

CMPT 435L ALGORITHMS

Assignment 3

November 15th 2024

Jonathan "Grant" Bever

[Link to github repo](#)

PART 1: Using the Bellman-Ford dynamic programming algorithm for Single Source Shortest Path (SSSP)

The Bellman-Ford algorithm is an approach to finding the shortest paths from a single source vertex to all other vertices in a weighted directed graph.

The algorithm begins by initializing the distance to the source vertex as 1 and all other vertices as infinity. It then systematically refines these distance estimates. The algorithm has a time complexity of $O(VE)$, where V is the number of vertices and E is the number of edges, and is particularly valuable because it can handle negative edge weights as long as there are no negative cycles.

After bringing our data into linked object representation we can apply the Bellman Ford algorithm to get this.

```
1 export function bellmanFord(graph: Graph, source: number):  
  BellmanFordResult {  
2     const distances = new Map<number, number>();  
3     const predecessors = new Map<number, number | null>();  
4     const vertices = graph.vertices;  
5     const edges = graph.edges;  
6     // Initialize distances and predecessors  
7     vertices.forEach(vertex => {  
8         distances.set(vertex, Infinity);  
9         predecessors.set(vertex, null);  
10    });  
11    distances.set(source, 0);  
12    // Relax edges |V| - 1 times  
13    for (let i = 0; i < vertices.length - 1; i++) {  
14        edges.forEach(([from, to, weight]) => {  
15            const distFrom = distances.get(from)!;  
16            const distTo = distances.get(to)!;  
17            if (distFrom !== Infinity && distFrom + weight <  
                distTo) {  
18                distances.set(to, distFrom + weight);  
19                predecessors.set(to, from); }  
20        }) } }
```

```

21 // Check for negative cycles
22 let hasNegativeCycle = false;
23 edges.forEach(([from, to, weight]) => {
24     if (distances.get(from)! !== Infinity &&
25         distances.get(from)! + weight < distances.get(to)!) {
26         hasNegativeCycle = true;      } });

```

This code begins by creating two Map structures: one for tracking the shortest distances to each vertex and another for storing the predecessor vertices that form the shortest paths. During initialization, all distances are set to Infinity except for the source vertex which is set to 0, and all predecessor pointers are set to null.

The second phase is the main relaxation phase, where the algorithm performs $|V| - 1$ iterations (V being the number of vertices) over all edges in the graph. Each iteration examines every edge and checks if taking that edge would result in a shorter path to its destination vertex. When a shorter path is found, both the distance to that vertex and its predecessor pointer are updated.

The final phase is the negative cycle detection, which makes one last pass through all edges in the graph. If during this pass the algorithm finds that any distance can still be improved it sets a `hasNegativeCycle` flag to true. This check works because after $|V| - 1$ iterations, all legitimate shortest paths should have been found, so any further improvements indicate the presence of a negative cycle that could be traversed indefinitely to keep reducing the path length.

RESULTS

Graph #1

- $1 \rightarrow 2$: Cost = 2, Path: $1 \rightarrow 4 \rightarrow 3 \rightarrow 2$
- $1 \rightarrow 3$: Cost = 4, Path: $1 \rightarrow 4 \rightarrow 3$
- $1 \rightarrow 4$: Cost = 7, Path: $1 \rightarrow 4$
- $1 \rightarrow 5$: Cost = -2, Path: $1 \rightarrow 4 \rightarrow 3 \rightarrow 2 \rightarrow 5$

Graph #2

- $1 \rightarrow 2$: Cost = 0, Path: $1 \rightarrow 2$
- $1 \rightarrow 3$: Cost = 0, Path: $1 \rightarrow 2 \rightarrow 3$
- $1 \rightarrow 4$: Cost = 0, Path: $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$
- $1 \rightarrow 5$: Cost = 0, Path: $1 \rightarrow 5$
- $1 \rightarrow 6$: Cost = 0, Path: $1 \rightarrow 6$
- $1 \rightarrow 7$: Cost = 0, Path: $1 \rightarrow 5 \rightarrow 7$

Graph #3

- $1 \rightarrow 2$: Cost = 1, Path: $1 \rightarrow 2$
- $1 \rightarrow 3$: Cost = 2, Path: $1 \rightarrow 2 \rightarrow 3$
- $1 \rightarrow 4$: Cost = 3, Path: $1 \rightarrow 2 \rightarrow 3 \rightarrow 4$
- $1 \rightarrow 5$: Cost = 1, Path: $1 \rightarrow 5$
- $1 \rightarrow 6$: Cost = 1, Path: $1 \rightarrow 6$
- $1 \rightarrow 7$: Cost = 2, Path: $1 \rightarrow 5 \rightarrow 7$

Graph #4

- $1 \rightarrow 2$: Cost = 2, Path: $1 \rightarrow 2$
- $1 \rightarrow 3$: Cost = 6, Path: $1 \rightarrow 2 \rightarrow 5 \rightarrow 3$
- $1 \rightarrow 4$: Cost = 7, Path: $1 \rightarrow 2 \rightarrow 5 \rightarrow 3 \rightarrow 4$
- $1 \rightarrow 5$: Cost = 1, Path: $1 \rightarrow 2 \rightarrow 5$
- $1 \rightarrow 6$: Cost = 3, Path: $1 \rightarrow 6$
- $1 \rightarrow 7$: Cost = 2, Path: $1 \rightarrow 2 \rightarrow 5 \rightarrow 7$

Part 2: Spice Heist