# LAGraph Algorithms

# LAGraph Working Group

February 16, 2022

#### Abstract

Theoretical documentation for LAGraph.

## 1 Notation

Table 1 contains the notation of GraphBLAS operations

Additionally, we use  $\mathbf{D} = diag(J, n)$  to construct a diagonal matrix  $\mathbf{D} \leftrightarrow \{J, J, [1, 1, \dots, 1]\}$ . The elements of the matrix are  $\mathbf{D}(j, j) = 1$  for  $j \in J$ .

Initializing scalars, vectors, and matrices (GraphBLAS methods):

- let:  $s \in \mathbb{Q}_{64}$
- let:  $\mathbf{u} \in \mathbb{Q}_{32}^n$
- let:  $\mathbf{A} \in \mathbb{N}_{16}^{m \times n}$
- let:  $\mathbf{A} \in \mathbb{Z}_{64}^{k \times m}$

# 2 Algorithms

LAGraph [12] implements graph algorithms using the GraphBLAS C API [13]. An incomplete list of GraphBLAS algorithms:

- MSBFS [8], bidirectional BFS [8], pushpull BFS [19]
- DFS [16]
- weakly connected components [21]
- SCC (LAGraph)
- SSSP, delta-stepping [17]
- triangle count [1, 5], triangle enumeration [1], item local clustering coefficient [4]
- *k*-truss [5]
- betweenness centrality [12]
- closeness centrality [8]
- DNN algorithm [10, 7]
- PageRank variants (at least 2) [4], IISWC paper, ...
- Louvain [11]
- property graphs: incremental TTC case [9], SIGMOD 2014 Contest [8] Roi Lipman's talk<sup>1</sup>
- CFPQs based on a string of GRADES/ADBIS/other papers [2, 3, 14, 18, 15]
- Implementations: GBTL<sup>2</sup>, SuiteSparse:GraphBLAS [6], GraphBLAST [20]

<sup>1</sup>http://wiki.ldbcouncil.org/pages/viewpage.action?pageId=106233859&preview=/106233859/111706128/LDBC-July-2019.pdf

