LAGraph Algorithms

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Abstract

Theoretical documentation for LAGraph.

1 Introduction

The goal of this document is to present a notation for GraphBLAS algorithms and showcase it using important GraphBLAS algorithms.

2 The GraphBLAS

Goal The goal of GraphBLAS is to create a layer of abstraction between the graph algorithms and the graph analytics framework, separating the concerns of the algorithm developers from those of the framework developers and hardware designers. To achieve this, it builds on the theoretical framework of matrix operations on arbitrary semirings [3], which allows defining graph algorithms in the language of linear algebra [4]. To ensure portability, the GraphBLAS standard defines a C API that can be implemented on a variety of hardware including GPUs.

Data structures A graph with n vertices can be stored as a square adjacency matrix $\mathbf{A} \in \mathbb{N}^{n \times n}$, where rows and columns both represent vertices of the graph and element A(i,j) contains the number of edges from vertex i to vertex j. If the graph is undirected, the matrix is symmetric.

Navigation The fundamental step in GraphBLAS is the multiplication of an adjacency matrix with another matrix or vector over a selected semiring. For example, the operation **HasMember**lor.land**IsLocatedIn** computed over the "logical or.logical and" semiring returns a matrix representing the Places where a Forum's members are located in. Meanwhile, when computed over the conventional arithmetic "plus.times" semiring, **HasMember** \oplus . Significant the number of such Persons. A traversal from a certain set of vertices can be expressed by using a boolean vector \mathbf{f} (often referred to as the frontier, wavefront, or queue) and setting true values for the elements corresponding to source vertices. For example, for Forums $\mathbf{f} \in \mathbb{B}^{|forums|}$, \mathbf{f} lor.land **HasMember** returns the Persons who belong to any of the forums in \mathbf{f} . The BFS navigation step can also be captured using other semirings such as lor.first, where first(x, y) = x; lor.second, where second(x, y) = y; and any.pair, where any(x, y) returns either x or y, and pair(x, y) = 1 [2].

2.1 Notation

Table 1 contains the notation of GraphBLAS operations Additionally, we use $\mathbf{D} = diag(\mathbf{j}, n)$ to construct a diagonal matrix $\mathbf{D} \leftarrow \{\mathbf{j}, \mathbf{j}, [1, 1, \dots, 1]\}$. The elements of the matrix are $\mathbf{D}(j, j) = 1$ for $j \in \mathbf{j}$.

2.1.1 Masks

Masks $\mathbf{C}\langle \mathbf{M} \rangle$ and $\mathbf{u}\langle \mathbf{m} \rangle$ are used to selectively write to the result matrix/vector. The complements of the masks can be selected with the negation symbol, denoted with: $\mathbf{C}\langle \neg \mathbf{M} \rangle$ and $\mathbf{u}\langle \neg \mathbf{m} \rangle$, respectively.

Masks with "replace" semantics (annihilating all elements outside the mask) are denoted with

- $\mathbf{C}\langle \mathbf{M}, r \rangle$
- $\mathbf{C}\langle \neg \mathbf{M}, r \rangle$
- $\mathbf{u}\langle\mathbf{m},\mathbf{r}\rangle$
- $\mathbf{u}\langle \neg \mathbf{m}, \mathbf{r} \rangle$

The structure of the mask is denoted with:

$_{ m op./method}$	name	notation
mxm	matrix-matrix multiplication	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}\oplus.\otimes\mathbf{B}$
vxm	vector-matrix multiplication	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}\oplus.\otimes\mathbf{A}$
mxv	matrix-vector multiplication	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}\oplus.\otimes\mathbf{u}$
eWiseAdd	element-wise addition	$\mathbf{C}\langle\mathbf{M}\rangle{\odot}{=}\mathbf{A}\oplus\mathbf{B}$
	set union of patterns	$\mathbf{w}\langle\mathbf{m}\rangle{\odot}{=}\mathbf{u}\oplus\mathbf{v}$
eWiseMult	element-wise multiplication	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}\otimes\mathbf{B}$
	set intersection of patterns	$\mathbf{w}\langle\mathbf{m}\rangle{\odot}{=}\mathbf{u}\otimes\mathbf{v}$
extract	extract submatrix	$\mathbf{C}\langle\mathbf{M} angle\odot=\mathbf{A}(m{i},m{j})$
	extract column vector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}(:,j)$
	extract row vector	$\mathbf{w}\langle\mathbf{m}\rangle{\odot}{=}\mathbf{A}(i,:)$
	extract subvector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}(m{i})$
assign	assign matrix to submatrix with mask for C	$\mathbf{C}\langle\mathbf{M} angle(i,j)\odot=\mathbf{A}$
	assign scalar to submatrix with mask for ${f C}$	$\mathbf{C}\langle\mathbf{M}\rangle(i,j)\odot=s$
	assign vector to subvector with mask for \mathbf{w}	$\mathbf{w}\langle\mathbf{m} angle(m{i})\odot=\mathbf{u}$
	assign scalar to subvector with mask for ${\bf w}$	$\mathbf{w}\langle\mathbf{m} angle(i)\odot=s$
subassign (GxB)	assign matrix to submatrix with submask for $\mathbf{C}(i,j)$	$\mathbf{C}(i,j)\langle\mathbf{M} angle\odot=\mathbf{A}$
	assign scalar to submatrix with submask for $C(i, i)$	$\mathbf{C}(i,j)\langle\mathbf{M}\rangle \odot = s$
	assign vector to subvector with submask for $\mathbf{w}(i)$	$\mathbf{w}(i)\langle\mathbf{m}\rangle$ \odot = \mathbf{u}
	assign scalar to subvector with submask for $\mathbf{w}(i)$	$\mathbf{w}(i)\langle\mathbf{m}\rangle\odot=s$
-	1	$\mathbf{C}\langle\mathbf{M}\rangle\odot=f(\mathbf{A})$
apply	apply unary operator	$\mathbf{w}\langle\mathbf{m}\rangle\odot=f(\mathbf{u})$
select (GxB)	apply select operator	$\begin{array}{c} \mathbf{C}\langle\mathbf{M}\rangle\bigcirc=select(\mathbf{A},f(k))\\ \mathbf{C}\langle\mathbf{M}\rangle\bigcirc=select(low\leq\mathbf{A}\leq up)\\ \mathbf{w}\langle\mathbf{m}\rangle\bigcirc=select(\mathbf{u},f(k))\\ \mathbf{w}\langle\mathbf{m}\rangle\bigcirc=select(low\leq\mathbf{u}\leq up) \end{array}$
reduce	reduce matrix to column vector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=[\oplus_{j}\mathbf{A}(:,j)]$
	reduce matrix to scalar	$s \odot = [\oplus_{ij} \mathbf{A}(i,j)]$
	reduce vector to scalar	$s\odot = [\oplus_i \mathbf{u}(i)]$
transpose	transpose	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}^{T}$
kronecker	Kronecker multiplication	$\mathbf{C}\langle\mathbf{M}\rangle \odot = kron(\mathbf{A}, \mathbf{B})$
	new matrix	let: $\mathbf{A} \in TYPE^{n \times m}_{PRECISION}$
new	new vector	let: $\mathbf{u} \in TYPE^n_{PRECISION}$
build	matrix from tuples vector from tuples	$\mathbf{C} \leftarrow \{oldsymbol{i}, oldsymbol{j}, oldsymbol{x}\}$
	vector from tupies	$\mathbf{w} \leftrightarrow \{i, x\}$
extractTuples	extract index/value arrays	$\{oldsymbol{i},oldsymbol{j},oldsymbol{x}\}\!\!\leftarrow\!$
dup	Juniticate metalic	
	duplicate matrix duplicate vector	$\begin{matrix} \mathbf{C} \!$
extractElement		$s = \mathbf{A}(i, j)$ $s = \mathbf{u}(i)$
setElement	set element	$\mathbf{C}(i,j) = s$ $\mathbf{w}(i) = s$

Table 1: GraphBLAS operations and methods based on [1]. *Notation:* Matrices and vectors are typeset in bold, starting with uppercase (**A**) and lowercase (**u**) letters, respectively. Scalars including indices are lowercase italic (k, i, j) while arrays are lowercase bold italic (x, i, j). \oplus and \otimes are the addition and multiplication operators forming a semiring and default to conventional arithmetic + and \times operators. \odot is the accumulation operator.

