# LAGraph Algorithms

PDF build on Thursday 11<sup>th</sup> February, 2021 at 01:57 UTC

#### Abstract

Theoretical documentation for LAGraph.

## 1 Introduction

The goal of this document is to present a notation for GraphBLAS algorithms and showcase it using important GraphBLAS algorithms.

# 2 The GraphBLAS

Goal The goal of GraphBLAS is to create a layer of abstraction between the graph algorithms and the graph analytics framework, separating the concerns of the algorithm developers from those of the framework developers and hardware designers. To achieve this, it builds on the theoretical framework of matrix operations on arbitrary semirings [3], which allows defining graph algorithms in the language of linear algebra [4]. To ensure portability, the GraphBLAS standard defines a C API that can be implemented on a variety of hardware including GPUs.

**Data structures** A graph with n vertices can be stored as a square adjacency matrix  $\mathbf{A} \in \mathbf{uint}^{n \times n}$ , where rows and columns both represent vertices of the graph and element A(i,j) contains the number of edges from vertex i to vertex j. If the graph is undirected, the matrix is symmetric.

Navigation The fundamental step in GraphBLAS is the multiplication of an adjacency matrix with another matrix or vector over a selected semiring. For example, the operation HasMember lor.land IsLocatedIn computed over the "logical or.logical and" semiring returns a matrix representing the Places where a Forum's members are located in. Meanwhile, when computed over the conventional arithmetic "plus.times" semiring, HasMember  $+.\times$  IsLocatedIn also returns the number of such Persons. A traversal from a certain set of vertices can be expressed by using a boolean vector f (often referred to as the frontier, wavefront, or queue) and setting true values for the elements corresponding to source vertices. For example, for Forums  $f \in bool^{|forums|}$ , flor.land HasMember returns the Persons who belong to any of the forums in f. The BFS navigation step can also be captured using other semirings such as lor.first, where first(x, y) = x; lor.second, where second(x, y) = y; and any.pair, where any(x, y) returns either x or y, and pair(x, y) = 1 [2].

## 2.1 Notation

Table 1 contains the notation of GraphBLAS operations Additionally, we use D = diag(j,n) to construct a diagonal matrix  $D \leftarrow \{j, j, [1, 1, ..., 1]\}$ . The elements of the matrix are D(j, j) = 1 for  $j \in j$ .

#### 2.1.1 Masks

Masks C < M> and w < m> are used to selectively write to the result matrix/vector. The complements of the masks can be selected with the negation symbol, denoted with: C < !M> and w < !m>, respectively.

Masks with "replace" semantics (annihilating all elements outside the mask) are denoted with

- C << M>>>
- C << !M>>>
- w << m>>
- w << !m>>

The structure of the mask is denoted with:

mxm   matrix-matrix multiplication   C < M > + = A + × B   vxm   vector-matrix multiplication   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + = u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w < m > + u + × A   w	op./method	name	notation
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reduce matrix to column vector $w < m > + = u < f((\dot)u, \dot u) >$ reduce matrix to column vector $w < m > + = [+A]$ reduce vector to scalar $s + = [+A]$ reduce vector to scalar $s + = [+u]$ transpose transpose $c < m > + = A$ kronecker Kronecker multiplication $c < m > + = A$ kronecker Kronecker multiplication $c < m > + = A$ new matrix $c < m > + = A$ new matrix $c < m > + = A$ new matrix $c < m > + = A$ new reduce matrix $c < m > + = A$ kronecker $c < m > + = A$ kr	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	apply analy operation	w < m > + = f(()u)
reduce matrix to column vector  reduce matrix to scalar  reduce vector to scalar  transpose transpose	select	apply select operator	( ) , ,
reducereduce watrix to scalar reduce vector to scalar $s+=[+A]$ $s+=[+u]$ transposetranspose $C < M > + = A'$ kroneckerKronecker multiplication $C < M > + = kron(A, B)$ newnew matrix new vector $A = TYPEPRECISION(n, m)$ $u = TYPEPRECISION(n)$ buildmatrix from tuples vector from tuples $C < - \{i, j, x\}$ $w < - \{i, x\}$ extractTuplesextract index/value arrays $\{i, j, x\} < - A$ $\{i, j, x\} < - u$ dupduplicate matrix duplicate vector $C < - A$ $w < - u$ extractElementextract scalar element $s = A(i, j)$ $s = u(i)$ setElementset element			w < m > + = u < f(()u, k) >
reduce vector to scalar $s+=\stackrel{\cdot}{[}+u\stackrel{\cdot}{]}$ transpose transpose $C < M>+=A^{\prime}$ kronecker Kronecker multiplication $C < M>+=kron(A,B)$ new matrix $new \text{ new matrix } u = TYPEPRECISION(n,m)$ new vector $u = TYPEPRECISION(n)$ build $matrix \text{ from tuples } vector  for a finite of the problem of the pr$	reduce		
transposetranspose $C < M > + = A'$ kroneckerKronecker multiplication $C < M > + = kron(A, B)$ newnew matrix new vector $A = TYPEPRECISION(n, m)$ $u = TYPEPRECISION(n)$ buildmatrix from tuples vector from tuples $C < -\{i, j, x\}$ $v < -\{i, x\}$ extractTuplesextract index/value arrays $\{i, j, x\} < -A$ $\{i, x\} < -u$ dupduplicate matrix duplicate vector $C < -A$ $v < -u$ extractElementextract scalar element $S = A(i, j)$ $S = u(i)$ setFlementset element			
kronecker       Kronecker multiplication $C < M > + = kron(A, B)$ new       new matrix new vector $A = TYPEPRECISION(n, m)$ build       matrix from tuples vector from tuples $C < -\{i, j, x\}$ extractTuples       extract index/value arrays $\{i, j, x\} < -A$ dup       duplicate matrix duplicate vector $C < -A$ extractElement       extract scalar element $S = A(i, j)$ set Element       set element $C(i, j) = s$		reduce vector to scalar	s+=[+u]
new       new matrix new vector $A = TYPEPRECISION(n,m)$ build       matrix from tuples vector from tuples $C <- \{i, j, x\}$ extractTuples       extract index/value arrays $\{i, j, x\} <- A$ dup       duplicate matrix duplicate vector $C <- A$ extractElement       extract scalar element $S = A(i, j)$ setElement       set element $C(i, j) = S$	transpose	transpose	C < M > + = A'
new       new vector $u = \text{TYPEPRECISION(n)}$ build       matrix from tuples vector from tuples $C <- \{i, j, x\}$ vector from tuples         extractTuples       extract index/value arrays $\{i, j, x\} <- A$ $\{i, x\} <- u$ dup       duplicate matrix duplicate vector $C <- A$ we under the content of the content o	kronecker	Kronecker multiplication	C < M > + = kron(A, B)
new vector $u = \text{TYPEPRECISION(n)}$ build matrix from tuples $C \leftarrow \{i, j, x\}$ vector from tuples $w \leftarrow \{i, x\}$ extractTuples extract index/value arrays $\{i, j, x\} \leftarrow A$ $\{i, j, x\} \leftarrow A$ $\{i, j, x\} \leftarrow a$ duplicate matrix $C \leftarrow A$ duplicate vector $W \leftarrow a$ extractElement extract scalar element $S = A(i, j)$ $S = B(i, j)$ $S = $	new	new matrix	$A = TYPEPRECISION(\mathtt{n},\mathtt{m})$
build       vector from tuples $w < -\{i,x\}$ extractTuples       extract index/value arrays		new vector	$\mathtt{u} = TYPEPRECISION(\mathtt{n})$
vector from tuples $w <= \{1, x\}$ extractTuples       extract index/value arrays $\{i, j, x\} <= A$ dup       duplicate matrix duplicate vector $C <= A$ extractElement       extract scalar element $s = A(i, j)$ setElement       set element $C(i, j) = s$	build		C <- {i,j,x}
extractiuples extract index/value arrays		vector from tuples	w <- {i,x}
	extractTuples	extract index/value arrays	
			{i,x}<- u
extractElement extract scalar element	dup		C<- A
extractElement extract scalar element $s = u(i)$ set element $C(i,j) = s$		duplicate vector	w<- u
	extractElement	extract scalar element	, , , , , , , , , , , , , , , , , , ,
			s = u(i)
$\mathtt{w}(\mathtt{i}) = \mathtt{s}$	setElement	set element	
		SOU CICIADIA	w(i) = s

Table 1: GraphBLAS operations and methods based on [1]. *Notation:* Matrices and vectors are typeset in bold, starting with uppercase ( $\mathbf{A}$ ) and lowercase ( $\mathbf{u}$ ) letters, respectively. Scalars including indices are lowercase italic ( $\mathbf{k}$ ,  $\mathbf{i}$ ,  $\mathbf{j}$ ) while arrays are lowercase bold italic ( $\mathbf{x}$ ,  $\mathbf{i}$ ,  $\mathbf{j}$ ). + and  $\times$  are the addition and multiplication operators forming a semiring and default to conventional arithmetic + and  $\times$  operators. + is the accumulator operator.

```
• C < \{M\} >
```

