

Proposition Let $\underline{A} \in \mathbb{R}^{m \times n}$ and \underline{U} be the row echelon form of \underline{A} . Then we have:

(i) $\kappa(\underline{A}) = \kappa(\underline{U})$, Hence $\dim \kappa(\underline{A}) = \dim \kappa(\underline{U})$;

(ii) $\dim c(\underline{A}) = \dim c(\underline{U})$.

Proof: (i) We first note that if u, v are vectors in a vector space X then

$$\text{span}\{u, v\} = \text{span}\{\alpha u, \beta v\} = \text{span}\{u, v + \alpha u\}$$

where α, β are nonzero real numbers. Indeed,

let $w = au + b(v + \alpha u)$ where $a, b \in \mathbb{R}$. Then

$$w = (a + b\alpha)u + bv \in \text{span}\{u, v\}.$$

On the other hand, if $c, d \in \mathbb{R}$, Then

$$cu + dv = cu + d(v + \alpha u) - d\alpha u$$

$$= (c - d\alpha)u + d(v + \alpha u) \in \text{span}\{u, v + \alpha u\}.$$

It is easy to see that the first two linear spans are the same. Thus the elementary row operations do not alter the row space of \underline{A} .

(ii) Suppose $\dim c(\underline{A}) = r$.

Without loss of generality, we may assume that the first r columns $\underline{C}_1, \dots, \underline{C}_r$ of \underline{A} are L.I.

Let \underline{B} be an invertible $m \times m$ matrix such that

$$\underline{U} = \underline{B} \underline{A}.$$

By the previous lemma, the columns

$$\underline{B} \underline{C}_1, \dots, \underline{B} \underline{C}_r \text{ of } \underline{B} \underline{A} \text{ are L.I.}$$

Hence $\dim c(\underline{U}) \geq r = \dim c(\underline{A})$.

On the other hand, since $\underline{A} = \underline{B}^{-1} \underline{U}$,

$$\dim c(\underline{A}) \geq \dim c(\underline{U}).$$

Thus, $\dim c(\underline{U}) = \dim c(\underline{A})$. ■

Theorem Let $\underline{A} \in \mathbb{R}^{m \times n}$. Then

$$\dim r(\underline{A}) = \dim c(\underline{A}).$$

Proof. We give an argument in a special case.

The general argument is similar.

Suppose that the row echelon form \underline{U} of \underline{A} looks like:

$$\underline{U} = \begin{bmatrix} d_1 & * & * & * & * & * \\ 0 & 0 & 0 & d_2 & * & * \\ 0 & 0 & 0 & 0 & 0 & d_3 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix},$$

where d_1, d_2, d_3 are the pivots.

Take a linear combination of the columns containing ^{pivots:} The \underline{v}

$$\alpha_1 \begin{bmatrix} d_1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} * \\ d_2 \\ 0 \\ 0 \end{bmatrix} + \alpha_3 \begin{bmatrix} * \\ * \\ d_3 \\ 0 \end{bmatrix} = \begin{bmatrix} \alpha_1 d_1 + \dots \\ \alpha_2 d_2 + \dots \\ \alpha_3 d_3 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

By back substitution, we obtain $\alpha_3 = \alpha_2 = \alpha_1 = 0$.
Thus the columns containing the pivots are L.I.

In a like manner, the nonzero rows of \underline{U} (rows containing the pivots) are L.I.

Hence $\dim \kappa(\underline{U}) = \dim c(\underline{U})$.

In conjunction with the previous proposition, we obtain

$$\dim \kappa(\underline{A}) = \dim \kappa(\underline{U}) = \dim c(\underline{U}) = \dim c(\underline{A}). \quad \blacksquare$$

Definition The rank of an $m \times n$ matrix A denoted by $\text{rank}(A)$ is $\dim \mathcal{C}(A) = \dim \mathcal{R}(A)$. The nullity of A denoted by $\text{nullity}(A)$ is the dimension of the null space $\mathcal{N}(A)$ of A .

