LAGraph Algorithms

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Abstract

Theoretical documentation for LAGraph.

1 Notation

Table 1 contains the notation of GraphBLAS operations

Additionally, we use D = diag(J, n) to construct a diagonal matrix $D \leftarrow \{J, J, [1, 1, ..., 1]\}$. The elements of the matrix are D(j, j) = 1 for $j \in J$.

Initializing scalars, vectors, and matrices (GraphBLAS methods):

- s = fp64()
- u = fp32(n)
- A = uint16(m, n)
- A = int64(k, m)

2 Algorithms

LAGraph [12] implements graph algorithms using the GraphBLAS C API [13]. An incomplete list of GraphBLAS algorithms:

- MSBFS [8], bidirectional BFS [8], pushpull BFS [19]
- DFS [16]
- weakly connected components [21]
- SCC (LAGraph)
- SSSP, delta-stepping [17]
- triangle count [1, 5], triangle enumeration [1], item local clustering coefficient [4]
- *k*-truss [5]
- betweenness centrality [12]
- closeness centrality [8]
- DNN algorithm [10, 7]
- PageRank variants (at least 2) [4], IISWC paper, ...
- Louvain [11]
- property graphs: incremental TTC case [9], SIGMOD 2014 Contest [8] Roi Lipman's talk¹
- CFPQs based on a string of GRADES/ADBIS/other papers [2, 3, 14, 18, 15]
- Implementations: GBTL², SuiteSparse:GraphBLAS [6], GraphBLAST [20]

¹http://wiki.ldbcouncil.org/pages/viewpage.action?pageId=106233859&preview=/106233859/111706128/LDBC-July-2019.pdf

²https://github.com/cmu-sei/gbtl

op./method	name	notation
mxm	matrix-matrix multiplication	$C < M > + = A + . \times B$
vxm mxv	vector-matrix multiplication matrix-vector multiplication	$ exttt{w} < exttt{m}>+ = exttt{u} + . imes exttt{A} exttt{w} < exttt{m}>+ = exttt{A} + . imes exttt{u}$
eWiseAdd	element-wise addition	C < M > + = A + B
	set union of patterns	w < m > + = u + v
eWiseMult	element-wise multiplication set intersection of patterns	$C < M > + = A \times B$ $w < m > + = u \times v$
extract	extract submatrix extract column vector extract row vector extract subvector	$ \begin{array}{l} {\tt C} < {\tt M} > + = {\tt A}({\tt I},{\tt J}) \\ {\tt w} < {\tt m} > + = {\tt A}({\tt i},{\tt j}) \\ {\tt w} < {\tt m} > + = {\tt A}({\tt i},{\tt :}) \\ {\tt w} < {\tt m} > + = {\tt u}({\tt I}) \\ \end{array} $
assign	assign matrix to submatrix with mask for C assign scalar to submatrix with mask for C assign vector to subvector with mask for C assign scalar to subvector with mask for C	$ \begin{array}{l} {\tt C} < {\tt M} > ({\tt I}, {\tt J}) + = {\tt A} \\ {\tt C} < {\tt M} > ({\tt I}, {\tt J}) + = {\tt s} \\ {\tt w} < {\tt m} > ({\tt I}) + = {\tt u} \\ {\tt w} < {\tt m} > ({\tt I}) + = {\tt s} \end{array} $
subassign (GxB)	assign matrix to submatrix with submask for $C(\mathtt{I},\mathtt{J})$ assign scalar to submatrix with submask for $C(\mathtt{I},\mathtt{J})$ assign vector to subvector with submask for $\mathtt{w}(\mathtt{I})$ assign scalar to subvector with submask for $\mathtt{w}(\mathtt{I})$	$\begin{array}{l} {\tt C(I,J) < M > + = A} \\ {\tt C(I,J) < M > + = s} \\ {\tt w(I) < m > + = u} \\ {\tt w(I) < m > + = s} \end{array}$
apply	apply unary operator	$ \begin{array}{l} \mathtt{C} < \mathtt{M} > + = \mathbf{f}(\mathtt{A}) \\ \mathtt{w} < \mathtt{m} > + = \mathbf{f}(\mathtt{u}) \end{array} $
select (GxB)	apply select operator	$\begin{split} & \texttt{C} < \texttt{M} > + = select(\texttt{A}, \texttt{f}(\texttt{k})) \\ & \texttt{C} < \texttt{M} > + = select(\texttt{low} \leq \texttt{A} \leq \texttt{up}) \\ & \texttt{w} < \texttt{m} > + = select(\texttt{u}, \texttt{f}(\texttt{k})) \\ & \texttt{w} < \texttt{m} > + = select(\texttt{low} \leq \texttt{u} \leq \texttt{up}) \end{split}$
reduce	reduce matrix to column vector reduce matrix to scalar reduce vector to scalar	$egin{aligned} & {\tt w} < {\tt m} > + = [+ {\tt A}] \ & {\tt s} + = [+ {\tt A}] \ & {\tt s} + = [+ {\tt u}] \end{aligned}$
transpose	transpose	C < M > + = A'
kronecker	Kronecker multiplication	$\mathtt{C} < \mathtt{M} > + = kron(\mathtt{A},\mathtt{B})$
new	new matrix new vector	$\begin{split} \textbf{A} &= TYPEPRECISION(\textbf{n}, \textbf{m}) \\ \textbf{u} &= TYPEPRECISION(\textbf{n}) \end{split}$
build	matrix from tuples vector from tuples	$C \leftarrow \{I, J, X\}$ $w \leftarrow \{I, X\}$
extractTuples	extract index/value arrays	
dup	duplicate matrix duplicate vector	C<- A w<- u
extractElement	extract scalar element	$egin{aligned} \mathbf{s} &= \mathtt{A}(\mathtt{i},\mathtt{j}) \\ \mathbf{s} &= \mathtt{u}(\mathtt{i}) \end{aligned}$
setElement	set element	$egin{aligned} \mathtt{C}(\mathtt{i},\mathtt{j}) &= \mathtt{s} \ \mathtt{w}(\mathtt{i}) &= \mathtt{s} \end{aligned}$

