```
In [0]:
```

```
import tensorflow.compat.v1 as tf
tf.disable_v2_behavior()
```

The default version of TensorFlow in Colab will soon switch to TensorFlow 2.x.

We recommend you <u>upgrade</u> now or ensure your notebook will continue to use TensorFlow 1.x via the <code>%tensorflow_version</code>

1.x magic: more info.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow_core/python/compat/v2_compat.py:68: disable_resource_variables (from tensorflow.python.ops.variable_scope) is deprecated and will be removed in a future version. Instructions for updating:
non-resource variables are not supported in the long term

In [0]:

```
# Credits: https://github.com/keras-team/keras/blob/master/examples/mnist_cnn.py

from __future__ import print_function
import keras
from keras.datasets import mnist
from keras.models import Sequential
from keras.layers import Dense, Dropout, Flatten
from keras.layers import Conv2D, MaxPooling2D
from keras.layers.normalization import BatchNormalization
from keras import backend as K
Using TensorFlow backend.
```

In [0]:

```
%matplotlib inline
import matplotlib.pyplot as plt
import numpy as np
import time
# https://gist.github.com/greydanus/f6eee59eaf1d90fcb3b534a25362cea4
# https://stackoverflow.com/a/14434334
# this function is used to update the plots for each epoch and error
def plt_dynamic(x, vy, ty, ax, colors=['b']):
    ax.plot(x, ty, 'r', label="Train Loss")
    ax.plot(x, vy, 'b', label="Validation Loss")
    plt.legend()
    plt.grid()
    fig.canvas.draw()
    plt.show()
```

```
batch size = 128
num classes = 10
epochs = 12
# input image dimensions
img rows, img cols = 28, 28
# the data, split between train and test sets
(x train, y train), (x test, y test) = mnist.load data()
if K.image data format() == 'channels first':
    x train = x train.reshape(x train.shape[0], 1, img rows, img cols)
    x_test = x_test.reshape(x_test.shape[0], 1, img_rows, img_cols)
    input shape = (1, img rows, img cols)
else:
    x train = x train.reshape(x train.shape[0], img rows, img cols, 1)
    x test = x test.reshape(x test.shape[0], img rows, img cols, 1)
   input_shape = (img_rows, img_cols, 1)
v train = v train actuma(!float3?!)
```

```
x_test = x_test.astype('float32')
x_train /= 255
x_test /= 255
print('x_train shape:', x_train.shape)
print(x_train.shape[0], 'train samples')
print(x_test.shape[0], 'test samples')

# convert class vectors to binary class matrices
y_train = keras.utils.to_categorical(y_train, num_classes)
y_test = keras.utils.to_categorical(y_test, num_classes)
```

1) Model-1: 3 Convnet layers

In [0]:

```
%%time
model = Sequential()
model.add(Conv2D(8, kernel size=(3, 3), activation='relu',
                 input shape=input shape, padding='same',
                 kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Dropout(0.25))
model.add(Conv2D(16, (3, 3), activation='relu',
                 padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(BatchNormalization())
model.add(Dropout(0.25))
model.add(Conv2D(32, (3, 3), activation='relu',
                 padding='same', kernel_initializer='he_normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(32, activation='relu'))
model.add(BatchNormalization())
model.add(Dropout(0.5))
model.add(Dense(num classes, activation='softmax'))
model.compile(loss=keras.losses.categorical crossentropy,
              optimizer=keras.optimizers.Adadelta(),
              metrics=['accuracy'])
history = model.fit(x_train, y_train,
         batch_size=batch_size,
          epochs=epochs,
          verbose=1,
          validation_data=(x_test, y_test))
score = model.evaluate(x_test, y_test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
#Error plot
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch') ; ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,epochs+1))
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:66: The name tf.get_default_graph is deprecated. Plea se use tf.compat.v1.get_default_graph instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:541: The name tf.placeholder is deprecated. Please us

