

Clockwise (CW) Path

$$v_{prop} = c - v_{drift}$$

Metric Drag Delay

$$\mathbf{L}_{vac}(+\mathbf{v})$$

Coherent Source ($E_0 \sin(\omega t)$)

Beam Splitter

Macroscopic Entrainment Ring (Ω)

Interferometric Detector

$$\Delta\Phi = \oint \mathbf{v}_{drift} \cdot d\mathbf{l}$$

Metric Drag Advance

$$\mathbf{L}_{vac}(-\mathbf{v})$$

Counter-Clockwise (CCW) Path

$$v_{prop} = c + v_{drift}$$