- $\mathbf{C}\langle s(\mathbf{M})\rangle$
- $\mathbf{C}\langle \neg s(\mathbf{M}) \rangle$
- $\mathbf{u}\langle s(\mathbf{m})\rangle$
- $\mathbf{u}\langle \neg s(\mathbf{m})\rangle$

Combining structure and replace semantics is possible:

- $\mathbf{C}\langle s(\mathbf{M}), \mathbf{r} \rangle$
- $\mathbf{C}\langle \neg s(\mathbf{M}), \mathbf{r} \rangle$
- $\mathbf{u}\langle s(\mathbf{m}), \mathbf{r}\rangle$
- $\mathbf{u}\langle \neg s(\mathbf{m}), \mathbf{r} \rangle$

Initializing scalars, vectors, and matrices (GraphBLAS methods):

- let: $s \in \mathbb{Q}_{64}$
- let: $\mathbf{u} \in \mathbb{Q}_{32}^n$
- let: $\mathbf{A} \in \mathbb{N}_{16}^{m \times n}$
- let: $\mathbf{A} \in \mathbb{Z}_{64}^{k \times m}$

3 Algorithms

LAGraph [5] implements graph algorithms using the GraphBLAS C API [6]. Here are a few algorithms that could be included in this document:

```
Input: A, n, startVertex
                                                                                                                 Input: A, A^T, n, startVertex Input: A, n, startVertices
                                                        Input: A, n, startVertex
   Function BFS
                                                                                                            {\bf 1} \ \ {\bf Function} \ \ {\it DirectionOptimix} \hbox{-} \ {\bf Function} \ \ {\it ConcurrentBFS}
                                                   1 Function ParentsBFS
          \mathbf{f}(startVertex) = \mathbf{T}
                                                               \mathbf{f}(startVertex) = 0
                                                                                                                   ingBFS
                                                    2
           for level = 1 to n-1 de
                                                               for level = 1 to n-1 do
                                                                                                                        f(startVertex) = T
                                                                                                                                                                                   diag(startVertices, n)
3
4
                 \mathbf{s}\langle\mathbf{f}\rangle = level
                                                                      \mathbf{s}\langle\mathbf{f}\rangle=\mathbf{f}
                                                                                                                        for level = 1 to n-1 dos
                                                                                                                                                                                 for level = 1 to n - 1 do
                                                                      \mathbf{f} \langle \neg \mathbf{s}, r \rangle \ = \ \mathbf{f} \ \mathsf{any.firstj4}
                                                                                                                               \mathbf{s}\langle\mathbf{f}\rangle = level
                                                                                                                                                                                       \mathbf{S}\langle\mathbf{F}\rangle = level
                                                                                                                               if Push(\mathbf{A}, \mathbf{f}) then 5
                                                                                                                                                                                       \mathbf{F}\langle \neg \mathbf{S}, \mathbf{r} \rangle = \mathbf{F}\mathbf{A}
                                                                                                                                \lfloor \mathbf{f} \langle \neg \mathbf{s}, \mathbf{r} \rangle = \mathbf{f} \mathbf{A}
                                                                                                             7
                                                                                                                                | \mathbf{f} \langle \neg \mathbf{s}, \mathbf{r} \rangle = \mathbf{A}^\mathsf{T} \mathbf{f}
```

Figure 1: Sketch algorithms of BFS variants. The $Push(\mathbf{A}, \mathbf{f})$ function makes a decision on whether it is cheaper to push or pull using heuristics based on the sparsity of the frontier \mathbf{f} and adjacency matrix \mathbf{A} .

Algorithm 1: Multi-source breadth-first search.

```
 \begin{array}{c|c} \textbf{Data:} \dots \\ \textbf{Result:} \dots \\ \textbf{1} & \textbf{Function} \ MSBFS \\ \textbf{2} & | \textbf{Frontier} = \text{diag}(\textbf{sources}, n) \\ \textbf{3} & | \textbf{for} \ level = 1 \ \textbf{to} \ n - 1 \ \textbf{do} \\ \textbf{4} & | | \textbf{Seen}\langle \textbf{Frontier} \rangle = level \\ \textbf{5} & | | \textbf{Frontier}\langle \neg \textbf{Seen}, \mathbf{r} \rangle = \textbf{Frontier} \ \text{any.pair} \ \textbf{A} \\ \end{array}
```

