

Equivalence of pushdown automata

FROM PDA to CFG

Theorem

Let $M = (Q, \Sigma, \Gamma, \delta, q_0, z_0)$ be a PDA. Then there is a context free grammar G such that $L(G) = N(M)$.

Proof

Let M be the PDA and $G = (V, \Sigma, P, S)$ be a context free grammar, where,

- i) S is the start symbol
- ii) V is the set of objects of the form $[q, A, p]$ where q and p in Q .

A in Γ

P is the set of production which are define as follows:-

$$1) S \rightarrow [q_0, z_0, q] \text{ for each } q \text{ in } Q.$$

$$2) [q, A, q_{m-1}] \rightarrow \bar{a} [q_1, B_1, q_2] [q_2, B_2, q_3] \dots$$

$$[q_m, B_m, q_{m-1}] \text{ for each } a \text{ in } \Sigma \vee \epsilon$$

$$q_1, q_2, \dots, q_{m-1} \text{ in } Q.$$

$$A, B_1, B_2, \dots, B_m \text{ in } \Gamma.$$

such that

$$\delta(q, a, A) = (q_1, B_1, B_2, \dots, B_m)$$

if $m=0$. i.e, $\delta(q, a, A) = (q_1, \epsilon)$ then,

$$[q, A, q_1] \rightarrow a$$

The variables and productions of a Q have been defined in such a way that a leftmost derivation in G of a sentence, v is a situation of the PDA M when feed the input x .

The variable that appear in any step of a leftmost derivation in G correspond to the symbol on the stack of M .

The intention is that $[q, A, p]$ derive x , it and only if x causes M to erase an A from its stack by some sequence of moves beginning in state q and ending in state p .

To show that $L(G) = N(M)$

By induction on the no. of steps in a derivation that

$$[q, A, p] = x$$

if and only if $(q, x, A) \vdash_M (p, \epsilon, \epsilon)$

if part.

Basis :-

if $i=1$ then,

$S(q, x, A) = (p, \epsilon)$ where $x = \epsilon$ or single input symbol, which produces $[q, A, p] \rightarrow x$ is a production of G .

Induction :-

if $i > 1$ and $x = ay$, then

$$\begin{aligned} (q, ay, A) &\vdash (q_1, v_1, B_1, B_2, \dots, B_n) \\ &\vdash (q_1, y_1, y_2, \dots, y_n, B_1, B_2, \dots, B_n) \\ &\vdash (q_2, y_2, \dots, y_n, B_1, B_2, \dots, B_n) \\ &\vdots \\ &\vdash (p, \epsilon, \epsilon) \end{aligned}$$

Here $y = y_1, y_2, \dots, y_n$, $A \rightarrow B_1 B_2 \dots B_n$

The input symbol y_i has the effect of popping B_i from the stack after a long sequence of moves, in general remains on the stack unchanged while y_1, y_2, \dots, y_{i+1} is read.

