

Clockwise (CW) Path

$$v_{prop} = c - v_{drift}$$

Metric Drag Delay

$$L_{vac}(+v)$$

Coherent Source ( $E_0 \sin(\omega t)$ )



Beam Splitter

Interferometric Detector  
 $\Delta\Phi = \oint \mathbf{v}_{drift} \cdot d\mathbf{l}$

Macroscopic Entrainment Ring ( $\Omega$ )

Metric Drag Advance

$$L_{vac}(-v)$$

Counter-Clockwise (CCW) Path

$$v_{prop} = c + v_{drift}$$