Algorithm 2: All-pairs shortest distance (on undirected, unweighted graphs) [7].

```
Data: ...
    Result: ...
 1 Function APD(\mathbf{A}, n, \mathbf{deg})
         Z = A
         Z \oplus = A \oplus . \otimes A
         \mathbf{B} = \{select(\mathbf{Z}, offdiag)\} // \text{ use the pattern as a Boolean matrix}
         if A == B then
 5
           return A
 6
         T = APD(B, n, deg)
 7
         X=T\oplus .\otimes A
 8
         \mathbf{Tscaled} = \mathbf{T} \oplus . \otimes \mathit{diag}(\mathbf{deg})
10
         Xfiltered = select(X, X < Tscaled)
         return (2 \otimes \mathbf{T}) \ominus \mathbf{X} filtered
11
12 Function APD(\mathbf{A})
         \mathbf{deg} = [\oplus_i \mathbf{A}(i,:)]
13
         Distance = APD(A, n, deg)
14
15
         \mathbf{sp} = [\oplus_i \mathbf{Distance}(i,:)]
```

Algorithm 3: Betweenness centrality.

```
1 Function MSBFS
       // The NumSp structure holds the number of shortest paths for each node and
            starting vertex discovered so far.
       // Initialized to source vertices.
       \mathbf{NumSp} \leftarrow \{s, [1, 1, \dots, 1]\}
 \mathbf{2}
       // The Frontier holds the number of shortest paths for each node and starting vertex
            discovered so far.
       // Initialized to source vertices.
       \mathbf{Frontier}\langle \mathbf{NumSp}\rangle = \mathbf{A}(s,:)
 3
       // The Sigmas matrices store frontier information for each level of the BFS phase.
       // BFS phase (forward sweep)
       do
 5
            // \mathbf{Sigmas}[d](:,s) = d^{\mathrm{th}} level frontier from source vertex s
           let: \mathbf{Sigmas}[d] \in \mathbb{B}^{n \times nsver}
 6
            \mathbf{Sigmas}[d](:,:) = \mathbf{Frontier}
                                                                                        // Convert matrix to Boolean
 7
            NumSp = NumSp \oplus Frontier
                                                                                            // Accumulate path counts
 8
           Frontier \langle \mathbf{NumSp}, \mathbf{r} \rangle = \mathbf{A}^{\mathsf{T}} \oplus . \otimes \mathbf{Frontier}
                                                                                                      // Update frontier
 9
       while nvals(Frontier) > 0
10
       let: NumSpInv \in \mathbb{Q}_{32}^{n \times nsver}
11
       NumSpInv = 1.0 \oslash NumSp
12
       let: \mathbf{BCU} \in \mathbb{Q}_{32}^{n \times nsver}
13
       BCU(:) = 1.0
                                                        // Make BCU dense, initialize all elements to 1.0
14
       let: \mathbf{W} \in \mathbb{Q}_{32}^{n \times nsver}
15
       // Tally phase (backward sweep)
       for i = d - 1 downto 0 do
16
            W(Sigmas[i], r) = NumSpInv \oslash BCU
17
            \mathbf{W}\langle \mathbf{Sigmas}[i-1], \mathbf{r}\rangle = \mathbf{A} \oplus . \otimes \mathbf{W}
                                                           // Add contributions by successors and mask with
18
             that BFS level's frontier.
           \mathbf{BCU} \oplus = \mathbf{W} \otimes \mathbf{NumSp}
19
       // Row reduce \operatorname{BCU} and subtract nsver from every entry to account for 1 extra value
            per BCU row element
       \mathbf{delta} = [\oplus_j \mathbf{BCU}(:,j)]
20
       \mathbf{delta} \ominus = nsver
21
```

Algorithm 4: PageRank (used in Graphalytics).

```
Data: \alpha constant (damping factor)
   \mathbf{Result:} \dots
 1 Function PageRank
        pr(:) = 1/n
 2
 3
        outdegrees = [\oplus_i \mathbf{A}(:,j)]
        for k = 1 to numIterations do
 4
             importance = pr \oslash outdegrees
 5
             importance = times(importance, \alpha)
                                                                                    // apply the times(x,s) = x \cdot s operator
 6
             importance = importance \oplus . \otimes A
 7
             \mathbf{danglingVertexRanks} \langle \neg \mathbf{outdegrees} \rangle = \mathbf{pr}(:)
 8
             totalDanglingRank = \frac{\alpha}{n} \otimes [\bigoplus_i \mathbf{danglingVertexRanks}(i)]
             \mathbf{pr} = \frac{1-\alpha}{n} \oplus totalDanglingRank
10
             \mathbf{pr} = \mathbf{pr} \oplus \mathbf{importance}
```

