

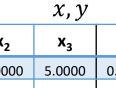
{Grady Kurpasi}

**{SSIE 616}** 

{Prof H. Lewis}



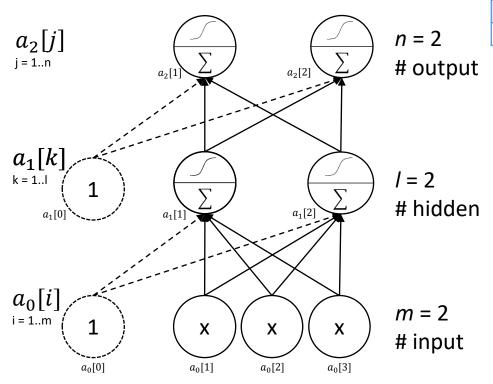
## Multilayer Perceptrons



X <sub>1</sub>	X <sub>2</sub>	X <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500
0.1000	-5.0000	3.0000	0.1221	0.0964
6.0000	-5.5420	4.8970	0.1061	0.0702
4.0000	8.0000	9.0000	0.0996	0.0641
12.0000	-2.0000	0.0063	0.1110	0.0732
6.0000	-5.5000	4.8970	0.1060	0.0701

$w_1[i,k]$			
i	w[i,1]	w[i,2]	
0	0.5	0.5	
1	0.1	0.2	
2	0.3	0.4	
3	0.5	0.6	

$w_2[k,j]$			
k	w[k,1]	w[k,2]	
0	0.5	0.5	
1	0.7	0.8	
2	0.9	0.1	



3-2-2 Multilayer Perceptron

## Multilayer Perceptrons

ν	17
Λ,	v

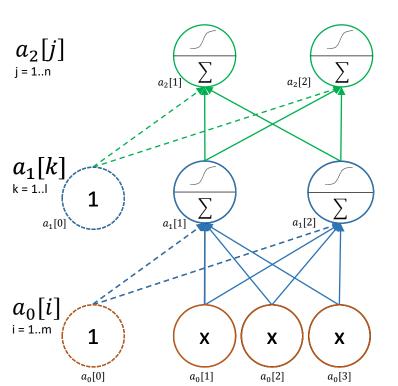
X <sub>1</sub>	X <sub>2</sub>	X <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500
0.1000	-5.0000	3.0000	0.1221	0.0964
6.0000	-5.5420	4.8970	0.1061	0.0702
4.0000	8.0000	9.0000	0.0996	0.0641
12.0000	-2.0000	0.0063	0.1110	0.0732
6.0000	-5.5000	4.8970	0.1060	0.0701

$w_1$	Γi.	k
•••	, · ·	

i	w[i,1]	w[i,2]
0	0.5	0.5
1	0.1	0.2
2	0.3	0.4
3	0.5	0.6

~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	$w_2$	[k,	j
---------------------------------------	-------	-----	---

k	w[k,1]	w[k,2]
0	0.5	0.5
1	0.7	0.8
2	0.9	0.1

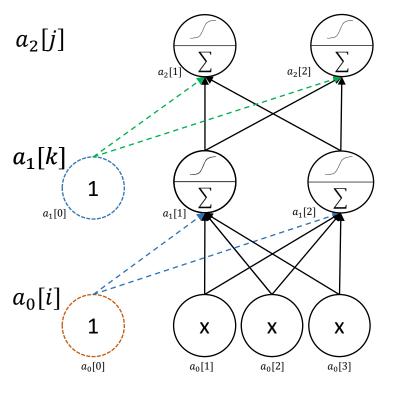


 $subscript_2$ 

 $subscript_1$ 

 $subscript_0$ 

3-2-2 Multilayer Perceptron



## Multilayer Perceptrons

*x*, *y* 

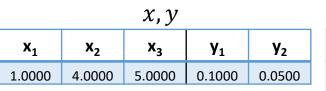
X <sub>1</sub>	X <sub>2</sub>	<b>X</b> <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500
0.1000	-5.0000	3.0000	0.1221	0.0964
6.0000	-5.5420	4.8970	0.1061	0.0702
4.0000	8.0000	9.0000	0.0996	0.0641
12.0000	-2.0000	0.0063	0.1110	0.0732
6.0000	-5.5000	4.8970	0.1060	0.0701

$w_1$	Γi.	$k^{-}$
V V	י י	10

i	w[i,1]	w[i,2]
0	0.5	0.5
1	0.1	0.2
2	0.3	0.4
3	0.5	0.6

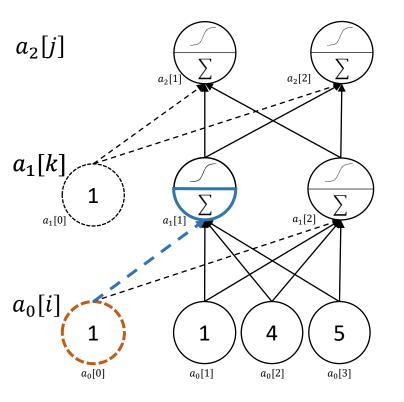
$W_2$	[k, i]	1
VV')	$I^{L}$	1

k	w[k,1]	w[k,2]
0	0.5	0.5
1	0.7	0.8
2	0.9	0.1

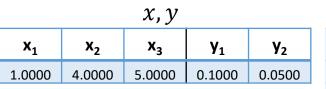


$w_1[i,k]$		
i	w[i,1]	w[i,2]
0	0.5	0.5
1	0.1	0.2
2	0.3	0.4
3	0.5	0.6

$w_2[k,j]$		
k	w[k,1]	w[k,2]
0	0.5	0.5
1	0.7	0.8
2	0.9	0.1

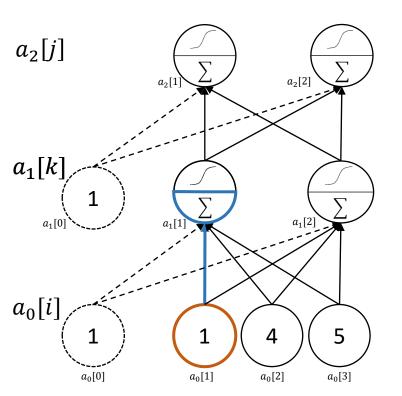


$$s_1[k] = \sum_{i=0}^{m} w_1[i,k] * a_0 i \text{ for } k = 1..l$$
  
 $s_1[1] = w_1[0,1] * a_0[0] = .05 * 1$ 

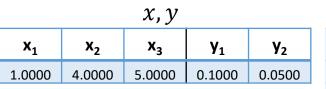


$w_1[i,k]$		
i	w[i,1]	w[i,2]
0	0.5	0.5
1	0.1	0.2
2	0.3	0.4
3	0.5	0.6

$w_2[k,j]$		
k	w[k,1]	w[k,2]
0	0.5	0.5
1	0.7	0.8
2	0.9	0.1

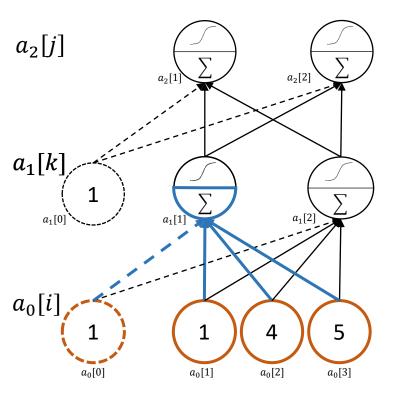


$$s_1[k] = \sum_{i=0}^{3} w_1[i,k] * a_0 i$$
 for  $k = 1, 2$   
 $s_1[1] = w_1[0,1] * a_0[0] = .05 * 1$   
 $w_1[1,1] * a_0[1] = .1 * 1$ 



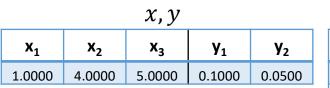
$w_1[i,k]$			
i	w[i,1]	w[i,2]	
0	0.5	0.5	
1	0.1	0.2	
2	0.3	0.4	
3	0.5	0.6	

$w_2[k,j]$		
k	w[k,1]	w[k,2]
0	0.5	0.5
1	0.7	0.8
2	0.9	0.1



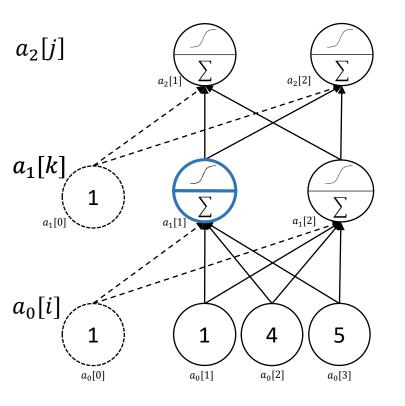
$$s_{1}[k] = \sum_{i=0}^{3} w_{1}[i,k] * a_{0}i \text{ for } k = 1,2$$

$$s_{1}[1] = w_{1}[0,1] * a_{0}[0] = .05 * 1 + w_{1}[1,1] * a_{0}[1] = .1 * 1 + w_{1}[2,1] * a_{0}[2] = .3 * 4 + w_{1}[3,1] * a_{0}[3] = .5 * 5 = 4.3$$

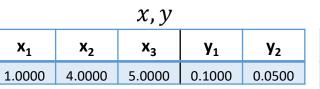


$w_1[i,k]$		
i	w[i,1]	w[i,2]
0	0.5	0.5
1	0.1	0.2
2	0.3	0.4
3	0.5	0.6

$w_2[k,j]$		
k	w[k,1]	w[k,2]
0	0.5	0.5
1	0.7	0.8
2	0.9	0.1

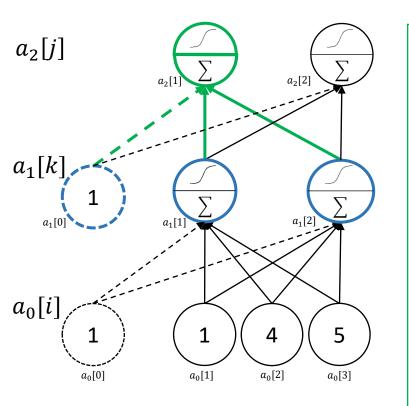


$$a_1[k] = \frac{1}{1 + e^{-s_1[k]}}$$
 for  $k = 1, 2$   
 $a_1[1] = \frac{1}{1 + e^{-4.3}} = .9866$ 



$w_1[i,k]$			
i	w[i,1]	w[i,2]	
0	0.5	0.5	
1	0.1	0.2	
2	0.3	0.4	
3	0.5	0.6	

$w_2[k,j]$		
k	w[k,1]	w[k,2]
0	0.5	0.5
1	0.7	0.8
2	0.9	0.1
_ 0.0 0.1		



$$s_{2}[j] = \sum_{k=0}^{l} w_{2}[k,j] * a_{1}i \text{ for } j = 1..m$$

$$a_{2}[j] = \frac{1}{1 + e^{-s_{2}[j]}} \text{ for } j = 1,2$$

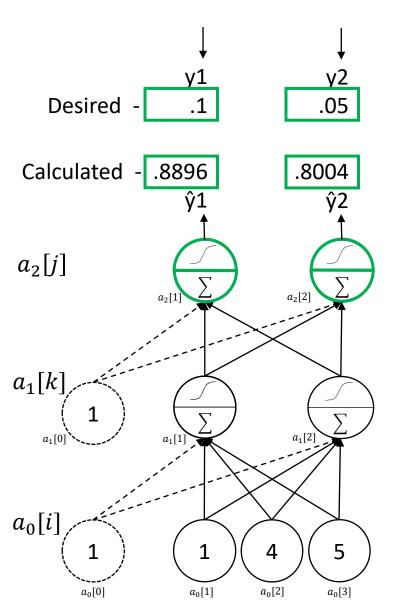
$$s_{2}[1] = w_{2}[0,2] * a_{1}[0] = .5 * 1$$

$$w_{2}[1,2] * a_{1}[1] = .7 * .9866$$

$$w_{2}[2,2] * a_{1}[2] = .9 * .9950$$

$$= 2.0862$$

$$a_{2}[1] = \frac{1}{1 + e^{-2.0862}} = .8896 = \hat{y}$$



### Error

<i>x</i> , <i>y</i>			
( <sub>2</sub>	<b>X</b> <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
000	5.0000	0.1000	0.0500

