## Continuous Random Variables

#### **General Information**

- A function  $f: \mathbb{R} \to \mathbb{R}$  is a probability mass function (pdf) of a continuous random variable X iff f is nonnegative and  $\int_{-\infty}^{\infty} f(x) dx = 1$ .
- For any probability mass function f, we have  $P(a \le X \le b) = \int_a^b f(x) dx$ . Whether the inequality is strict or nonstrict does not affect the above identity.
- A mode of X is any value m such that f(m) is maximum.
- A cumulative distribution function (cdf)  $F: \mathbb{R} \to [0,1]$  of a random variable X is defined by

$$F(x) := P(X \le x) = \int_{-\infty}^{x} f(x) dx.$$

- When writing out the cdf as a piecewise function, we explicitly write out the range of values for each case. We reserve the use of "otherwise" for pdf's.
- Any cdf is continuous and nondecreasing.
- Let X be a continuous random variable with cdf F. To find the pdf g of any y(X), we first find its cdf, then differentiate. We achieve this by reverse engineering  $y(X) \leq y$  to find an inequality that relates X with y. E.g.  $e^X \leq y$  iff  $X \leq \ln(y)$ .
- A median of X is any value m such that  $P(X \le m) = F(m) = 1/2$ .
- Mean/Expectation:

$$\mu = \mathrm{E}(X) := \int_{-\infty}^{\infty} x f(x) \, dx$$
 and  $\mathrm{E}(g(X)) = \int_{-\infty}^{\infty} g(x) f(x) \, dx$ .

• Important property:

$$E(ag(X) \pm bh(x)) = a E(g(X)) \pm E(h(X)).$$

• Variance:

$$\operatorname{Var}(X) := \operatorname{E}(X^2) - [\operatorname{E}(X)]^2.$$

• Important property:

$$Var(aX \pm b) = a^2 Var(X).$$

# Special Continuous Random Variables

## **Definition 2.1**

A continuous random variable X has a normal distribution with mean  $\mu$  and standard deviation  $\sigma$ , denoted by  $X \sim N(\mu, \sigma^2)$ , iff its pdf f is such that

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right).$$

#### **General Information**

• A normal distribution is symmetrical about the line  $x = \mu$ . That is

$$P(X \le \mu - \delta) = P(X \ge \mu + \delta)$$

for each  $\delta > 0$ . Note that the mean, median, and mode coincide with  $\mu$ .

- Properties of the normal distribution. Let X and Y be independent, such that  $X \sim N(\mu, \sigma^2)$  and  $Y \sim N(m, s^2)$ . Then, for any  $n \in \mathbb{N}$  and  $x, y \in \mathbb{R}$ ,
  - $-nX \sim N(n\mu, n^2\sigma^2),$
  - $-X_1 + X_2 + \dots + X_n \sim N(n\mu, n\sigma^2),$
  - $-aX \pm bY \sim N(a\mu \pm bm, a^2\sigma^2 + b^2s^2).$
- At times, the question may be phrased in a misleading manner. Try using some inference to figure out the intended interpretation.

#### Example 2.1

"The mass of the padding is 30% of the mass of a randomly selected light bulb of mass L. Find the probability that a light bulb with padding has mass c."

Then for any light bulb of mass  $L_1$ , the mass of the padding is  $0.3L_2$  (and not  $0.3L_1$ ). i.e. we are to find  $P(L_1 + 0.3L_2)$ .

- A variable Z ~ N(0,1) is said to follow the standard normal distribution.
   Note: Z is reserved for this purpose.
- Let  $X \in \mathcal{N}(\mu, \sigma^2)$ . Then,  $\frac{X-\mu}{\sigma}$  follows the standard normal distribution.
- What Tail do we select for invNorm?

P(X < x) = p	LEFT
P(-x < X < x) = p	CENTER
P(X > x) = p	RIGHT

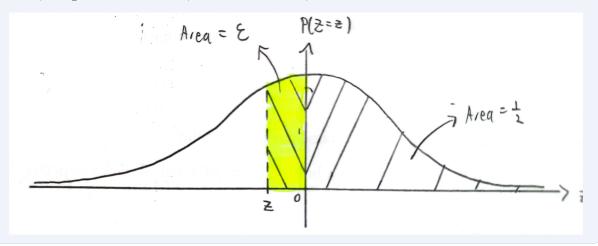
• When using invNorm on an inequality, what should the sign be? For simplicity, we write  $\mathcal{L}(p) = \text{invNorm}(p, 0, 1, \text{RIGHT})$ , and  $\mathcal{R}(p) = \text{invNorm}(p, 0, 1, \text{LEFT})$ . Then,