Algorithm 5: Algebraic Bellman-Ford.

```
Function SSSP

\begin{array}{c|cccc}
\mathbf{d}(s) &= 0 \\
\mathbf{d} & \mathbf{for} \ k = 1 \ \mathbf{to} \ n - 1 \ \mathbf{do} \\
\mathbf{d}' &= \mathbf{d} \ \mathsf{min.plus} \ \mathbf{A} \\
\mathbf{f} & \mathbf{d}' &= \mathbf{d} \ \mathsf{then} \ \mathsf{break} \\
\mathbf{d} & \mathbf{d}' &= \mathbf{d}'
\end{array}
```

Algorithm 6: Delta-stepping SSSP.

```
Data:
            \mathbf{A}, \mathbf{A_H}, \mathbf{A_L} \in \mathbb{Q}^{|V| \times |V|}
            s, i \in \mathbb{N}
            \Delta \in \mathbb{Q}
            \mathbf{t}, \mathbf{t_{Req}} \in \mathbb{Q}^{|V|}
            \mathbf{t_{B_i}}, \mathbf{e} \in \mathbb{N}^{|V|}
  1 Function DeltaStepping
               \mathbf{A_L} = select(0 < \mathbf{A} < \Delta)
  2
               \mathbf{A_H} = select(\Delta < \mathbf{A})
  3
               \mathbf{t}(:) = \infty
  4
               \mathbf{t}(s) = 0
  5
               while nvals(select(i\Delta \leq \mathbf{t})) \neq 0 do
  6
                       s = 0
  7
                       \mathbf{t_{B_i}} = select(i\Delta \leq \mathbf{t} < (i+1)\Delta)
  8
  9
                       while \mathbf{t_{B_i}} \neq 0 do
                                \mathbf{t_{Req}} = \mathbf{A_L^T} \oplus . \otimes (\mathbf{t} \otimes \mathbf{t_{B_i}})
10
                                \mathbf{e} = select(0 < \mathbf{e} \oplus \mathbf{t}_{\mathbf{B_i}})
11
                                \mathbf{t_{B_i}} = select(i\Delta \leq \mathbf{t_{Req}} < (i+1)\Delta) \otimes (\mathbf{t_{Req}} \min \mathbf{t})
12
                                \mathbf{t_{B_i}} = select(i\Delta \leq \mathbf{t_{Req}} < (i+1)\Delta) \otimes (\mathbf{t_{Req}} \oplus_{\mathsf{min}} \mathbf{t})
13
                                \mathbf{t_{B_i}} = select(i\Delta \leq \mathbf{t_{Req}} < (i+1)\Delta) \otimes (\mathbf{t_{Req}} \min_{\oplus} \mathbf{t})
14
                               \mathbf{t} = \mathbf{t} \, \mathsf{min} \, \mathbf{t}_{\mathbf{Req}}
15
                       \mathbf{t_{Req}} = \mathbf{A_H^T} \oplus . \otimes (\mathbf{t} \otimes \mathbf{e})
16
                       \mathbf{t} = \mathbf{t} \, \mathsf{min} \, \mathbf{t_{Req}}
17
                       i = i + 1
18
```

Algorithm 7: All-pairs shortest path (Floyd-Warshall algorithm).

```
1 Function FloydWarshall

2 | \mathbf{D} \leftrightarrow \mathbf{A}

3 | for k = 1 to n do

4 | \mathbf{D} = \mathbf{D} \min[\mathbf{D}(:,k) \min.plus(\mathbf{D}(k,:)]
```

Algorithm 8: FastSV algorithm.

```
1 Function FastSV
        n = nrows(\mathbf{A})
 \mathbf{2}
        gf = f
 3
        dup = gf
 4
        mngf = gf
 5
        \{i, x\} \leftarrow f
 6
        repeat
            // Step 1: Stochastic hooking
             \mathbf{mngf} = \mathbf{mngf} \, \mathsf{min} \, \mathbf{A}
 8
             \mathbf{mngf} = \mathbf{mngf} second.min \mathbf{gf}
             f(x) = f \min mngf
10
             // Step 2: Aggressive hooking
             f = f \min mngf
11
             // Step 3: Shortcutting
             f = f \min gf
12
             // Step 4: Calculate grandparents
             \{i,x\} \leftarrow \mathbf{f}
13
             \mathbf{gf} = \mathbf{f}(\mathbf{x})
14
             // Step 5: Check termination
             \mathbf{diff} = \mathbf{dup} \neq \mathbf{gf}
15
             sum = [\bigoplus_i \mathbf{diff}(i)]
16
             dup = gf
17
        until sum == 0
18
```

