LAGraph Algorithms

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Abstract

Theoretical documentation for LAGraph.

1 Notation

Table 1 contains the notation of GraphBLAS operations

Additionally, we use $\mathbf{D} = diag(J, n)$ to construct a diagonal matrix $\mathbf{D} \leftrightarrow \{J, J, [1, 1, \dots, 1]\}$. The elements of the matrix are $\mathbf{D}(j, j) = 1$ for $j \in J$.

Initializing scalars, vectors, and matrices (GraphBLAS methods):

- let: $s \in \mathbb{Q}_{64}$
- let: $\mathbf{u} \in \mathbb{Q}_{32}^n$
- let: $\mathbf{A} \in \mathbb{N}_{16}^{m \times n}$
- let: $\mathbf{A} \in \mathbb{Z}_{64}^{k \times m}$

2 Algorithms

LAGraph [12] implements graph algorithms using the GraphBLAS C API [13]. An incomplete list of GraphBLAS algorithms:

- MSBFS [8], bidirectional BFS [8], pushpull BFS [19]
- DFS [16]
- weakly connected components [21]
- SCC (LAGraph)
- SSSP, delta-stepping [17]
- triangle count [1, 5], triangle enumeration [1], item local clustering coefficient [4]
- *k*-truss [5]
- betweenness centrality [12]
- closeness centrality [8]
- DNN algorithm [10, 7]
- PageRank variants (at least 2) [4], IISWC paper, ...
- Louvain [11]
- property graphs: incremental TTC case [9], SIGMOD 2014 Contest [8] Roi Lipman's talk¹
- CFPQs based on a string of GRADES/ADBIS/other papers [2, 3, 14, 18, 15]
- Implementations: GBTL², SuiteSparse:GraphBLAS [6], GraphBLAST [20]

¹http://wiki.ldbcouncil.org/pages/viewpage.action?pageId=106233859&preview=/106233859/111706128/LDBC-July-2019.pdf

²https://github.com/cmu-sei/gbtl

op./method	name	notation
mxm	matrix-matrix multiplication	$\mathbf{C}\langle\mathbf{M}\rangle \odot = \mathbf{A} \oplus . \otimes \mathbf{B}$
vxm	vector-matrix multiplication	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}\oplus.\otimes\mathbf{A}$
mxv	matrix-vector multiplication	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}\oplus.\otimes\mathbf{u}$
eWiseAdd	element-wise addition	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}\oplus\mathbf{B}$
	set union of patterns	$\mathbf{w}\langle\mathbf{m}\rangle{\odot}{=}\mathbf{u}\oplus\mathbf{v}$
eWiseMult	element-wise multiplication	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}\otimes\mathbf{B}$
	set intersection of patterns	$\mathbf{w}\langle\mathbf{m}\rangle{\odot}{=}\mathbf{u}\otimes\mathbf{v}$
extract	extract submatrix	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}(I,J)$
	extract column vector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}(:,j)$
	extract row vector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}(i,:)$
	extract subvector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}(I)$
assign	assign matrix to submatrix with mask for ${\bf C}$	$\mathbf{C}\langle\mathbf{M}\rangle(I,J)\odot=\mathbf{A}$
	assign scalar to submatrix with mask for \mathbb{C}	$\mathbf{C}\langle\mathbf{M}\rangle(I,J)\odot=s$
	assign vector to subvector with mask for w	$\mathbf{w}\langle\mathbf{m}\rangle(I)\odot=\mathbf{u}$
	assign scalar to subvector with mask for w	$\mathbf{w}\langle\mathbf{m}\rangle(I)\odot=s$
subassign (GxB)	assign matrix to submatrix with submask for $\mathbf{C}(I, J)$	$\mathbf{C}(I,J)\langle\mathbf{M}\rangle\odot=\mathbf{A}$
	assign scalar to submatrix with submask for $C(I, J)$	$\mathbf{C}(I,J)\langle\mathbf{M}\rangle \odot = s$
	assign vector to subvector with submask for $\mathbf{w}(1)$	$\mathbf{w}(I)\langle\mathbf{m}\rangle\odot=\mathbf{u}$
	assign scalar to subvector with submask for $\mathbf{w}(I)$	$\mathbf{w}(I)\langle\mathbf{m}\rangle \odot = s$
apply	apply unary operator	$\mathbf{C}\langle\mathbf{M}\rangle\odot=f(\mathbf{A})$
		$\mathbf{w}\langle\mathbf{m}\rangle\odot=f(\mathbf{u})$
select (GxB)	apply select operator	$\begin{array}{l} \mathbf{C}\langle\mathbf{M}\rangle\bigcirc=select(\mathbf{A},f(k))\\ \mathbf{C}\langle\mathbf{M}\rangle\bigcirc=select(low\leq\mathbf{A}\leq up)\\ \mathbf{w}\langle\mathbf{m}\rangle\bigcirc=select(\mathbf{u},f(k))\\ \mathbf{w}\langle\mathbf{m}\rangle\bigcirc=select(low\leq\mathbf{u}\leq up) \end{array}$
reduce	reduce matrix to column vector	$\mathbf{w}\langle\mathbf{m}\rangle \odot = [\oplus_j \mathbf{A}(:,j)]$
	reduce matrix to scalar	$s \odot = [\bigoplus_{ij} \mathbf{A}(i,j)]$
	reduce vector to scalar	$s \odot = [\bigoplus_i \mathbf{u}(i)]$
transpose	transpose	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}^{\top}$
kronecker	Kronecker multiplication	$\mathbf{C}\langle\mathbf{M}\rangle\odot=kron(\mathbf{A},\mathbf{B})$
new	new matrix	let: $\mathbf{A} \in TYPE_{PRECISION}^{n \times m}$
	new vector	let: $\mathbf{u} \in TYPE^n_{PRECISION}$
build	build matrix from index/value arrays	$\mathbf{C} \leftrightarrow \{I, J, X\}$
	build vector from index/value arrays	$\mathbf{w} \leftrightarrow \{I, X\}$
extractTuples	extract index/value arrays	$\{I,J,X\} \leftrightarrow \mathbf{A}$
		$\{I, X\} \longleftrightarrow \mathbf{u}$
dup	duplicate matrix	C ← A
	duplicate vector	w ← u
extractElement	extract scalar element	$s = \mathbf{A}(i, j)$ $s = \mathbf{u}(i)$
setElement	set element	$\mathbf{C}(i,j) = s$ $\mathbf{w}(i) = s$

