	0.61 0.71	0.71 0.50 0.79	5860 5860 5860

\_\_\_\_\_\_

#### Plotting Train and Test Confusion matrices



#### Printing F1-scores for our LGBM model

\_\_\_\_\_\_

For Train data:

0.17844188186887555

For Test data:

0.178256611165524

#### time: 2.1 s (started: 2022-11-23 16:53:32 +00:00)

# storing fl scores of Train and Test data in another variable to tabulate them at a larger stage

 $f1\_Score\_train\_LGBM = 0.17844188186887555$  $f1\_Score\_test\_LGBM = 0.178256611165524$ 

time: 621 μs (started: 2022-11-23 17:37:24 +00:00)

print("F1-score of Train data using LGBM is : ", f1\_Score\_train\_LGBM)
print("F1-score of Test data using LGBM is : ", f1\_Score\_test\_LGBM)

F1-score of Train data using LGBM is: 0.17844188186887555 F1-score of Test data using LGBM is: 0.178256611165524 time: 1.66 ms (started: 2022-11-23 17:52:37 +00:00)

```
# Modelling - Catboost
# loading train data
df train = pd.read csv('train qWM28Yl.csv')
df train.head(2)
  policy id policy tenure age of car age of policyholder
area cluster \
    ID00001
                   0.515874
                                   0.05
                                                      0.644231
C1
1
    ID00002
                   0.672619
                                   0.02
                                                      0.375000
C2
   population_density make segment model fuel_type
                                                          max torque
0
                                                        60Nm@3500rpm
                 4990
                           1
                                   Α
                                         Μ1
                                                  CNG
1
                27003
                           1
                                   Α
                                         Μ1
                                                  CNG
                                                        60Nm@3500rpm
          max power
                            engine type airbags is esc
is adjustable steering
  40.36bhp@6000rpm F8D Petrol Engine
                                                2
                                                      No
No
1
  40.36bhp@6000rpm F8D Petrol Engine
                                                2
                                                      No
No
  is tpms is parking sensors is parking camera rear brakes type
displacement \
       No
                          Yes
                                              No
                                                              Drum
796
                          Yes
                                                              Drum
1
       No
                                              No
796
   cylinder transmission type gear box steering type turning radius
length \
          3
                        Manual
                                        5
                                                  Power
                                                                     4.6
3445
                        Manual
                                        5
                                                                     4.6
          3
                                                  Power
1
3445
   width height gross_weight is_front_fog_lights
is rear window wiper \
    151\overline{5}
            14\overline{7}5
0
                           1185
                                                  No
No
    1515
            1475
                           1185
1
                                                  No
No
  is rear window washer is rear window defogger is brake assist \
0
                      No
                                               No
                                                                No
1
                                               No
                      No
                                                                No
  is_power_door_locks is_central_locking is_power_steering \
```

```
0
                                                          Yes
                    No
                                        No
1
                    No
                                        No
                                                          Yes
  is_driver_seat_height_adjustable is_day_night_rear_view mirror
is_ecw \
0
                                  No
                                                                 No
No
1
                                 No
                                                                 No
No
  is_speed_alert ncap_rating
                                is claim
0
                             0
             Yes
                             0
                                        0
1
             Yes
time: 332 ms (started: 2022-11-23 16:58:23 +00:00)
References for Catboost classifier algorithm:
     https://dataaspirant.com/catboost-algorithm/#t-1609567161984
 2. https://catboost.ai/en/docs/
 3.
    https://stackoverflow.com/questions/59746304/catboost-classifier-for-class-
     imbalance
# we have a total of 58k observations in our Train data
df train.shape
(58592, 44)
time: 7.54 ms (started: 2022-11-23 17:00:35 +00:00)
df train.info()
# all the columns are not-null and this will help us a lot
<class 'pandas.core.frame.DataFrame'>
RangeIndex: 58592 entries, 0 to 58591
Data columns (total 44 columns):
#
     Column
                                         Non-Null Count Dtype
 0
     policy id
                                         58592 non-null
                                                          obiect
                                         58592 non-null
 1
     policy_tenure
                                                          float64
 2
                                         58592 non-null float64
     age of car
 3
     age_of_policyholder
                                         58592 non-null
                                                          float64
 4
     area cluster
                                         58592 non-null
                                                          object
 5
     population_density
                                         58592 non-null
                                                          int64
 6
     make
                                         58592 non-null
                                                          int64
 7
     segment
                                         58592 non-null
                                                          object
 8
     model
                                         58592 non-null
                                                          object
 9
                                         58592 non-null
                                                          object
     fuel type
```

