

State machines

An embedded system is used to control the environment condition in a room. It is composed by a temperature sensor, a CPU, and an actuator that can control the air conditioner or the heat pump. The sensor senses the room from an Erlang distributed amount of time ($Erlang_{\langle \lambda=0.1 \text{ s}^{-1}, k=3 \rangle}$). Then the CPU works for a uniform distributed amount of time ($Uniform_{\langle a=10 \text{ s}, b=20 \text{ s} \rangle}$), and after that: it returns sensing with probability $p_1 = 50\%$, it activates the air conditioning with probability $p_2 = 30\%$, or turns on the heat pump with probability $p_3 = 20\%$. The actuations take an exponentially distributed amount of time, respectively with rates ($Exp_{\langle \lambda=0.03 \text{ s}^{-1} \rangle}$) for the heat pump and ($Exp_{\langle \lambda=0.05 \text{ s}^{-1} \rangle}$) for the air conditioning.

- Draw a state machine based model of the system
- Implement it in a programming language of your choice
- Compute the probability of the system being sensing, using the CPU, actuating the air conditioning or the heat pump.
- Determine the sensing frequency (throughput) of the system, measured in times the system enters the sensing state per time unit.