$P(Z>z) \ge p$	$z \leq \mathscr{L}(p)$
$P(Z>z) \le p$	$z \geq \mathscr{L}(p)$
$P(Z < z) \ge p$	$z \ge \mathcal{R}(p)$
$P(Z < z) \le p$	$z \leq \mathcal{R}(p)$

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### Example 2.2

Suppose we want to find the least integer value of m for which  $P(Z > 1 - m) \ge 1/2$ . Then, using invNorm (RIGHT), we infer that  $z \le 0$ , not  $z \ge 0$ . An illustration:



#### **Definition 2.2**

continuous random variable X has a uniform distribution over the interval (a, b), which is denoted by  $X \sim U(a, b)$ , iff its pdf f is such that

$$f(x) = \begin{cases} \frac{1}{b-a} & \text{if } a < x < b, \\ 0 & \text{otherwise.} \end{cases}$$

### **Definition 2.3**

continuous random variable Y has an (negative) exponential distribution, which we denote with  $Y \sim \text{Exp}(\lambda)$ , iff its pdf g is such that

$$g(Y) = \begin{cases} \lambda e^{-\lambda x} & \text{if } x \ge 0, \\ 0 & \text{otherwise.} \end{cases}$$

#### Note

Let  $Y \sim \text{Exp}(\lambda)$ , then

$$P(Y > z + y | Y > y) = P(Y > z).$$

• Expectation and variance:

Distribution	Expectation	Variance
$X \sim \mathrm{U}(a,b)$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
$Y \sim \text{Exp}(\lambda)$	$\frac{1}{\lambda}$	$\frac{1}{\lambda^2}$

*Note*: We need to remember the expectation and variance for the uniform distribution, as it is not provided in the MF26 formula sheet (unlike all other distributions).

• Warning: The G.C. tends to incorrectly process an integral if its upper and lower bounds contain  $\pm E99$ .

# Sampling and Estimation

## **Definition 3.1**

A sample is a finite subset of the population.

## **Definition 3.2**

A random sample is a sample selected such that each member of the population has an equal probability of being selected.

## **Definition 3.3**

Any statistic T derived from a random sample and used to estimated an unknown population parameter  $\theta$  is known as an *estimator*. It is an *unbiased* estimator iff  $E(T) = \theta$ . If T is unbiased we commonly write  $\hat{\theta}$  for T.

#### **General Information**

- Either write  $\hat{\mu}$  or write out "Unbiased estimate of the population mean  $\mu, \bar{x} = \dots$ " Same holds for other population parameters  $\theta$ .
- Estimators you should know:

	Parameter	Estimator	Unbiased?	Formula
	Population Mean $\mu$	Sample Mean $\overline{X}$	✓	$\frac{X_1 + X_2 + \dots + X_n}{n}$
		Sample Variance $\sigma_n^2$	×	$\frac{\sum (X_i - \overline{X})^2}{n}$ $\frac{\sum X_i^2}{n} - \overline{X}^2$
•	Population Variance $\sigma^2$	$S^2$	✓	$\frac{n}{n-1}\sigma_n^2$ $\frac{\sum (X_i - \overline{X})^2}{n-1}$ $\frac{1}{n-1} \left[ \sum X_i^2 - \frac{(\sum X_i)^2}{n} \right]$
	Population Proportion $p$	Sample Proportion $P_s$	<b>√</b>	$\frac{X}{n}$

• Let X be a random variable following any distribution, and suppose we have a random sample  $X_1, X_2, ..., X_n$  of size  $n \ge 50$ . Then by CLT (Central Limit Theorem), since  $n \ge 50$  is large,

$$\overline{X} \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$
 and  $X_1 + X_2 + \dots + X_n \sim N(n\mu, \nu\sigma^2)$ 

approximately.

- Assumptions when using CLT:
  - The sample is random.
  - Each  $X_i$  is independent and identically distributed.
- Suppose  $X \sim N(\mu, \sigma^2)$  is known and we pick a particular sample. Then,

Distribution	Is An Approximation?
$\overline{X} \sim N(\mu, \sigma^2)$	No
$\overline{X} \sim N(\overline{x}, \sigma^2)$	Yes
$\overline{X} \sim N(\mu, s^2)$	Yes
$\overline{X} \sim N(\overline{x}, s^2)$	Yes

So, if we obtain any of the latter three in solving a question, we must write " $X \sim N(\_,\_)$ approximately" (even though we knew X exactly follows a normal distribution!)