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The rank-nullity Theorem

Theorem :

Let A be an $m \times n$ matrix. Then

$$\text{rank } A + \text{nullity } A = n.$$

Proof :

Suppose that $\text{rank } A = r$. Hence there are r linearly independent columns in A . For simplicity of argument we assume that the first r columns of A are linearly independent.

The columns of A are Ae_1, Ae_2, \dots, Ae_n .

Since the column space $\mathcal{C}(A)$ of A is the linear span of Ae_1, Ae_2, \dots, Ae_r ,

we can express $Ae_{r+1}, Ae_{r+2}, \dots, Ae_n$, as linear combinations of Ae_1, Ae_2, \dots, Ae_r . We write

$$Ae_{r+1} = \alpha_{r+11}Ae_1 + \alpha_{r+12}Ae_2 + \dots + \alpha_{r+1r}Ae_r$$

$$Ae_{r+2} = \alpha_{r+21}Ae_1 + \alpha_{r+22}Ae_2 + \dots + \alpha_{r+2r}Ae_r$$

$$Ae_n = \alpha_{n1}Ae_1 + \alpha_{n2}Ae_2 + \dots + \alpha_{nr}Ae_r.$$

$\text{rank}(A) =$ maximum no. of l.i. row vectors of A

$=$ maximum no. of l.i. column vectors of A

If A is an $m \times n$ matrix, $\text{rank}(A) \leq \min\{m, n\}$.

Hence for $j = r + 1, r + 2, \dots, n$,

$$A \left[e_j - \sum_{k=1}^r \alpha_{jk} e_k \right] = 0$$

Hence for $j = r + 1, \dots, n$,

$$v_j =: e_j - \sum_{k=1}^r \alpha_{jk} e_k \in \mathcal{N}(A)$$

We now show that $\{v_{r+1}, v_{r+2}, \dots, v_n\}$ is a basis of $\mathcal{N}(A)$.

First we show that

any vector v satisfying $Av = 0$ is a linear combination of $v_{r+1}, v_{r+2}, \dots, v_n$.

Let $\beta_1, \beta_2, \dots, \beta_n$ be scalars such that

$$v = \beta_1 e_1 + \beta_2 e_2 + \dots + \beta_n e_n.$$

Then

$$\begin{aligned} Av &= \beta_1 Ae_1 + \beta_2 Ae_2 + \dots + \beta_n Ae_n \\ &= \beta_1 Ae_1 + \dots + \beta_r Ae_r + \sum_{j=r+1}^n \beta_j Ae_j \\ &= \sum_{k=1}^r \beta_k Ae_k + \sum_{j=r+1}^n \beta_j \left[\sum_{k=1}^r \alpha_{jk} Ae_k \right] \\ &= \sum_{k=1}^r \left[\beta_k + \sum_{j=r+1}^n \beta_j \alpha_{jk} \right] Ae_k \end{aligned}$$

Since Ae_1, Ae_2, \dots, Ae_r are linearly independent,

$$\beta_k = - \sum_{j=r+1}^n \beta_j \alpha_{jk} \quad \text{for } k = 1, 2, \dots, r.$$

Substitute this into the expression for v

$$\begin{aligned} v &= \sum_{k=1}^r \beta_k e_k + \sum_{k=r+1}^n \beta_k e_k \\ &= \sum_{k=1}^r \left(- \sum_{j=r+1}^n \beta_j \alpha_{jk} \right) e_k + \sum_{j=r+1}^n \beta_j e_j \\ &= \sum_{j=r+1}^n \beta_j \left[e_j - \sum_{k=1}^r \alpha_{jk} e_k \right] \\ &= \sum_{j=r+1}^n \beta_j v_j \end{aligned}$$

It remains to show $v_{r+1}, v_{r+2}, \dots, v_n$ are linearly independent.

