ECE271, Final Project

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Contents

1 Introduction

The purpose of this project is to create a digital logic design that uses various parallel input modules with various output modules for implementation on an Field Programmable Gate Array-or FPGA. FPGA programming and design allows smaller digital logic modules to be implemented all on the same board. This paper discusses a number of input and output modules and an easily implementable top-level example design that ties all of these modules together.

2 High Level Descriptions

3 Input Device Descriptions

This section is meant to provide a brief but thorough low-level view of the operations of our chosen input devices.

3.1 NES Controller

The Nintendo Entertainment System (NES) first became available in America in 1985 and revolutionized society as the first accessible home video game system. NES controllers (pictured in figure 1) work by receiving "clock" and "latch" signals from the NES console and transmitting a data signal to the console. NES controllers use a shift register to store all of the controller's button data when the console sends the latch signal (As in figure 2). Each successive clock signal shifts the controller register down and the controller's data wire outputs a value that represents the next button's signal (See figure 3).

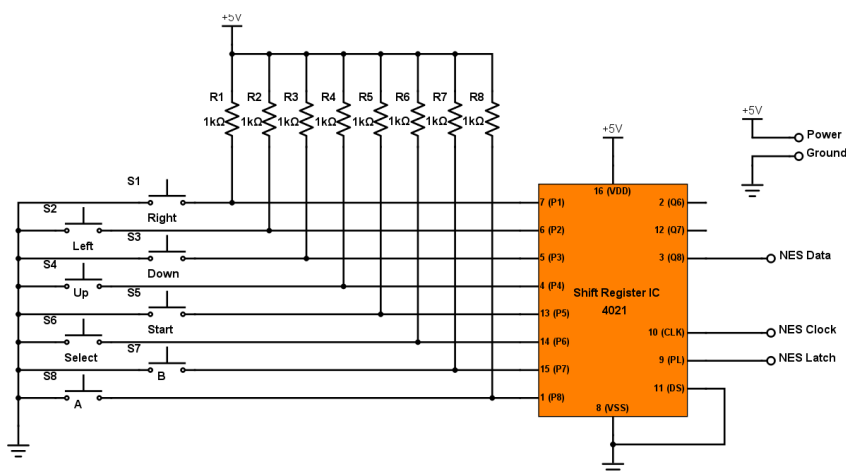Figure 1: An NES controller (Picture courtesy of Wikipedia)

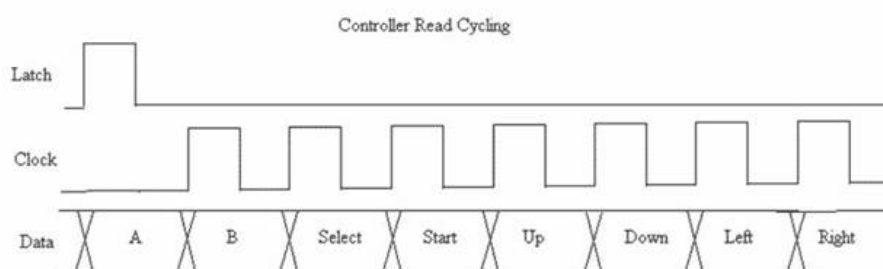Figure 2: The buttons and shift register inside of an NES controller

Figure 3: One shift register worth of data, transmitted after pulsing the latch input high

An example of the NES controller decoder module was provided for us in the course materials, and a discussion of the code is included in the appendix of this document.

3.2 Analog-to-Digital Converter

The second input that we chose was an Analog-to-Digital Converter, also known as an ADC. After talking to a fellow classmate[1] about how hard a time he was having accessing the DE10-Lite's on-board ADC (even with the help of teachers and TAs), our group decided to use an external one to interface with the DE10-Lite. An Arduino Nano converts an analog potentiometer's voltage from 0-5Vdc to 0 to 1023 bits. The code running on the Arduino is included in the appendix section.

4 HDL Components

5 Appendix

5.1 Source Code

5.1.1 NES Controller Reader

The NES reader module depends on four sub-modules. The "Counter4" module is just a resettable four-bit counter. "NesLatchStateDecoder" receives the count from the "Counter4" counter and outputs a signal when all bits are zero. This signifies the latch signal which corresponds with the first high half of every eight clock cycles. The "NesClockStateDecoder" module holds the combinational logic which controls the reader module's clock. Finally, the "NesDataReceiverDecoder" module reads data from the data wire at the negative edge of the controller's "Clock" signal and outputs a vector of these values.

```
module NesReader(
  input logic dataYellow,
  input logic clock,
  input logic reset_n,
  output logic latchOrange,
  output logic clockRed,
  output logic up,
  output logic down,
  output logic left,
  output logic right,
  output logic start,
  output logic select,
  output logic a,
  output logic b
  );
  logic [3:0] count;

  Counter4 matt_i1(
    .clk              (clock),
    .reset_n          (reset_n),
    .count            (count)
  );

  NesClockStateDecoder matt_i2(
    .controllerState  (count),
    .nesClock         (clockRed)
  );

  NesLatchStateDecoder matt_i3 (
    .controllerState  (count),
    .nesLatch         (latchOrange)
  );
```