- $C < !\{M\} >$
- $w < \{m\} >$
- $w < !\{m\} >$

Combining structure and replace semantics is possible:

```
• C << {M} >>
```

- C << !{M}>>>
- w << {m}>>>
- w << !{m}>>>

Initializing scalars, vectors, and matrices (GraphBLAS methods):

```
• s = fp64()
```

- w = fp32(n)
- A = uint16(m, n)
- A = int64(k, m)

# 3 Algorithms

LAGraph [5] implements graph algorithms using the GraphBLAS C API [6]. Here are a few algorithms that could be included in this document:

## Algorithm 1: BFS / Levels variant.

### **Algorithm 2:** BFS / Parents variant.

## Algorithm 3: Direction Optimizing (push/pull) BFS.

## Algorithm 4: Multi-source breadth-first search.

## **Algorithm 5:** All-pairs shortest distance (on undirected, unweighted graphs) [7].

```
Data: ...
   Result: ...
 1 Function APD(A, n, deg)
       Z = A
       {\bf Z} + = {\bf A} + . \times {\bf A}
       B = \{ \langle Z, offdiag \rangle \} //  use the pattern as a Boolean matrix
 4
       if A == B then
        return A
 6
       T = APD(B, n, deg)
 7
       X = T + . \times A
 8
       {\tt Tscaled} = {\tt T} + . \times {\tt diag}((){\tt deg})
 9
       Xfiltered = X < X, X < Tscaled >
10
       return (2 \times T) MINUS Xfiltered
11
12 Function APD(A)
       deg = [+A]
13
       Distance = APD(A, n, deg)
14
      sp = [+Distance]
15
```

#### **Algorithm 6:** Betweenness centrality.

#### 1 Function MSBFS // The NumSp structure holds the number of shortest paths for each node and starting vertex discovered so far. // Initialized to source vertices. $NumSp < -\{s, [1, 1, ..., 1]\}$ // The Frontier holds the number of shortest paths for each node and starting vertex discovered so far. // Initialized to source vertices. Frontier < NumSp>= A(s,:) d = 0// The Sigmas matrices store frontier information for each level of the BFS phase. // BFS phase (forward sweep) 5 do// $Sigmas[d](:,s) = d^{th}$ level frontier from source vertex s Sigmas[d] = bool(n, nsver)6 Sigmas[d](:,:) = Frontier// Convert matrix to Boolean 7 NumSp = NumSp + Frontier// Accumulate path counts Frontier << NumSp>>= A' + . × Frontier // Update frontier 9 while nvals(Frontier) > 010 NumSpInv = fp32(n, nsver)11 NumSpInv = 1.0DIV NumSp12 BCU = fp32(n, nsver)13 BCU(:) = 1.0// Make BCU dense, initialize all elements to 1.014 W = fp32(n, nsver)15 // Tally phase (backward sweep) for i = d - 1 downto 0 do 16 W << Sigmas[i] >>= NumSpInv DIV BCU 17 $\mathbb{W} \ll \operatorname{Sigmas}[i-1] >>= \mathbb{A} + ... \mathbb{W}$ // Add contributions by successors and mask with that 18 BFS level's frontier. $BCU += W \times NumSp$ 19 // Row reduce BCU and subtract nsver from every entry to account for 1 extra value per BCU row element delta = [+BCU]20 delta MINUS = nsver21

### Algorithm 7: PageRank (used in Graphalytics).

```
Data: alpha constant (damping factor)
  Result: ...
1 Function PageRank
      pr(:) = 1/n
      outdegrees = [+_i A(:,j)]
3
      for k = 1 to numIterations do
4
         importance = pr DIV outdegrees
5
         importance = times(()importance, alpha)
                                                         // apply the times(()x,s) = x \cdot s operator
6
         importance = importance + . \times A
         danglingVertexRanks < !outdegrees >= pr(:)
8
         totalDanglingRank = (alpha)/(n) \times [+ danglingVertexRanks]
9
         pr = (1 - alpha)/(n) + totalDanglingRank
10
         pr = pr + importance
11
```

