



# CMLG Course Lab II

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# Outline

- How to store graph data for ML?
- How to implement GNNs for different tasks?
- Q & A

# How to store graph data for ML?



## How to store image data?

- A sample:
  - $x = ?, y = ?$
  - $x \in \mathbb{R}^?, y \in \mathbb{Z}^+?$

# How to store graph data for ML?

## How to store image data?

- A sample:

- $x = ?, y = ?$

- $x =$



- $y = \text{Dog (or, the } k^{\text{th}} \text{ class)}$

- $x \in \mathbb{R}^?, y \in \mathbb{Z}^+?$

# How to store graph data for ML?

## How to store image data?

- A sample:

- $x = ?, y = ?$

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- $y = \text{Dog (or, the } k^{\text{th}} \text{ class)}$

- $x \in \mathbb{R}^?, y \in \mathbb{Z}^+?$

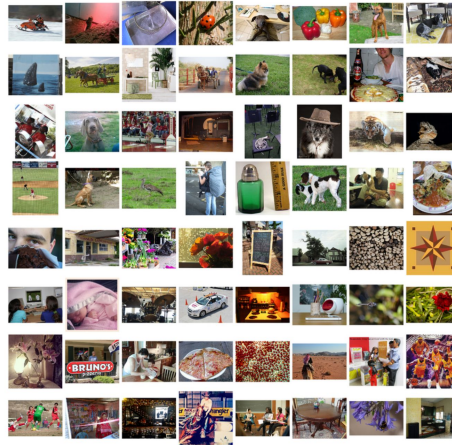
- $x \in \mathbb{R}^{W \times H \times 3}, y \in \mathbb{Z}^+$

# How to store graph data for ML?

## How to store image data?

- The entire dataset with  $N$  samples:

○  $x =$



$y =$  all  $N$  labels

○  $x \in \mathbb{R}^?, y \in \mathbb{Z}^+?$

# How to store graph data for ML?



## How to train an image classifier?

- The entire dataset with  $N$  samples:
  - CNN:  $f$  , images:  $x$  , labels:  $y$
  - **1. Forward pass:**
    - $\hat{y} = f(x)$
  - **2. Compute loss**
    - $\text{loss} = \mathcal{L}(y, \hat{y})$
  - **3. Backward pass**
    - $\text{Grad} = \frac{d\mathcal{L}}{df}$
  - **4. Update  $f$  using** Grad

# How to store graph data for ML?

## How to train an image classifier?

- The entire dataset with  $N$  samples:

- CNN:  $f$  , images:  $x$  , labels:  $y$

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- 3. Backward pass

- $\text{Grad} = \frac{d\mathcal{L}}{df}$

- 4. Update  $f$  using Grad

```
def train_one_epoch(data):  
    model.train()  
    optimizer.zero_grad()  
    y_hat = model(data.x)  
    loss = criterion(y_hat, data.y)  
    loss.backward()  
    optimizer.step()  
    return loss
```

It's impractical to do full-batch training when  $N$  is large!



# How to store graph data for ML?

## How to store image data?

- A batch of  $B$  samples:

○  $x =$



$y =$  all  $B$  labels

○  $x \in \mathbb{R}^?, y \in \mathbb{Z}^+?$

# How to store graph data for ML?



## How to train an image classifier?

- A batch has  $B$  samples; the dataset has  $N$  samples:

```
def train_one_epoch(data):  
    model.train()  
    optimizer.zero_grad()  
    y_hat = model(data.x)  
    loss = criterion(y_hat, data.y)  
    loss.backward()  
    optimizer.step()
```

Full-batch training

```
def train_one_epoch():  
    model.train()  
    # what's the number of iterations per epoch?  
    for batch in train_loader:  
        ptimizer.zero_grad()  
        y_hat = model(data.x)  
        loss = criterion(y_hat, data.y)  
        loss.backward()  
        optimizer.step()
```