---

[1] Luke Goldsworthy

```systemverilog
  NesDataReceiverDecoder matt_i4 (
    .dataYellow        (dataYellow),
    .reset_n           (reset_n),
    .controllerState   (count),
    .readButtons       ({a, b, select, start, up, down, left, right})
  );
endmodule


module Counter4(
  input logic clk, reset_n,
  output logic [3:0] count);

  always_ff @ (posedge clk, negedge reset_n)
    if(!reset_n) count <= 4'b0;
    else count <= count + 1;
endmodule


module NesLatchStateDecoder(
  input logic [3:0] controllerState,
  output logic nesLatch);

  always_comb
    case(controllerState)
      4'h0: nesLatch = 1;
      default: nesLatch = 0;
    endcase
endmodule


module NesClockStateDecoder(
  input logic [3:0] controllerState,
  output logic nesClock);

  always_comb
    case (controllerState)
      4'h2: nesClock = 1;
      4'h4: nesClock = 1;
      4'h6: nesClock = 1;
      4'h8: nesClock = 1;
      4'ha: nesClock = 1;
      4'hC: nesClock = 1;
      4'hE: nesClock = 1;
      default: nesClock = 0;
    endcase
endmodule


module NesDataReceiverDecoder(
  input logic dataYellow,
  input logic reset_n,
  input logic [3:0] controllerState,
  output logic [7:0] readButtons);

  always_ff @ (posedge controllerState[0], negedge reset_n)
    if(!reset_n) readButtons <= 8'b0;
```

```
    else case(controllerState[3:0])
       4'h1: readButtons[7] <= dataYellow;    //a button
       4'h3: readButtons[6] <= dataYellow;    //b button
       4'h5: readButtons[5] <= dataYellow;    //select button
       4'h7: readButtons[4] <= dataYellow;    //start button
       4'h9: readButtons[3] <= dataYellow;    //up button
       4'hB: readButtons[2] <= dataYellow;    //down button
       4'hD: readButtons[1] <= dataYellow;    //left button
       4'hF: readButtons[0] <= dataYellow;    //right button
       default: readButtons <= readButtons;
    endcase
endmodule
```

5.1.2 ADC

The following code is written in Arduino C and uploaded to an Arduino Nano microcontroller.

```
int analogPin = A0;    // the potentiometer's analog voltage
int d0 = 0;                 // the first output bit
int d1 = 1;
int d2 = 2;
int d3 = 3;
int d4 = 4;
int d5 = 5;
int d6 = 6;
int d7 = 7;
int d8 = 8;
int d9 = 9;                 // the last (most significant) output bit

void setup()
{
  pinMode(analogPin, INPUT);            // Potentiometer input pin

  pinMode(d0, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d1, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d2, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d3, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d4, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d5, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d6, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d7, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d8, OUTPUT);          //Indicates the pinmode of selected pin
  pinMode(d9, OUTPUT);          //Indicates the pinmode of selected pin
}

void loop()
{
  int value = analogRead(analogPin);
  int pinArray[10];
  bool bitArray[10];
  for (int i=0; i<=9; i++)
  {
    pinArray[i] = i;            // assigns outputs 0-9
    if (bitRead(value,i))
       {digitalWrite( pinArray[i],HIGH);}
    else
       {digitalWrite( pinArray[i],LOW);}
```

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```
    }
}
```

5.1.3 Square Wave Generator

```
module periodTime(input logic clk,
                  input logic [2:0] data,
                  output logic q);

int compareNumber;
int count;

always_comb
        case(data)
            0: compareNumber = 6400;      // just mod input clock until audio spectrum periods
            1: compareNumber = 3200;      // one octave
            2: compareNumber = 1600;
            3: compareNumber = 8000;