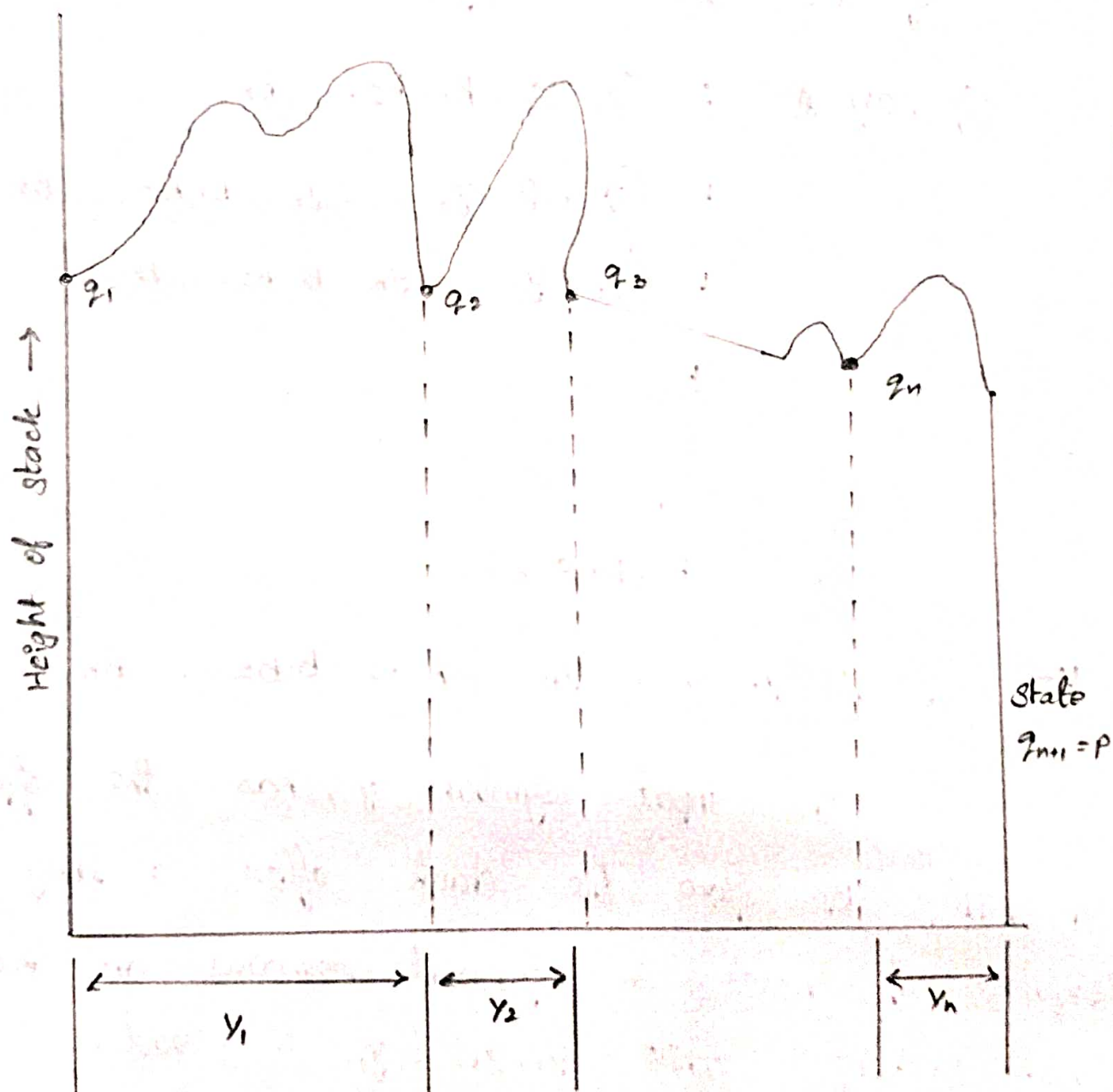
And also $Q = \{q_1, q_2, \dots, q_{n+1}\}$ where $q_{n+1} = p$

$$\therefore (q_j, y_j, B_j) + (q_{n+1}, \varepsilon, \varepsilon)$$

Thus it produces the production

$$(q_j, B_j, q_{j+1}) \Rightarrow y_j \text{ for } 1 \leq j \leq n$$

The popping of B_j is shown.



if $(q, ay, A) \vdash (x, y, B, B_2, \dots, B_n)$ then

$$[q, A, p] \text{ a } [q_1, B, q_2] [q_2, B_2, q_3] \dots [q_m, B_n, q_{m+1}]$$

$$[q, A, p] \Rightarrow \text{ a } y, y_2, \dots, y_n = x$$

Only if part

$$\text{suppose } [q, A, p]^i \Rightarrow x$$

This is proved by induction on i , the no. of steps.

Basis :

if $i=1$, then

$$[q, x, A] \vdash^* [p, \varepsilon, \varepsilon]$$

Because $[q, A, p] \rightarrow x$ must be a production of G
 $\delta(q, x, A) = (p, \varepsilon)$

INDUCTION :-

if $i > n$, then $(q_j, x_j, B_j) \vdash^* (q_{j+1}, \varepsilon, \varepsilon)$ for
 $i \leq j \leq n$ if we insert B_{j+1}, \dots, B_n at the bottom
 of each stack in the above sequence of ID's

$$(q_j, x_j, B_j B_{j+1} \dots B_n) \vdash^* (q_{j+1}, \varepsilon, B_{j+1} \dots B_n)$$