## **Algorithm 8:** Algebraic Bellman-Ford.

## Algorithm 9: Delta-stepping SSSP.

```
Data:
```

```
A, A_H, A_L \in \mathtt{fp}(|V|, |V|)
            s, i \in uint()
            \Delta \in \mathtt{fp}()
            \mathtt{t},\mathtt{t}_{\mathtt{Req}}\in\mathtt{fp}(|\mathtt{V}|)
            t_{B_i}, e \in uint(|V|)
  1 Function DeltaStepping
               {\tt A_L} = {\tt A} < 0 < {\tt A} \le \Delta >
               \mathtt{A}_{\mathtt{H}} = \mathtt{A} < \Delta < \mathtt{A} >
  3
               t(:) = \infty
  4
               t(s) = 0
  5
               while nvals(t < i\Delta \le t >) \ne 0 do
  6
                        s = 0
  7
                        \mathsf{t}_{\mathtt{B}_{\mathsf{i}}} = \mathsf{t} < \mathsf{i}\Delta \leq \mathsf{t} < (\mathsf{i}+1)\Delta >
  8
                        while t_{B_i} \neq 0 do
  9
                                t_{Req} = A_L' + . \times (t \times t_{B_i})
10
                                e = t < 0 < e + t_{B_i} >
                                \mathtt{t}_{\mathtt{B}_{\mathtt{i}}} = \mathtt{t} < \mathtt{i}\Delta \leq \mathtt{t}_{\mathtt{Req}} < (\mathtt{i}+1)\Delta > \times (\mathtt{t}_{\mathtt{Req}} \cup [\mathtt{min}]\,\mathtt{t})
12
                            \mathtt{t}=\mathtt{t}\cup [\mathtt{min}]\,\mathtt{t}_{\mathtt{Req}}
13
                        \texttt{t}_{\texttt{Req}} = \texttt{A}_{\texttt{H}} \, \texttt{'} + . \times (\texttt{t} \times \texttt{e})
14
                        \mathtt{t} = \mathtt{t} \cup [\mathtt{min}] \, \mathtt{t}_{\mathtt{Req}}
15
                        \mathtt{i}=\mathtt{i}+1
16
```

## Algorithm 10: All-pairs shortest path (Floyd-Warshall algorithm).

#### Algorithm 11: FastSV algorithm.

```
1 Function FastSV
 \mathbf{2}
       n = nrows(A)
       gf = f
 3
       dup = gf
 4
       mngf = gf
       \{i, x\} < -f
       repeat
          // Step 1: Stochastic hooking
           mngf = mngf min A
 8
           mngf = mngf second.min gf
           f(x) = f \min mngf
10
           // Step 2: Aggressive hooking
           \mathtt{f} = \mathtt{f}\,\mathtt{min}\,\mathtt{mngf}
11
           // Step 3: Shortcutting
           f = f \min gf
12
           // Step 4: Calculate grandparents
           \{i, x\} \leftarrow f
13
           gf = f(x)
14
           // Step 5: Check termination
           diff = dup \neq gf
15
           sum = [+_i diff(i)]
16
           dup = gf
17
       \mathbf{until}\ \mathtt{sum} == 0
18
```

## Algorithm 12: Triangle count (Cohen's algorithm).

## Algorithm 13: Triangle count (Sandia).

## Algorithm 14: Triangle count (FLAME).

```
1 Function TriangleCountFlame
2 | for i = 2 to n - 1 do
3 | A_{20} = A(i + 1 : n, 0 : i - 1)
4 | a_{10} = A(0 : i - 1, i)
5 | a_{12} = A(i, i + 1 : n)
6 | t + = a_{10} + . \times A_{20} + . \times a_{12}
```

## Algorithm 15: Local clustering coefficient.

### **Algorithm 16:** *k*-truss algorithm.

```
1 Function KTruss
2
     C <- A
     nonzeros <- nvals(C)
3
     for i = 1 to n - 1 do
4
        C < C > = C + . land C
5
        C = C < C \ge k - 2 >
6
        if nonzeros == nvals(C) then
7
         break
8
9
        nonzeros <- nvals(C)
```

## Algorithm 17: Louvain algorithm (WIP).

```
1 Function Louvain
      G += G'
 \mathbf{2}
      k = [+A]
 3
      \mathbf{m} = (1)/(2)[+k]
 4
      S <- I
 5
 6
      vertices_changed <- nvals(k)</pre>
 7
      while vertices_changed > 0 do
 8
          for j \in range(|V|) do
 9
10
              v = G(j,:)
              t_q = v any.pair S
11
              sr = S(j,:)
12
              S(j,:) = empty
13
              q <- k
15
              q < k > x = -k(j)/m
16
              q + = v
17
18
              q_1 < t_q >= q + . \times S
19
              t = (q_1 == [\max q_1])
20
              while nvals(t) \neq 1 do
21
                 p = random() \times t
22
                t = (p == [\max p])
23
              S(j,:) = t
24
25
              if nvals(sr \times t) == 0 then
26
               vertices_changed = nvals(k)
27
              vertices\_changed = vertices\_changed - 1
28
```

#### Algorithm 18: Community detection using label propagation (for undirected graphs).

## References

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