58592 non-null

58592 non-null

58592 non-null

58592 non-null

object

object

object

int64

10 max torque

airbags

max power

engine type

11

12

13

```
14 is esc
                                      58592 non-null
                                                      object
 15 is adjustable steering
                                      58592 non-null object
                                      58592 non-null object
 16 is_tpms
 17 is parking sensors
                                      58592 non-null object
                                      58592 non-null object
 18 is parking camera
                                      58592 non-null object
 19 rear_brakes_type
 20 displacement
                                      58592 non-null int64
 21 cylinder
                                      58592 non-null int64
 22 transmission type
                                      58592 non-null object
 23 gear box
                                      58592 non-null int64
                                      58592 non-null object
 24 steering_type
                                      58592 non-null
 25 turning_radius
                                                      float64
 26 length
                                      58592 non-null
                                                      int64
 27 width
                                      58592 non-null int64
 28 height
                                      58592 non-null
                                                      int64
 29 gross_weight
                                      58592 non-null int64
 30 is front fog lights
                                      58592 non-null object
                                      58592 non-null object
 31 is_rear_window_wiper
 32 is rear window washer
                                      58592 non-null object
 33 is_rear_window_defogger
                                      58592 non-null
                                                      object
 34 is brake assist
                                      58592 non-null
                                                      object
 35 is power_door_locks
                                      58592 non-null object
 36 is central locking
                                      58592 non-null object
 37 is power steering
                                      58592 non-null object
 38 is driver seat height adjustable 58592 non-null
                                                      object
 39 is day night rear view mirror
                                      58592 non-null
                                                      object
                                      58592 non-null
 40 is ecw
                                                      object
 41
    is speed alert
                                      58592 non-null
                                                      object
42
    ncap rating
                                      58592 non-null
                                                      int64
    is_claim
 43
                                      58592 non-null
                                                      int64
dtypes: float64(4), int64(12), object(28)
memory usage: 19.7+ MB
time: 94.7 ms (started: 2022-11-23 17:00:39 +00:00)
df train.describe()
       policy tenure
                       age of car
                                   age of policyholder
population density \
       58592.000000 58592.000000
                                          58592.000000
count
58592.000000
           0.611246
                         0.069424
                                              0.469420
mean
18826.858667
           0.414156
                         0.056721
                                              0.122886
std
17660.174792
           0.002735
                         0.000000
                                              0.288462
min
290.000000
                                              0.365385
25%
           0.210250
                         0.020000
6112.000000
           0.573792
50%
                         0.060000
                                              0.451923
8794.000000
```

0.110000

75%

1.039104

0.548077

27003.000000 1.000000 1.000000 1.396641 max 73430.000000 make airbags displacement cylinder gear box \ 58592.000000 58592.000000 count 58592.000000 58592.000000 58592.000000 1.763722 3.137066 1162.355851 3.626963 mean 5.245443 266.304786 std 1.136988 1.832641 0.483616 0.430353 1.000000 1.000000 796.000000 3.000000 min 5.000000 25% 1.000000 2.000000 796.000000 3.000000 5.000000 50% 1.000000 2.000000 1197.000000 4.000000 5.000000 6.000000 75% 3.000000 1493.000000 4.000000 5.000000 6.000000 1498.000000 5.000000 4.000000 max 6.000000 turning radius length width height gross weight 58592.000000 count 58592.000000 58592.000000 58592.00000 58592.000000 3850.476891 4.852893 1672.233667 1553.33537 mean 1385.276813 0.228061 311.457119 112.089135 79.62227 std 212,423085 4.500000 3445.000000 1475.000000 1475.00000 min 1051.000000 25% 4.600000 3445.000000 1515.000000 1475.00000 1185.000000 50% 4.800000 3845.000000 1735.000000 1530.00000 1335.000000 75% 5.000000 3995.000000 1755.000000 1635.00000 1510.000000 4300.000000 1811.000000 1825.00000 5.200000 max 1720.000000