<sup>&</sup>lt;sup>2</sup>https://github.com/cmu-sei/gbtl

op./method	name	notation
mxm	matrix-matrix multiplication	$\mathbf{C}\langle\mathbf{M}\rangle \odot = \mathbf{A} \oplus . \otimes \mathbf{B}$
vxm	vector-matrix multiplication	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}\oplus.\otimes\mathbf{A}$
mxv	matrix-vector multiplication	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}\oplus.\otimes\mathbf{u}$
eWiseAdd	element-wise addition	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}\oplus\mathbf{B}$
	set union of patterns	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}\oplus\mathbf{v}$
eWiseMult	element-wise multiplication	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}\otimes\mathbf{B}$
	set intersection of patterns	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}\otimes\mathbf{v}$
extract	extract submatrix	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}(I,J)$
	extract column vector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}(:,j)$
	extract row vector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{A}(i,:)$
	extract subvector	$\mathbf{w}\langle\mathbf{m}\rangle\odot=\mathbf{u}(I)$
assign	assign matrix to submatrix with mask for ${\Bbb C}$	$\mathbf{C}\langle\mathbf{M}\rangle(I,J)\odot=\mathbf{A}$
	assign scalar to submatrix with mask for C	$\mathbf{C}\langle\mathbf{M}\rangle(I,J)\odot=s$
	assign vector to subvector with mask for w	$\mathbf{w}\langle\mathbf{m}\rangle(I)\odot=\mathbf{u}$
	assign scalar to subvector with mask for w	$\mathbf{w}\langle\mathbf{m}\rangle(I)\odot=s$
subassign (GxB)	assign matrix to submatrix with submask for $\mathbb{C}(I, J)$	
	assign scalar to submatrix with submask for $C(I, J)$	$\mathbf{C}(I,J)\langle\mathbf{M}\rangle\odot=s$
	assign vector to subvector with submask for $\mathbf{w}(I)$	$\mathbf{w}(I)\langle \mathbf{m} \rangle \odot = \mathbf{u}$
	assign scalar to subvector with submask for $\mathbf{w}(I)$	$\mathbf{w}(I)\langle\mathbf{m}\rangle \odot = s$
apply	apply unary operator	$\mathbf{C}\langle\mathbf{M}\rangle\odot=f(\mathbf{A})$
		$\mathbf{w}\langle\mathbf{m}\rangle\odot=f(\mathbf{u})$
select (GxB)	apply select operator	$ \mathbf{C}\langle\mathbf{M}\rangle\bigcirc=select(\mathbf{A}, f(k))  \mathbf{C}\langle\mathbf{M}\rangle\bigcirc=select(low \leq \mathbf{A} \leq up)  \mathbf{w}\langle\mathbf{m}\rangle\bigcirc=select(\mathbf{u}, f(k))  \mathbf{w}\langle\mathbf{m}\rangle\bigcirc=select(low \leq \mathbf{u} \leq up) $
reduce	reduce matrix to column vector	$\mathbf{w}\langle\mathbf{m}\rangle\bigcirc=[\oplus_{j}\mathbf{A}(:,j)]$
	reduce matrix to scalar	$s \odot = [\bigoplus_{i \neq j} \mathbf{A}(i, j)]$
	reduce vector to scalar	$s \odot = [\oplus_i \mathbf{u}(i)]$
transpose	transpose	$\mathbf{C}\langle\mathbf{M}\rangle\odot=\mathbf{A}^{ op}$
kronecker	Kronecker multiplication	$\mathbf{C}\langle\mathbf{M}\rangle \odot = kron(\mathbf{A}, \mathbf{B})$
new	new matrix	let: $\mathbf{A} \in TYPE^{n \times m}_{PRECISION}$
	new vector	let: $\mathbf{u} \in TYPE^n_{PRECISION}$
build	build matrix from index/value arrays	$\mathbf{C} \leftrightarrow \{I, J, X\}$
	build vector from index/value arrays	$\mathbf{w} \leftrightarrow \{I, X\}$
extractTuples	extract index/value arrays	$ \begin{cases} I, J, X \\  & \\  & \\ I, X \\  & \\  & \\  & \\  & \\  & \\  & \\  & \\ $
dup	duplicate matrix	C↔ A
	duplicate vector	w ← u
extractElement	extract scalar element	$s = \mathbf{A}(i, j)$ $s = \mathbf{u}(i)$
setElement	set element	$\mathbf{C}(i,j) = s$ $\mathbf{w}(i) = s$

Table 1: GraphBLAS operations and methods based on [6]. Notation: Matrices and vectors are typeset in bold, starting with uppercase ( $\mathbf{A}$ ) and lowercase ( $\mathbf{u}$ ) letters, respectively. Scalars including indices are lowercase italic (s, i, j) while arrays are uppercase italic (s, s, s) while arrays are uppercase italic (s, s) and s are the addition and multiplication operators forming a semiring and default to conventional arithmetic + and × operators. s is the apply operator. Masks (s) and (s) are used to selectively write to the result matrix/vector. The complements of masks (s), (s) can be selected with the negation symbol, denoted with (s), (s

## Algorithm 1: Breadth-first search.

```
1 Function BFS
2 | frontier(s) = TRUE
3 | for level = 1 to n - 1 do
4 | seen\langle frontier \rangle = level
5 | frontier(\langle \neg seen \rangle \rangle = frontier any.pair A
```

## Algorithm 2: Breadth-first search (push/pull).

```
_{1} Function BFS
       frontier(s) = TRUE
\mathbf{2}
       for level = 1 to n - 1 do
3
           seen\langle frontier \rangle = level
4
           push = use some heuristics to determine whether to push/pull
5
           if push then
6
            frontier \langle \langle \neg seen \rangle \rangle = frontier any.pair A
7
           else
8
            frontier \langle \neg seen \rangle = A any pair frontier
```

## Algorithm 3: Multi-source breadth-first search.

```
Data: ...

Result: ...

1 Function MSBFS

2 Frontier \leftrightarrow \operatorname{diag}(S, n)

3 for level = 1 to n - 1 do

4 Seen\langle Frontier \rangle = level

5 Frontier\langle \neg Seen \rangle = Frontier any.pair A
```