Table 1: GraphBLAS operations and methods based on [6]. Notation: Matrices and vectors are typeset in bold, starting with uppercase (\mathbf{A}) and lowercase (\mathbf{u}) letters, respectively. Scalars including indices are lowercase italic (s, i, j) while arrays are uppercase italic (s, s, s) while arrays are uppercase italic (s, s) and s are the addition and multiplication operators forming a semiring and default to conventional arithmetic + and × operators. s is the apply operator. Masks (s) and (s) are used to selectively write to the result matrix/vector. The complements of masks (s), (s) can be selected with the negation symbol, denoted with (s), (s), respectively. Masks with "replace" semantics (annihilating all elements outside the mask) are denoted with (s), (

Algorithm 1: Breadth-first search.

```
1 Function BFS
2 | frontier(s) = TRUE
3 | for level = 1 to n - 1 do
4 | seen\langle frontier \rangle = level
5 | frontier(\langle \neg seen \rangle \rangle = frontier any.pair A
```

Algorithm 2: Breadth-first search (push/pull).

```
_{1} Function BFS
       frontier(s) = TRUE
\mathbf{2}
       for level = 1 to n - 1 do
3
           seen\langle frontier \rangle = level
4
           push = use some heuristics to determine whether to push/pull
5
           if push then
6
            | frontier\langle\langle \neg seen \rangle\rangle = frontier any.pair A
7
           else
8
             frontier \langle \langle \neg seen \rangle \rangle = A any pair frontier
```

Algorithm 3: Multi-source breadth-first search.

```
Data: ...
Result: ...

Function MSBFS

Frontier \leftarrow \operatorname{diag}(S, n)

for level = 1 to n - 1 do

Seen\langle Frontier \rangle = level

Frontier\langle \langle \neg Seen \rangle \rangle = Frontier any.pair A
```

Algorithm 4: Betweenness centrality.

```
1 Function MSBFS
       // The NumSp structure holds the number of shortest paths for each node and
           starting vertex discovered so far.
       // Initialized to source vertices.
 3
       NumSp \leftrightarrow {s, [1, 1, ..., 1]}
 4
       // The Frontier holds the number of shortest paths for each node and starting vertex
 5
           discovered so far.
       // Initialized to source vertices.
 6
       Frontier\langle NumSp \rangle = A(s,:)
 7
       d = 0
 8
       // The Sigmas matrices store frontier information for each level of the BFS phase.
 9
       // BFS phase (forward sweep)
10
       do
11
           // \mathbf{Sigmas}[d](:,s) = d^{\mathrm{th}} level frontier from source vertex s
12
          let: Sigmas [d] \in \mathbb{B}^{n \times nsver}
13
           Sigmas[d](:,:) = Frontier
                                                                                // Convert matrix to Boolean
14
           NumSp = NumSp \oplus Frontier
                                                                                     // Accumulate path counts
15
           Frontier \langle \langle NumSp \rangle \rangle = A^{\top} \oplus . \otimes Frontier
                                                                                              // Update frontier
16
       while nvals(Frontier) > 0
17
       let: NumSpInv \in \mathbb{Q}_{32}^{n \times nsver}
18
       NumSpInv = 1.0 \oslash NumSp
19
       let: \mathbf{BCU} \in \mathbb{Q}_{32}^{n \times nsver}
20
       BCU(:) = 1.0
                                                   // Make BCU dense, initialize all elements to 1.0
21
       let: \mathbf{W} \in \mathbb{Q}_{32}^{n \times nsver}
22
       // Tally phase (backward sweep)
23
       for i = d - 1 downto 0 do
24
           W(Sigmas[i]) = NumSpInv \oslash BCU
25
           \mathbf{W}\langle \mathbf{Sigmas}[i-1] \rangle = \mathbf{A} \oplus . \otimes \mathbf{W} // Add contributions by successors and mask with that
26
           BFS level's frontier.
          BCU \oplus = W \otimes NumSp
27
       // Row reduce \overline{BCU} and subtract nsver from every entry to account for 1 extra value
28
           per BCU row element
29
       delta = [\bigoplus_{i} \mathbf{BCU}(:,j)]
       delta \ominus = nsver
30
```