	ncap_rating	is_claim
count	58592.000000	58592.000000
mean	1.759950	0.063968
std	1.389576	0.244698
min	0.000000	0.000000
25%	0.000000	0.000000
50%	2.000000	0.000000

75% 3.000000 0.000000 max 5.000000 1.000000

time: 92 ms (started: 2022-11-23 17:00:43 +00:00)

# train.select\_dtypes(include = ['int64']) This gives you a filtered
dataframe where the dataframe is entirely NUMERIC dedicated.
# Similarly, when you perform train\_df.dscribe(include = ['0']) it
pulls out the objects dtypes attributes and shows their
count/frequency/max/quartiles.

time: 567 μs (started: 2022-11-23 17:59:57 +00:00)

df train.describe(include=['0'])

\	<pre>policy_id</pre>	area_cluster	segment	model	fuel_type	max_torque
count	58592	58592	58592	58592	58592	58592
unique	58592	22	6	11	3	9
top	ID00001	C8	B2	M1	Petrol	113Nm@4400rpm
freq	1	13654	18314	14948	20532	17796

	max_power	engine_type	is_esc
	stable_steering \	E0E03	E0E02
count 58592	58592	58592	58592
unique	9	11	2
2	3		۷
top	88.50bhp@6000rpm	F8D Petrol Engine	No
Yes			
freq	17796	14948	40191
35526			

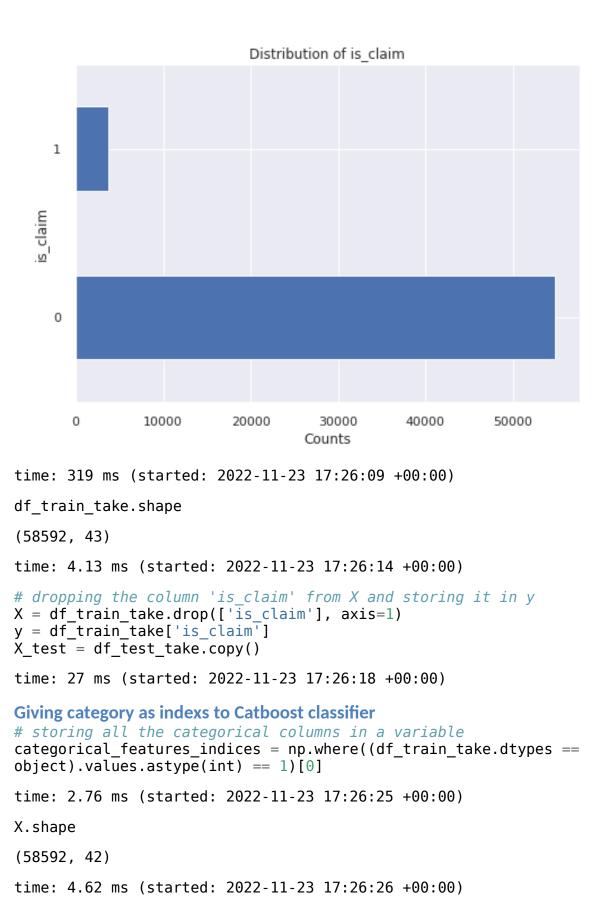
is tpms is parking sensors is parking camera rear brakes type \ count 58592 58592 58592 58592 2 2 unique 2 2 No Yes No Drum top 56219 35704 freq 44574 44574