```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
```

packages/keras/backend/tensorflow_backend.py:4479: The name tf.truncated_normal is deprecated. Ple ase use tf.random.truncated normal instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

 $\verb|packages/keras/backend/tensorflow_backend.py:4267: The name tf.nn.max_pool is deprecated. Please use tf.nn.max_pool2d instead.$

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:148: The name tf.placeholder_with_default is deprecated. Please use tf.compat.v1.placeholder with default instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow backend.py:3733: calling dropout (from

tensorflow.python.ops.nn_ops) with keep_prob is deprecated and will be removed in a future version.

Instructions for updating:

Please use `rate` instead of `keep_prob`. Rate should be set to `rate = 1 - keep_prob`.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:190: The name tf.get_default_session is deprecated. P
lease use tf.compat.v1.get_default_session instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:197: The name tf.ConfigProto is deprecated. Please us e tf.compat.v1.ConfigProto instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:203: The name tf.Session is deprecated. Please use tf
.compat.v1.Session instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:207: The name tf.global_variables is deprecated. Plea se use tf.compat.v1.global variables instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:216: The name tf.is_variable_initialized is deprecated. Please use tf.compat.v1.is_variable_initialized instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:223: The name tf.variables_initializer is deprecated. Please use tf.compat.v1.variables_initializer instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:2041: The name tf.nn.fused_batch_norm is deprecated. Please use tf.compat.v1.nn.fused batch norm instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:4432: The name tf.random_uniform is deprecated. Pleas e use tf.random.uniform instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name t f.train.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:3576: The name tf.log is deprecated. Please use tf.ma
th.log instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/tensorflow core/python/ops/math grad.py:1424: where (from

tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.where in 2.0, which has the same broadcast rule as np.where

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:1033: The name tf.assign_add is deprecated. Please us e tf.compat.v1.assign_add instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/backend/tensorflow_backend.py:1020: The name tf.assign is deprecated. Please use tf
.compat.vl.assign instead.

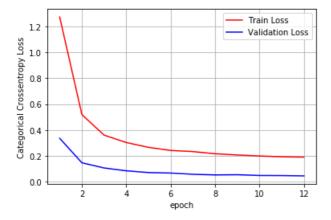
Train on 60000 samples, validate on 10000 samples

Epoch 1/12

oss: 0.3357 - val_acc: 0.9200

Epoch 2/12

```
oss: 0.1465 - val acc: 0.9559
Epoch 3/12
60000/60000 [==============] - 32s 532us/step - loss: 0.3602 - acc: 0.8909 - val 1
oss: 0.1065 - val acc: 0.9658
Epoch 4/12
60000/60000 [==============] - 32s 529us/step - loss: 0.3033 - acc: 0.9093 - val 1
oss: 0.0845 - val acc: 0.9754
Epoch 5/12
60000/60000 [============== ] - 32s 530us/step - loss: 0.2659 - acc: 0.9207 - val 1
oss: 0.0711 - val acc: 0.9781
Epoch 6/12
60000/60000 [============= ] - 32s 530us/step - loss: 0.2419 - acc: 0.9267 - val 1
oss: 0.0673 - val acc: 0.9784
Epoch 7/12
60000/60000 [============== ] - 32s 532us/step - loss: 0.2333 - acc: 0.9323 - val 1
oss: 0.0578 - val acc: 0.9814
Epoch 8/12
60000/60000 [=============] - 32s 535us/step - loss: 0.2163 - acc: 0.9363 - val 1
oss: 0.0526 - val acc: 0.9839
Epoch 9/12
60000/60000 [===============] - 32s 529us/step - loss: 0.2069 - acc: 0.9405 - val 1
oss: 0.0541 - val_acc: 0.9819
Epoch 10/12
oss: 0.0484 - val_acc: 0.9852
Epoch 11/12
60000/60000 [============= ] - 32s 532us/step - loss: 0.1927 - acc: 0.9446 - val 1
oss: 0.0478 - val acc: 0.9842
Epoch 12/12
60000/60000 [============= ] - 32s 536us/step - loss: 0.1904 - acc: 0.9452 - val 1
oss: 0.0455 - val acc: 0.9845
Test loss: 0.045479313206672665
Test accuracy: 0.9845
```



CPU times: user 10min 51s, sys: 29.3 s, total: 11min 20s Wall time: 6min 27s

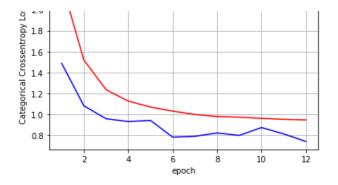
Observation: This model is doing good with a relatively lower loss and higher accuracy and is not overfitting much.

2) Variation of Model-1: 3 Convnet layers