Table 1: GraphBLAS operations and methods based on [6]. Notation: Matrices and vectors are typeset in bold, starting with uppercase (A) and lowercase (u) letters, respectively. Scalars including indices are lowercase italic (s, i, j) while arrays are uppercase italic (X, I, J). + and × are the addition and multiplication operators forming a semiring and default to conventional arithmetic + and × operators. \odot is the apply operator. Masks <M> and <m> are used to selectively write to the result matrix/vector. The complements of masks <M>, <m> can be selected with the negation symbol, denoted with <!M>, <!m>, respectively. Masks with "replace" semantics (annihilating all elements outside the mask) are denoted with <<M>>>, <<!M>>>, <<m>>>, and <<!m>>>, The structure of the mask is denoted with <{M}>, <!m}>, and <!{m}>>.

Algorithm 1: Breadth-first search.

Algorithm 2: Breadth-first search (push/pull).

```
Function BFS
frontier(s) = TRUE
for level = 1 to n - 1 do

seen < frontier >= level
push = use some heuristics to determine whether to push/pull
if push then
frontier << !seen >>= frontier any.pair A

else
frontier << !seen >>= A any.pair frontier
```

Algorithm 3: Multi-source breadth-first search.

```
Data: ...
Result: ...

Function MSBFS

Frontier <- diag(S, n)

for level = 1 to n-1 do

Seen <Frontier >= level

Frontier << !Seen >>= Frontier any.pair A
```