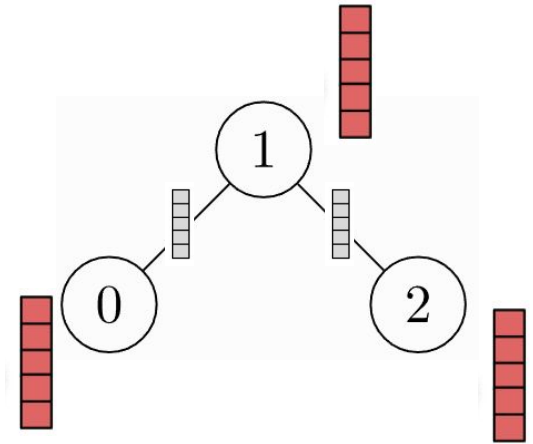
Mini-batch training

# How to store graph data for ML?



## How to store graph data?

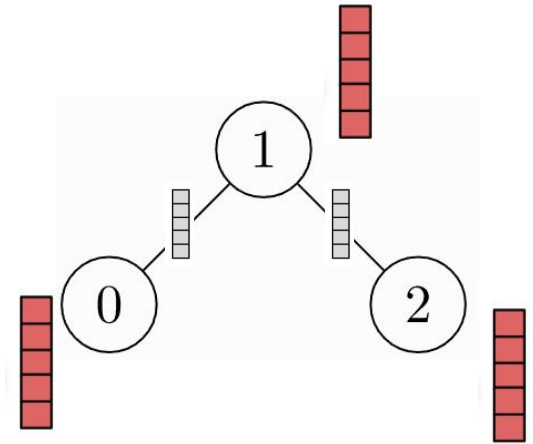
- A graph with  $V$  nodes and  $E$  edges:
  - $x = ?, y = ?$
  - What should be included as features?



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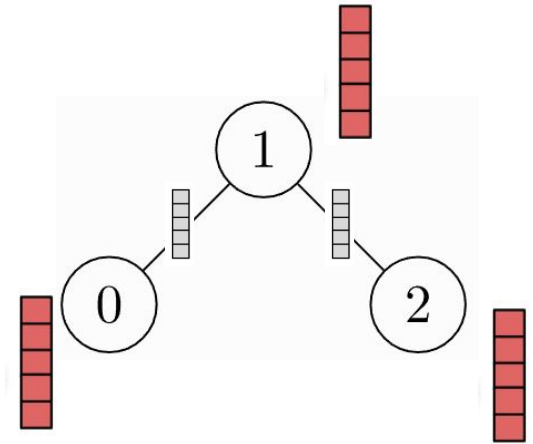
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      - Edge list!  $\text{edge\_index} \in \mathbb{Z}^+?$



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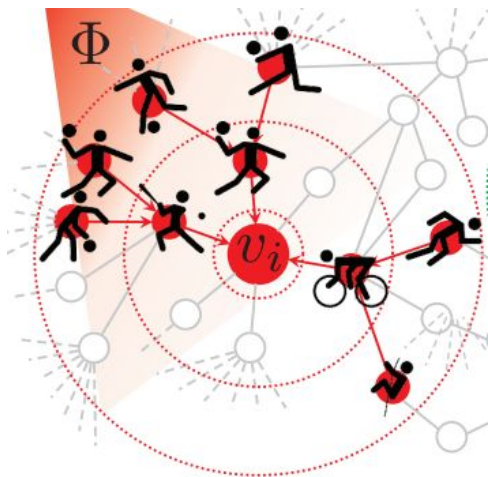
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  - What can  $y$  be?



# How to store graph data for ML?

## How to store graph data?

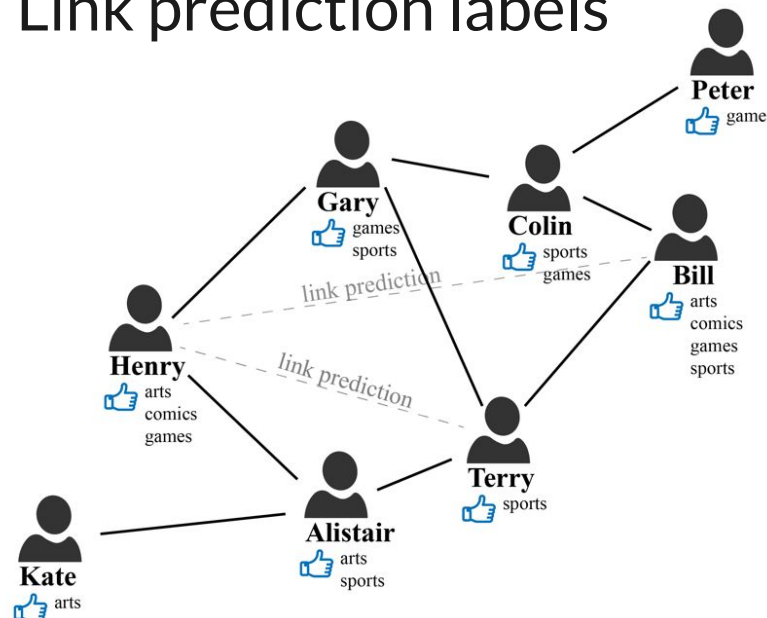
- A graph with  $V$  nodes and  $E$  edges:
  - What can  $y$  be?
    - Node classification labels



