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Solution to Assignment 1

$$(x_1) = (\frac{1}{3}), \quad y = 32$$

$$W = \begin{pmatrix} 2 & 1 & 3 \\ 2 & -1 & 1 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

$$W = \begin{pmatrix} 3 \\ \frac{1}{2} \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$assume input to a neuron layor (a) assume is a ctilinary actilinary acti$$

16) RelV activation function

$$Taw^{CIJ} = \begin{pmatrix} 9 \\ -2 \\ 5 \end{pmatrix}$$

$$= act^{CIJ} = \begin{pmatrix} 9 \\ | 0 | | 5 \end{pmatrix}$$

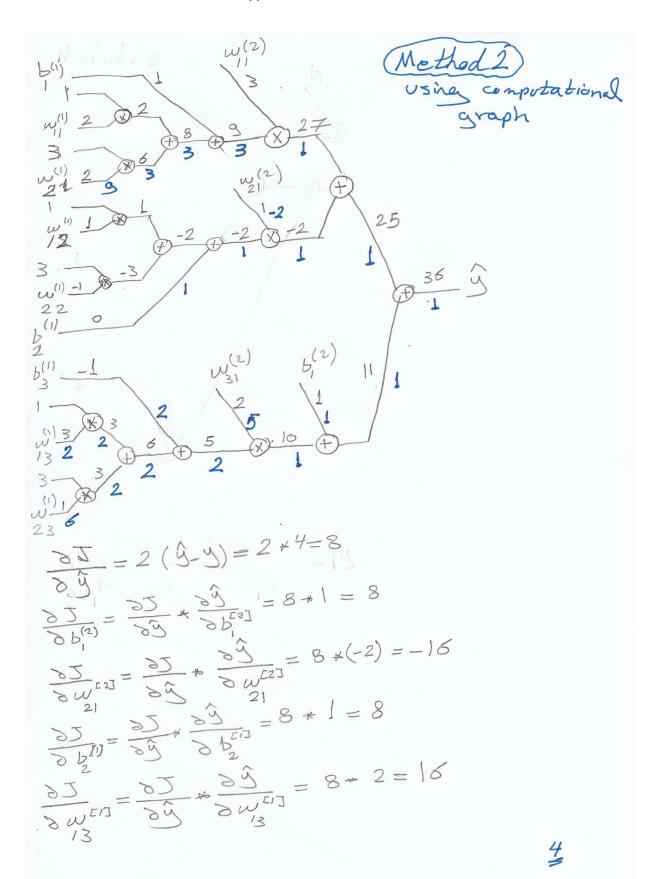
$$= raw = \begin{pmatrix} 3 & 1 & 2 \end{pmatrix} \begin{pmatrix} 5 \\ 6 \end{pmatrix} + 1 = 38$$

$$= \begin{pmatrix} 2 \\ 3 \end{pmatrix} = Rel (38) = 38 = - \begin{pmatrix} 3 \\ 2 \end{pmatrix} = 38 \end{pmatrix}$$

$$= \begin{pmatrix} 3 \\ -2 \end{pmatrix} = Rel (38) = 38 = - \begin{pmatrix} 3 \\ -2 \end{pmatrix} = 38 \end{pmatrix}$$

$$= \begin{pmatrix} 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 3 \\ -2$$

2)
$$raw_{i}^{[i]} = \frac{2}{3i} w_{i}^{[i]} \times_{j}^{[i]} + b_{i}^{[i]}$$
 $raw_{i}^{[i]} = \frac{3}{3i} w_{i}^{[i]} act_{i}^{[i]} + b_{i}^{[i]}$
 $raw_{i}^{[i]} = \frac{3}{3i} w_{i}^{[i]} act_{i}^{[i]} + b_{i}^{[i]}$
 $raw_{i}^{[i]} = \frac{3}{3i} * \frac{3}{3} raw_{i}^{[i]} + \frac{3}{3} raw_{i}^{[i]}$
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 $raw_{i}^{[i]} = \frac{3}{3} w_{i}^{[i]}$
 $raw_{i}^{[i]} = \frac{3$



Id)

$$\begin{array}{l}
-b_2^{EIJ} = b_2^{EIJ} - 7 \quad \frac{\delta J}{\delta b^{EIJ}} \\
= 0 - 2 + 8 \quad \Rightarrow \quad \begin{bmatrix} b_2^{EIJ} - 16 \end{bmatrix} \\
w_1 = w_1^{EIJ} - 7 \quad \frac{\delta J}{\delta w^{EIJ}} \\
= 3 - 2 + 16 = -29 \Rightarrow \begin{bmatrix} w_{13}^{EIJ} - 29 \end{bmatrix} \\
\text{le) Test dataset is used to assess the perforance} \\
\text{(generalization) of a fully specified model.}

Yes, test dataset could be used to assess the out-of-sample error as these are unseen samples & if the model fits these samples, it's assumed that minimal overfitting has taken place during training (or training noise has minimal impact over the model)

\[
\begin{align*}
\text{continuous training (or training noise} \\
\text{has minimal impact over the model}
\end{align*}
\]$$

$$\frac{2}{f} = \sin \alpha_{1} + \alpha_{2}^{2}$$

$$\frac{3f}{3\alpha_{1}} = \cos \alpha_{1} = \cos (x_{1}e^{x_{2}})$$

$$\frac{3f}{3\alpha_{2}} = 2 \cos (x_{1}e^{x_{2}})$$

$$\frac{3g}{3\alpha_{2}} = 2 \cos (x_{1}e^{x_{2}})$$

$$\frac{3g}{3\alpha_{2}} = 1$$

$$\frac{3g}{3\alpha_{2}} = 2 \cos (x_{1}e^{x_{2}})$$

$$\frac{3f}{3\alpha_{2}} = \frac{3f}{3\alpha_{1}} + \frac{3f}{3\alpha_{2}} + \frac{3g}{3\alpha_{2}}$$

$$\frac{3f}{3\alpha_{2}} = \frac{3f}{3\alpha_{1}} + \frac{3f}{3\alpha_{2}} + \frac{3g}{3\alpha_{2}}$$

$$\frac{3f}{3\alpha_{2}} = \frac{3f}{3\alpha_{1}} + \frac{3g}{3\alpha_{2}} + \frac{3g}{3\alpha_{2}}$$

$$\frac{3g}{3\alpha_{2}} = \frac{3g}$$



$$\frac{\sqrt{3}}{\sqrt{3}} = \frac{1}{1+e^{-z}}$$

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$$\frac{\sqrt{3}}{\sqrt{3}} =$$

4)
$$\int (\omega) = \frac{1}{2} \int \frac{m}{2\pi i} (\omega^{T} x^{(i)} - y^{(i)})^{2} + \lambda \int_{J=1}^{2} \omega^{2} y^{2} + \lambda \int_{J=1}^{2} \omega^{2}$$

$$=\frac{37}{3W}=\begin{bmatrix} 3W\\ 3W\\ 3W \end{bmatrix}$$

8)
$$f = tanh(w^Tx)$$

 $= \frac{\partial f}{\partial w_K} = sech^2(w^Tx) \times_K$
 $= \frac{\partial f}{\partial w_K} = sech^2(w^Tx) \times_K$
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