

Taming Local Effects in Graph-based Spatiotemporal Forecasting

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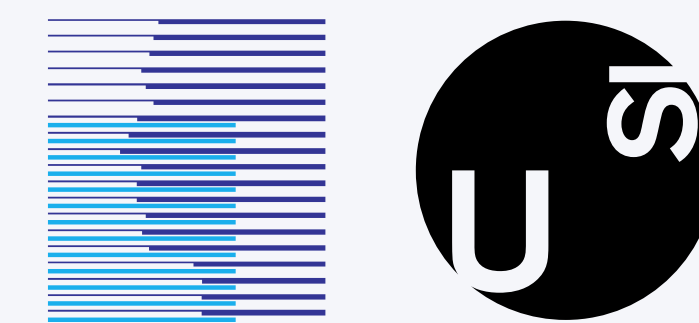
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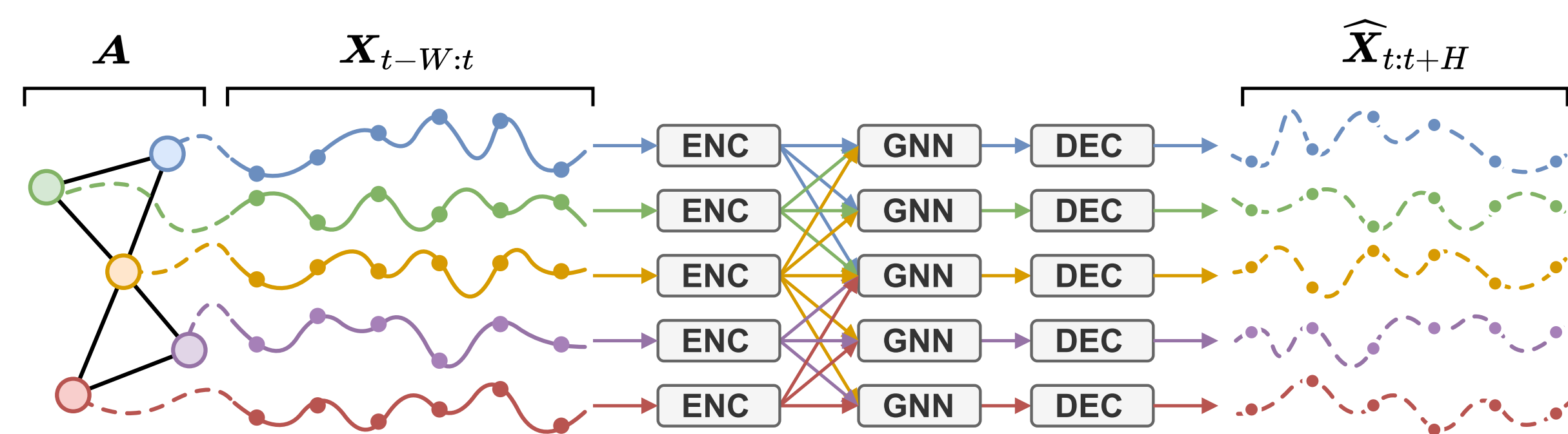


Motivation

Spatiotemporal GNNs (STGNNs) are effective in forecasting **collections of time series**, but **fully global** models often underperform.

- Global models **share parameters among time series**.
- While very flexible, they might fail in accounting for the **specific dynamics of each time series**.
- Understanding the **interplay between global and local components** in graph-based predictors is critical.
- Guidelines to design **effective hybrid global-local STGNNs**, amenable to **transfer learning**, are missing.

Graph-based Forecasting



We consider **graph-based forecasting models** composed of 3 blocks: **ENCODER** encodes input features (e.g., with an MLP).

(ST)GNN propagates information along time and through the graph.

DECODER generates forecasts from obtained node representations.

The Issue

Models of this kind are **global**, i.e., all parameters are **shared** among the time series.

- 😊 **Fewer** parameters (in total)
- 😊 **More data** available for training
- 😊 Work in **inductive** settings
- 😞 Struggle to model **local effects**
- 😞 Require **large model capacity**...
- 😞 ...or impractically **long windows**

💡 Make **STGNNs global-local** with specialized local components!