#### **Algorithm 4:** Betweenness centrality.

```
1 Function MSBFS
       // The NumSp structure holds the number of shortest paths for each node and
           starting vertex discovered so far.
       // Initialized to source vertices.
 3
       NumSp \leftrightarrow {s, [1, 1, ..., 1]}
 4
       // The Frontier holds the number of shortest paths for each node and starting vertex
 5
           discovered so far.
       // Initialized to source vertices.
 6
       Frontier\langle NumSp \rangle = A(s,:)
 7
       d = 0
 8
       // The Sigmas matrices store frontier information for each level of the BFS phase.
 9
       // BFS phase (forward sweep)
10
       do
11
           // \mathbf{Sigmas}[d](:,s) = d^{\mathrm{th}} level frontier from source vertex s
12
           let: Sigmas [d] \in \mathbb{B}^{n \times nsver}
13
           Sigmas[d](:,:) = Frontier
                                                                                   // Convert matrix to Boolean
14
           NumSp = NumSp \oplus Frontier
                                                                                       // Accumulate path counts
15
           Frontier \langle \langle NumSp \rangle \rangle = A^{\top} \oplus . \otimes Frontier
                                                                                                // Update frontier
16
       while nvals(Frontier) > 0
17
       let: NumSpInv \in \mathbb{Q}_{32}^{n \times nsver}
18
       \mathbf{NumSpInv} = 1.0 \oslash \mathbf{NumSp}
19
       let: \mathbf{BCU} \in \mathbb{Q}_{32}^{n \times nsver}
20
       BCU(:) = 1.0
                                                     // Make BCU dense, initialize all elements to 1.0
21
       let: \mathbf{W} \in \mathbb{Q}_{32}^{n \times nsver}
22
       // Tally phase (backward sweep)
23
       for i = d - 1 downto 0 do
24
           W(\langle Sigmas[i] \rangle) = NumSpInv \oslash BCU
25
           \mathbf{W}\langle\langle \mathbf{Sigmas}[i-1]\rangle\rangle = \mathbf{A} \oplus . \otimes \mathbf{W} // Add contributions by successors and mask with that
26
            BFS level's frontier.
          BCU \oplus = W \otimes NumSp
27
       // Row reduce \overline{BCU} and subtract nsver from every entry to account for 1 extra value
28
           per BCU row element
29
       delta = [\bigoplus_{i} \mathbf{BCU}(:,j)]
       delta \ominus = nsver
30
```

#### **Algorithm 5:** PageRank (used in Graphalytics).

```
Data: \alpha constant (damping factor)
   Result: ...
 1 Function PageRank
       pr(:) = 1/n
       outdegrees = [\oplus_j \mathbf{A}(:,j)]
 3
       for k = 1 to numIterations do
 4
            importance = pr \oslash outdegrees
 5
            importance = times(importance, \alpha)
                                                                             // apply the times(x,s) = x \cdot s operator
 6
            importance = importance \oplus . \otimes A
 7
            danglingVertexRanks\langle\neg outdegrees\rangle = pr(:)
 8
            totalDanglingRank = [\bigoplus_i \mathbf{danglingVertexRanks}(i)(\otimes)] \frac{\alpha}{n}
 9
            \mathbf{pr}(:) = \frac{1-\alpha}{n} \oplus totalDanglingRank
10
            pr\langle importance \rangle = pr \oplus importance
11
```

## Algorithm 6: Algebraic Bellman-Ford for SSSP.

```
1 Function SSSP

2 | \mathbf{d}(s) = 0

3 | \mathbf{for} \ k = 1 \ \mathbf{to} \ n - 1 \ \mathbf{do}

4 | \mathbf{dtmp} = \mathbf{d} \ \mathsf{min.plus} \ \mathbf{A}

5 | \mathbf{if} \ \mathbf{dtmp} = \mathbf{d} \ \mathsf{then}

6 | \mathbf{break}

7 | \mathbf{d} \leftrightarrow \mathbf{dtmp}
```