**X**<sub>1</sub>

$w_1[i,k]$				
i	w[i,1]	w[i,2]		
0	0.5	0.5		
1	0.1	0.2		
2	0.3	0.4		
3	0.5	0.6		

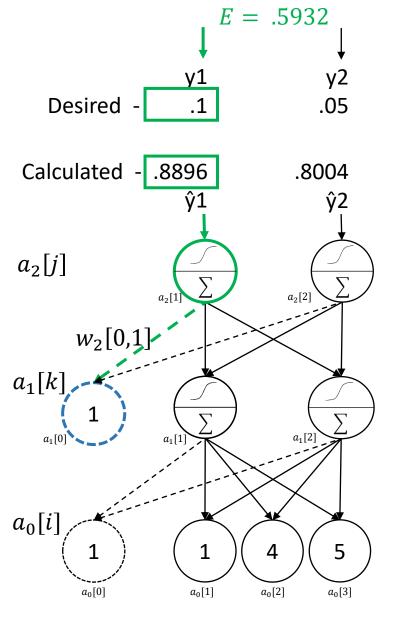
$$w_2[k,j]$$
 $k$ 
 $w[k,1]$ 
 $w[k,2]$ 

0
0.5
0.5
1
0.7
0.8
2
0.9
0.1

$$E = \frac{1}{2} \sum_{j=1}^{n} (a_2[j] - y_r[j])^2$$

$$= \frac{1}{2} ((.8896 - .1)^2 + (.8004 - .5)^2)$$

$$= .5932$$



		<i>x</i> , <i>y</i>		
$\mathbf{x_1}$	X <sub>2</sub>	<b>X</b> <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500

$w_1[i,k]$				
i	w[i,1]	w[i,2]		
0	0.5	0.5		
1	0.1	0.2		
2	0.3	0.4		
3	0.5	0.6		

$w_2[k,j]$				
k	w[k,1]	w[k,2]		
0	0.5	0.5		
1	0.7	0.8		
2	0.9	0.1		

Partial Derivative of Error with respect to Weight<sub>2</sub>[0,1]

**Functional Dependencies** 

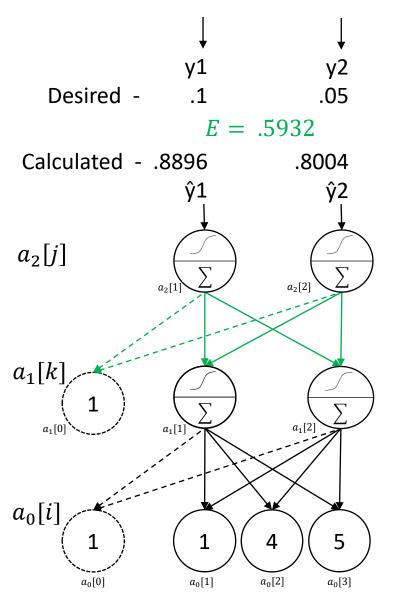
$$a_1[k] * \mathbf{w_2}[\mathbf{0}, \mathbf{1}] \rightarrow f$$

$$\sum f + .6906 + .8955 \rightarrow g$$

$$\sigma(g) \longrightarrow h$$
$$(h - y1)^2 \longrightarrow E$$

Chain Rule

$$E(h\left(g\left(f\left(w_{0,1}\right)\right)\right))$$

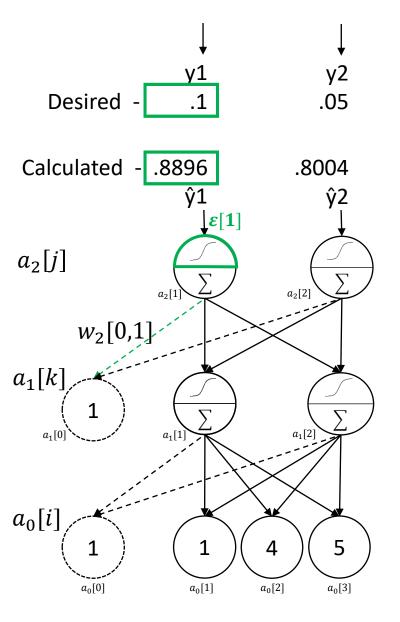


$w_1[i,k]$				
i	w[i,1]	w[i,2]		
0	0.5	0.5		
1	0.1	0.2		
2	0.3	0.4		
3	0.5	0.6		

$w_2[k,j]$				
w[k,1]	w[k,2]			
0.5	0.5			
0.7	0.8			
0.9	0.1			
	w[k,1] 0.5 0.7			

$$\frac{\partial E}{\partial w_2[k,j]} = \frac{\partial E}{\partial a_2[j]} * \frac{\partial a_2[j]}{\partial s_2[j]} * \frac{\partial s_2[j]}{\partial w_2[k,j]}$$

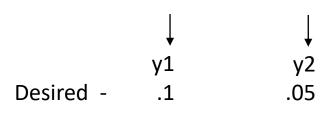
$$= \{\varepsilon[j]\} * \{a_2[j](1-a_2[j])\} * \{a_1[k]\}$$

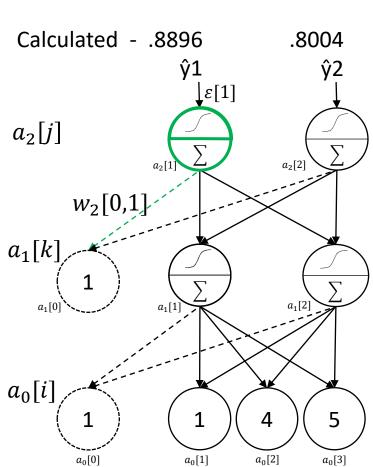


$w_1[i,k]$				
i w[i,1] w[i,2]				
0	0.5	0.5		
1	0.1	0.2		
2	0.3	0.4		
3	0.5	0.6		

$w_2[k,j]$				
k	w[k,1]	w[k,2]		
0	0.5	0.5		
1	0.7	0.8		
2	0.9	0.1		
2 0.9 0.1				

$$\frac{\partial E}{\partial w_2[0,1]} = \frac{\partial E}{\partial a_2[1]} * \frac{\partial a_2[1]}{\partial s_2[1]} * \frac{\partial s_2[1]}{\partial w_2[0,1]} 
= {\varepsilon[1]} * {a_2[1](1 - a_2[1])} * {a_1[0]} 
= .8896 - .1$$



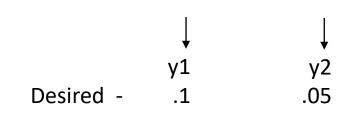


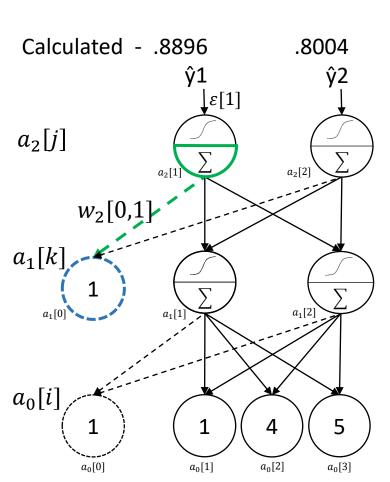
		x, y		
$\mathbf{X_1}$	X <sub>2</sub>	<b>X</b> <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500

$w_1[i,k]$				
i	w[i,1]	w[i,2]		
0	0.5	0.5		
1	0.1	0.2		
2	0.3	0.4		
3	0.5	0.6		

$w_2[k,j]$				
k	w[k,1]	w[k,2]		
0	0.5	0.5		
1	0.7	0.8		
2	0.9	0.1		

$$\frac{\partial E}{\partial w_2[0,1]} = \frac{\partial E}{\partial a_2[1]} * \frac{\partial a_2[1]}{\partial s_2[1]} * \frac{\partial s_2[1]}{\partial w_2[0,1]} 
= {\varepsilon[1]} * {a_2[1](1 - a_2[1])} * {a_1[0]} 
= .8896 - .1 * .8896(1 - .8896)$$





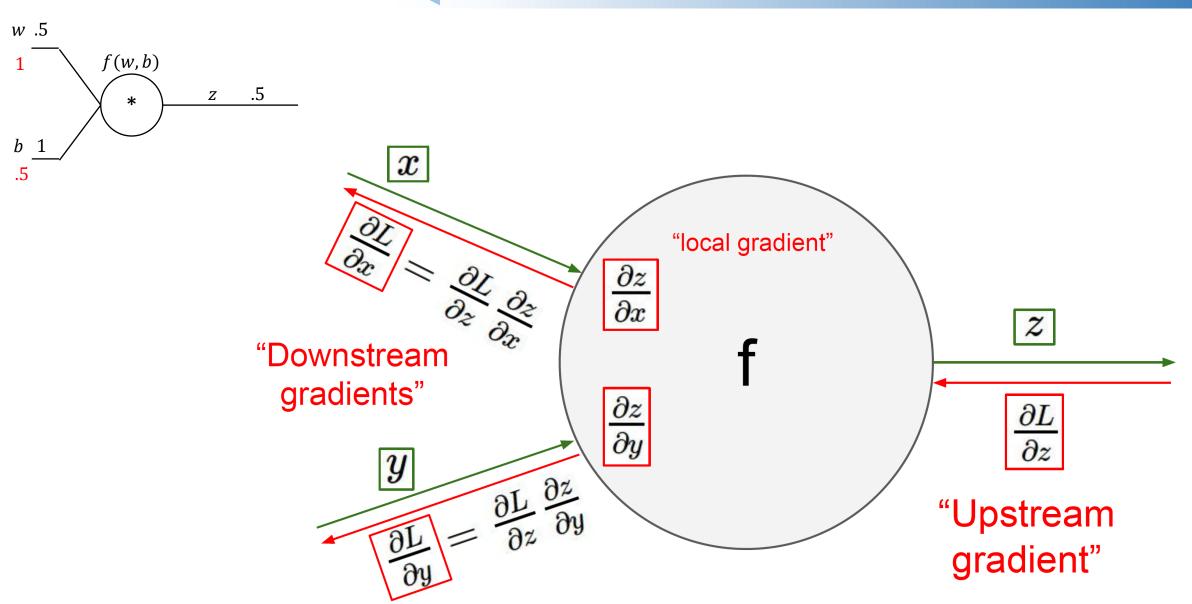
		x,y		
$\mathbf{x_1}$	X <sub>2</sub>	<b>X</b> <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500