Main Findings

- **Local components** can be crucial for **accurate predictions**.
- **Node embeddings** can **amortize** the learning of **local components**.
- **Global-local STGNNs** capture local effects with **contained model complexity** and **smaller input windows** w.r.t. global approaches.
- **Node embeddings** facilitate **transferability** of global-local models.
- **Structuring** the embedding space is an effective **regularization**.

Taming local effects in STGNNs

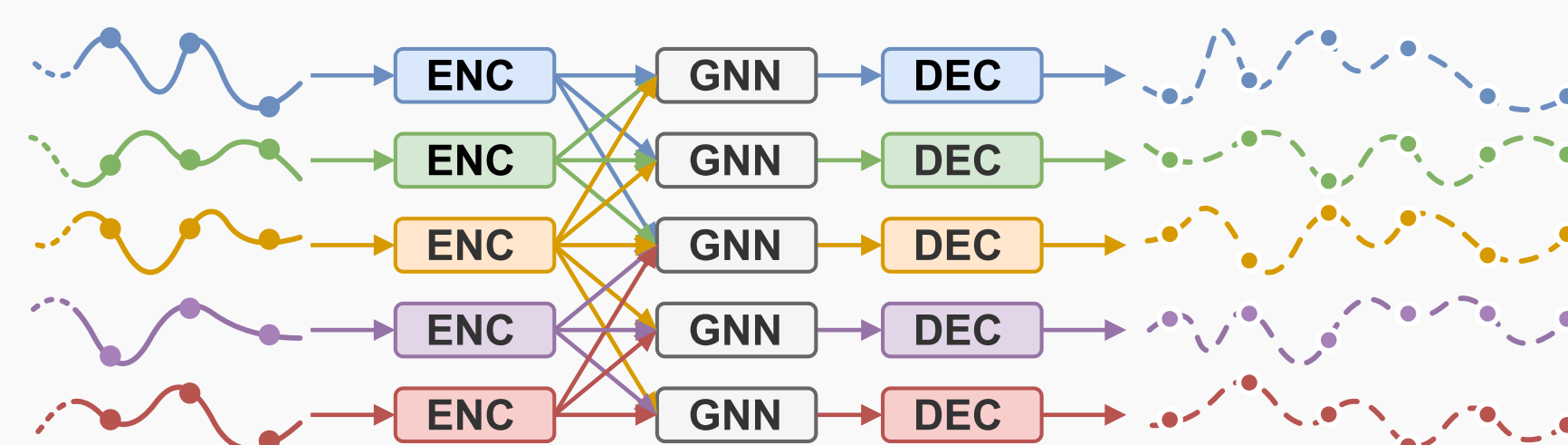
We study the impact of **introducing local components in global STGNNs**.

Option 1

Local blocks

(with node-specific weights)

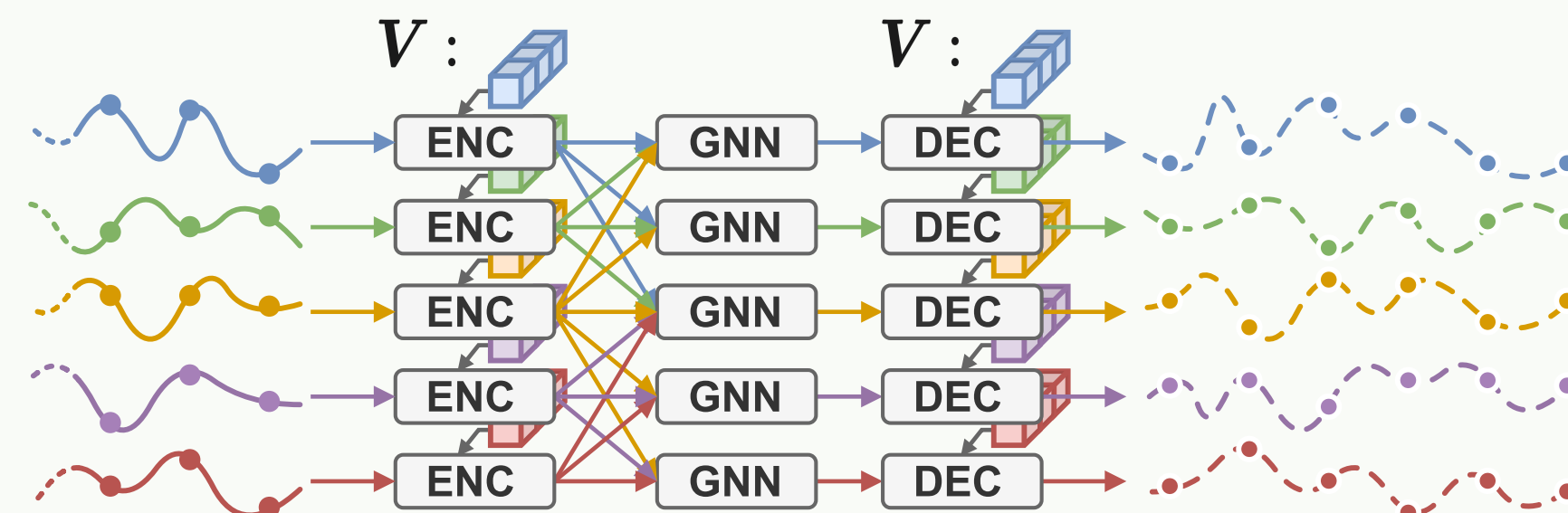
- 😊 Can deal with **local effects**
- 😞 **Flexibility is compromised**
- 😞 **Model complexity increases**