Suppose that $a_{r+1}, \dots, a_n \in \mathbb{R}$ and

$$a_{r+1} \left[e_{r+1} - \sum_{k=1}^r \alpha_{r+1k} e_k \right] + \dots + a_n \left[e_n - \sum_{k=1}^r \alpha_{nk} e_k \right] = 0.$$

Hence

$$a_{r+1} e_{r+1} + a_{r+2} e_{r+2} + \dots + a_n e_n + () e_1 + \dots + () e_r = 0.$$

Therefore $a_{r+1} = a_{r+2} = \dots = a_n = 0$ by linear independence of e_1, e_2, \dots, e_n . Hence v_{r+1}, \dots, v_n are linearly independent. ▀

Fundamental Theorem for Systems of Linear Equations

Theorem Consider the following system of m linear equations in n unknowns x_1, x_2, \dots, x_n :

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} \quad \text{or } \underline{A} \underline{x} = \underline{b} \quad (1)$$

(i) (Existence) The system admits a solution iff

$$\text{rank}(\underline{A}) = \text{rank}(\underline{\tilde{A}})$$

where $\underline{\tilde{A}} = (\underline{A}, \underline{b})$ denotes the augmented matrix of the system (1).

(ii) (Uniqueness) The system admits a unique solution if and only if

$$\text{rank}(\underline{A}) = \text{rank}(\underline{\tilde{A}}) = n$$

(iii) If $\text{rank}(\underline{A}) = \text{rank}(\underline{\tilde{A}}) = r < n$, then the system admits infinitely many solutions

Proof. Let $\underline{C}_1, \dots, \underline{C}_n$ be the columns of \underline{A} . Then

$$\underline{A} \underline{x} = (\underline{C}_1, \dots, \underline{C}_n) \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \underline{C}_1 + \dots + x_n \underline{C}_n.$$

Hence if $\underline{A} \underline{x} = \underline{b}$ has a solution $x_1 = a_1, \dots, x_n = a_n$,

Then $a_1 \underline{C}_1 + a_2 \underline{C}_2 + \dots + a_n \underline{C}_n = \underline{b}.$

This implies that $\underline{b} \in c(\underline{A})$ so \underline{A} and $\tilde{\underline{A}}$ have same column space: $c(\underline{A}) = c(\tilde{\underline{A}}).$

Thus they have equal rank. Conversely, if

$\text{rank}(\underline{A}) = \text{rank}(\tilde{\underline{A}})$, then $\underline{b} \in c(\underline{A}).$

Hence $\underline{b} = d_1 \underline{C}_1 + \dots + d_n \underline{C}_n$ for some scalars

d_1, d_2, \dots, d_n . Then

$$d_1 \underline{C}_1 + \dots + d_n \underline{C}_n = \underline{A} \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \end{bmatrix} = \underline{b}.$$

Hence $x_1 = d_1, \dots, x_n = d_n$ is a solution.

(ii) Let $\text{rank}(\underline{A}) = \text{rank}(\tilde{\underline{A}}) = n$.

Then by the rank-nullity theorem,

$$\text{nullity}(\underline{A}) = 0.$$

Hence $\underline{A} \underline{x} = \underline{0}$ has unique solution, namely, $x_1 = \dots = x_n = 0$.

9) $\underline{A} \underline{x} = \underline{b} = \underline{A} \underline{y}$ then $\underline{A} (\underline{x} - \underline{y}) = \underline{0}$. Hence

$\underline{x} - \underline{y} = \underline{0} \Rightarrow \underline{x} = \underline{y}$. This establishes uniqueness.

(iii) Suppose $\text{rank}(\underline{A}) = \text{rank}(\underline{\tilde{A}}) = r < n$.

Then $n - r = \dim \mathcal{N}(\underline{A}) > 0$.

Thus $\underline{A} \underline{x} = \underline{0}$ has infinitely many solutions.

Let $\underline{c} \in \mathbb{R}^n$ and $\underline{A} \underline{c} = \underline{b}$.

9) $\underline{x} \in \mathbb{R}^n$ satisfies $\underline{A} \underline{x} = \underline{b}$ Then

$$\underline{A} \underline{x} = \underline{A} \underline{c} \Rightarrow \underline{A} (\underline{x} - \underline{c}) = \underline{0} \Rightarrow \underline{x} - \underline{c} \in \mathcal{N}(\underline{A})$$

$$\Rightarrow \underline{x} \in \underline{c} + \mathcal{N}(\underline{A}).$$

Thus any solution \underline{x} of $\underline{A} \underline{x} = \underline{b}$ is in the set

$$\underline{c} + \mathcal{N}(\underline{A}) = \left\{ \underline{c} + \underline{y} : \underline{A} \underline{y} = \underline{0} \right\}.$$

Conversely, if we take an element $\underline{c} + \underline{y}$ of $\underline{c} + \mathcal{N}(\underline{A})$

where $\underline{A} \underline{y} = \underline{0}$, then $\underline{A} (\underline{c} + \underline{y}) = \underline{A} \underline{c} + \underline{A} \underline{y} = \underline{b}$.