$w_1[i,k]$			
i	w[i,1]	w[i,2]	
0	0.5	0.5	
1	0.1	0.2	
2	0.3	0.4	
3	0.5	0.6	

$w_2[k,j]$			
k	w[k,1]	w[k,2]	
0	0.5	0.5	
1	0.7	0.8	
2	0.9	0.1	
2	0.9	0.1	

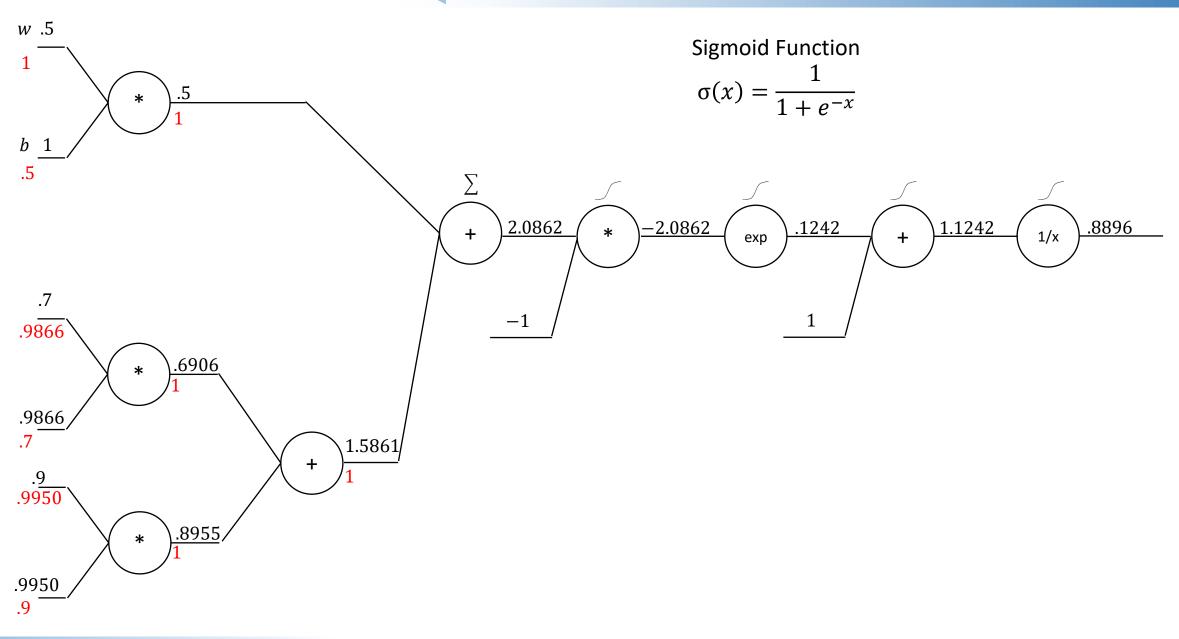
$$\frac{\partial E}{\partial w_2[0,1]} = \frac{\partial E}{\partial a_2[1]} * \frac{\partial a_2[1]}{\partial s_2[1]} * \frac{\partial s_2[1]}{\partial w_2[0,1]} 
= {\varepsilon[1]} * {a_2[1](1 - a_2[1])} * {a_1[0]} 
= .8896 - .1 * .8896(1 - .8896) * 1 
= .0775$$

## 

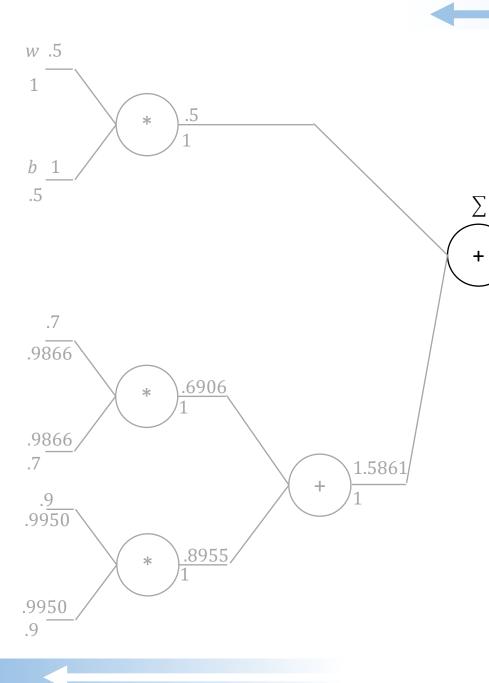


## *w* .5 2.0862 .9866 .6906 .9866 1.5861 .<u>9</u> .9950 .8955

.99<u>50</u>



1.1242



$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

.1242

$$\frac{1}{1.1242^2} = -.7913$$

.8896

1.0000

$$f(x) = ax, \qquad \frac{df}{dx} = a$$

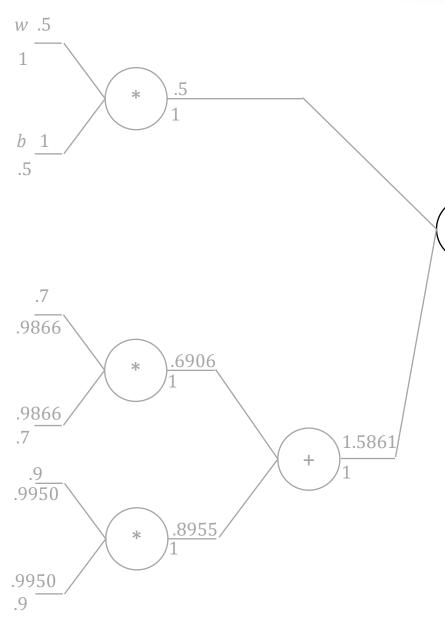
-2.0862

2.0862

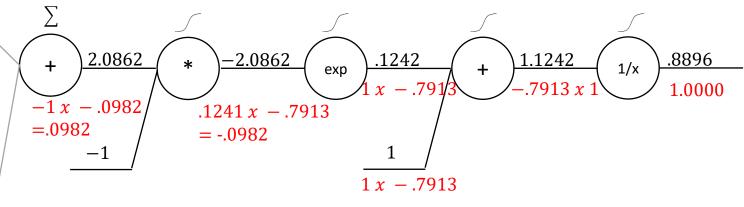
$$f(x) = e^x, \qquad \frac{df}{dx} = e^x$$

$$f(x) = c + x, \qquad \frac{df}{dx} = 1$$

$$f(x) = \frac{1}{x}, \qquad \frac{df}{dx} = -\frac{1}{x^2}$$



$$\sigma(x) = \frac{1}{1 + e^{-x}}$$



$$f(x) = ax, \qquad \frac{df}{dx} = a$$

 $e^{-2.0862} = .1241$ 

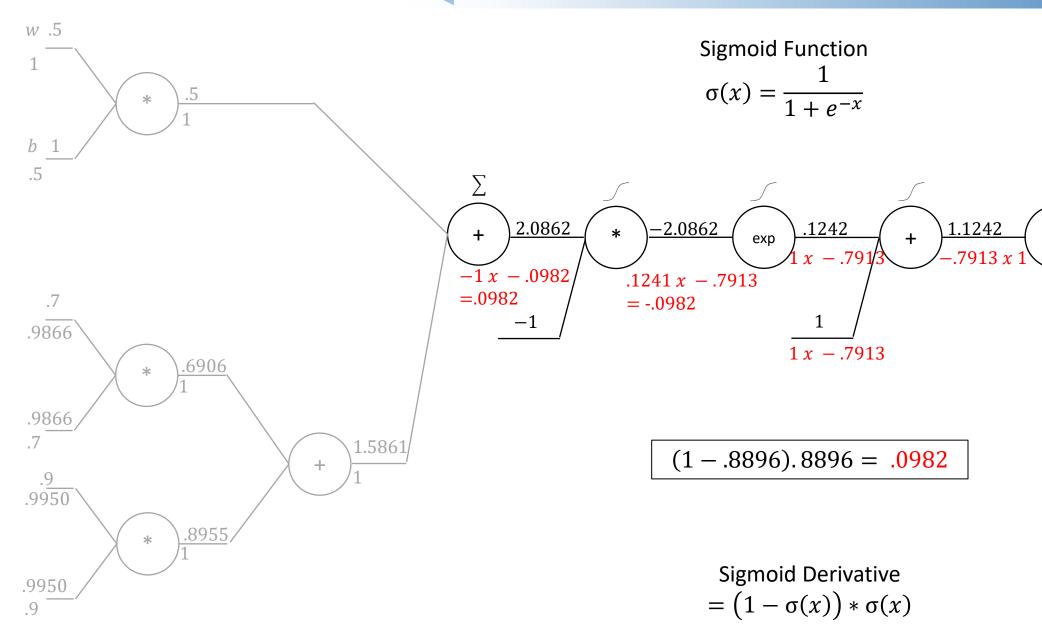
$$f(x) = c + x, \qquad \frac{df}{dx} = 1$$

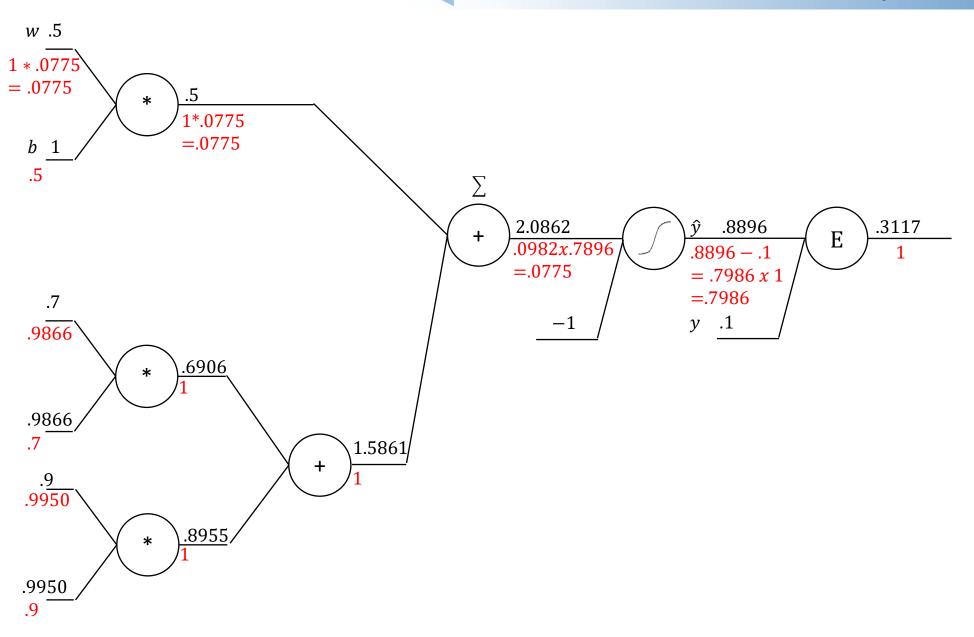
$$f(x) = e^x, \qquad \frac{df}{dx} = e^x$$

$$f(x) = \frac{1}{x}, \qquad \frac{df}{dx} = -\frac{1}{x^2}$$

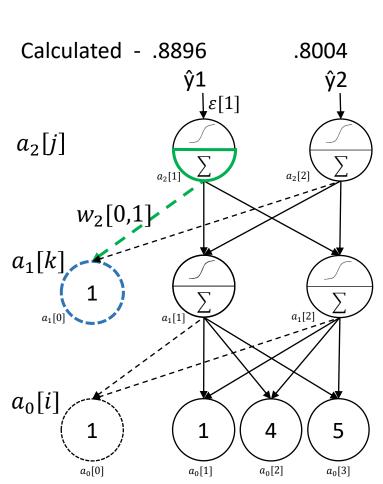
.8896

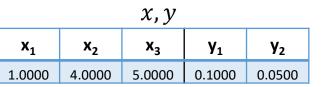
1.0000





# $\begin{array}{cccc} & \downarrow & \downarrow \\ & \downarrow & \\ & y1 & y2 \\ \text{Desired -} & .1 & .05 \end{array}$