```
%%time
model = Sequential()
model.add(Conv2D(1, kernel_size=(3, 3), activation='relu',
                input shape=input shape, padding='same',
                kernel initializer='he normal'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))
model.add(Conv2D(3, (3, 3), activation='relu',
               padding='same', kernel_initializer='he_normal'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(BatchNormalization())
model.add(Dropout(0.25))
```

```
model.add(ConvZD(5, (3, 3), activation='relu',
               padding='same', kernel_initializer='he_normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(32, activation='relu'))
model.add(BatchNormalization())
model.add(Dropout(0.5))
model.add(Dense(num classes, activation='softmax'))
model.compile(loss=keras.losses.categorical crossentropy,
            optimizer=keras.optimizers.Adadelta(),
            metrics=['accuracy'])
history = model.fit(x train, y train,
        batch size=batch size,
        epochs=epochs,
        verbose=1,
        validation_data=(x_test, y_test))
score = model.evaluate(x_test, y_test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
#Error plot
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch') ; ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,epochs+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
Train on 60000 samples, validate on 10000 samples
Epoch 1/12
oss: 1.4862 - val acc: 0.5907
Epoch 2/12
60000/60000 [============== ] - 23s 379us/step - loss: 1.5176 - acc: 0.4647 - val 1
oss: 1.0804 - val acc: 0.6886
Epoch 3/12
60000/60000 [=============== ] - 23s 379us/step - loss: 1.2345 - acc: 0.5740 - val 1
oss: 0.9566 - val acc: 0.7149
Epoch 4/12
60000/60000 [============== ] - 23s 378us/step - loss: 1.1255 - acc: 0.6186 - val 1
oss: 0.9302 - val acc: 0.6993
Epoch 5/12
60000/60000 [============= ] - 22s 372us/step - loss: 1.0689 - acc: 0.6400 - val 1
oss: 0.9409 - val acc: 0.6849
Epoch 6/12
60000/60000 [============= ] - 22s 371us/step - loss: 1.0297 - acc: 0.6595 - val 1
oss: 0.7807 - val acc: 0.7493
Epoch 7/12
60000/60000 [============== ] - 22s 368us/step - loss: 0.9978 - acc: 0.6691 - val 1
oss: 0.7890 - val acc: 0.7371
Epoch 8/12
60000/60000 [============== ] - 22s 368us/step - loss: 0.9783 - acc: 0.6782 - val 1
oss: 0.8208 - val_acc: 0.7222
Epoch 9/12
60000/60000 [============== ] - 22s 367us/step - loss: 0.9720 - acc: 0.6818 - val 1
oss: 0.7970 - val_acc: 0.7334
Epoch 10/12
oss: 0.8728 - val_acc: 0.7003
Epoch 11/12
60000/60000 [============= ] - 22s 370us/step - loss: 0.9507 - acc: 0.6872 - val 1
oss: 0.8115 - val acc: 0.7192
Epoch 12/12
60000/60000 [============ ] - 22s 370us/step - loss: 0.9458 - acc: 0.6904 - val 1
oss: 0.7395 - val acc: 0.7609
Test loss: 0.739545515537262
Test accuracy: 0.7609
                              Train Loss
```

Validation Loss



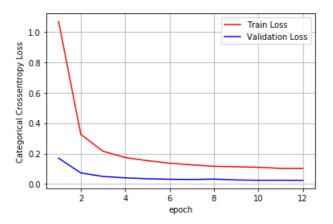
```
CPU times: user 7min 16s, sys: 24.3 s, total: 7min 40s Wall time: 4min 32s
```

Observation: The train loss and the Validation loss vary a little, but does not seem to converge.

3) Variation of Model-1: 3 Convnet layers