transmission\_type steering\_type is\_front\_fog\_lights \
count 58592 58592 58592

```
unique
                       2
                                      3
                                                          2
                  Manual
top
                                  Power
                                                        Yes
freq
                   38181
                                  33502
                                                      33928
       is rear window wiper is rear window washer
is rear window defogger \
count
                      58592
                                             58592
58592
                          2
                                                 2
unique
2
                                                No
top
                         No
No
freq
                      41634
                                             41634
38077
       is_brake_assist is_power_door_locks is_central_locking \
count
                 58592
                                      58592
                                                         58592
unique
                     2
                                                              2
                                          2
top
                   Yes
                                        Yes
                                                           Yes
                                                         42435
freq
                 32177
                                      42435
       is power steering is driver seat height adjustable \
                                                     58592
count
                   58592
                       2
                                                         2
unique
top
                     Yes
                                                       Yes
freq
                   57383
                                                     34291
       is day night rear view mirror is ecw is speed alert
count
                                58592 58592
                                                      58592
unique
                                    2
                                           2
                                                          2
top
                                   No
                                         Yes
                                                        Yes
freq
                                36309 42435
                                                      58229
time: 271 ms (started: 2022-11-23 17:00:47 +00:00)
# loading Test data
df test = pd.read csv('test zo1G9sv.csv')
df test.head(2)
  policy id policy tenure age of car age of policyholder
area cluster \
    ID58593
                                   0.00
                  0.341732
                                                    0.586538
C3
                  0.307241
                                   0.13
1
    ID58594
                                                    0.442308
C8
   population density make segment model fuel type
                                                         max torque \
                 4076
0
                          1
                                        Μ1
                                                 CNG
                                                        60Nm@3500rpm
                                   Α
1
                 8794
                          1
                                  B2
                                        М6
                                              Petrol
                                                      113Nm@4400rpm
```

```
max power
                            engine type airbags is esc
is adjustable steering \
0 40.36bhp@6000rpm F8D Petrol Engine
                                                2
                                                       No
No
1 88.50bhp@6000rpm K Series Dual jet
                                                2
                                                       No
Yes
  is_tpms is_parking_sensors is_parking_camera rear_brakes_type
displacement \
0
       No
                          Yes
                                              No
                                                              Drum
796
       No
                          Yes
                                              No
                                                              Drum
1197
   cylinder transmission type gear box steering type turning radius
length
          3
                        Manual
                                        5
                                                   Power
                                                                      4.6
3445
                        Manual
                                        5
                                                                      4.8
1
          4
                                               Electric
3845
   width height gross weight is front fog lights
is rear window wiper \
    151\overline{5}
            14\overline{7}5
                           1185
                                                   No
No
    1735
            1530
                           1335
                                                  Yes
1
No
  is rear window washer is rear window defogger is brake assist \
0
                      No
                                               No
                                                                No
1
                      No
                                               No
                                                               Yes
  is power door locks is central locking is power steering
0
                    No
                                        No
                                                          Yes
                                       Yes
1
                   Yes
                                                          Yes
  is driver seat height adjustable is day night rear view mirror
is ecw \
                                  No
                                                                  No
0
No
                                 Yes
                                                                 Yes
1
Yes
  is speed alert ncap rating
0
             Yes
                             0
                             2
1
             Yes
time: 230 ms (started: 2022-11-23 17:00:55 +00:00)
```

```
df test.shape
# we have a total of 39k observations in our Test data
(39063, 43)
time: 3.58 ms (started: 2022-11-23 17:00:55 +00:00)
# copying Train and Test data into new DataFrames
df train take = df train.copy()
df test \overline{t}ake = df \overline{t}est.copy()
time: 20.5 ms (started: 2022-11-23 17:00:56 +00:00)
# removing policy id columns from the new DataFrames
df train take.drop(['policy id'], axis = 1, inplace = True)
df test take.drop(['policy id'], axis =1, inplace = True)
time: 30.5 ms (started: 2022-11-23 17:01:00 +00:00)
df_train['is_claim'].value_counts()
# this data is very much imbalanced
0
     54844
      3748
1
Name: is claim, dtype: int64
time: 6.84 ms (started: 2022-11-23 17:01:00 +00:00)
df train['is claim'].value counts( normalize = True)
# this data is very much imbalanced
0
     0.936032
1
     0.063968
Name: is_claim, dtype: float64
time: 9.63 ms (started: 2022-11-23 17:01:03 +00:00)
df train['is claim'].value counts().plot(kind='barh')
plt.xlabel('Counts')
plt.ylabel('is_claim')
plt.title('Distribution of is claim')
plt.show()
# from the plot we can clearly see that Data is imbalanced
```



```
# splitting data into train and validation with 30% of validation data
X train, X val, y train, y val = train test split(X, y, test size =
0.3, random state = 42)
time: 43.9 ms (started: 2022-11-23 17:34:48 +00:00)
# shape of training and testing data sets
X train.shape, X val.shape
((41014, 42), (17578, 42))
time: 4.08 ms (started: 2022-11-23 17:34:54 +00:00)
# implementing Catboost with default parameters and scale pos weight =
10
catboost base = CatBoostClassifier( random state = 1, scale pos weight
= 10, verbose = False)
catboost base.fit(X train, y train, cat features =
categorical features indices, eval set = (X val, y val))
print('\n')
time: 1min 54s (started: 2022-11-23 17:32:54 +00:00)
# predicting on the Train data
y train pred CB = catboost base.predict(X train)
# predicting on the Validaiton data
y test pred CB = catboost base.predict(X val)
# predicting on the actual given Test data
y pred = catboost base.predict(X test)
time: 655 ms (started: 2022-11-23 17:35:07 +00:00)
Evaluation Metrics
# function to evaluate our model using different metrics
# values to be passed :
# model name = Our Model name, model = classifier used used to
predict, y train pred, y test pred, x train, x test
y_test = y_val
model name = 'Catboost Classifier'
evaluate model(model name, catboost base, y train pred CB,
y test pred CB, X train, X val);
Printing various Evaluation metrics for our Catboost Classifier
model......
```