Hence $\underline{c} + \underline{y}$ is a solution of $\underline{A} \underline{x} = \underline{b}$. We conclude

that the solution set of $\underline{A} \underline{x} = \underline{b}$ is the set

$\underline{c} + \mathcal{N}(\underline{A})$ which contains infinitely many elements. ■

Let $c \in \mathbb{R}^n$ and $Ac = b$.

Then we have seen before that

all the solutions of $Ax = b$ are in the set

$$c + \mathcal{N}(A) = \{c + x \mid Ax = 0\}.$$

Hence $Ax = b$ has infinitely many solutions. ■

Corollary A homogeneous system of linear equations with fewer equations than unknowns always admits nontrivial solutions.

Example : Consider the system of linear equations

$$\begin{bmatrix} 1 & 0 & 2 & 1 & 3 \\ 2 & 4 & 3 & 1 & 3 \\ 0 & 0 & 0 & 0 & 1 \\ 3 & 4 & 5 & 2 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$

By GEM we transform the coefficient matrix A to its row echelon form :

$$U = \begin{bmatrix} 1 & 0 & 2 & 1 & 0 \\ 0 & 1 & -1/4 & -1/4 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

The equations for $Ux = 0$ are

$$\begin{aligned}x_1 + 2x_3 + x_4 &= 0 \\x_2 - \frac{1}{4}x_3 - \frac{1}{4}x_4 &= 0 \\x_5 &= 0\end{aligned}$$

The first, second and the fifth column of A contain the pivots. So they are linearly independent.

Hence the corresponding columns of A are linearly independent.

Thus $r(A) = 3$, and nullity $(A) = 2$. We find a basis for the nullspace.

Express the **basic variables** (corresponding to the column containing the pivots) x_1, x_2, x_5 in terms of the **free variables** (non basic variable) x_3 and x_4 .

$$\begin{aligned}x_1 &= -2x_3 - x_4 \\x_2 &= \frac{1}{4}x_3 + \frac{1}{4}x_4 \\x_5 &= 0\end{aligned}$$

Hence solutions to $Ax = 0$ have the form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} -2x_3 - x_4 \\ \frac{1}{4}x_3 + \frac{1}{4}x_4 \\ x_3 \\ x_4 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} -2 \\ \frac{1}{4} \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ \frac{1}{4} \\ 0 \\ 1 \\ 0 \end{bmatrix}.$$

Hence a basis for $\mathcal{N}(A)$ is

$$\left\{ \left(-2, \frac{1}{4}, 1, 0, 0\right)^t, \left(-1, \frac{1}{4}, 0, 1, 0\right)^t \right\}.$$

Rank in terms of determinants

Lemma :

Let C_1, C_2, \dots, C_n be the columns of an $n \times n$ matrix A . Then they are linearly independent iff $\det A$ is nonzero.

Proof :

Suppose that all the columns of A are linearly dependent.

Then all the rows of A are also linearly dependent.

Hence by the multilinearity property, $\det A$ is zero. Conversely suppose that $\det A = 0$.

C_1, C_2, \dots, C_n are L.D. \Leftrightarrow one of them can be expressed as a nontrivial linear combination of the others, say

$C_1 = \alpha_2 C_2 + \dots + \alpha_n C_n$. Then

$$\begin{aligned} \det(C_1, \dots, C_n) &= \det(\alpha_2 C_2 + \dots + \alpha_n C_n, C_2, \dots, C_n) \\ &= \alpha_2 \det(C_2, C_2, \dots, C_n) + \alpha_3 \det(C_3, C_2, \dots, C_n) + \dots = 0 \end{aligned}$$

Let U be the row echelon form of A . Then $\det U = 0$.