# How to store graph data for ML?

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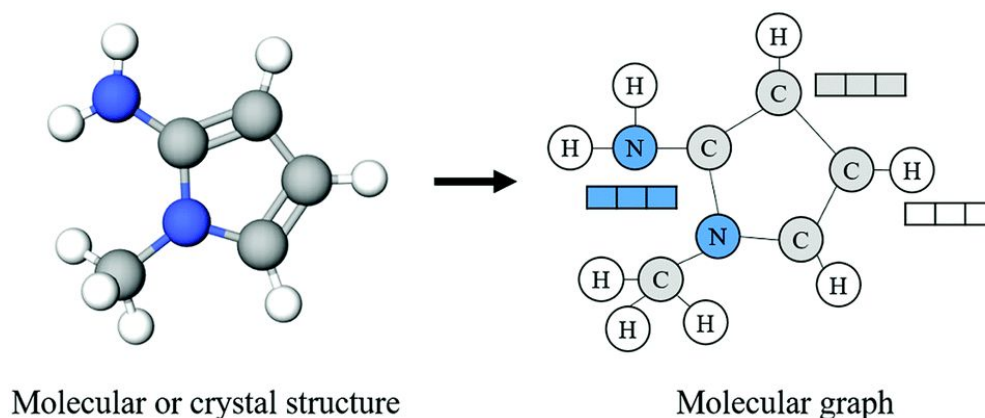
- A graph with  $V$  nodes and  $E$  edges:
  - What can  $y$  be?
    - Link prediction labels



# How to store graph data for ML?

## How to store graph data?

- A graph with  $V$  nodes and  $E$  edges:
  - What can  $y$  be?
    - Graph classification labels

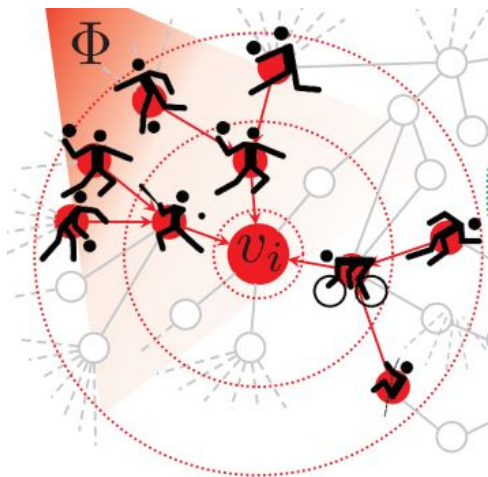




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- A graph with  $V$  nodes and  $E$  edges:
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# How to store graph data for ML?



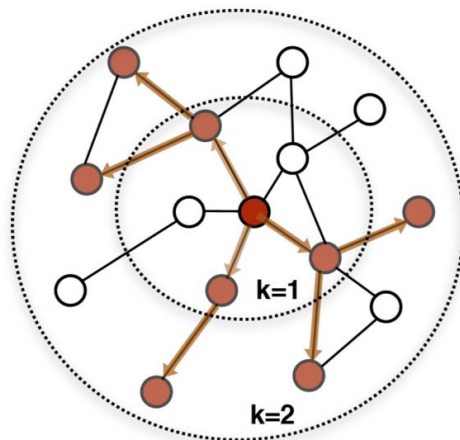
## How to train a node classifier?

- A graph with  $V$  nodes and  $E$  edges:
  - Full-batch training
    - What if  $V$  is 1 million?
  - Mini-batch training
    - How?