$w_1[i,k]$			
i	w[i,1]	w[i,2]	
0	0.5	0.5	
1	0.1	0.2	
2	0.3	0.4	
3	0.5	0.6	

$w_2[k,j]$			
w[k,1]	w[k,2]		
0.5	0.5		
0.7	0.8		
0.9	0.1		
	w[k,1] 0.5 0.7		

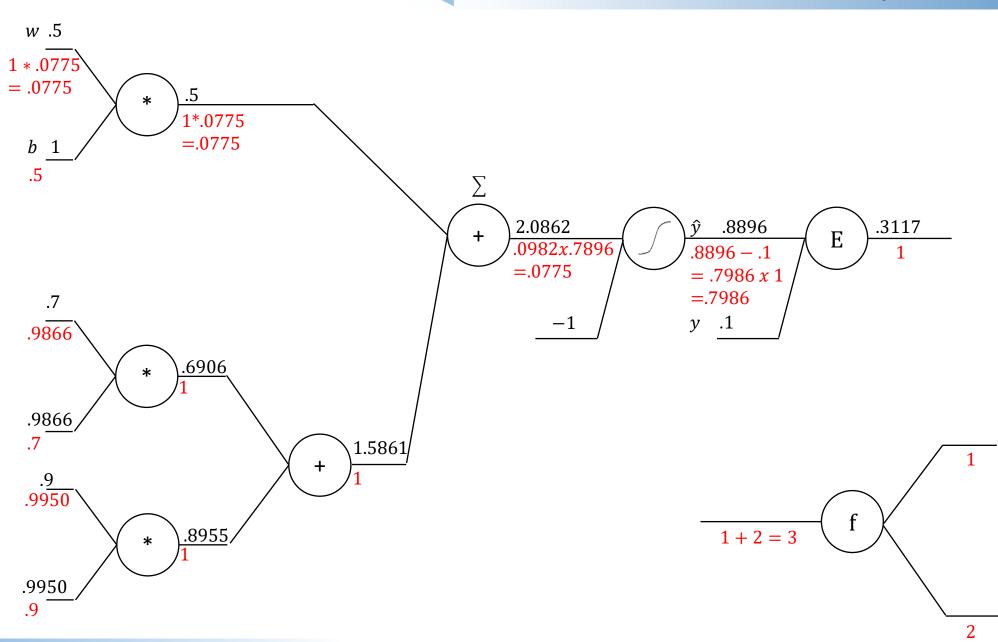
$$\frac{\partial E}{\partial w_2[0,1]} = \frac{\partial E}{\partial a_2[1]} * \frac{\partial a_2[1]}{\partial s_2[1]} * \frac{\partial s_2[1]}{\partial w_2[0,1]}$$

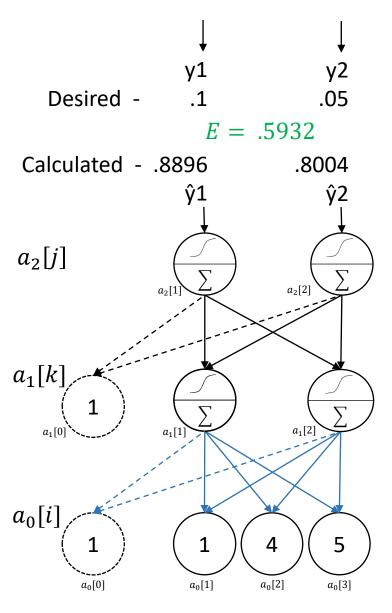
$$= \{\varepsilon[1]\} * \{a_2[1](1 - a_2[1])\} * \{a_1[0]\}$$

$$= .8896 - .1 * .8896(1 - .8896) * 1$$

$$= .0775$$

$c_2[k,j]$			
k	c[k,1]	c[k,2]	
0	.0775	0	
1	0	0	
2	0	0	



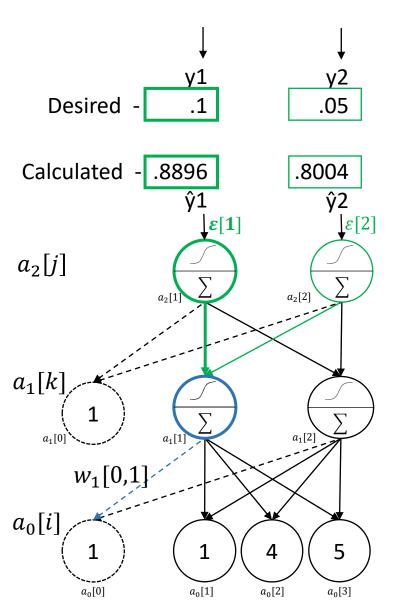


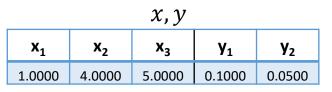
$w_1[i,k]$				
i	w[i,1]	w[i,2]		
0	0.5	0.5		
1	0.1	0.2		
2	0.3	0.4		
3	0.5	0.6		

$w_2[k,j]$			
k	w[k,1]	w[k,2]	
0	0.5	0.5	
1	0.7	0.8	
2	0.9	0.1	

$$\frac{\partial E}{\partial w_1[i,k]} = \frac{\partial E}{\partial a_1[k]} * \frac{\partial a_1[k]}{\partial s_1[k]} * \frac{\partial s_1[k]}{\partial w_1[i,k]}$$

$$= \frac{\partial E}{\partial a_1[k]} * \{a_1[j](1-a_1[j])\} * \{a_0[i]\}$$





$w_1[i,k]$			
i	w[i,1]	w[i,2]	
0	0.5	0.5	
1	0.1	0.2	
2	0.3	0.4	
3	0.5	0.6	

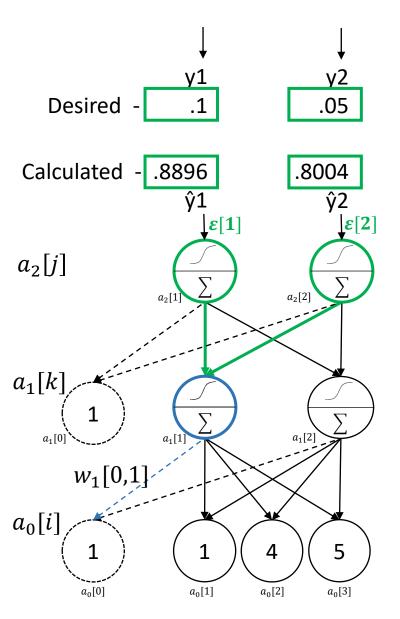
$w_2[k,j]$			
k	w[k,1]	w[k,2]	
0	0.5	0.5	
1	0.7	0.8	
2	0.9	0.1	

$$\frac{\partial E}{\partial w_1[i,k]} = \frac{\partial E}{\partial a_1[k]} * \frac{\partial a_1[k]}{\partial s_1[k]} * \frac{\partial s_1[k]}{\partial w_1[i,k]}$$

$$= \frac{\partial E}{\partial a_1[k]} * \{a_1[k](1-a_1[k])\} * \{a_0[i]\}$$

$$\frac{\partial E}{\partial a_1[k]} = \sum_{j=1}^n \frac{\partial E}{\partial a_2[j]} * \frac{\partial a_2[j]}{\partial s_2[j]} * \frac{\partial s_2[j]}{\partial a_1[k,j]}$$

$$= \sum_{j=1}^n \{\varepsilon[j]\} * \{a_2[j](1-a_2[j])\} * \{w_2[k,j]\}$$

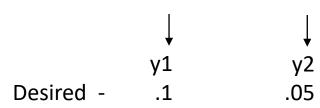


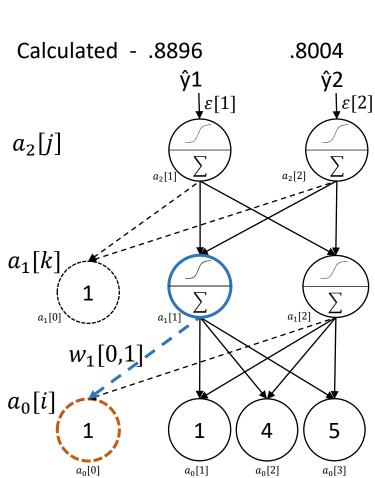
		<i>x</i> , <i>y</i>		
$\mathbf{x_1}$	X <sub>2</sub>	<b>X</b> <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500

$w_1[i,k]$				
i	w[i,1]	w[i,2]		
0	0.5	0.5		
1	0.1	0.2		
2	0.3	0.4		
3	0.5	0.6		

$w_2[k,j]$			
k	w[k,1]	w[k,2]	
0	0.5	0.5	
1	0.7	8.0	
2	0.9	0.1	

$$\frac{\partial E}{\partial w_1[0,1]} = \frac{\partial E}{\partial a_1[1]} * \frac{\partial a_1[1]}{\partial s_1[1]} * \frac{\partial s_1[1]}{\partial w_1[0,1]} * \frac{\partial F}{\partial w_1[0,1]} = \frac{\partial F}{\partial a_1[1]} * \frac{\partial F}{\partial a_1[1]} * \frac{\partial F}{\partial a_1[1]} * \frac{\partial F}{\partial a_2[1]} * \frac{\partial F}{\partial a_2[1]} * \frac{\partial F}{\partial a_2[1]} * \frac{\partial F}{\partial a_2[1]} * \frac{\partial F}{\partial a_1[1]} * \frac{\partial F}{\partial a_1[$$





x, y		
<b>X</b> <sub>3</sub>	<b>y</b> <sub>1</sub>	<b>y</b> <sub>2</sub>
5.0000	0.1000	0.0500

 $\mathbf{x_1}$ 

1.0000

 $\mathbf{X_2}$ 

4.0000

$w_1[i,k]$			
i	w[i,1]	w[i,2]	
0	0.5	0.5	
1	0.1	0.2	
2	0.3	0.4	
3	0.5	0.6	

$w_2[k,j]$			
k	w[k,1]	w[k,2]	
0	0.5	0.5	
1	0.7	0.8	
2	0.9	0.1	

$$\frac{\partial E}{\partial w_1[0,1]} = \frac{\partial E}{\partial a_1[1]} * \frac{\partial a_1[1]}{\partial s_1[1]} * \frac{\partial s_1[1]}{\partial w_1[0,1]}$$

$$= \frac{\partial E}{\partial a_1[1]} * \{a_1[1](1 - a_1[1])\} * \{a_0[0]\}$$

$$= .1502 * .9866(1 - .9866) * 1$$

$$= .0020$$

 $c_1[i,k]$ 

<u> </u>				
i	w[i,1]	w[i,2]		
0	.0020	0		
1	0	0		
2	0	0		
3	0	0		

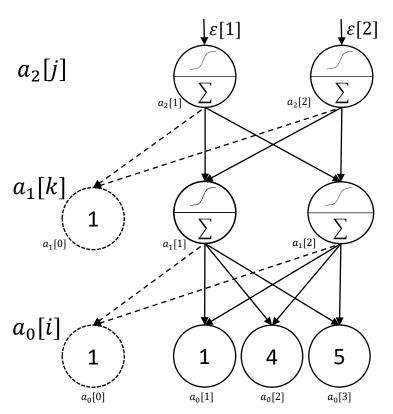


Desired - y1

y2

Calculated - ŷ1

ŷ2



### Backpropagation

*x*, *y* 

r =1

r =4

X <sub>1</sub>	X <sub>2</sub>	X <sub>3</sub>	y <sub>1</sub>	y <sub>2</sub>
1.0000	4.0000	5.0000	0.1000	0.0500
0.1000	-5.0000	3.0000	0.1221	0.0964
6.0000	-5.5420	4.8970	0.1061	0.0702
4.0000	8.0000	9.0000	0.0996	0.0641
12.0000	-2.0000	0.0063	0.1110	0.0732
6.0000	-5.5000	4.8970	0.1060	0.0701