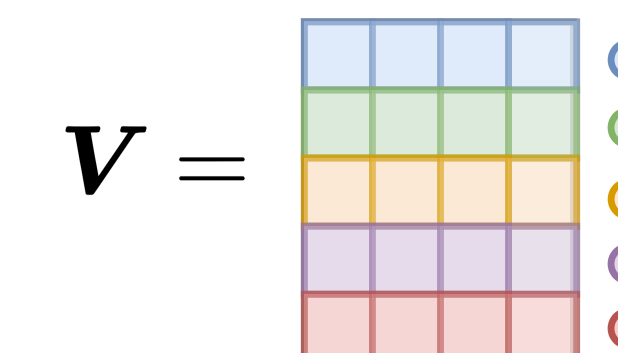
Option 2

Node embeddings

- 😊 Amortize the cost of learning **local components**
- 😊 Ease **transfer learning**



Node embeddings are a table of **learnable parameter vectors**, each associated with a node.



Some Empirical Results

Models	MetrLA	PemsBAY	CER-E	AQI	MetrLA	PemsBAY	CER-E	AQI
Reference arch.	Global models				+ Embeddings			
RNN	3.54 \pm .00	1.77 \pm .00	456.98 \pm 0.61	14.02 \pm .04	3.15 \pm .03	1.59 \pm .00	421.50 \pm 1.78	13.73 \pm .04
T&S-IMP	3.35 \pm .01	1.70 \pm .01	443.85 \pm 0.99	12.87 \pm .02	3.10 \pm .01	1.59 \pm .00	417.71 \pm 1.28	12.48 \pm .03
TTS-IMP	3.34 \pm .01	1.72 \pm .00	439.13 \pm 0.51	12.74 \pm .02	3.08 \pm .01	1.58 \pm .00	412.44 \pm 2.80	12.33 \pm .02
T&S-AMP	3.22 \pm .02	1.65 \pm .00	N/A	N/A	3.07 \pm .02	1.59 \pm .00	N/A	N/A
TTS-AMP	3.24 \pm .01	1.66 \pm .00	431.33 \pm 0.68	12.30 \pm .02	3.06 \pm .01	1.58 \pm .01	412.95 \pm 1.28	12.15 \pm .02
Baseline arch.	Original				+ Embeddings			
DCRNN	3.22 \pm .01	1.64 \pm .00	428.36 \pm 1.23	12.96 \pm .03	3.07 \pm .02	1.60 \pm .00	412.87 \pm 1.51	12.53 \pm .02
GraphWaveNet	3.05 \pm .03	1.56 \pm .01	397.17 \pm 0.67	12.08 \pm .11	2.99 \pm .02	1.58 \pm .00	401.15 \pm 1.49	11.81 \pm .04
AGCRN	3.16 \pm .01	1.61 \pm .00	444.80 \pm 1.25	13.33 \pm .02	3.14 \pm .00	1.62 \pm .00	436.84 \pm 2.06	13.28 \pm .03