Train Accuracy: 0.823621202516214 Test Accuracy: 0.8152804642166345

\_\_\_\_\_

Train Confusion Matrix: [[32978 5449]

[ 1785 802]]

Test Confusion Matrix:

[[13996 2421] [ 826 335]]

------

## Classification report for our Model's Training data:

	precision	recall	f1-score	support
0 1	0.95 0.13	0.86 0.31	0.90 0.18	38427 2587
accuracy macro avg weighted avg	0.54 0.90	0.58 0.82	0.82 0.54 0.86	41014 41014 41014

\_\_\_\_\_\_

## Classification report for our Model's Test data:

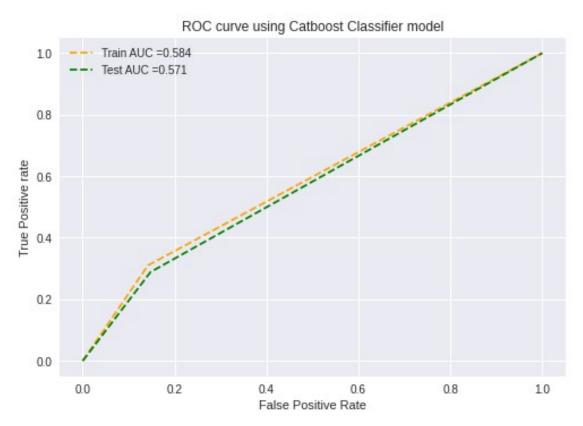
	precision	recall	f1-score	support
0 1	0.94 0.12	0.85 0.29	0.90 0.17	16417 1161
accuracy macro avg weighted avg	0.53 0.89	0.57 0.82	0.82 0.53 0.85	17578 17578 17578