Algorithm 4: Betweenness centrality.

```
1 Function MSBFS
      // The NumSp structure holds the number of shortest paths for each node and starting
         vertex discovered so far.
      // Initialized to source vertices.
3
      NumSp < -\{s, [1, 1, ..., 1]\}
4
      // The Frontier holds the number of shortest paths for each node and starting vertex
5
         discovered so far.
      // Initialized to source vertices.
6
      Frontier < NumSp>= A(s,:)
7
      d = 0
8
      // The Sigmas matrices store frontier information for each level of the BFS phase.
9
      // BFS phase (forward sweep)
10
11
      do
         // Sigmas[d](:,s) = d^{th} level frontier from source vertex s
12
         Sigmas[d] = bool(n, nsver)
13
         Sigmas[d](:,:) = Frontier
                                                                       // Convert matrix to Boolean
14
         NumSp = NumSp + Frontier
                                                                           // Accumulate path counts
15
         Frontier << NumSp>>= A' +. \times Frontier
                                                                                   // Update frontier
16
      while nvals(Frontier) > 0
17
      NumSpInv = fp32(n, nsver)
18
      {\tt NumSpInv} = 1.0\,{\tt DIV}\,{\tt NumSp}
19
      BCU = fp32(n, nsver)
20
      BCU(:) = 1.0
                                               // Make BCU dense, initialize all elements to 1.0
21
      W = fp32(n, nsver)
22
      // Tally phase (backward sweep)
23
      for i = d - 1 downto 0 do
24
         W << Sigmas[i] >>= NumSpInv DIV BCU
25
         \mathbb{W} \ll \operatorname{Sigmas}[i-1] >>= \mathbb{A} + . \times \mathbb{W} // Add contributions by successors and mask with that
26
          BFS level's frontier.
        \mathtt{BCU} += \mathtt{W} 	imes \mathtt{NumSp}
27
      // Row reduce BCU and subtract nsver from every entry to account for 1 extra value
28
         per BCU row element
      delta = [+BCU]
29
      delta MINUS = nsver
30
```

Algorithm 5: PageRank (used in Graphalytics).

```
Data: alpha constant (damping factor)
  Result: ...
1 Function PageRank
      pr(:) = 1/n
      outdegrees = [+_{i} A(:, j)]
3
      for k = 1 to numIterations do
4
         {\tt importance} = {\tt pr\,DIV\,outdegrees}
5
         importance = times(importance, alpha)
                                                             // apply the times(x,s) = x \cdot s operator
6
         importance = importance + . \times A
         danglingVertexRanks < !outdegrees >= pr(:)
8
         totalDanglingRank = [+ danglingVertexRanks(i)](alpha)/(n)
9
         pr(:) = (1 - alpha)/(n) + totalDanglingRank
10
         pr < importance > = pr + importance
11
```

Algorithm 6: Algebraic Bellman-Ford for SSSP.

Algorithm 7: Delta-stepping SSSP.

```
Data:
              \mathtt{A},\mathtt{A}_\mathtt{H},\mathtt{A}_\mathtt{L} \in \mathtt{fp}(|\mathtt{V}|,|\mathtt{V}|)
               \mathtt{s},\mathtt{i} \in \mathtt{uint}()
               \Delta \in \mathtt{fp}()
               \mathtt{t},\mathtt{t}_{\mathtt{Req}}\in\mathtt{fp}(|\mathtt{V}|)
               \mathtt{t}_{\mathtt{B_i}},\mathtt{e} \in \mathtt{uint}(|\mathtt{V}|)
  1 Function DeltaStepping
                  \mathtt{A_L} = select(0 < \mathtt{A} \leq \Delta)
                  A_{H} = select(\Delta < A)
  3
  4
                  t(:) = \infty
                  \mathsf{t}(\mathsf{s}) = 0
  5
                  while nvals(select(i\Delta \leq t)) \neq 0 do
  6
                            \mathtt{t}_{\mathtt{B}_{\mathtt{i}}} = select(\mathtt{i}\Delta \leq \mathtt{t} < (\mathtt{i}+1)\Delta)
  8
                            while t_{B_i} \neq 0 do
  9
                                     \begin{aligned} \mathbf{t}_{\text{Req}} &= \mathbf{A}_{\text{L}}' + . \times (\mathbf{t} \times \mathbf{t}_{\text{B}_{i}}) \\ \mathbf{e} &= select(0 < \mathbf{e} + \mathbf{t}_{\text{B}_{i}}) \end{aligned}
10
11
                                      \mathtt{t_{B_i}} = select(\mathtt{i}\Delta \leq \mathtt{t_{Req}} < (\mathtt{i}+1)\Delta) \times (\mathtt{t_{Req}} \min_{\bot} \mathtt{t})
12
                            \mathtt{t}_{\mathtt{Req}} = \mathtt{A}_{\mathtt{H}} \, {}^{\boldsymbol{\cdot}} + . \times (\mathtt{t} \times \mathtt{e})
13
                            t = t \min t_{Req}
14
                            \mathbf{i} = \mathbf{i} + 1
15
```