Learning rate  $\alpha = .01$  $w^* = w - \alpha * c$ 

V	$v_1$	[i,	k]	

i	w[i,1]	w[i,2]
0	0.5	0.5
1	0.1	0.2
2	0.3	0.4
3	0.5	0.6

$W_2$	[k,	j
	L '.	, ,

w[k,1]	w[k,2]
0.5	0.5
0.7	0.8
0.9	0.1
	0.5

### $c_1[i,k]$

<u>*</u> L ' J			
i	w[i,1]	w[i,2]	
0	.0604	.0332	
1	.1134	.0427	
2	2929	1658	
3	.2193	.1129	

### $c_2[k,j]$

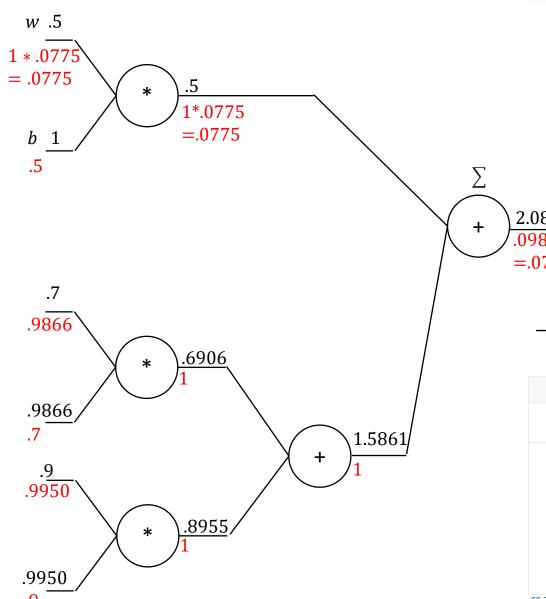
k	c[k,1]	c[k,2]
0	.3447	.4816
1	.2929	.4176
2	.2930	.4191

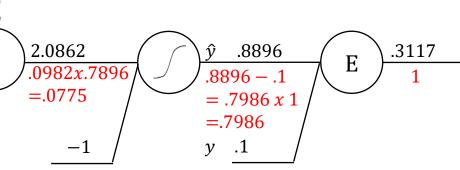
### $w_1^*[i,k]$

w[i,1]	w[i,2]		
.4994	.4997		
.0989	.1996		
.3029	.4017		
.4978	.5989		
	.4994 .0989 .3029		

### $w_2^*[k,j]$

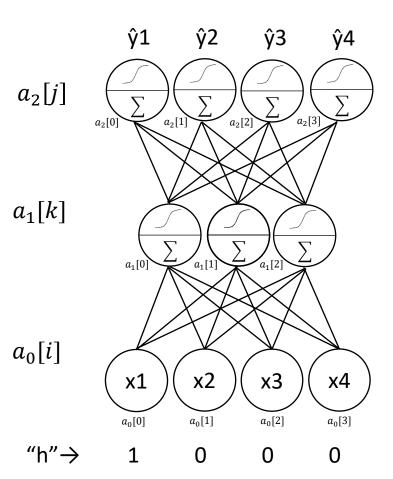
k	w[k,1]	w[k,2]
0	.4966	.0039
1	.4971	.0038
2	.0021	.0004





Sigmoid	Tanh	RELU
$g(z) = \frac{1}{1+e^{-z}}$	$g(z)=rac{e^z-e^{-z}}{e^z+e^{-z}}$	$g(z) = \max(0,z)$
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	

CS 230 - Recurrent Neural Networks Cheatsheet (stanford.edu)



### Character Prediction

"hello"

### Vocabulary

```
"h" [1, 0, 0, 0]
"e" [0, 1, 0, 0]
"l" [0, 0, 1, 0]
"o" [0, 0, 0, 1]
```

### Character Prediction



### Vocabulary

$$"" \rightarrow ""$$
 $"" \rightarrow "o"$ 

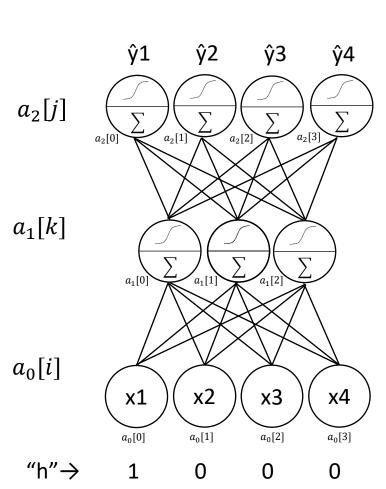
"hel"
$$\rightarrow$$
 "p"

"hell" 
$$\rightarrow$$
 "o"

"heliu" 
$$\rightarrow$$
 "m"

**Ambiguous Targets** 

Fixed Width Input/Output



$$a_{2}[j]$$
  $a_{2}[0]$   $a_{2}[1]$   $a_{2}[2]$   $a_{2}[3]$   $a_{2}[3]$ 

0

0

0

"h"→

### Character Prediction

"hello"

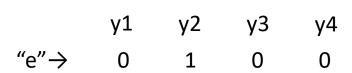
#### Vocabulary

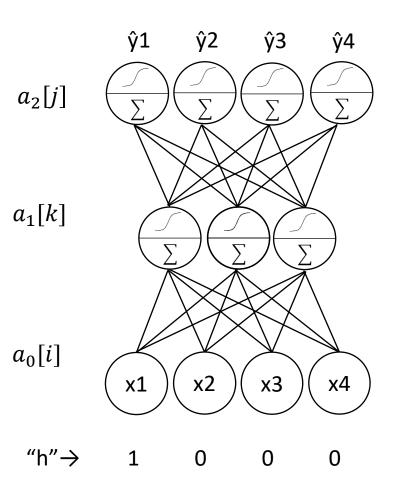
"e"
$$\rightarrow$$
 "I"

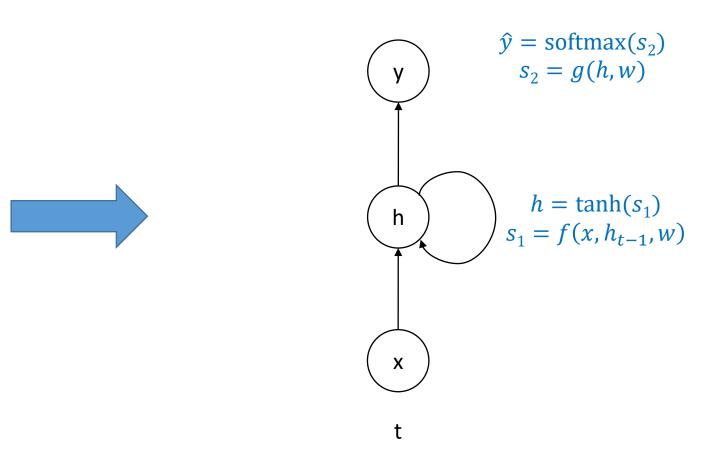
$$"" \rightarrow ""$$
 $"" \rightarrow "o"$ 

**Ambiguous Targets** 

### Recurrent Neural Networks

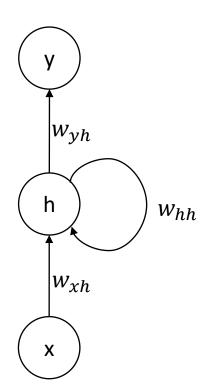


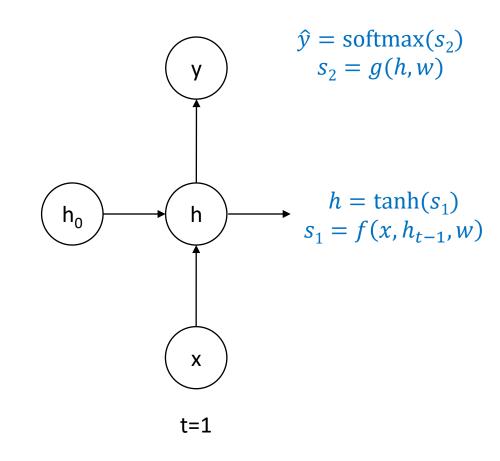


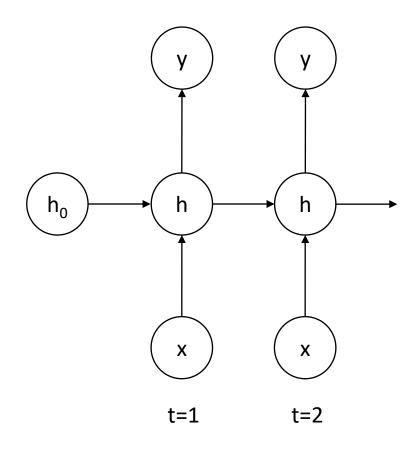


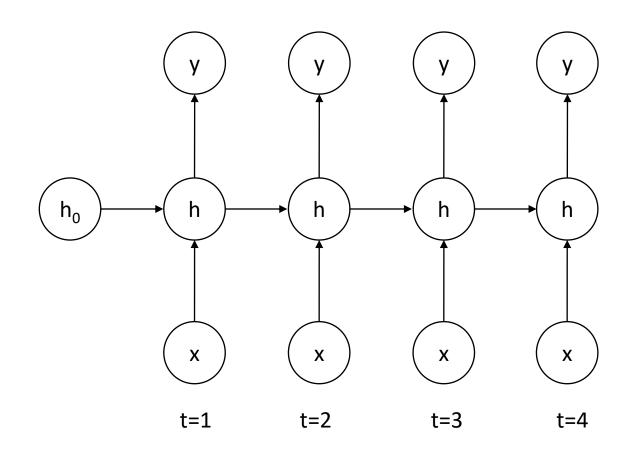
### Recurrent Neural Networks

$$W_{yh} H \\ Y \begin{bmatrix} y_1 h_1, y_2 h_2 \dots y_1 h_k \\ y_2 h_1, y_2 h_2 \dots y_2 h_k \\ y_n h_1, y_n \ddot{h_2} \dots y_n h_k \end{bmatrix}$$









$$\begin{bmatrix} w_{yh} & w_{yh} & b_{x} \\ y_{2}h_{1}, y_{2}h_{2} \dots y_{2}h_{k} \\ y_{2}h_{1}, y_{2}h_{2} \dots y_{2}h_{k} \\ y_{n}h_{1}, y_{n}h_{2} \dots y_{n}h_{k} \end{bmatrix} * \begin{bmatrix} h_{1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} = \begin{bmatrix} s_{1} \\ s_{2} \\ \dots \\ s_{k} \end{bmatrix}, \text{ softmax}(s_{2}) = \begin{bmatrix} y_{1} \\ y_{2} \\ \dots \\ y_{k} \end{bmatrix}$$

$$\begin{bmatrix} w_{xh} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} x_{1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} + \begin{bmatrix} h_{t-1} \\ h_{t}h_{1}, h_{1}h_{2} \dots h_{1}h_{k} \\ h_{2}h_{1}, h_{2}h_{2} \dots h_{2}h_{k} \\ h_{k}h_{1}, h_{k}h_{2} \dots h_{k}h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} = \begin{bmatrix} s_{1} \\ s_{2} \\ \dots \\ s_{k} \end{bmatrix}, \text{ tanh}(s_{1}) = \begin{bmatrix} h_{1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix}$$