```
%%time
model = Sequential()
model.add(Conv2D(32, kernel size=(3, 3), activation='relu',
                 input shape=input shape, padding='same',
                 kernel_initializer='he_normal'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))
model.add(Conv2D(32, (3, 3), activation='relu',
                 padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(BatchNormalization())
model.add(Dropout(0.25))
model.add(Conv2D(32, (3, 3), activation='relu',
                 padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(32, activation='relu'))
model.add(BatchNormalization())
model.add(Dropout(0.5))
model.add(Dense(num_classes, activation='softmax'))
model.compile(loss=keras.losses.categorical crossentropy,
              optimizer=keras.optimizers.Adadelta(),
              metrics=['accuracy'])
history = model.fit(x_train, y_train,
          batch size=batch size,
          epochs=epochs,
          verbose=1,
         validation data=(x test, y test))
score = model.evaluate(x test, y test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
#Error plot
fig,ax = plt.subplots(1,1)
ax.set_xlabel('epoch') ; ax.set_ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,epochs+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
```

```
s: 0.0726 - val acc: 0.9760
Epoch 3/12
60000/60000 [============= ] - 64s 1ms/step - loss: 0.2148 - acc: 0.9364 - val los
s: 0.0492 - val acc: 0.9834
Epoch 4/12
60000/60000 [============= ] - 64s lms/step - loss: 0.1739 - acc: 0.9499 - val los
s: 0.0402 - val acc: 0.9865
Epoch 5/12
60000/60000 [============= ] - 64s 1ms/step - loss: 0.1529 - acc: 0.9560 - val los
s: 0.0341 - val acc: 0.9881
Epoch 6/12
60000/60000 [============== ] - 64s 1ms/step - loss: 0.1364 - acc: 0.9604 - val los
s: 0.0308 - val_acc: 0.9899
Epoch 7/12
60000/60000 [============== ] - 64s 1ms/step - loss: 0.1256 - acc: 0.9643 - val los
s: 0.0292 - val_acc: 0.9892
Epoch 8/12
60000/60000 [============= ] - 64s 1ms/step - loss: 0.1161 - acc: 0.9663 - val los
s: 0.0320 - val acc: 0.9899
Epoch 9/12
60000/60000 [============= ] - 64s 1ms/step - loss: 0.1132 - acc: 0.9677 - val los
s: 0.0262 - val acc: 0.9905
Epoch 10/12
60000/60000 [============== ] - 64s lms/step - loss: 0.1096 - acc: 0.9681 - val_los
s: 0.0242 - val_acc: 0.9916
Epoch 11/12
60000/60000 [============== ] - 64s 1ms/step - loss: 0.1023 - acc: 0.9708 - val los
s: 0.0243 - val acc: 0.9907
Epoch 12/12
s: 0.0236 - val acc: 0.9910
Test loss: 0.023584829754967358
Test accuracy: 0.991
```



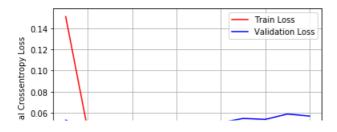
CPU times: user 23min 24s, sys: 42.7 s, total: 24min 6s Wall time: 12min 55s

Observation: This model is doing very good with a relatively lower loss and higher accuracy and is not overfitting very much.

4) Variation of Model-1: 3 Convnet layers

```
%%time
model = Sequential()
model.add(Conv2D(32, kernel_size=(3, 3), activation='relu',
                 input shape=input shape, padding='valid',
                 kernel initializer='he normal'))
model.add(Conv2D(32, (3, 3), activation='relu',
                 padding='valid', kernel_initializer='he_normal'))
model.add(Conv2D(32, (3, 3), activation='relu',
                 padding='valid', kernel_initializer='he_normal'))
model.add(Flatten())
```

