ECE271, Final Project

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The purpose of this project is to create a digital logic design that uses an NES controller to convarious kinds of output through an $FPGA$.	trol
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<pre>module periodTime(input logic clk,</pre>	
<pre>int compareNumber; int count;</pre>	
always_comb	
<pre>case(data) 0: compareNumber = 6400;</pre>	ectrum period
4: compareNumber = 4000; 5: compareNumber = 2000; 6: compareNumber = 1000; 7: compareNumber = 500; // consider adding default case	
endcase	

always_ff @(posedge clk)

endmodule

5.2 Simulation Results

5.2.1 NES Controller Reader

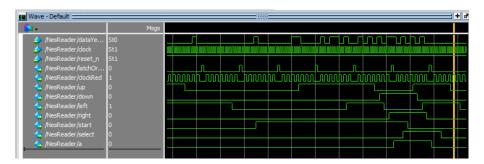


Figure 1: "Button Mashing" on the NES

At first, I wanted to test the NES controller reader by just simulating a bunch of random inputs as seen in Figure 1. I remembered the NES game CONTRA had a cheat code that involved most of the controller's buttons (all but SELECT). The "Contra Code" was then simulated I'm gonna rewrite this



Figure 2: CONTRA screenshot

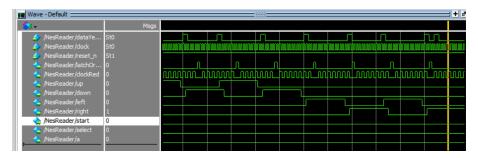


Figure 3: Simulating the "Contra Code"

```
force -freeze sim:/NesReader/dataYellow 0 0, 0 \{20\ ps\} , 0 \{40\ ps\} , 0 \{60\ ps\} ,
    1 {80 ps} , 0 {100 ps} , 0 {120 ps} , 0 {140 ps} #up
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 \{80 \text{ ps}\} , 1 \{100 \text{ ps}\} , 0 \{120 \text{ ps}\} , 0 \{140 \text{ ps}\} #down
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    1 {80 ps} , 0 {100 ps} , 0 {120 ps} , 0 {140 ps} #up
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 \{80 \text{ ps}\} , 1 \{100 \text{ ps}\} , 0 \{120 \text{ ps}\} , 0 \{140 \text{ ps}\} #down
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 \{80 \text{ ps}\} , 0 \{100 \text{ ps}\} , 1 \{120 \text{ ps}\} , 0 \{140 \text{ ps}\} #left
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 0 {120 ps} , 1 {140 ps} #right
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 1 {120 ps} , 0 {140 ps} #left
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 \{80 ps\} , 0 \{100 ps\} , 0 \{120 ps\} , 1 \{140 ps\} #right
force -freeze sim:/NesReader/dataYellow 0 0, 1 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 \{80 ps\} , 0 \{100 ps\} , 0 \{120 ps\} , 0 \{140 ps\} #b
force -freeze sim:/NesReader/dataYellow 1 0, 0 \{20 \text{ ps}\} , 0 \{40 \text{ ps}\} , 0 \{60 \text{ ps}\} ,
    0 \{80 \text{ ps}\} , 0 \{100 \text{ ps}\} , 0 \{120 \text{ ps}\} , 0 \{140 \text{ ps}\} #a
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 1 {60 ps} ,
    0 \{80\ ps\} , 0 \{100\ ps\} , 0 \{120\ ps\} , 0 \{140\ ps\} start
```

5.2.2 Square Wave Generator



Figure 4: Simulating button inputs to control the square wave oscillator