Hence U has a zero diagonal entry.

Hence there are at most $n - 1$ pivots in U .

Hence $\text{rank } A = \text{rank } U \leq n - 1$.

Hence the columns of A are linearly dependent.

Theorem :

An $m \times n$ matrix A has $\text{rank } r \geq 1$ iff $\det M \neq 0$ for some order r minor M of A and $\det N = 0$ for all order $r + 1$ minors N of A .

Proof :

Let U be the row echelon form of A .

Then the first r rows of U are linearly independent if $\text{rank } A = r$.

Let M_1 denote the order r minor consisting of the first r rows and the r columns of U containing the pivots.

Then M_1 is an upper triangular matrix whose diagonal entries are the pivots of U .

Hence $\det M_1 = \text{product of the pivots}$ is nonzero.

Therefore the columns of M_1 are linearly independent.

Let M be the corresponding minor of A .

Then all the columns of M are also linearly independent.

Hence $\det M \neq 0$. Any minor N_1 of U of order $r + 1$ must contain a zero row,

hence $\det N_1 = 0$.

Therefore $\det N = 0$ for all order $r + 1$ minors N of A .

Conversely suppose that A has an order r minor M with nonzero determinant and all minors of order $r + 1$ of A have zero determinant.

Let M_1 , be the corresponding minor of U .

Then M_1 has r nonzero rows.

Hence $\text{rank } U \geq r$.

On the other hand if U has $r + 1$ nonzero rows then

A will have an order $r + 1$ minor with nonzero determinant.

Theorem p vectors $\underline{R}_1 = (R_{11}, \dots, R_{1n}), \dots, \underline{R}_p = (R_{p1}, \dots, R_{pn})$ are L.I. if and only if the matrix \underline{A} with row vectors

$$\underline{R}_1, \dots, \underline{R}_p : \underline{A} = \begin{bmatrix} \underline{R}_1 \\ \vdots \\ \underline{R}_p \end{bmatrix} \text{ has rank } p;$$

they are L.D. (linearly dependent) if and only if

$$\text{Rank}(\underline{A}) < p.$$

If $n < p$, then $\text{rank}(\underline{A}) \leq \min\{n, p\} < p$.

Hence the p vectors $\underline{R}_1, \dots, \underline{R}_p$ are L.D.

Corollary p vectors with $n < p$ components ($\in \mathbb{R}^n$) are always L.D.

Determinants

Second-Order Determinants

If $A = [a_{ij}]_{2 \times 2} \in M_{2 \times 2}(\mathbb{K})$, then the determinant of A

written $\det A = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix}$ is the number $a_{11}a_{22} - a_{12}a_{21}$.

Third-Order Determinants

If $A = [a_{ij}]_{3 \times 3} \in M_{3 \times 3}(\mathbb{K})$, then its determinant is defined

$$\text{by } \det A = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

equivalently

$$\det A = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{21} \begin{vmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{vmatrix} + a_{31} \begin{vmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{vmatrix}$$

It is a fundamental fact, that this defines a unique number.

Here $M_{2 \times 2}(\mathbb{K})$ is the same as what we denoted by

$\mathbb{K}^{2 \times 2} :=$ collection of 2×2 matrices with entries in

$\mathbb{K} =$ either \mathbb{R} or \mathbb{C} .

Determinant of Any Order n

Let $A = [a_{ij}]_{n \times n} \in M_{n \times n}(\mathbb{K})$. The determinant of A

written $\det A =$

$$\begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{vmatrix}$$

is defined for $n=1$ by $\det A = a_{11}$, and for $n \geq 2$ by

$$\det A = a_{i1} C_{i1} + a_{i2} C_{i2} + \dots + a_{in} C_{in} = \sum_{k=1}^n a_{ik} C_{ik}$$

Expansion by i th row

or

$$\det A = a_{1j} C_{1j} + a_{2j} C_{2j} + \dots + a_{nj} C_{nj} = \sum_{k=1}^n a_{kj} C_{kj}$$

Expansion by j th column

Let $\underline{A} = (a_{ij})$ be an $n \times n$ matrix, we define $\det \underline{A}$ inductively. For $n=1$, $\det (a_{11}) = a_{11}$. Let $n > 1$.