```
model.add(Dense(num classes, activation='softmax'))
model.compile(loss=keras.losses.categorical crossentropy,
             optimizer=keras.optimizers.Adadelta(),
             metrics=['accuracy'])
history = model.fit(x train, y train,
         batch size=batch size,
         epochs=epochs,
         verbose=1,
         validation data=(x test, y test))
score = model.evaluate(x_test, y_test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
#Error plot
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch'); ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1, epochs+1))
vy = history.history['val loss']
ty = history.history['loss']
plt_dynamic(x, vy, ty, ax)
Train on 60000 samples, validate on 10000 samples
Epoch 1/12
60000/60000 [============== ] - 155s 3ms/step - loss: 0.1510 - acc: 0.9534 - val lo
ss: 0.0531 - val_acc: 0.9850
Epoch 2/12
60000/60000 [============== ] - 155s 3ms/step - loss: 0.0436 - acc: 0.9865 - val lo
ss: 0.0436 - val acc: 0.9862
Epoch 3/12
60000/60000 [============== ] - 153s 3ms/step - loss: 0.0262 - acc: 0.9923 - val lo
ss: 0.0363 - val acc: 0.9894
Epoch 4/12
60000/60000 [============ ] - 155s 3ms/step - loss: 0.0161 - acc: 0.9949 - val lo
ss: 0.0426 - val acc: 0.9881
Epoch 5/12
60000/60000 [============== ] - 153s 3ms/step - loss: 0.0110 - acc: 0.9964 - val lo
ss: 0.0441 - val acc: 0.9885
Epoch 6/12
60000/60000 [==============] - 154s 3ms/step - loss: 0.0068 - acc: 0.9979 - val lo
ss: 0.0414 - val_acc: 0.9900
Epoch 7/12
60000/60000 [==============] - 153s 3ms/step - loss: 0.0045 - acc: 0.9984 - val lo
ss: 0.0477 - val_acc: 0.9874
Epoch 8/12
60000/60000 [=============] - 154s 3ms/step - loss: 0.0030 - acc: 0.9991 - val_lo
ss: 0.0507 - val acc: 0.9896
Epoch 9/12
60000/60000 [=============] - 154s 3ms/step - loss: 0.0023 - acc: 0.9993 - val_lo
ss: 0.0547 - val acc: 0.9890
Epoch 10/12
60000/60000 [============= ] - 155s 3ms/step - loss: 0.0013 - acc: 0.9997 - val lo
ss: 0.0538 - val acc: 0.9905
Epoch 11/12
60000/60000 [============== ] - 153s 3ms/step - loss: 9.1630e-04 - acc: 0.9998 - va
l loss: 0.0589 - val acc: 0.9899
Epoch 12/12
60000/60000 [============== ] - 154s 3ms/step - loss: 0.0011 - acc: 0.9998 - val lo
ss: 0.0569 - val acc: 0.9901
Test loss: 0.056943806147187616
Test accuracy: 0.9901
```



model.add(Dense(32, activation='relu'))

```
0.02
0.02
0.00
2 4 6 8 10 12
epoch
```

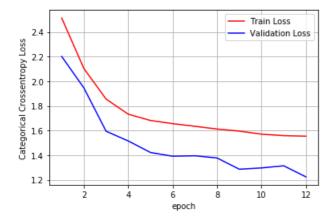
```
CPU times: user 58\min 7s, sys: 1\min 10s, total: 59\min 18s Wall time: 30\min 55s
```

Observation: The train loss and the Validation loss vary much here.

5) Model -2: 4 - Convnet layers

```
%%time
model = Sequential()
model.add(Conv2D(1, kernel_size=(4, 4), activation='relu',
                 input shape=input shape, padding='same',
                 kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Dropout(0.25))
model.add(Conv2D(3, (4, 4), activation='relu',
                 padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(BatchNormalization())
model.add(Dropout(0.25))
model.add(Conv2D(5, (4, 4), activation='relu',
                 padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(BatchNormalization())
model.add(Dropout(0.3))
model.add(Conv2D(7, (4, 4), activation='relu',
                 padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(16, activation='relu'))
model.add(BatchNormalization())
model.add(Dropout(0.5))
model.add(Dense(num classes, activation='softmax'))
model.compile(loss=keras.losses.categorical crossentropy,
              optimizer=keras.optimizers.Adadelta(),
              metrics=['accuracy'])
history = model.fit(x train, y train,
          batch size=batch size,
          epochs=epochs,
          verbose=1,
         validation data=(x test, y test))
score = model.evaluate(x_test, y_test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
#Error plot
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch'); ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,epochs+1))
vy = history.history['val_loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
```