            4: compareNumber = 4000;
            5: compareNumber = 2000;
            6: compareNumber = 1000;
            7: compareNumber = 500;          // consider adding default case
        endcase

always_ff @(posedge clk)
    begin
        if (count >= compareNumber)     // could modify to not restart notes when changed
            count <= 0;
        else
            count <= count +1;
    end

always_comb
    begin
            if( count < compareNumber)
                q = (count > compareNumber/2);      //assigns output with initial low
            else
                q = 0;
    end

endmodule
```

5.2 Simulation Results
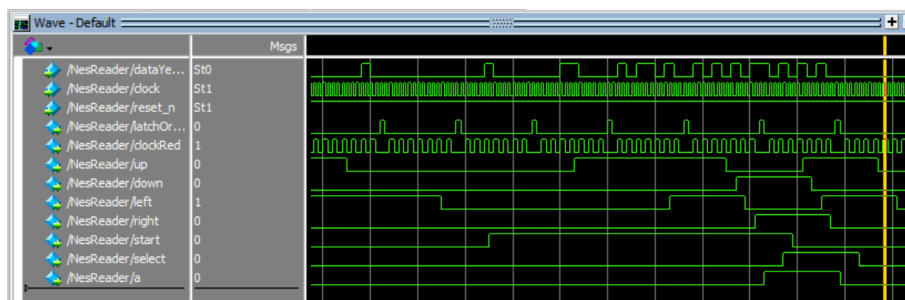
5.2.1 NES Controller Reader

Figure 4: "Button Mashing" on the NES

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At first, I wanted to test the NES controller reader by just simulating a bunch of random inputs as seen in Figure 4. I remembered the NES game CONTRA had a cheat code that involved most of the controller's buttons (all but SELECT). The "Contra Code" was then simulated with the following ModelSim macro code.
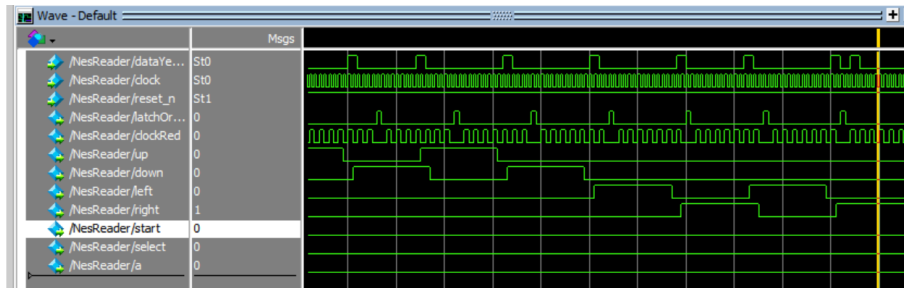

Figure 5: CONTRA screenshot

Figure 6: Simulating the "Contra Code"

```
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    1 {80 ps} , 0 {100 ps} , 0 {120 ps} , 0 {140 ps} #up
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 1 {100 ps} , 0 {120 ps} , 0 {140 ps} #down
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    1 {80 ps} , 0 {100 ps} , 0 {120 ps} , 0 {140 ps} #up
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 1 {100 ps} , 0 {120 ps} , 0 {140 ps} #down
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 1 {120 ps} , 0 {140 ps} #left
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 0 {120 ps} , 1 {140 ps} #right
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 1 {120 ps} , 0 {140 ps} #left
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 0 {120 ps} , 1 {140 ps} #right
force -freeze sim:/NesReader/dataYellow 0 0, 1 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 0 {120 ps} , 0 {140 ps} #b
force -freeze sim:/NesReader/dataYellow 1 0, 0 {20 ps} , 0 {40 ps} , 0 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 0 {120 ps} , 0 {140 ps} #a
```

```
force -freeze sim:/NesReader/dataYellow 0 0, 0 {20 ps} , 0 {40 ps} , 1 {60 ps} ,
    0 {80 ps} , 0 {100 ps} , 0 {120 ps} , 0 {140 ps} start
```

5.2.2   Square Wave Generator

Our square wave generator module works by receiving a 3-bit data bus and outputs successive octaves of a music note. This module was simply tested by simulating various data inputs on the 3-bit bus. This is pictured in figure 7.
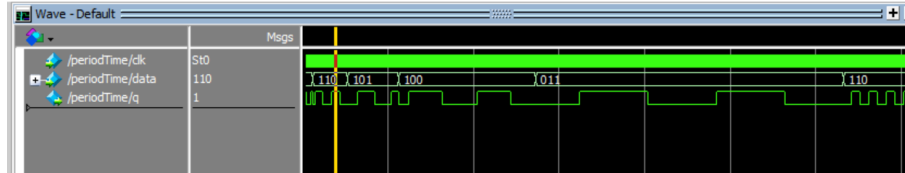

Figure 7: Simulating button inputs to control the square wave oscillator