Algorithm 8: All-pairs shortest path (Floyd-Warshall algorithm).

Algorithm 9: FastSV algorithm.

```
1 Function FastSV
 \mathbf{2}
       n = nrows(A)
        gf = f
 3
        dup = gf
 4
        \mathtt{mngf} = \mathtt{gf}
 5
        \{I,X\} \leftarrow f
 6
        repeat
 7
            // Step 1: Stochastic hooking
 8
            mngf = mngf min A
 9
            mngf = mngf second.min gf
10
            f(X) = f \min mngf
11
            // Step 2: Aggressive hooking
12
13
            f = f \min mngf
14
            // Step 3: Shortcutting
            f = f \min gf
15
            // Step 4: Calculate grandparents
16
            \{I,X\} \leftarrow f
17
            gf = f(X)
18
            // Step 5: Check termination
19
            diff = dup \neq gf
20
21
            \mathtt{sum} = [+_{\mathtt{i}} \, \mathtt{diff}(\mathtt{i})]
            \mathtt{dup} = \mathtt{gf}
\mathbf{22}
        \mathbf{until}\ \mathtt{sum} == 0
23
```

Algorithm 10: Triangle count (Cohen's algorithm).

Algorithm 11: Triangle count (Sandia).

```
    Function Triangle Count
    L = tril(A)
    C < L >= L + . × L
    t = [+ C]
```

Algorithm 12: Triangle count (FLAME).

Algorithm 13: Local clustering coefficient.

Algorithm 14: *k*-truss algorithm.

```
1 Function KTruss
      C <- A
2
      nonzeros <- nvals(C)
3
      for i = 1 to n - 1 do
4
           \mathtt{C}<\mathtt{C}>=\mathtt{C}+.\mathtt{land}\,\mathtt{C}
5
           C = select(C \ge k - 2)
6
           if nonzeros == nvals(C) then
7
              \mathbf{break}
8
9
           nonzeros \leftarrow nvals(C)
```

Algorithm 15: Louvain algorithm (WIP).

```
1 Function Louvain
         \mathtt{G} += \mathtt{G}'
 \mathbf{2}
         k = [+A]
 3
         m = (1)/(2)[+k]
 4
         S <- I
 5
 6
         vertices_changed <- nvals(k)</pre>
 7
         while vertices_changed > 0 \ do
 8
              for j \in range(|V|) do
 9
10
                   v = G(j,:)
                   t_q = v any.pair S
11
                   sr = S(j,:)
12
                   \mathtt{S}(\mathtt{j},:)=\mathrm{empty}
13
                   q <- k
15
                   \mathtt{q}<\mathtt{k}>\times=-\,\mathtt{k}(\mathtt{j})/\mathtt{m}
16
                   q + = v
17
18
                   \mathtt{q_1} <\! \mathtt{t_q} \! > = \mathtt{q} + . \times \mathtt{S}
19
                   \mathtt{t} = (\mathtt{q_1} == [\mathtt{max}\,\mathtt{q_1}])
20
                   while nvals(t) \neq 1 do
21
                        p = random() \times t
22
                      \mathsf{t} = (\mathsf{p} == [\max \mathsf{p}])
23
                   S(j,:) = t
24
25
                   if nvals(sr \times t) == 0 then
26
                     | vertices_changed = nvals(k)
27
                   vertices\_changed = vertices\_changed - 1
28
```

Algorithm 16: Community detection using label propagation (for undirected graphs).

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