Suppose we know $\det \underline{A}$ where \underline{A} is $(n-1) \times (n-1)$.

Let M_{ij} = the determinant of the submatrix $(n-1) \times (n-1)$ size obtained by erasing the i th row and the j th column.

M_{ij} is called the minor of the element a_{ij} .

The cofactor of a_{ij} denoted by C_{ij} is defined by

$$C_{ij} = (-1)^{i+j} M_{ij}$$

Definition

$$\begin{aligned} \det \underline{A} &= a_{i1} C_{i1} + a_{i2} C_{i2} + \dots + a_{in} C_{in} \\ &\quad \text{(Expansion by the } i\text{th row)} \\ &= a_{1j} C_{1j} + a_{2j} C_{2j} + \dots + a_{nj} C_{nj} \\ &\quad \text{(Expansion by the } j\text{th column)} \end{aligned}$$

Here

$$C_{ij} = (-1)^{i+j} M_{ij}$$

→ called the cofactor
of a_{ij} , also written
cof a_{ij} .

and M_{ij} called the minor of a_{ij} is the
determinant of order $n-1$ obtained by erasing the
 i th row and the j th column of A

$$\begin{vmatrix} a_{11} & \dots & a_{1j} & \dots & a_{1n} \\ \vdots & & \vdots & & \vdots \\ a_{i1} & \dots & a_{ij} & \dots & a_{in} \\ \vdots & & \vdots & & \vdots \\ a_{n1} & \dots & a_{nj} & \dots & a_{nn} \end{vmatrix}$$

This definition is unambiguous. It yields the same
value for $\det A$ no matter which row or column
we use in expanding the determinant.

General properties of determinants are the same
as the familiar properties of determinants of order 3.

Consider

$$a_{1l} C_{1j} + a_{2l} C_{2j} + \dots + a_{nl} C_{nj} = \sum_{k=1}^n a_{kl} C_{kj}$$

$$= \sum_{k=1}^n a_{kl} \text{cof}(a_{kj})$$

$$= \delta_{lj} \det(A) = \begin{cases} 0, & \text{if } l \neq j \\ \det A, & \text{if } l = j. \end{cases}$$

In fact, if $l \neq j$, then it is the expansion of the determinant in which two columns: l^{th} and j^{th} columns are identical. Hence its value $= 0$.

If $l = j$, then this is precisely the expansion of $\det A$.

On the same lines

$$\begin{aligned} \sum_{k=1}^n a_{lk} C_{ik} &= \sum_{k=1}^n a_{lk} \text{cof}(a_{ik}) = \delta_{li} \det(A) \\ &= \begin{cases} 0, & \text{if } l \neq i \\ \det A, & \text{if } l = i. \end{cases} \end{aligned}$$

$$\sum_{k=1}^n a_{kl} C_{kj} = \delta_{lj} \det A = \begin{cases} 0, & l \neq j \\ \det A, & l = j \end{cases}$$

Determinant of transpose of a matrix

Theorem For any $n \times n$ matrix \underline{A} ,
 $\det \underline{A} = \det \underline{A}^t$.

Proof. Induct on n . The theorem holds for $n=1$ and $n=2$ trivially. Assume that

$\det \underline{A} = \det \underline{A}^t$ for all $(n-1) \times (n-1)$ matrices.

Let $\underline{B} = \underline{A}^t = [b_{ij}] = [a_{ji}]$. Then

expanding by the minors of the first column

$$\det \underline{A} = a_{11} \det A_{11} - a_{21} \det A_{21} \dots + (-1)^{n+1} a_{n1} \det A_{n1}$$

Likewise, expanding $\det \underline{B}$ by the minors of the first row,

$$\det \underline{B} = b_{11} \det B_{11} - b_{12} \det B_{12} + \dots + (-1)^{n+1} b_{1n} \det B_{1n}$$

Since $B_{1i} = (A_{i1})^t$ for all i , by induction hypothesis
 $\det B_{1i} = \det A_{i1}$. Hence $\det \underline{A} = \det \underline{B}$. \square