# **Algorithm 7:** Delta-stepping SSSP.

```
Data:
```

```
\mathbf{A}, \mathbf{A_H}, \mathbf{A_L} \in \mathbb{Q}^{|V| \times |V|}
             s, i \in \mathbb{N}
             \Delta\in\mathbb{Q}
             \mathbf{t}, \mathbf{t_{Req}} \in \mathbb{Q}^{|V|}
             \mathbf{t_{B_i}}, \mathbf{e} \in \mathbb{N}^{|V|}
  1 Function DeltaStepping
                \mathbf{A_L} = select(0 < \mathbf{A} \le \Delta)
  2
                \mathbf{A_H} = select(\Delta < \mathbf{A})
  3
                \mathbf{t}(:) = \infty
  4
                \mathbf{t}(s) = 0
  5
                while nvals(select(i\Delta \leq \mathbf{t})) \neq 0 do
  6
                         \mathbf{t}_{\mathbf{B}_i} = select(i\Delta \le \mathbf{t} < (i+1)\Delta)
  8
                         while \mathbf{t_{B_i}} \neq 0 \ \mathbf{do}
  9
                                 \mathbf{t_{Req}} = \mathbf{A}_{\mathbf{L}}^{\top} \oplus . \otimes (\mathbf{t} \otimes \mathbf{t_{B_i}})
10
                                 \mathbf{e} = select(\mathbf{0} < \mathbf{e} \oplus \mathbf{t}_{\mathbf{B_i}})
11
                                 \mathbf{t_{B_i}} = select(i\Delta \leq \mathbf{t_{Req}} < (i+1)\Delta) \otimes (\mathbf{t_{Req}} \min_{\Delta} \mathbf{t})
12
                         \mathbf{t_{Req}} = \mathbf{A}_{\mathbf{H}}^{\top} \oplus . \otimes (\mathbf{t} \otimes \mathbf{e})
13
                        \mathbf{t} = \mathbf{t} \, \mathsf{min} \, \mathbf{t}_{\mathbf{Req}}
14
15
                         i = i + 1
```

## Algorithm 8: All-pairs shortest path (Floyd-Warshall algorithm).

```
1 Function FloydWarshall

2 D \leftrightarrow A

3 for k = 1 to n do

4 D = D \min[D(:, k) \min.plus(D(k, :)]
```

#### Algorithm 9: FastSV algorithm.

```
1 Function FastSV
 \mathbf{2}
       n = nrows(\mathbf{A})
       gf = f
 3
       dup = gf
 4
       mngf = gf
 5
       \{I, X\} \leftarrow \mathbf{f}
 6
       repeat
 7
           // Step 1: Stochastic hooking
 8
           mngf = mngf min A
 9
           mngf = mngf second.min gf
10
           f(X) = f \min mngf
11
           // Step 2: Aggressive hooking
12
           f = f \min mngf
13
14
           // Step 3: Shortcutting
           f = f \min gf
15
           // Step 4: Calculate grandparents
16
           \{I,X\} \leftarrow \mathbf{f}
17
           \mathbf{gf} = \mathbf{f}(X)
18
           // Step 5: Check termination
19
           diff = dup \neq gf
20
           sum = [\bigoplus_i \mathbf{diff}(i)]
21
           dup = gf
\mathbf{22}
       until sum == 0
23
```

## Algorithm 10: Triangle count (Cohen's algorithm).

## Algorithm 11: Triangle count (Sandia).

```
1 Function TriangleCount
2  L = tril(A)
3  C\langle L \rangle = L \oplus . \otimes L
4  t = [\oplus_{ij} C(i,j)]
```

## Algorithm 12: Triangle count (FLAME).

```
1 Function TriangleCountFlame
2 | for i = 2 to n - 1 do
3 | A_{20} = A(i + 1: n, 0: i - 1)
4 | a_{10} = A(0: i - 1, i)
5 | a_{12} = A(i, i + 1: n)
6 | t \oplus = a_{10} \oplus . \otimes A_{20} \oplus . \otimes a_{12}
```

# Algorithm 13: Local clustering coefficient.

```
Function PageRank2Tri\langle A \rangle = A \oplus . \otimes A// compute triangle count matrix3tri = [\bigoplus_j Tri(:,j)]// reduce to triangle count vector4deg = [\bigoplus_j A(:,j)]// reduce to vertex degree vector5wed = perm2(deg)// apply perm2(x) = x \cdot (x-1) to get wedge count vector6lcc = tri \oslash wed// LCC vector
```