• Pooled estimators. First assume we have two populations, from which we select a random sample of size  $n_1$  and  $n_2$ . We let  $\overline{X}_1$  and  $S_1^2$  denote the sample mean and unbiased estimator for variance, respectively, for the first sample. Similarly define  $\overline{X}_2$  and  $S_2^2$ , for the second sample.

Parameter	Unbiased Pooled Estimator
Mean	$\hat{\mu} = \frac{n_1 \overline{X}_1 + n_2 \overline{X}_2}{n_1 + n_2}$
Variance	$S_p^2 = \frac{(n_1 - 1)S_1^2 + (n_2 - 1)S_2^2}{n_1 + n_2 - 2}$

The following definition is found in Hogg-McKean-Craig. Similar definitions are also found in Wackerly-Mendenhall-Schaefer and Nitis Mukhopadhyay.

## **Definition 3.4**

Let  $X_1, X_2, \ldots, X_n$  be a sample on a random variable X, where X has pdf  $f(x; \theta)$ ,  $\theta \in \Omega$ . Let  $0 < \alpha < 1$  be specified. Let  $L = L(X_1, X_2, \ldots, X_n)$  and  $U = U((X_1, X_2, \ldots, X_n))$  be two statistics. We say that the interval (L, U) is a  $(1 - \alpha)100\%$  confidence interval for  $\theta$  iff

$$1 - \alpha = P_{\theta}[\theta \in (L, U)].$$

That is, the probability that the interval contains  $\theta$  is  $1-\alpha$ , which is called the *confidence coefficient* or *confidence level* of the interval.

- We cannot write "a  $1-\alpha$  (e.g. 0.95) confidence interval". The  $1-\alpha$  must always be expressed as a *percentage*.
- Let  $\hat{\theta}$  be a statistic that is normally distributed with mean  $\theta$  and standard error  $\sigma_{\hat{\theta}}$ . We see that

$$\frac{\hat{\theta} - \theta}{\sigma_{\hat{\theta}}} = Z \sim \mathcal{N}(0, 1).$$

Rewriting  $P(-z_{1-\alpha/2} < Z < z_{1-\alpha/2}) = 1 - \alpha$  gives

$$P(\hat{\theta} - z_{1-\alpha/2}\sigma_{\hat{\theta}} < \theta < \hat{\theta} + z_{1-\alpha/2}\sigma_{\hat{\theta}}) = 1 - \alpha.$$

Hence, a  $(1-\alpha)100\%$  confidence interval for  $\theta$  is

$$(\hat{\theta} - z_{1-\alpha/2}\sigma_{\hat{\theta}}, \ \hat{\theta} + z_{1-\alpha/2}\sigma_{\hat{\theta}}).$$

(Wackerly-Mendenhall-Schaefer)

• Let  $0 < \alpha < 1$  and  $X_1, X_2, \dots, X_n$  be a sample on a random variable X with mean  $\mu$ , where n is large. Then, an approximate  $(1 - \alpha)100\%$  confidence interval for  $\mu$  is

$$\left(\bar{x}-z_{1-\alpha/2}\frac{s}{\sqrt{n}}\,,\;\bar{x}+z_{1-\alpha/2}\frac{s}{\sqrt{n}}\right).$$

When the variance  $\sigma^2$  is known, we can replace s with  $\sigma$ . If the distribution of X is known to be normal, in addition to  $\sigma^2$  being known exactly, then the confidence interval is exact; it is not just an approximation.

(Hogg-McKean-Craig)

• Let X be a Bernoulli random variable with probability of success p, where X is 1 or 0 if the outcome is success or failure, respectively. Suppose  $X_1, X_2, \ldots, X_n$  is a random sample from the distribution of X, where n is large. Let  $\hat{p} = \overline{X}$  be the sample proportion of successes. Then, an approximate  $(1 - \alpha)100\%$  confidence interval for p is given by

$$\left(\hat{p} - z_{1-\alpha/2} \sqrt{\frac{\hat{p}(1-\hat{p})}{n}}, \ \hat{p} + z_{1-\alpha/2} \sqrt{\frac{\hat{p}(1-\hat{p})}{n}}\right).$$

(Letting  $Y = X_1 + X_2 + \cdots + X_n \sim B(n, p)$  gives  $\hat{p} = Y/n$ , which is the presentation used in the school's notes.)