Algorithm 5: PageRank (used in Graphalytics).

```
Data: \alpha constant (damping factor)
   Result: ...
 1 Function PageRank
       pr(:) = 1/n
       outdegrees = [\oplus_j \mathbf{A}(:,j)]
 3
       for k = 1 to numIterations do
 4
            importance = pr \oslash outdegrees
 5
            importance = times(importance, \alpha)
                                                                             // apply the times(x,s) = x \cdot s operator
 6
            importance = importance \oplus . \otimes A
 7
            danglingVertexRanks\langle\neg outdegrees\rangle = pr(:)
 8
            totalDanglingRank = [\bigoplus_i \mathbf{danglingVertexRanks}(i)(\otimes)] \frac{\alpha}{n}
 9
            \mathbf{pr}(:) = \frac{1-\alpha}{n} \oplus totalDanglingRank
10
            pr\langle importance \rangle = pr \oplus importance
11
```

Algorithm 6: Algebraic Bellman-Ford for SSSP.

```
1 Function SSSP

2 d(s) = 0

3 for k = 1 to n - 1 do

4 dtmp = d min.plus A

5 if dtmp = d then

6 break

7 d \leftrightarrow dtmp
```

Algorithm 7: Delta-stepping SSSP.

```
Data:
```

```
\mathbf{A}, \mathbf{A_H}, \mathbf{A_L} \in \mathbb{Q}^{|V| \times |V|}
             s, i \in \mathbb{N}
             \Delta\in\mathbb{Q}
             \mathbf{t}, \mathbf{t_{Req}} \in \mathbb{Q}^{|V|}
             \mathbf{t_{B_i}}, \mathbf{e} \in \mathbb{N}^{|V|}
  1 Function DeltaStepping
                \mathbf{A_L} = select(0 < \mathbf{A} \le \Delta)
  2
                \mathbf{A_H} = select(\Delta < \mathbf{A})
  3
                \mathbf{t}(:) = \infty
  4
                \mathbf{t}(s) = 0
  5
                while nvals(select(i\Delta \leq \mathbf{t})) \neq 0 do
  6
                          \mathbf{t}_{\mathbf{B}_i} = select(i\Delta \le \mathbf{t} < (i+1)\Delta)
  8
                          while \mathbf{t_{B_i}} \neq 0 \ \mathbf{do}
  9
                                  \mathbf{t_{Req}} = \mathbf{A}_{\mathbf{L}}^{\top} \oplus . \otimes (\mathbf{t} \otimes \mathbf{t_{B_i}})
10
                                   \mathbf{e} = select(\mathbf{0} < \mathbf{e} \oplus \mathbf{t}_{\mathbf{B_i}})
11
                                  \mathbf{t}_{\mathbf{B_i}} = select(i\Delta \leq \mathbf{t}_{\mathbf{Req}} < (i+1)\Delta) \otimes (\mathbf{t}_{\mathbf{Req}} \min_{\mathcal{D}} \mathbf{t})
12
                          \mathbf{t_{Req}} = \mathbf{A}_{\mathbf{H}}^{\top} \oplus . \otimes (\mathbf{t} \otimes \mathbf{e})
13
                         \mathbf{t} = \mathbf{t} \, \mathsf{min} \, \mathbf{t}_{\mathbf{Req}}
14
15
                          i = i + 1
```

Algorithm 8: All-pairs shortest path (Floyd-Warshall algorithm).

```
1 Function FloydWarshall

2 D \leftrightarrow A

3 for k = 1 to n do

4 D = D min[D(:,k) min.plus(D(k,:)]
```