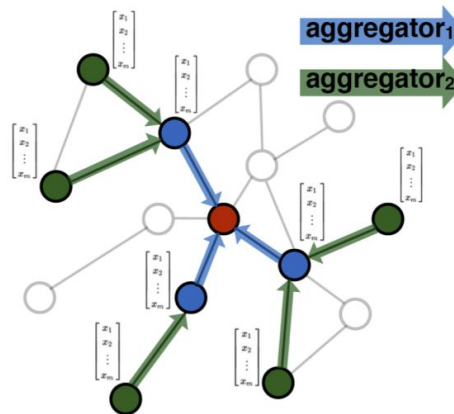
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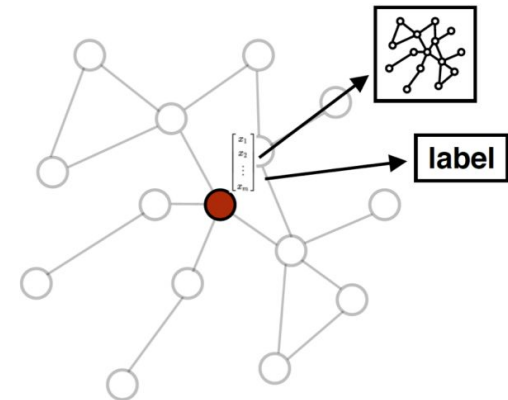
- A graph with  $\underline{V}$  nodes and  $\underline{E}$  edges:
  - Mini-batch training



1. Sample neighborhood



2. Aggregate feature information from neighbors



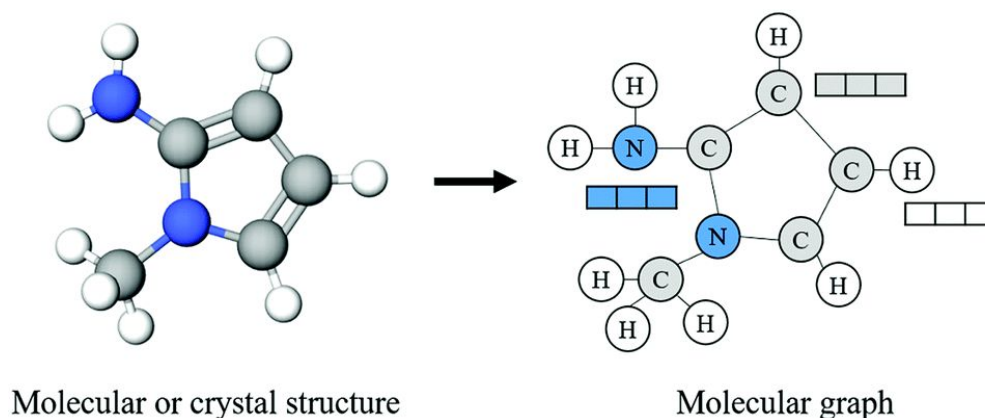
3. Predict graph context and label using aggregated information

Figure 1: Visual illustration of the GraphSAGE sample and aggregate approach.