(Hogg-McKean-Craig)

#### Note

Standard phrasing for the interpretation of a  $(1 - \alpha)100\%$  confidence interval (a, b).

The probability that the interval (a, b) contains the true value of the [population mean/proportion in context] is  $1 - \alpha$ .

#### Note

Standard phrasing for what is a  $(1 - \alpha)100\%$  confidence interval for  $\theta$ ?

It is an interval which has probability  $1 - \alpha$  of containing the true value of  $\theta$ .

#### Note

Standard phrasing for whether mean/proportion in context has likely increased/decreased, when given suitable confidence intervals.

1. There is no conclusive result.

Since the old and new  $(1-\alpha)\%$  confidence intervals overlap, we are unable to conclude whether the [mean/proportion in context] has decreased or not. Hence, it is inconclusive from these figures as to whether the [context (e.g. an awareness campaign)] has been effective.

2. It has likely increased/decreased.

The old  $(1 - \alpha)\%$  confidence interval is to the left/right of the new  $(1 - \alpha)\%$  confidence interval, such that they do not overlap. So, can conclude that the [mean/proportion in context] likely increased/decreased. Hence, these figures suggests that the [context (e.g. an awareness campaign)] has been effective.

## G.C. Skills

Calculating statistics (i.e.  $\bar{x}$ , s, etc) by G.C. given data for a sample.

- 1. Keying in the data: stat  $\Longrightarrow$  1:Edit  $\Longrightarrow$  Key in the data into one of the lists  $L_i$ .
- 2. Calculating the statistic: stat  $\Longrightarrow$  CALC  $\Longrightarrow$  1-Var Stats (List:L<sub>i</sub>)  $\Longrightarrow$  Calculate.
- 3. Getting the statistic for further calculations: vars ⇒ 5:Statistics ⇒ Select the desired statistic.

## G.C. Skills

Calculating the symmetric confidence interval by G.C.

 $\begin{array}{ll} \text{Mean:} & \text{stat} \Longrightarrow \text{TESTS} \Longrightarrow 7\text{:}\text{ZInterval}\dots \\ \text{Proportion:} & \text{stat} \Longrightarrow \text{TESTS} \Longrightarrow \text{A:}1\text{-PropZInt}\dots \\ \end{array}$ 

# Statistics: Hypothesis Testing

## **Definition 4.1**

The *null hypothesis*  $H_0$  and *alternative hypothesis*  $H_1$  is the hypotheses that we hope to reject and accept, respectively.

### **General Information**

• Without going into details, a *critical region C* is just a set that defines the decision rule / test

Reject 
$$H_0$$
 (Accept  $H_1$ ) if  $(X_1, X_2, ..., X_n) \in C$ ,

for any random sample  $X_1, X_2, \dots, X_n$  from the distribution of a random variable X.

#### **Definition 4.2**

The significance level  $\alpha \cdot 100\%$  of a test is the probability of rejecting  $H_0$  when it is in fact true. i.e.  $\alpha = P(H_0 \text{ is rejected} \mid H_0 \text{ is true}).$ 

## **Definition 4.3**

The *p-value* is the lowest level of significance for which the null hypothesis will be rejected. In other words, for the null hypotheses

(a) 
$$\mu < \mu_0$$
, (b)  $\mu \neq \mu_0$ , (c)  $\mu > \mu_0$ ,

we have

(a) 
$$p$$
-value =  $P(Z \le z_{calc})$ , (b)  $p$ -value =  $P(|Z| \ge |z_{calc}|)$ , (c)  $p$ -value =  $P(Z \ge z_{calc})$ .

• Large sample test for the mean. Steps:

- 1. Test  $H_0: \mu = \mu_0$  against  $H_1:$  (a)  $\mu < \mu_0$ , (b)  $\mu \neq \mu_0$ , or (c)  $\mu > \mu_0$ .
- 2. Under  $H_0$ , we have  $\overline{X} \sim N(\mu_0, \hat{\sigma}^2/n)$  approximately. Or, if  $\sigma^2$  is known exactly, then by CLT  $\overline{X} \sim N(\mu_0, \sigma^2/n)$  approximately.
- 3. Test statistic:

$$Z = \frac{\overline{X} - \mu_0}{\sigma / \sqrt{n}} \sim N(0, 1).$$

- 4. Find  $z_{1-\alpha}$  or  $z_{1-\alpha/2}$ , which satisfies
  - (a)  $P(Z < z_{1-\alpha/2}) = \alpha$ ,
  - (b)  $P(-z_{1-\alpha} < Z < z_{1-\alpha}) = \alpha$ , or
  - (c)  $P(Z > z_{1-\alpha/2})$ .
- 5. Find the test statistic value

$$z_{\rm calc} = \frac{\hat{\mu} - \mu_0}{\sigma / \sqrt{n}}.$$

- 6. Reject  $H_0$  iff
  - (a)  $z_{\text{calc}} < z_{1-\alpha}$ ,
  - (b)  $|z_{\text{calc}}| > z_{1-\alpha/2}$ , or
  - (c)  $z_{\text{calc}} > z_{1-\alpha}$ .
- If we have a null hypothesis

$$H_0: \mu \leq \mu_0 \quad \text{or} \quad H_0: \mu \geq \mu_0,$$

we can just use  $H_0$ :  $\mu = \mu_0$  instead.

#### Note

Standard phrasing for rejecting  $H_0$ .

Since (a)  $z_{\rm calc} < z_{1-\alpha}$ , (b)  $|z_{\rm calc}| > z_{1-\alpha/2}$ , (c)  $z_{\rm calc} > z_{1-\alpha}$ , or p-value  $< \alpha$ , the value  $z_{\rm calc}$  lies in the critical region. We thus reject  $H_0$  and conclude that there is sufficient evidence at significance level  $\alpha \cdot 100\%$  that  $[H_1$  in context].

For not rejecting  $H_0$ , simply change to the appropriate inequality (such that  $z_{\text{calc}}$  is outside the critical region) and write "insufficient" instead of "sufficient".

## G.C. Skills

Calculating the p-value of a sample.

4. Find the *p*-value using GC.

$$\texttt{stat} \implies \texttt{TESTS} \implies \texttt{1:Z-Test}.$$

5. Reject  $H_0$  iff p-value is less than  $\alpha$ .

# Correlation and Linear Regression

#### Note

A good scatter diagram should follow the guidelines below.

- The relative position of each point on the scatter diagram should be clearly shown.
- The range of values for the set of data should be clearly shown by marking out the extreme x and y values on the corresponding axis.
- The axes should be labeled clearly with the variables.

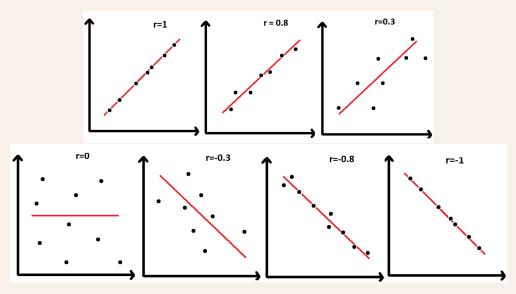
#### **General Information**

• The Product Moment Correlation Coefficient is a measure of the linear correlation between two variables. It is defined by

$$r = \frac{\sum (x - \bar{x})(y - \bar{y})}{\sqrt{\sum (x - \bar{x})^2 \sum (y - \bar{y})^2}} = \frac{\sum xy - \frac{\sum x \sum y}{n}}{\sqrt{\left[\sum x^2 - \frac{(\sum x)^2}{n}\right] \left[\sum y^2 - \frac{(\sum y)^2}{n}\right]}},$$

which takes on a value from 0 to 1.

- When r = 0, there is no linear relationship. But, a nonlinear relationship may be present. Additionally, the regression lines are perpendicular.
- The closer the value of r is to 1 (or -1), the stronger the positive (or negative) linear correlation. Furthermore, the regression lines coincide.



• The regression line of y on x minimises the sum of squares deviation (error) in the y-direction. (i.e. we are assuming x is the independent variable whose values are known exactly.) It is given by

$$y = \bar{y} + b(x - \bar{x}),$$
 where  $b = \frac{\sum (x - \bar{x})(y - \bar{y})}{\sum (x - \bar{x})^2} = \frac{\sum xy - \frac{\sum x \sum y}{n}}{\sum x^2 - \frac{(\sum x)^2}{n}}.$ 

- The point  $(\bar{x}, \bar{y})$  always lies on both the regression lines of y on x, and x on y.
- Say we are given the value of one variable, and asked to approximate the the value of the other variable. Then, we should always use the line of the *dependent* variable on the *independent*.
- ullet Estimations should not be taken for data outside the range of the sample provided, even if the value of r is close to 1.