Algorithm 9: FastSV algorithm.

```
1 Function FastSV
 \mathbf{2}
       n = nrows(\mathbf{A})
       gf = f
 3
       dup = gf
 4
       mngf = gf
 5
       \{I, X\} \leftarrow \mathbf{f}
 6
       repeat
 7
           // Step 1: Stochastic hooking
 8
           mngf = mngf min A
 9
           mngf = mngf second.min gf
10
           f(X) = f \min mngf
11
           // Step 2: Aggressive hooking
12
           f = f \min mngf
13
14
           // Step 3: Shortcutting
           f = f \min gf
15
           // Step 4: Calculate grandparents
16
           \{I,X\} \leftarrow \mathbf{f}
17
           \mathbf{gf} = \mathbf{f}(X)
18
           // Step 5: Check termination
19
           diff = dup \neq gf
20
           sum = [\bigoplus_i \mathbf{diff}(i)]
21
           dup = gf
\mathbf{22}
       until sum == 0
23
```

Algorithm 10: Triangle count (Cohen's algorithm).

```
1 Function TriangleCount
2 L = tril(\mathbf{A})
3 U = triu(\mathbf{A})
4 \mathbf{B} = \mathbf{L} \oplus \otimes \mathbf{U}
5 \mathbf{C} = \mathbf{B} \otimes \mathbf{A}
6 t = [\oplus_{ij} \mathbf{C}(i,j)]/2
```

Algorithm 11: Triangle count (Sandia).

```
1 Function TriangleCount
2 L = tril(\mathbf{A})
3 \mathbf{C}\langle \mathbf{L} \rangle = \mathbf{L} \oplus . \otimes \mathbf{L}
4 t = [\oplus_{ij} \mathbf{C}(i,j)]
```

Algorithm 12: Triangle count (FLAME).

Algorithm 13: Local clustering coefficient.

```
Function PageRank2Tri\langle A \rangle = A \oplus . \otimes A// compute triangle count matrix3tri = [\oplus_j Tri(:,j)]// reduce to triangle count vector4deg = [\oplus_j A(:,j)]// reduce to vertex degree vector5wed = perm2(deg)// apply perm2(x) = x \cdot (x-1) to get wedge count vector6lcc = tri \oslash wed// LCC vector
```

Algorithm 14: k-truss algorithm.

```
1 Function KTruss
        \mathbf{C} \leftrightarrow \mathbf{A}
\mathbf{2}
3
         nonzeros \leftarrow nvals(C)
        for i = 1 to n - 1 do
4
              \mathbf{C}\langle\mathbf{C}\rangle = \mathbf{C} \oplus . land \mathbf{C}
5
              \mathbf{C} = select(\mathbf{C} \ge k - 2)
6
              if nonzeros == nvals(C) then
7
                break
8
9
              nonzeros \leftarrow nvals(C)
```

Algorithm 15: Louvain algorithm (WIP).

```
1 Function Louvain
            \mathbf{G} \oplus = \mathbf{G}^{\mathsf{T}}
  \mathbf{2}
            \mathbf{k} = [\oplus_j \mathbf{A}(:,j)]
  3
            m = \frac{1}{2} [\bigoplus_i \mathbf{k}(i)]
  4
            S \leftrightarrow \overline{I}
  5
  6
             vertices\_changed \leftrightarrow nvals(\mathbf{k})
  7
             while vertices\_changed > 0 do
  8
                   for j \in range(|V|) do
  9
10
                          \mathbf{v} = \mathbf{G}(j,:)
                          \mathbf{t_q} = \mathbf{v} any.pair \mathbf{S}
11
                          \mathbf{sr} = \mathbf{S}(j,:)
12
                          S(j,:) = \text{empty}
13
14
                          q \leftrightarrow k
15
                          \mathbf{q}\langle\mathbf{k}\rangle\otimes=-\mathbf{k}(j)/m
16
                          q \oplus = v
17
18
                          \mathbf{q_1}\langle\mathbf{t_q}\rangle = \mathbf{q} \oplus . \otimes \mathbf{S}
19
                          \mathbf{t} = (\mathbf{q_1} == [\max_i \mathbf{q_1}(i)])
20
                          while nvals(t) \neq 1 do
21
                                 \mathbf{p} = random() \otimes \mathbf{t}
22
                              \mathbf{t} = (\mathbf{p} == [\mathsf{max}_i \ \mathbf{p}(i)])
23
                          \mathbf{S}(j,:) = \mathbf{t}
\mathbf{24}
25
                          if nvals(\mathbf{sr} \otimes \mathbf{t}) == 0 then
26
                            vertices\_changed = nvals(\mathbf{k})
27
                          vertices\_changed = vertices\_changed - 1
28
```

Algorithm 16: Community detection using label propagation (for undirected graphs).

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