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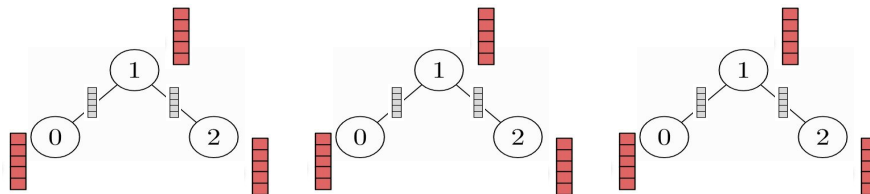
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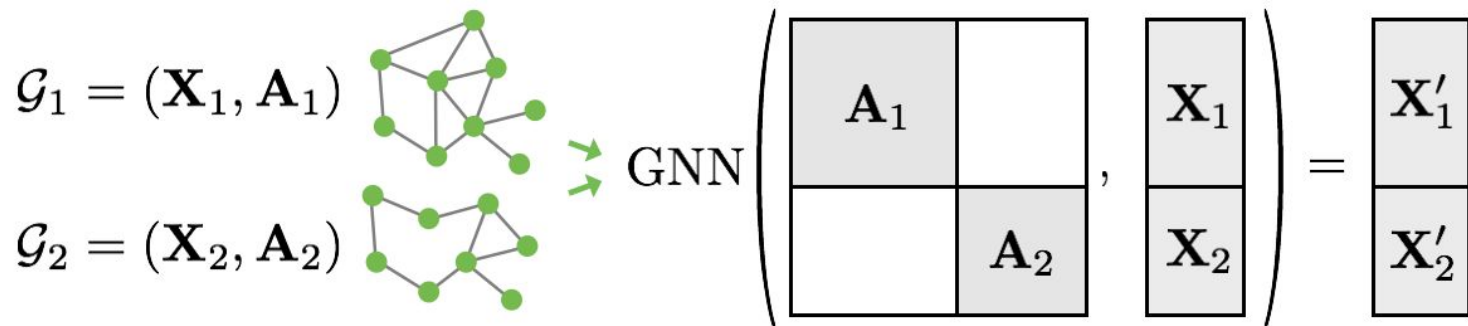
- How about a batch of  $B$  graphs:
  - What should be included as features?
    - Node features  $x \in \mathbb{R}^?$
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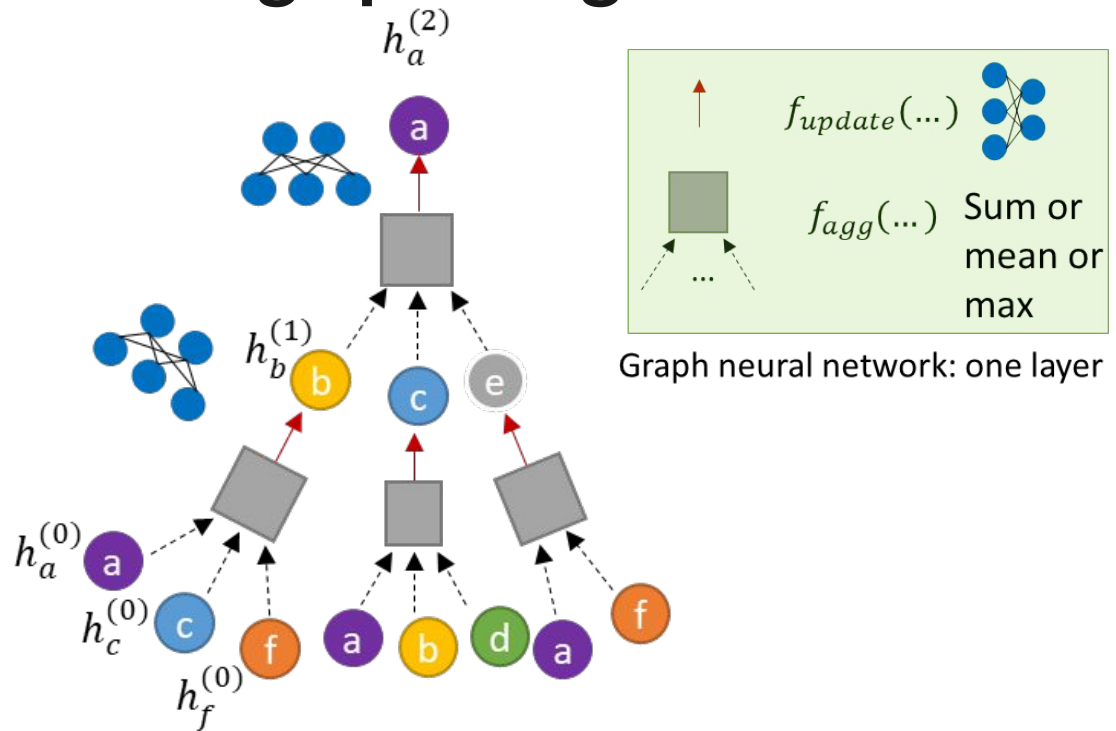
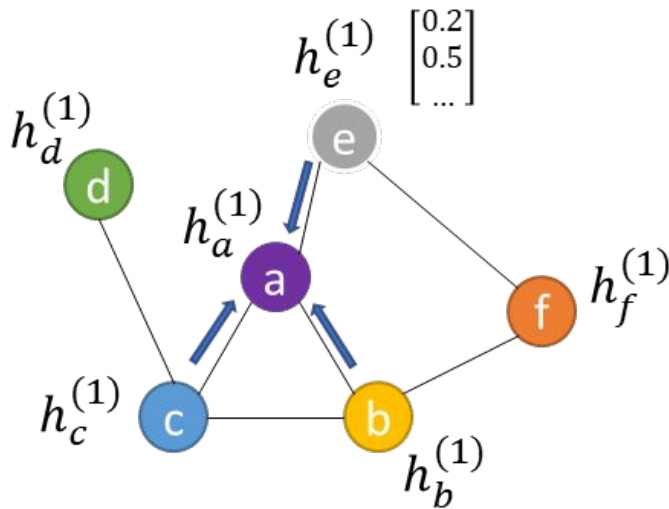
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# How to implement GNNs?