Algorithm 9: Triangle count (Cohen's algorithm).

```
1 Function TriangleCount
2 L = tril(\mathbf{A})
3 U = triu(\mathbf{A})
4 \mathbf{B} = \mathbf{L} \oplus . \otimes \mathbf{U}
5 \mathbf{C} = \mathbf{B} \otimes \mathbf{A}
6 t = [\oplus_{ij} \mathbf{C}(i,j)]/2
```

Algorithm 10: Triangle count (Sandia).

```
1 Function Triangle Count

2 | \mathbf{L} = tril(\mathbf{A})

3 | \mathbf{C}\langle \mathbf{L} \rangle = \mathbf{L} \oplus . \otimes \mathbf{L}

4 | t = [\oplus_{ij} \mathbf{C}(i,j)]
```

Algorithm 11: Triangle count (FLAME).

```
1 Function TriangleCountFlame

2 | for i = 2 to n - 1 do

3 | \mathbf{A_{20}} = \mathbf{A}(i+1:n,0:i-1)

4 | \mathbf{a_{10}} = \mathbf{A}(0:i-1,i)

5 | \mathbf{a_{12}} = \mathbf{A}(i,i+1:n)

6 | \mathbf{t} \oplus = \mathbf{a_{10}} \oplus ... \otimes \mathbf{A_{20}} \oplus ... \otimes \mathbf{a_{12}}
```

Algorithm 12: Local clustering coefficient.

Algorithm 13: k-truss algorithm.

```
1 Function KTruss
        \mathbf{C} \leftarrow \mathbf{A}
\mathbf{2}
3
        nonzeros \leftarrow nvals(C)
        for i = 1 to n - 1 do
4
              \mathbf{C}\langle\mathbf{C}\rangle=\mathbf{C}\oplus. land \mathbf{C}
5
              \mathbf{C} = select(\mathbf{C} \ge k - 2)
6
              if nonzeros == nvals(C) then
7
               break
8
9
              nonzeros \leftarrow nvals(C)
```

Algorithm 14: Louvain algorithm (WIP).

```
1 Function Louvain
 2
            G \oplus = G^T
            \mathbf{k} = [\oplus_j \mathbf{A}(:,j)]
 3
            m = \frac{1}{2} [\bigoplus_i \mathbf{k}(i)]
 4
            S \leftarrow I
 5
 6
            vertices\_changed \leftarrow nvals(\mathbf{k})
 7
            while vertices\_changed > 0 do
 8
                  for j \in range(|V|) do
 9
10
                        \mathbf{v} = \mathbf{G}(j,:)
                        \mathbf{t_q} = \mathbf{v} any.pair \mathbf{S}
11
                         \mathbf{sr} = \mathbf{S}(j,:)
12
                        \mathbf{S}(j,:) = \text{empty}
13
14
                         \mathbf{q} \leftarrow \mathbf{k}
15
                         \mathbf{q}\langle\mathbf{k}\rangle\otimes=-\mathbf{k}(j)/m
16
                         q \oplus = v
17
18
                         \mathbf{q_1}\langle\mathbf{t_q}\rangle=\mathbf{q}\oplus.\otimes\mathbf{S}
19
                        \mathbf{t} = (\mathbf{q_1} == [\max_i \mathbf{q_1}(i)])
20
                         while nvals(t) \neq 1 do
21
                               \mathbf{p} = random() \otimes \mathbf{t}
22
                             \mathbf{t} = (\mathbf{p} == [\mathsf{max}_i \ \mathbf{p}(i)])
23
                         \mathbf{S}(j,:) = \mathbf{t}
\bf 24
25
                        if nvals(\mathbf{sr} \otimes \mathbf{t}) == 0 then
26
                           vertices\_changed = nvals(\mathbf{k})
27
                        vertices\_changed = vertices\_changed - 1
28
```

Algorithm 15: Community detection using label propagation (for undirected graphs).

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