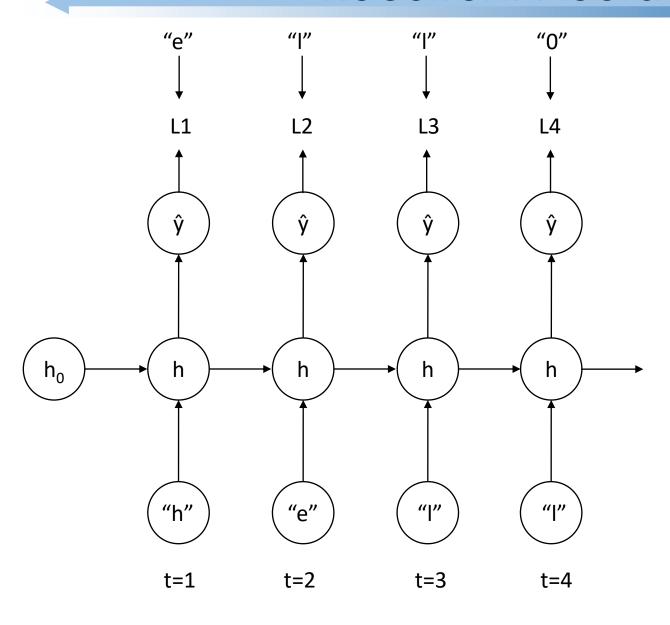
$$\begin{bmatrix} h_{1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{2} \\ \dots \\ h_{k} \end{bmatrix} * \begin{bmatrix} h_{t-1} \\ h_{$$

$$\begin{bmatrix} y_1h_1, y_2h_2 \dots y_1h_k \\ y_2h_1, y_2h_2 \dots y_2h_k \\ y_nh_1, y_nh_2 \dots y_nh_k \end{bmatrix} * \begin{bmatrix} h_1 \\ h_2 \\ h_2 \\ \dots \\ h_k \end{bmatrix} = \begin{bmatrix} s_1 \\ s_2 \\ \dots \\ s_k \end{bmatrix}, \text{ softmax}(s_2) = \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_k \end{bmatrix}$$

$$\begin{bmatrix} h_1x_1, h_1x_2 \dots h_1x_m \\ h_2x_1, h_2x_2 \dots h_2x_m \\ h_kx_1, h_k\ddot{x_2} \dots h_kx_m \end{bmatrix} * \begin{bmatrix} x \\ x_1 \\ x_2 \\ \dots \\ x_m \end{bmatrix} + \begin{bmatrix} h_1h_1, h_1h_2 \dots h_1h_k \\ h_2h_1, h_2h_2 \dots h_2h_k \\ h_kh_1, h_kh_2 \dots h_kh_k \end{bmatrix} * \begin{bmatrix} h_1 \\ h_2 \\ \dots \\ h_k \end{bmatrix} * \begin{bmatrix} h_1 \\ h_2 \\ \dots \\ h_k \end{bmatrix}, \text{ tanh}(s_1) = \begin{bmatrix} h_1 \\ h_2 \\ \dots \\ h_k \end{bmatrix}$$

$$L_{total} = -\sum_{t=1}^{n} y_t \log(\hat{y})$$

 $L_t = -y_t \log(\hat{y})$ Multi-class Cross Entropy Loss

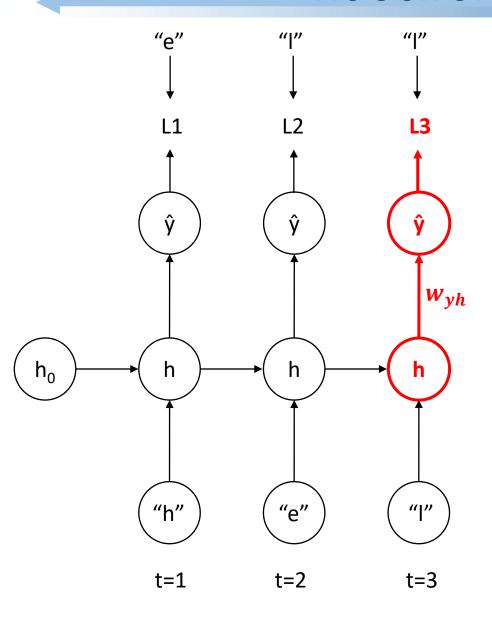


$$L_{total} = -\sum_{t=1}^{n} y_t \log(\hat{y})$$

$$L_t = -y_t \log(\hat{y})$$

Part 2: Softmax Regression (saitcelebi.com)

How to compute the derivative of softmax and cross-entropy – Charlee Li



$$\frac{\partial L3}{\partial W_{yh}} = \frac{\partial L3}{\partial \hat{Y}3} * \frac{\partial \hat{Y}3}{\partial W_{yh}}$$

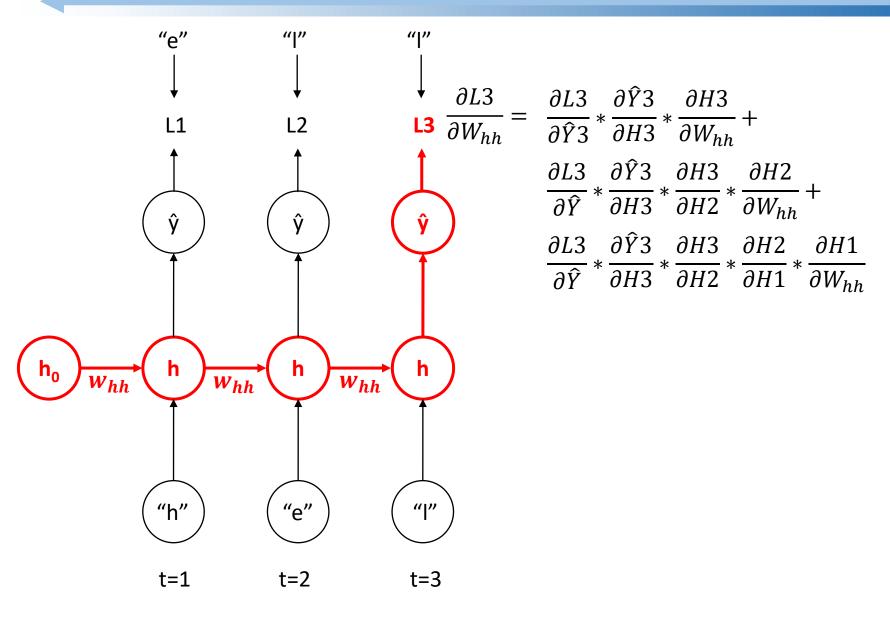
$$\frac{\partial LT}{\partial W_{yh}} = \frac{\partial LT}{\partial \hat{Y}T} * \frac{\partial \hat{Y}T}{\partial W_{yh}}$$

$$L_{total} = -\sum_{t=1}^{n} y_t \log(\hat{y})$$

$$L_t = -y_t \log(\hat{y})$$

Part 2: Softmax Regression (saitcelebi.com)

How to compute the derivative of softmax and cross-entropy – Charlee Li

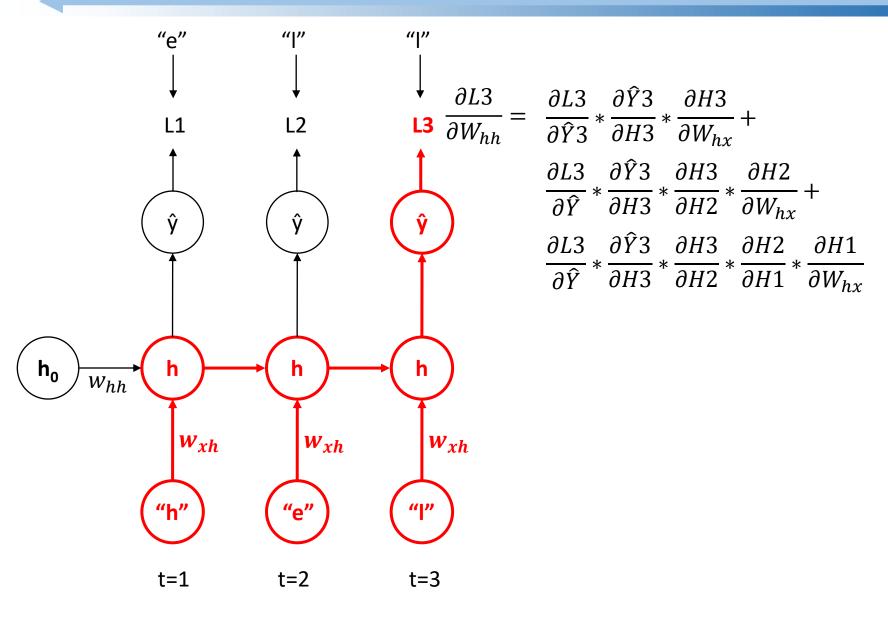


$$L_{total} = -\sum_{t=1}^{n} y_t \log(\hat{y})$$

$$L_t = -y_t \log(\hat{y})$$

Part 2: Softmax Regression (saitcelebi.com)