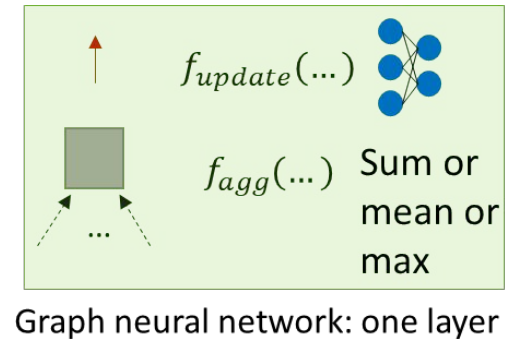
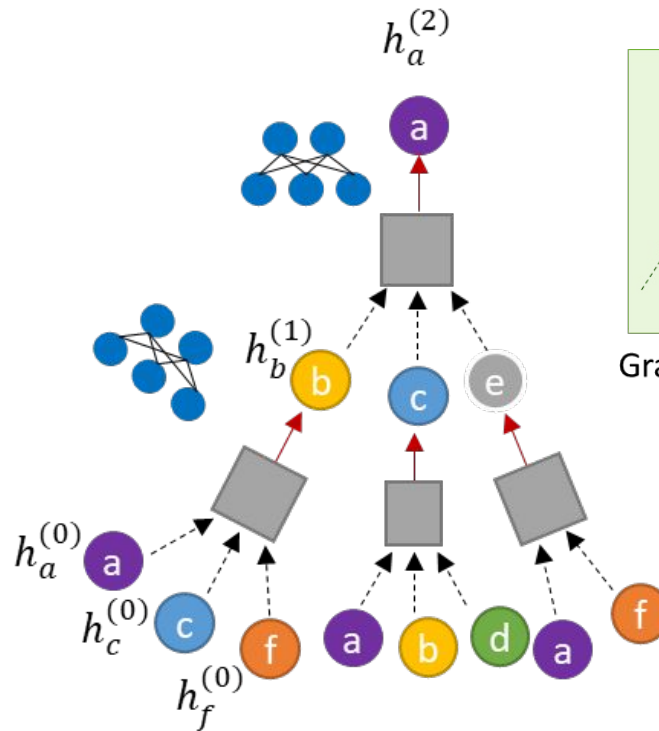
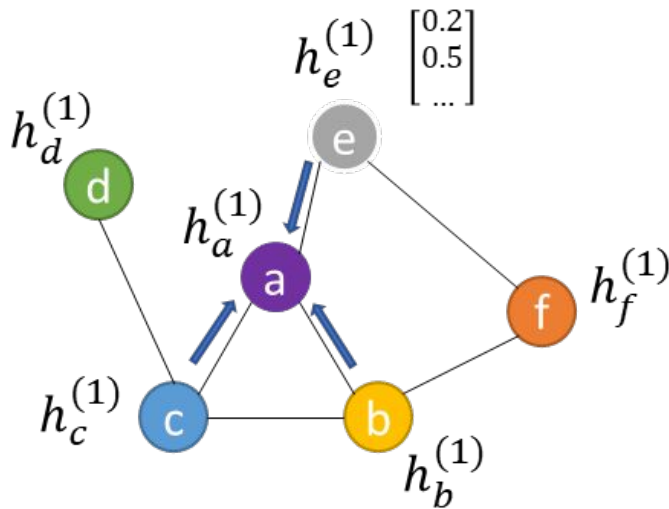
Most GNNs use a message passing scheme



$$h_v^{(t+1)} = f_{update} \left( h_v^{(t)}, f_{agg} \left( \left\{ h_u^{(t)} \mid u \in N_v \right\} \right) \right)$$