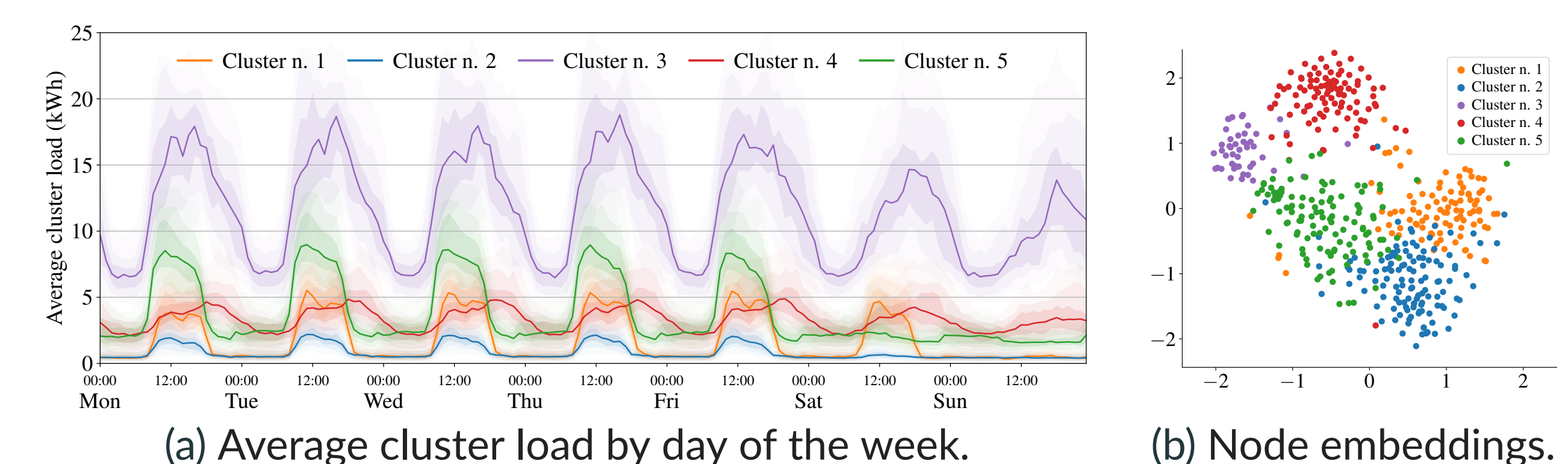
Table 1. Performance (MAE) on benchmark datasets.

Transfer Learning

	TTS-IMP	PEMS03	PEMS04	PEMS07	PEMS08
Global	15.30 \pm .03	21.59 \pm .11	23.82 \pm .03	15.90 \pm .07	
Embeddings	14.64 \pm .05	20.27 \pm .11	22.23 \pm .08	15.45 \pm .06	
- Variational	14.56 \pm .03	20.19 \pm .05	22.43 \pm .02	15.41 \pm .06	
- Clustering	14.60 \pm .02	19.91 \pm .11	22.16 \pm .07	15.41 \pm .06	
Zero-shot	18.20 \pm .09	23.88 \pm .08	32.76 \pm .69	20.41 \pm .07	

Table 2. Performance (MAE) on traffic datasets.

Clusterized embedding space (CER dataset)



Structuring the Embedding Space

Regularizing the embedding space improves **transferability** and **interpretability**.

- **Variational**: the smoother embedding space enables **interpolation**.

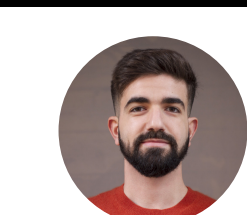
$$\mathcal{L}_t^i \doteq \mathbb{E}_{Q \sim M} \left[\left\| \widehat{\mathbf{X}}_{t:t+H} - \mathbf{X}_{t:t+H} \right\|_2^2 \right] + \beta D_{\text{KL}}(M | \mathcal{N}(\mathbf{0}, \mathbb{I}))$$

- **Clustering**: clusters in the latent space improve **interpretability**.

$$\mathcal{L}_{\text{reg}} \doteq \mathbb{E}_M \left[\left\| \mathbf{V} - \mathbf{M}\mathbf{C} \right\|_2 \right], \quad p(\mathbf{M}_{ij} = 1) = \frac{e^{\mathbf{S}_{ij}/\tau}}{\sum e^{\mathbf{S}_{ik}/\tau}}$$



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Check out our library for STGNNs!

TorchSpatiotemporal/tsl