From (q, x, A) derivation, we know that

$(q, x, A) \vdash^* (q, x_1, x_2, \dots, x_n, B, B, \dots, B_n)$ is a legal move of M .

$$(q, x, A) \vdash^* (p, \varepsilon, \varepsilon) \text{ for } j=1, 2, \dots, n$$

The proof concludes with the observation that,

$$[q, A, P] \xrightarrow{*} x \text{ with } q = q_0 \text{ and } A = Z$$

$$[q_0, Z_0, P] \xrightarrow{*} x \text{ if and only if}$$

$$(q_0, x, Z_0) \vdash^* (p, \varepsilon, \varepsilon)$$

$$\therefore S^* \Rightarrow x \text{ if and only if}$$

$$(q_0, x, Z_0) \vdash^* (p, \varepsilon, \varepsilon) \text{ for some state in } p$$

That is x is in $L(A)$ if and only if x is in $N(M)$.

Example :-

Convert the PDA $P = \{ (p, q), \{0, 1\} = \{x, z_0\}, \delta, z, z_0 \}$

$$\delta(q, 1, z_0) = \{(q, xz_0)\}$$

$$\delta(q, 1, x) = \{(q, xx)\}$$

$$\delta(q, 0, x) = \{(p, x)\}$$

$$\delta(q, \varepsilon, z_0) = \{(q, \varepsilon)\}$$

$$\delta(p, \epsilon, x) = \{(p, \epsilon)\}$$

$$\delta(p, 0, z_0) = \{(q, z_0)\}$$

Solution :-

The variables involved in this PDA are,

$$V = \{s, [q, x, q], [q, x, p], [p, x, q], [p, x, p], [q, z_0, q], [q, z_0, p], [p, z_0, q], [p, z_0, p]\}$$

The production are,

$$s \rightarrow [q, z_0, q]$$

$$s \rightarrow [q, z_0, p]$$

$$i) \delta(q, 1, z_0) = \{(q, x, z_0)\}$$

$$[q, z_0, q] \rightarrow 1 [q, x, q] [q, z_0, q]$$

$$1 [q, x, p] [q, z_0, q]$$

$$[q, z_0, p] \rightarrow 1 [q, x, q] [q, z_0, p]$$

$$1 [q, x, p] [q, z_0, p]$$

$$ii) \delta(q, 1, x) = \{(q, xx)\}$$

$$[q, x, q] \rightarrow 1 [q, x, q] [q, x, q]$$

$$1 [q, x, p] [p, x, q]$$

$$\text{iii) } \delta(q, 0, x) = \{ (p, x) \}$$

$$[q, x, q] \rightarrow 0 [p, x, q]$$

$$[q, x, p] \rightarrow 0 [p, x, p]$$

$$\text{iv) } \delta(q, \varepsilon, z_0) = \{ (q, \varepsilon) \}$$

$$[q, z_0, q] \rightarrow \varepsilon$$

$$\text{v) } \delta(p, 1, x) = \{ (p, \varepsilon) \}$$

$$[p, x, p] \rightarrow 1$$

$$\text{vi) } \delta(p, 0, z_0) = \{ (q, z_0) \}$$

$$[p, z_0, q] \rightarrow 0 [q, z_0, q]$$

$$[p, z_0, p] \rightarrow 0 [q, z_0, p]$$

After Eliminating the unwanted variable

The CFG is given by.

$$S \rightarrow [q, z_0, q]$$

$$[q, z_0, q] \rightarrow \{ 1 [q, x, p] [p, z_0, q], \varepsilon \}$$

$$[q, x, p] \rightarrow \{ 1 [q, x, p] [p, x, p], 0 [p, x, p] \}$$

$$[p, x, p] \rightarrow 1$$

$$[p, z_0, q] \rightarrow 0 [q, z_0, q]$$

$$S \rightarrow [q, z_0, q]$$

$$[z_0, q] \rightarrow 1 [a, x, p], [p, z_0, q] 1 \varepsilon$$

$$[a, x, p] \rightarrow 1 [a, x, p] [p, x, p] 1 0 [p, x, p] 3$$

$$[p, z_0, q] \rightarrow 0 [a, z_0, q]$$

$$[p, x, p] \rightarrow 1$$