Cramer's Rule

Theorem If the system of equations $\underline{A} \underline{x} = \underline{b}$, where $\underline{A} \in M_{n \times n}(\mathbb{K})$, $\underline{x} = [x_1, \dots, x_n]^t$ and $\underline{b} = [b_1, \dots, b_n]^t$ has a nonzero coefficient determinant $D = \det \underline{A}$, then the system has precisely one solution. This sol.ⁿ is given by

$$x_j = \frac{D_j}{D}, \quad j=1, 2, \dots, n.$$

Here D_j is the determinant obtained from D by replacing in D the j th column by the column $[b_1, \dots, b_n]^t$.

Proof. Multiply the first eq.ⁿ by C_{1j} , the second by C_{2j} , ..., the n th by C_{nj} and add:

$$C_{1j}(a_{11}x_1 + \dots + a_{1n}x_n) + \dots + C_{nj}(a_{n1}x_1 + \dots + a_{nn}x_n) = b_1 C_{1j} + \dots + b_n C_{nj}.$$

$M_{n \times n}(\mathbb{K}) \equiv \mathbb{K}^{n \times n}$ matrices of size $n \times n$ with entries in \mathbb{K} .

Hence

$$(a_{11}C_{1j} + \dots + a_{n1}C_{nj})x_1 + \dots + (a_{1n}C_{1j} + \dots + a_{nn}C_{nj})x_n \\ = b_1C_{1j} + \dots + b_nC_{nj}$$

Since

$$\sum_k a_{kl}C_{kj} = \delta_{lj} \det A,$$

We obtain

$$(\det A) x_j = D_j,$$

Hence, if $\det A \neq 0$, $x_j = \frac{D_j}{\det(A)} = \frac{D_j}{D_{jj}}$,
 $j=1, 2, \dots, n$.

This also proves that if $\det A \neq 0$, then the system has a unique solution. ■

Lemma If $A \in M_{n \times n}(\mathbb{K})$ is an upper diagonal or a lower diagonal matrix, Then

$\det A =$ The product of the diagonal elements.

Proof.

Let $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ 0 & 0 & a_{33} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & a_{nn} \end{bmatrix}$

be an upper diagonal matrix. Expand $\det A$ by the minors of the first column, to obtain

$$\det A = a_{11} \det \begin{bmatrix} a_{22} & \dots & a_{2n} \\ \vdots & & \vdots \\ 0 & & a_{nn} \end{bmatrix} \xrightarrow[\text{the process}]{\text{Continue}}$$

$$= a_{11} a_{22} \dots a_{nn}.$$

□

Properties:

$$(i) \det \underline{A} = \det \underline{A}^t$$

$$(ii) \det (\underline{A}\underline{B}) = \det (\underline{A}) \cdot \det (\underline{B})$$

(iii) If \underline{A} is invertible, then $\det \underline{A} \neq 0$ and

Rank and Determinants

$$\det \underline{A}^{-1} = \frac{1}{\det \underline{A}}$$

Theorem. Let $\underline{A} = (a_{ij})$ be an $n \times n$ matrix. Then

$$\text{rank } \underline{A} = \max \left\{ r : \det \underline{B} \neq 0, \text{ where } \underline{B} \text{ is some } r \times r \text{ square submatrix of } \underline{A} \right\}$$

In particular, for a square matrix $\underline{A}_{n \times n}$, ~~$\det \underline{A} \neq 0$~~

$$\det \underline{A} \neq 0 \Leftrightarrow \text{rank } \underline{A} = n \Leftrightarrow \underline{A} \text{ is invertible}$$

Examples

(1) The matrix

$$A = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \\ 1 & 2 & \dots & n \end{bmatrix}$$

has rank $= n$. $(n+1) \times n$ on fact det

$$\begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} = 1 \neq 0$$

(2) The matrix

$$\begin{bmatrix} 1 & 2 & 3 & 0 \\ 3 & 5 & 4 & 3 \\ 4 & 7 & 7 & 3 \\ 2 & 3 & 1 & 3 \end{bmatrix}$$

has rank 2.