#### **Algorithm 14:** k-truss algorithm.

```
1 Function KTruss
        \mathbf{C} \leftrightarrow \mathbf{A}
\mathbf{2}
3
         nonzeros \leftarrow nvals(C)
        for i = 1 to n - 1 do
4
              \mathbf{C}\langle\mathbf{C}\rangle = \mathbf{C} \oplus . land \mathbf{C}
5
              \mathbf{C} = select(\mathbf{C} \ge k - 2)
6
              if nonzeros == nvals(C) then
7
                break
8
9
              nonzeros \leftarrow nvals(C)
```

#### Algorithm 15: Louvain algorithm (WIP).

```
1 Function Louvain
            \mathbf{G} \oplus = \mathbf{G}^{\mathsf{T}}
 \mathbf{2}
            \mathbf{k} = [\oplus_j \mathbf{A}(:,j)]
 3
            m = \frac{1}{2} [\bigoplus_i \mathbf{k}(i)]
 4
            S \leftrightarrow \overline{I}
 5
 6
            vertices\_changed \leftrightarrow nvals(\mathbf{k})
 7
            while vertices\_changed > 0 do
 8
                   for j \in range(|V|) do
 9
10
                         \mathbf{v} = \mathbf{G}(j,:)
                         \mathbf{t_q} = \mathbf{v} any.pair \mathbf{S}
11
                          \mathbf{sr} = \mathbf{S}(j,:)
12
                         S(j,:) = \text{empty}
13
14
                          q \leftrightarrow k
15
                          \mathbf{q}\langle\mathbf{k}\rangle\otimes=-\mathbf{k}(j)/m
16
                          q \oplus = v
17
18
                          \mathbf{q_1}\langle\mathbf{t_q}\rangle=\mathbf{q}\oplus.\otimes\mathbf{S}
19
                          \mathbf{t} = (\mathbf{q_1} == [\max_i \mathbf{q_1}(i)])
20
                          while nvals(t) \neq 1 do
21
                                \mathbf{p} = random() \otimes \mathbf{t}
22
                             \mathbf{t} = (\mathbf{p} == [\mathsf{max}_i \ \mathbf{p}(i)])
23
                          \mathbf{S}(j,:) = \mathbf{t}
\mathbf{24}
25
                         if nvals(\mathbf{sr} \otimes \mathbf{t}) == 0 then
26
                           vertices\_changed = nvals(\mathbf{k})
27
                          vertices\_changed = vertices\_changed - 1
28
```