```
FDOCH Z/IZ
oss: 1.9461 - val_acc: 0.2744
Epoch 3/12
oss: 1.5946 - val_acc: 0.4629
Epoch 4/12
oss: 1.5156 - val_acc: 0.4682
Epoch 5/12
oss: 1.4222 - val acc: 0.4849
Epoch 6/12
60000/60000 [============== ] - 26s 427us/step - loss: 1.6564 - acc: 0.3741 - val 1
oss: 1.3917 - val acc: 0.4994
Epoch 7/12
60000/60000 [=============] - 26s 429us/step - loss: 1.6348 - acc: 0.3833 - val 1
oss: 1.3957 - val acc: 0.4645
Epoch 8/12
60000/60000 [============== ] - 26s 428us/step - loss: 1.6126 - acc: 0.3936 - val 1
oss: 1.3775 - val acc: 0.4769
Epoch 9/12
oss: 1.2864 - val acc: 0.5122
Epoch 10/12
60000/60000 [============= ] - 26s 435us/step - loss: 1.5708 - acc: 0.4063 - val 1
oss: 1.2968 - val acc: 0.5025
Epoch 11/12
60000/60000 [============== ] - 26s 430us/step - loss: 1.5590 - acc: 0.4105 - val 1
oss: 1.3142 - val acc: 0.5041
Epoch 12/12
oss: 1.2243 - val acc: 0.5520
Test loss: 1.2242729833602906
Test accuracy: 0.552
```

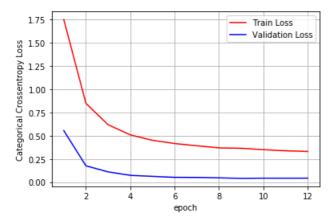


CPU times: user 8min 28s, sys: 17 s, total: 8min 45s Wall time: 5min 13s

Observation: The train loss and the Validation loss vary much here.

6) Model -3: 5 - Convnet layers

```
model.add(Dropout(U.25))
model.add(Conv2D(16, (5, 5), activation='relu',
              padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(BatchNormalization())
model.add(Dropout(0.3))
model.add(Conv2D(16, (5, 5), activation='relu',
              padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(BatchNormalization())
model.add(Dropout(0.3))
model.add(Conv2D(16, (5, 5), activation='relu',
              padding='same', kernel initializer='he normal'))
model.add(MaxPooling2D(pool size=(2, 2)))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(32, activation='relu'))
model.add(BatchNormalization())
model.add(Dropout(0.5))
model.add(Dense(num_classes, activation='softmax'))
model.compile(loss=keras.losses.categorical crossentropy,
            optimizer=keras.optimizers.Adadelta(),
            metrics=['accuracy'])
history = model.fit(x_train, y_train,
        batch size=batch size,
        epochs=epochs,
        verbose=1,
        validation data=(x test, y test))
score = model.evaluate(x_test, y_test, verbose=0)
print('Test loss:', score[0])
print('Test accuracy:', score[1])
#Error plot
fig,ax = plt.subplots(1,1)
ax.set xlabel('epoch'); ax.set ylabel('Categorical Crossentropy Loss')
# list of epoch numbers
x = list(range(1,epochs+1))
vy = history.history['val loss']
ty = history.history['loss']
plt dynamic(x, vy, ty, ax)
Train on 60000 samples, validate on 10000 samples
Epoch 1/12
60000/60000 [============= ] - 101s 2ms/step - loss: 1.7502 - acc: 0.4025 - val lo
ss: 0.5551 - val acc: 0.8840
Epoch 2/12
60000/60000 [============= ] - 99s 2ms/step - loss: 0.8473 - acc: 0.7273 - val los
s: 0.1756 - val acc: 0.9696
Epoch 3/12
60000/60000 [============= ] - 99s 2ms/step - loss: 0.6179 - acc: 0.8120 - val los
s: 0.1104 - val_acc: 0.9759
Epoch 4/12
60000/60000 [============= ] - 98s 2ms/step - loss: 0.5089 - acc: 0.8485 - val los
s: 0.0732 - val_acc: 0.9828
Epoch 5/12
60000/60000 [==============] - 98s 2ms/step - loss: 0.4502 - acc: 0.8660 - val los
s: 0.0621 - val_acc: 0.9846
Epoch 6/12
s: 0.0517 - val acc: 0.9871
Epoch 7/12
60000/60000 [============= ] - 99s 2ms/step - loss: 0.3915 - acc: 0.8855 - val los
s: 0.0504 - val acc: 0.9867
Epoch 8/12
s: 0.0462 - val acc: 0.9882
Epoch 9/12
60000/60000 [============= ] - 99s 2ms/step - loss: 0.3645 - acc: 0.8933 - val_los
s: 0.0405 - val acc: 0.9894
Epoch 10/12
```



Observation: This model is doing good with a relatively low loss and high accuracy and is not overfitting very much.

Summary

In [3]:

```
from prettytable import PrettyTable
pt = PrettyTable()
pt.field_names = ["Number of Convolutional Layers", "Activation", "Kernel dimension", "Channels", "
BatchNormalization", "Dropout", "Max Pooling (2x2)", "Test loss", "Test accuracy"]
pt.add_row(["3", "relu", "3,3", "8,16,32", "Yes", "Yes (0.25,0.25,0.4,0.5)", "Yes", "0.045","0.985"
])
pt.add_row(["3", "relu", "3,3", "1,3,5", "Yes", "Yes (0.25,0.25,0.4,0.5)", "Yes", "0.740","0.761"])
pt.add_row(["3", "relu", "3,3", "32,32,32", "Yes", "Yes (0.25,0.25,0.4,0.5)", "Yes", "0.024","0.991
"])
pt.add_row(["3", "relu", "3,3", "32,32,32", "No", "No", "No", "No", "0.057","0.990"])
pt.add_row(["4", "relu", "4,4", "1,3,5,7", "Yes", "Yes (0.25,0.25,0.3,0.4,0.5)", "Yes", "1.224","0.552"])
pt.add_row(["5", "relu", "5,5", "16,16,16,16,16", "Yes", "Yes (0.25,0.25,0.3,0.4,0.5)", "Yes", "0.0
43","0.990"])
print(pt)
```

| atchNormalization | | | | Kernel dimension Channels Max Pooling (2x2) Test loss | | | | | | Test accuracy | |
|---------------------------------|-----|------|--|--|--------------|---|--|----------------|--|---------------|--|
| | + | | | +- | | + | | + | | | |
| 3 | - 1 | relu | | | 3,3 | | | 8,16,32 | | Yes | |
| Yes (0.25,0.25,0.4,0.5) | | Yes | | | 0.045 | | | 0.985 | | | |
| 3 | - 1 | relu | | | 3,3 | | | 1,3,5 | | Yes | |
| Yes (0.25,0.25,0.4,0.5) | | Yes | | | 0.740 | | | 0.761 | | | |
| 3 | - 1 | relu | | | 3,3 | | | 32,32,32 | | Yes | |
| Yes (0.25,0.25,0.4,0.5) | | Yes | | | 0.024 | | | 0.991 | | | |
| 3 | | relu | | | 3 , 3 | | | 32,32,32 | | No | |
| No | | No | | | 0.057 | | | 0.990 | | | |
| 4 | | relu | | | 4,4 | | | 1,3,5,7 | | Yes | |
| Yes (0.25, 0.25, 0.3, 0.4, 0.5) | | Yes | | | 1.224 | | | 0.552 | | | |
| 5 | - 1 | relu | | | 5 , 5 | | | 16,16,16,16,16 | | Yes | |
| Yes (0.25, 0.25, 0.3, 0.4, 0.5) | 1 | Yes | | | 0.043 | | | 0.990 | | | |

- The best model is the one with 3 Convnet layers, 3x3x32 Kernel filters along with techniques like Batch normalization, Dropout, Max pooling having the minimum Test loss and Maximum Test accuracy without overfitting.
- Techniques like Batch normalization and Dropout are important for a model's better performance, Max pooling is required to reduce the matrix dimension to reduce time and space utilization.
- The Number of channels is also important to get a minimum Test loss and Maximum Test accuracy without overfitting.
- It is better to have the Kernel's dimension in odd number and the number of channels in powers of 2.
- For a 28x28 image 3x3 kernel seems enough and as the image's dimension gets bigger filters like 5x5 or even 7x7 can be used.
- Since the MNIST dataset is not a very complex dataset even a 3 layer Convnet seems sufficient.