AUC scores for

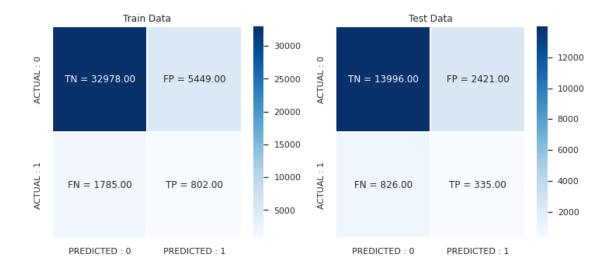
Train data is : 0.5841051294212958 &

Test data is : 0.5705376356948536

### Plotting AUC ROC curves for Train and Test Data



Plotting Train and Test Confusion matrices



# Printing F1-scores for our Catboost Classifier model

For Train data:

```
0.18148902466621408
For Test data:
  0.17104927240234874
time: 3.92 s (started: 2022-11-23 17:36:39 +00:00)
# storing f1 scores of Train and Test data in another variable to
tabulate them at a larger stage
f1 Score train CB = 0.18148902466621408
f1 Score test CB = 0.17104927240234874
time: 10.3 ms (started: 2022-11-23 17:38:19 +00:00)
print("F1-score of Train data using Cathoost Classifier is : ",
f1 Score train CB)
print("F1-score of Test data using Cathoost Classifier is : ",
f1 Score test CB)
F1-score of Train data using Catboost Classifier is :
0.18148902466621408
F1-score of Test data using Catboost Classifier is :
0.17104927240234874
time: 3.09 ms (started: 2022-11-23 17:53:18 +00:00)
# predicting the given test data with our model
y_pred = catboost_base.predict(X_test)
```

```
time: 269 ms (started: 2022-11-23 17:38:46 +00:00)
# loading the sample submission file given to us
submission df = pd.read csv('sample submission KvRh9Sx.csv')
submission df.head(2)
  policy id is claim
    ID58593
                    1
1
    ID58594
time: 605 ms (started: 2022-11-23 17:38:50 +00:00)
# taking the 'policy id' given in our test data to our submission
DataFrame
submission df['policy id'] = df test['policy id']
time: 4.47 ms (started: 2022-11-23 17:38:54 +00:00)
# storing the predicted value in 'is claim' column of our submission
DataFrame
submission df['is claim'] = y pred
time: 1.44 ms (started: 2022-11-23 17:38:57 +00:00)
print("Percentage of each status present in our column 'is claim'")
(submission df['is claim'].value counts(normalize = True) ) * 100
Percentage of each status present in our column 'is claim'
0
     84.3714
     15.6286
1
Name: is claim, dtype: float64
time: 18.7 ms (started: 2022-11-23 17:47:59 +00:00)
print("Occurrences of each status present in our column 'is claim'")
submission df['is claim'].value counts()
Occurrences of each status present in our column 'is claim'
0
     32958
1
      6105
Name: is claim, dtype: int64
time: 14.8 ms (started: 2022-11-23 17:48:21 +00:00)
# storing our submission results into a csv file
submission df.to csv('submission catboost best.csv', index = False) #
index = False to avoid row index values in our CSV
time: 695 ms (started: 2022-11-23 17:39:05 +00:00)
```

```
# Tabulating our results
from prettytable import PrettyTable
# initializing a table
table = PrettyTable()
# adding title
table.title = "Peformance of Insurance Claim Prediction modelling
overview"
# adding fields
table.field_names = ["Model", "Test F1-score"]
# adding rows to our table
table.add row(['LGBM', f1 Score test LGBM])
table.add_row(['Catboost Classifier', f1_Score_test_CB])
# printing the table
print(table)
+----+
| Peformance of Insurance Claim Prediction modelling overview |
÷-----
| Model | Test F1-score | +-----
time: 3.51 ms (started: 2022-11-23 17:49:10 +00:00)
```