# How to implement GNNs?

## How about node classification tasks?

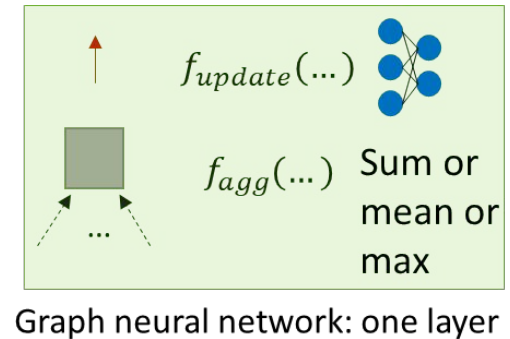
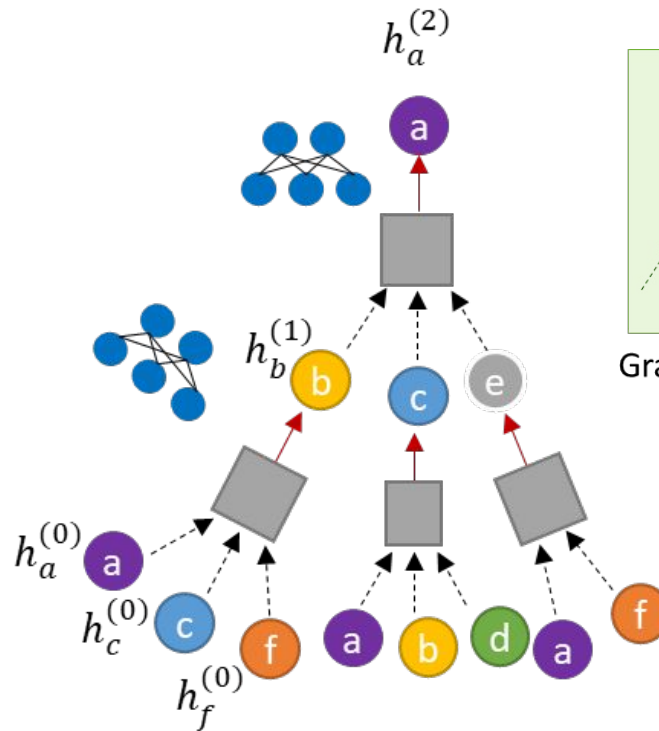
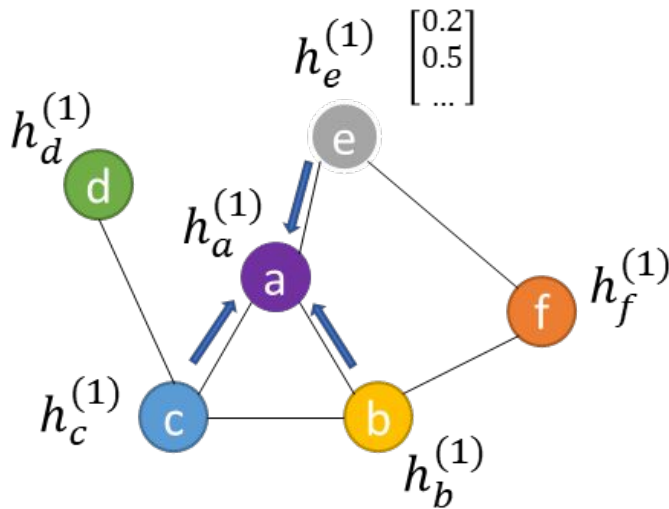


$$y_v = \text{Softmax}(\text{MLP}(h_v^{(L)}))$$



# How to implement GNNs?

How about graph classification tasks?



$$h_G = \text{POOL} \left( \left\{ h_v^{(L)} \mid v \in V \right\} \right)$$

# How to implement GNNs?



Create your own GNNs!

$$h_v^{(t+1)} = f_{update} \left( h_v^{(t)}, f_{agg} \left( \{ h_u^{(t)} \mid u \in N_v \} \right) \right)$$

# Q & A