How to compute the derivative of softmax and cross-entropy – Charlee Li

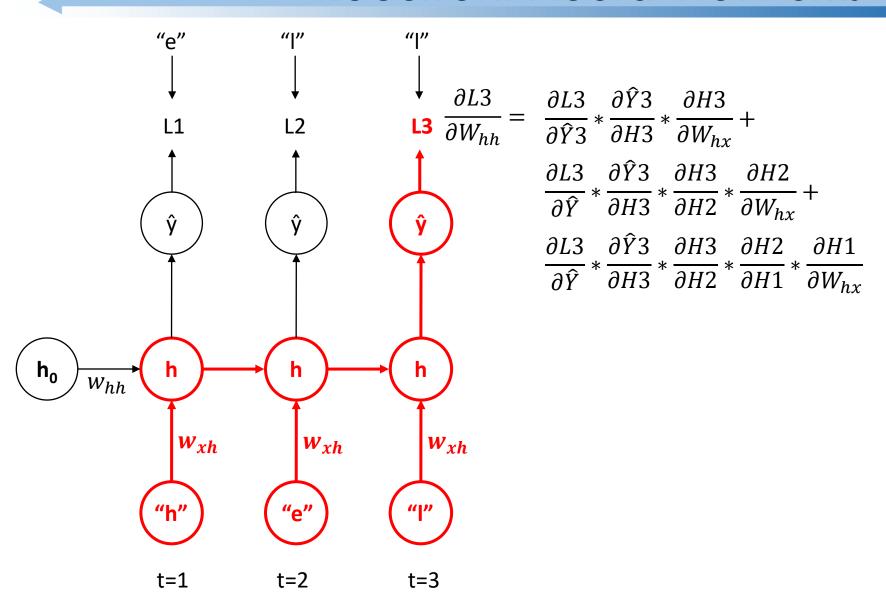


$$L_{total} = -\sum_{t=1}^{n} y_t \log(\hat{y})$$

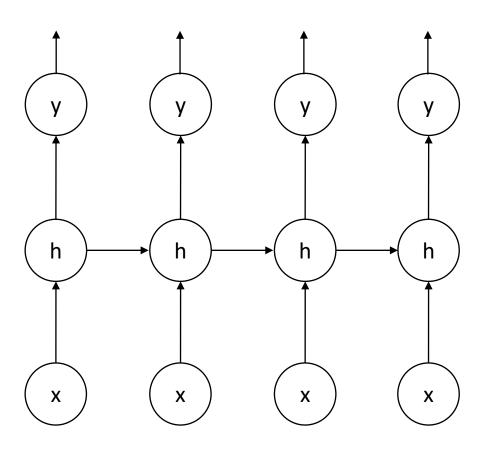
$$L_t = -y_t \log(\hat{y})$$

Part 2: Softmax Regression (saitcelebi.com)

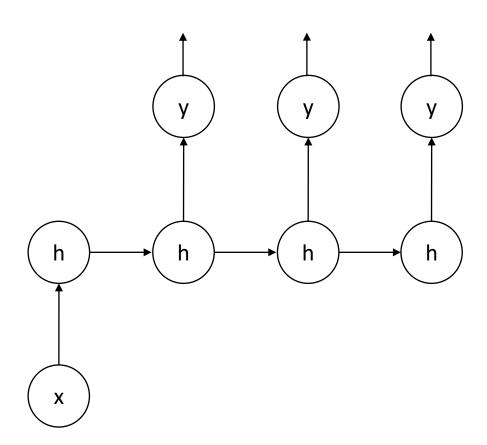
How to compute the derivative of softmax and cross-entropy – Charlee Li