#### Algorithm 16: Community detection using label propagation (for undirected graphs).

# References

- [1] A. Azad, A. Buluç, and J. R. Gilbert, "Parallel triangle counting and enumeration using matrix algebra," in *GABB at IPDPS*. IEEE Computer Society, 2015, pp. 804–811. [Online]. Available: https://doi.org/10.1109/IPDPSW.2015.75
- [2] R. Azimov and S. Grigorev, "Context-free path querying by matrix multiplication," in *GRADES-NDA at SIGMOD*. ACM, 2018, pp. 5:1–5:10. [Online]. Available: https://doi.org/10.1145/3210259.3210264
- [3] —, "Path querying with conjunctive grammars by matrix multiplication," *Programming and Computer Software*, vol. 45, no. 7, pp. 357–364, 2019. [Online]. Available: https://doi.org/10.1134/S0361768819070041
- [4] M. Aznaveh, J. Chen, T. A. Davis, B. Hegyi, S. P. Kolodziej, T. G. Mattson, and G. Szárnyas, "Parallel GraphBLAS with OpenMP," in *CSC*. SIAM, 2020, pp. 138–148. [Online]. Available: https://doi.org/10.1137/1.9781611976229.14
- [5] T. A. Davis, "Graph algorithms via SuiteSparse:GraphBLAS: Triangle counting and K-truss," in *HPEC*. IEEE, 2018. [Online]. Available: https://doi.org/10.1109/HPEC.2018.8547538
- [6] —, "Algorithm 1000: SuiteSparse:GraphBLAS: Graph algorithms in the language of sparse linear algebra," *ACM Trans. Math. Softw.*, 2019. [Online]. Available: https://doi.org/10.1145/3322125
- [7] T. A. Davis, M. Aznaveh, and S. P. Kolodziej, "Write quick, run fast: Sparse deep neural network in 20 minutes of development time via SuiteSparse:GraphBLAS," in *HPEC*. IEEE, 2019, pp. 1–6. [Online]. Available: https://doi.org/10.1109/HPEC.2019.8916550
- [8] M. Elekes, A. Nagy, D. Sándor, J. B. Antal, T. A. Davis, and G. Szárnyas, "A GraphBLAS solution to the SIGMOD 2014 programming contest using multi-source BFS," in *HPEC*, 2020.
- [9] M. Elekes and G. Szárnyas, "An incremental GraphBLAS solution for the 2018 TTC Social Media case study," in *GrAPL at IPDPS*. IEEE, 2020, pp. 203–206. [Online]. Available: https://doi.org/10.1109/IPDPSW50202.2020.00045
- [10] J. Kepner, M. Kumar, J. E. Moreira, P. Pattnaik, M. J. Serrano, and H. M. Tufo, "Enabling massive deep neural networks with the GraphBLAS," in *HPEC*. IEEE, 2017, pp. 1–10. [Online]. Available: https://doi.org/10.1109/HPEC.2017.8091098
- [11] T. M. Low, D. G. Spampinato, S. McMillan, and M. Pelletier, "Linear algebraic louvain method in python," in *GrAPL at IPDPS*. IEEE, 2020, pp. 223–226. [Online]. Available: https://doi.org/10.1109/IPDPSW50202.2020.00050
- [12] T. Mattson, T. A. Davis, M. Kumar, A. Buluç, S. McMillan, J. E. Moreira, and C. Yang, "LAGraph: A community effort to collect graph algorithms built on top of the GraphBLAS," in *GrAPL at IPDPS*, 2019. [Online]. Available: https://doi.org/10.1109/IPDPSW.2019.00053
- [13] T. G. Mattson, C. Yang, S. McMillan, A. Buluç, and J. E. Moreira, "GraphBLAS C API: Ideas for future versions of the specification," in *HPEC*. IEEE, 2017. [Online]. Available: https://doi.org/10.1109/HPEC.2017.8091095
- [14] N. Mishin, I. Sokolov, E. Spirin, V. Kutuev, E. Nemchinov, S. Gorbatyuk, and S. Grigorev, "Evaluation of the context-free path querying algorithm based on matrix multiplication," in *GRADES-NDA at SIGMOD*. ACM, 2019, pp. 12:1–12:5. [Online]. Available: https://doi.org/10.1145/3327964.3328503
- [15] E. Orachev, I. Epelbaum, R. Azimov, and S. Grigorev, "Context-free path querying by Kronecker product," in *ADBIS*, ser. Lecture Notes in Computer Science, vol. 12245. Springer, 2020, pp. 49–59. [Online]. Available: https://doi.org/10.1007/978-3-030-54832-2\_6
- [16] D. G. Spampinato, U. Sridhar, and T. M. Low, "Linear algebraic depth-first search," in ARRAY at PLDI. ACM, 2019, pp. 93–104. [Online]. Available: https://doi.org/10.1145/3315454.3329962
- [17] U. Sridhar, M. Blanco, R. Mayuranath, D. G. Spampinato, T. M. Low, and S. McMillan, "Delta-stepping SSSP: From vertices and edges to graphblas implementations," in *GrAPL at IPDPS*. IEEE, 2019, pp. 241–250. [Online]. Available: https://doi.org/10.1109/IPDPSW.2019.00047
- [18] A. Terekhov, A. Khoroshev, R. Azimov, and S. Grigorev, "Context-free path querying with single-path semantics by matrix multiplication," in *GRADES-NDA at SIGMOD*. ACM, 2020, pp. 5:1–5:12. [Online]. Available: https://doi.org/10.1145/3398682.3399163

- [19] C. Yang, A. Buluç, and J. D. Owens, "Implementing push-pull efficiently in GraphBLAS," in *ICPP*. ACM, 2018, pp. 89:1–89:11. [Online]. Available: https://doi.org/10.1145/3225058.3225122
- [20] —, "GraphBLAST: A high-performance linear algebra-based graph framework on the GPU," *CoRR*, vol. abs/1908.01407, 2019, http://arxiv.org/abs/1908.01407. [Online]. Available: http://arxiv.org/abs/1908.01407
- [21] Y. Zhang, A. Azad, and Z. Hu, "FastSV: A distributed-memory connected component algorithm with fast convergence," in *PPSC*. SIAM, 2020, pp. 46–57. [Online]. Available: https://doi.org/10.1137/1. 9781611976137.5