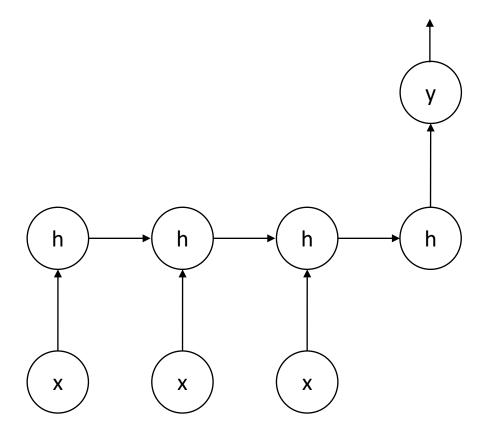
#### One-to-One



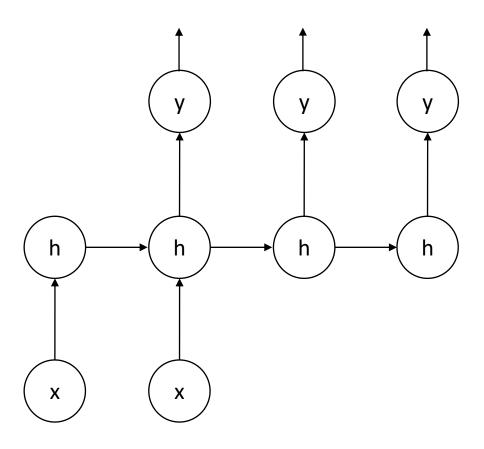
# One-to-Many



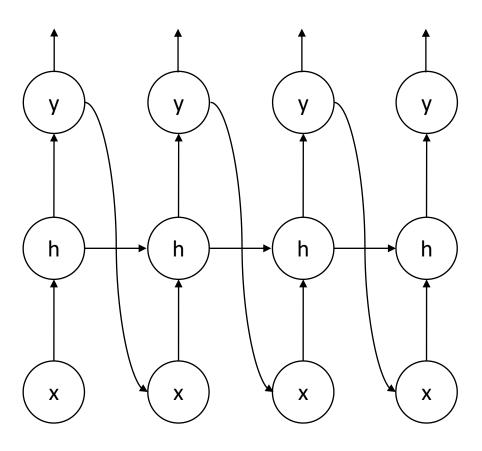
## Many-to-One



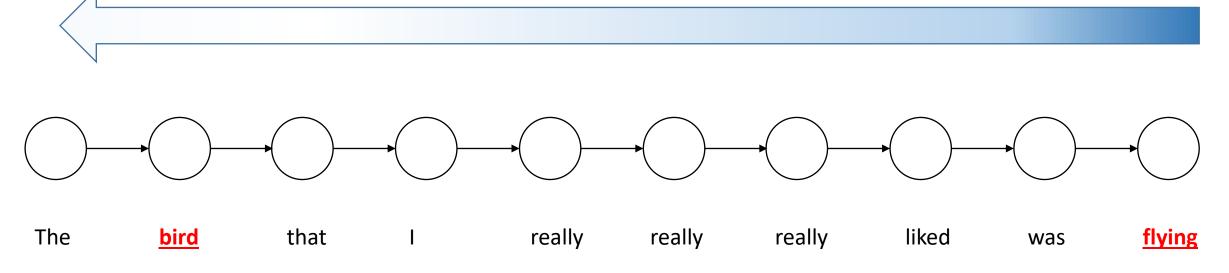
## Many-to-Many



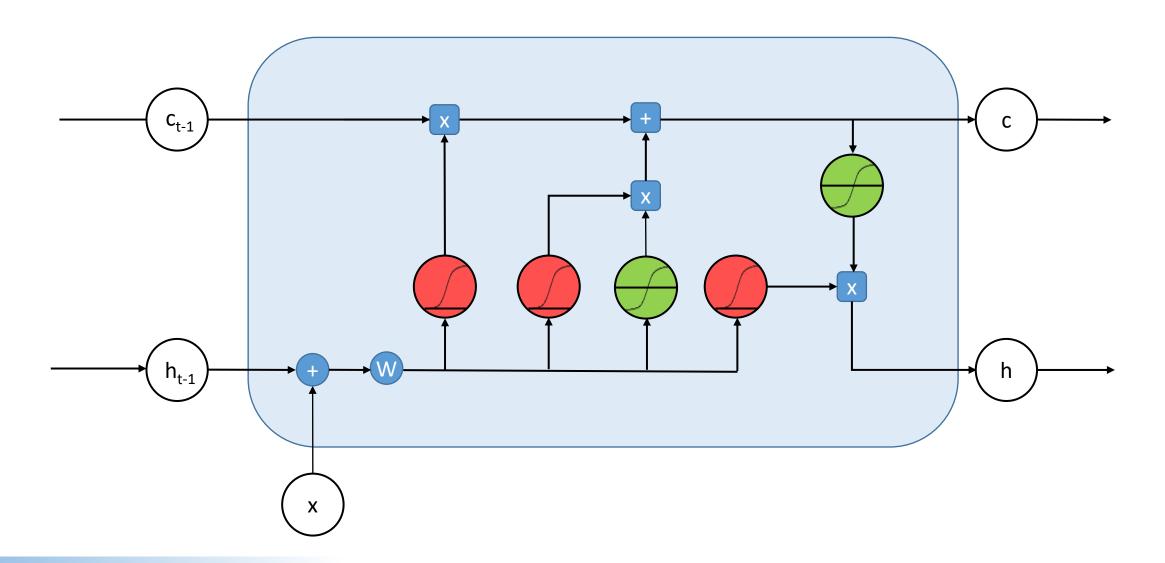
### Generation

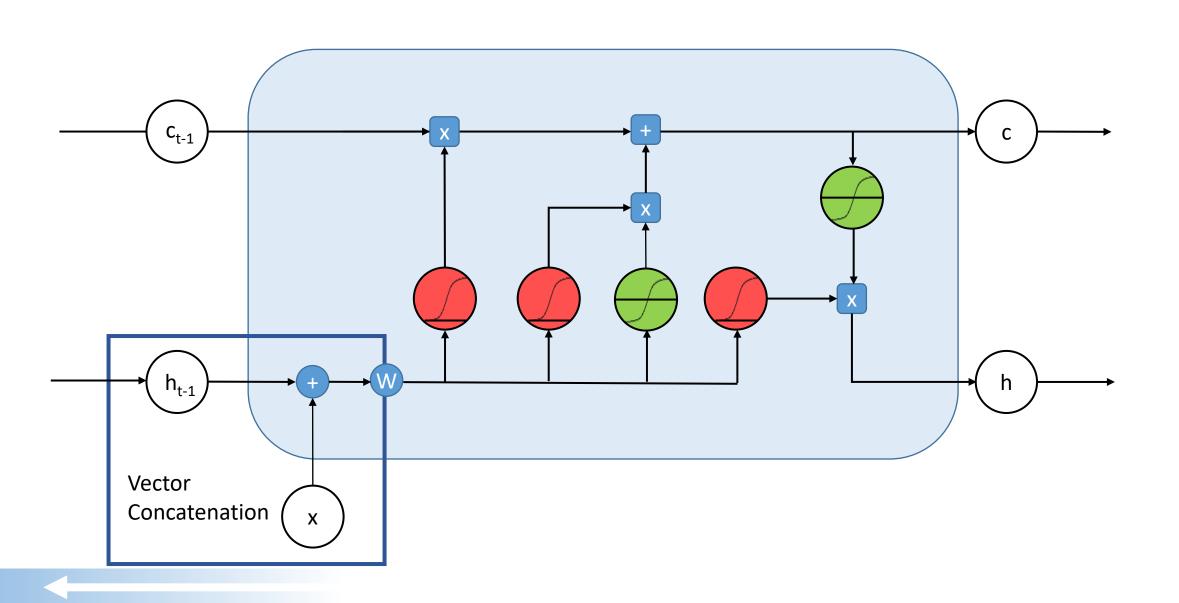


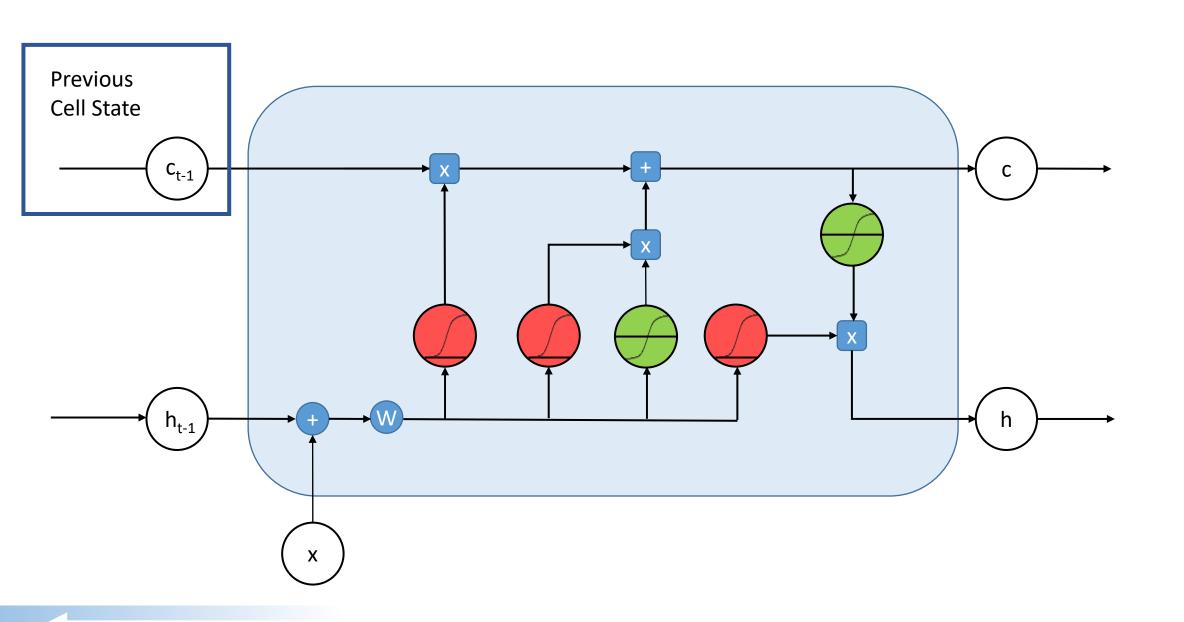
## Vanishing Gradients

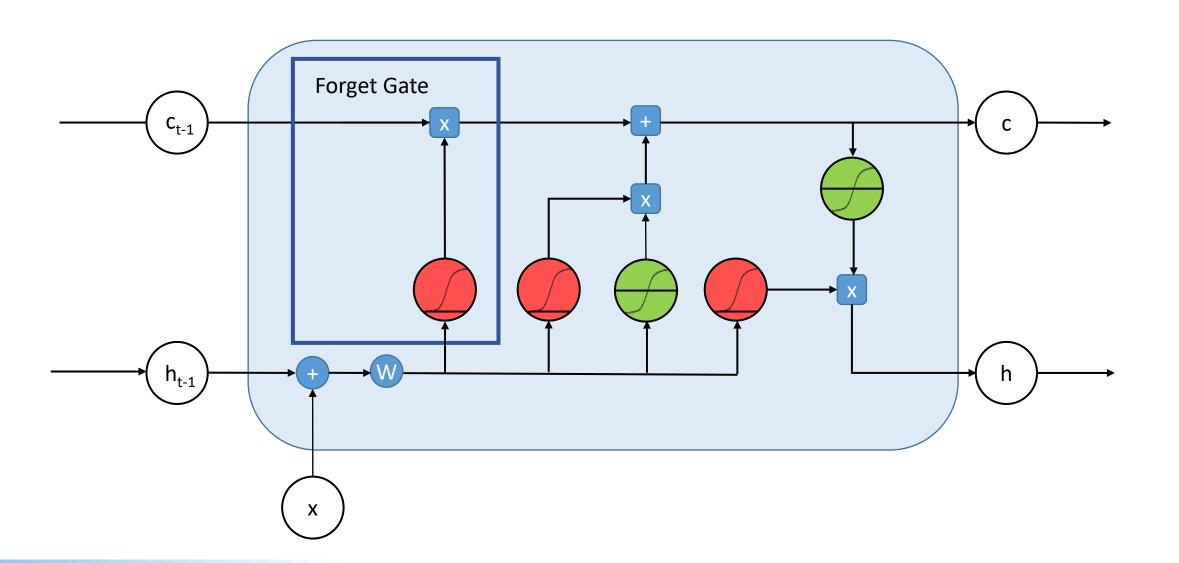


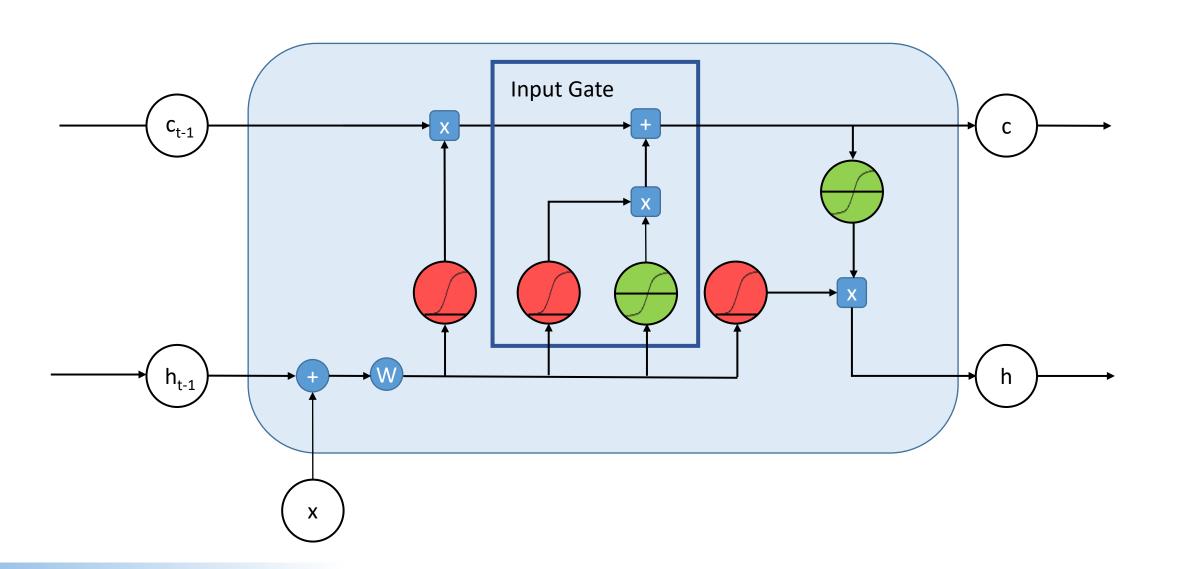


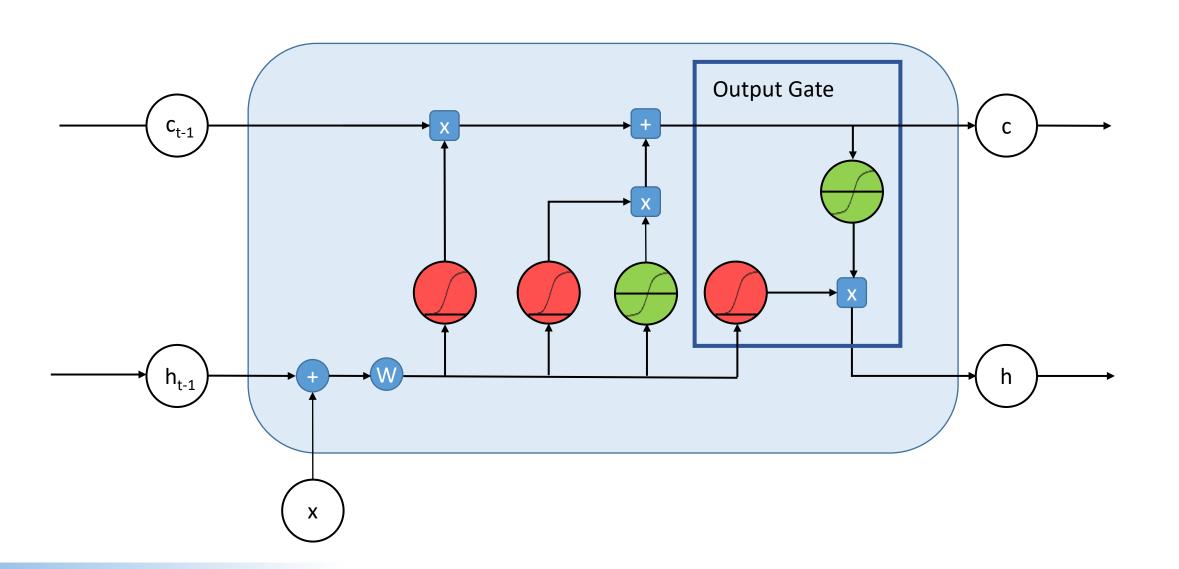


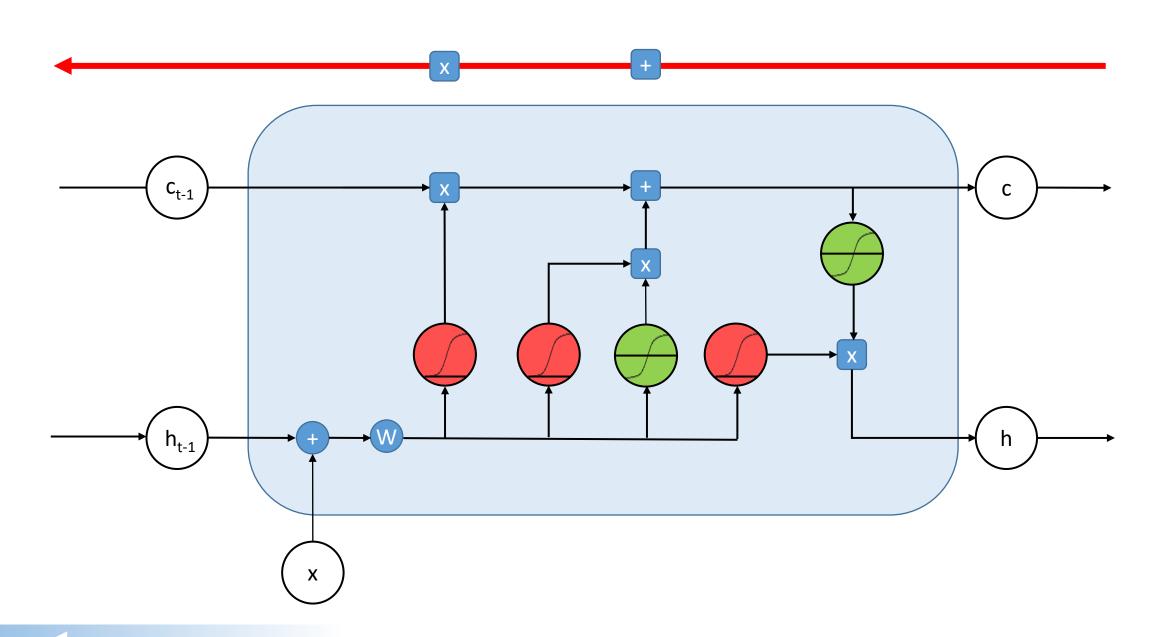












```
"You mean to imply that I have nothing to eat out of.... On the contrary, I can supply you with everything even if you want to give dinner parties," warmly replied Chichagov, who tried by every word he spoke to prove his own rectitude and therefore imagined Kutuzov to be animated by the same desire.

Kutuzov, shrugging his shoulders, replied with his subtle penetrating smile: "I meant merely to say what I said."
```

#### quote detection cell

```
The sole importance of the crossing of the Berezina lies in the fact that it plainly and indubitably proved the fallacy of all the plans for cutting off the enemy's retreat and the soundness of the only possible line of action--the one Kutuzov and the general mass of the army demanded--namely, simply to follow the enemy up. The French crowd fled at a continually increasing speed and all its energy was directed to reaching its goal. It fled like a wounded animal and it was impossible to block its path. This was shown not so much by the arrangements it made for crossing as by what took place at the bridges. When the bridges broke down, unarmed soldiers, people from Moscow and women with children who were with the French transport, all--carried on by vis inertiae--pressed forward into boats and into the ice-covered water and did not, surrender.
```

line length tracking cell