

# Mapping Kickstarter's Success Formula

...

April 27th 2018

# Overview

- Why learn a Winning Formula?
- Exploring Kickstarter
- How to measure a “Successful” Campaign
- Three Regression Models
- Which Features Matter

# What is Kickstarter?

## Purpose

- To allow small-scale creators to fund their work through donations from members of their community

## Finances

- \$3 Billion pledged
- 150K successful projects
- 14 Million Backers

## Community

- Vast majority of campaigns raised less than 20K
- No money for analytics, advertising, videography, market research, etc.

# The Goal:

Demystify the crowdfunding formula to help small scale creators and entrepreneurs.

# Exploring Kickstarter:



By Emma Cohen & Miles  
Pepper  
First created

# FinalStraw, the world's first collapsible, reusable straw

Clean, compact, and totally badass: For anyone who wants to rid their lives—and the planet  
—of single-use plastic.



Project We Love



Product Design



Los Angeles, CA

\$616,954

pledged of \$12,500 goal

13,183

backers

22

days to go

Back this project



Remind me



All or nothing. This project will only be funded if it reaches its goal by  
Sat, May 19 2018 12:12 AM PDT.

Campaign

FAQ <sup>32</sup>

Updates <sup>4</sup>

Comments <sup>93</sup>

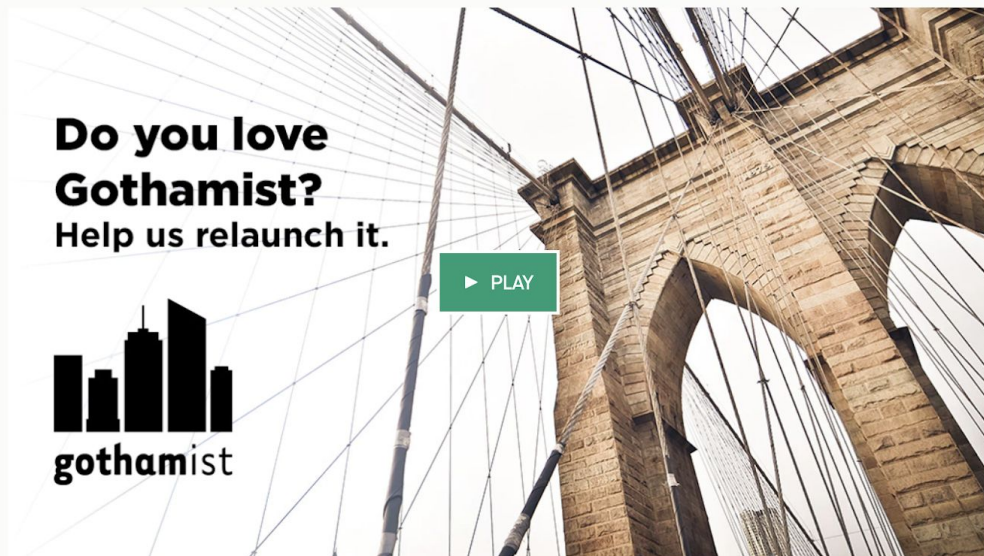
Community



By Gothamist  
First created

## Bring Back Gothamist

Gothamist has joined New York institution WNYC, now they need you to step up and bring the site back to its former glory.



**\$142,367**

pledged of \$100,000 goal

**2,054**

backers

**8**

days to go

Back this project

 Remind me



All or nothing. This project will only be funded if it reaches its goal by Fri, May 4 2018 8:59 PM PDT.



Project We Love



Journalism



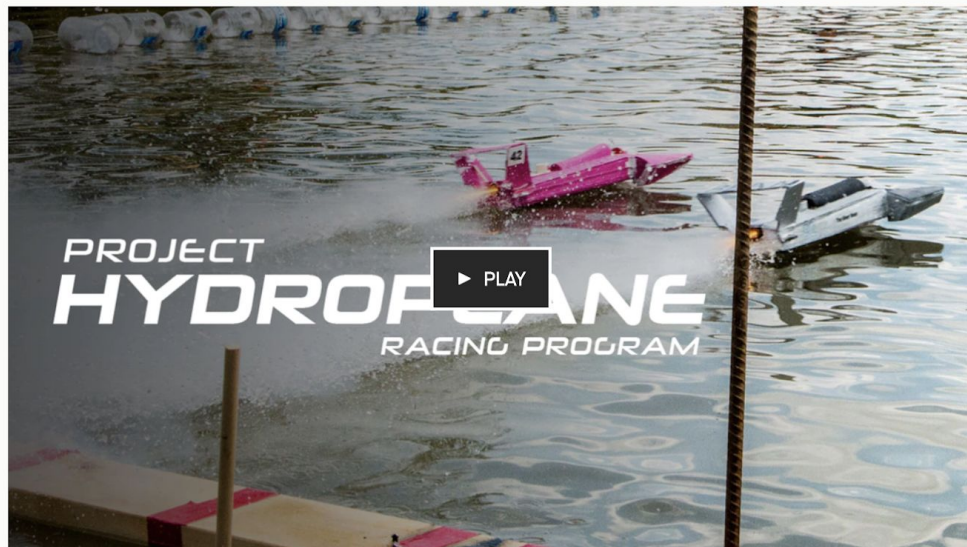
New York, NY



By Thad Greer  
First created

# Project Hydroplane Racing Program - STEM Learning Made Fun

Project-based STEM curriculum that fully engages otherwise bored students and prepares them for the real world!



Project We Love Product Design Louisville, KY

\$7,348

pledged of \$55,000 goal

18

backers

12

days to go

Back this project

Remind me



All or nothing. This project will only be funded if it reaches its goal by Wed, May 9 2018 7:30 AM PDT.

Campaign

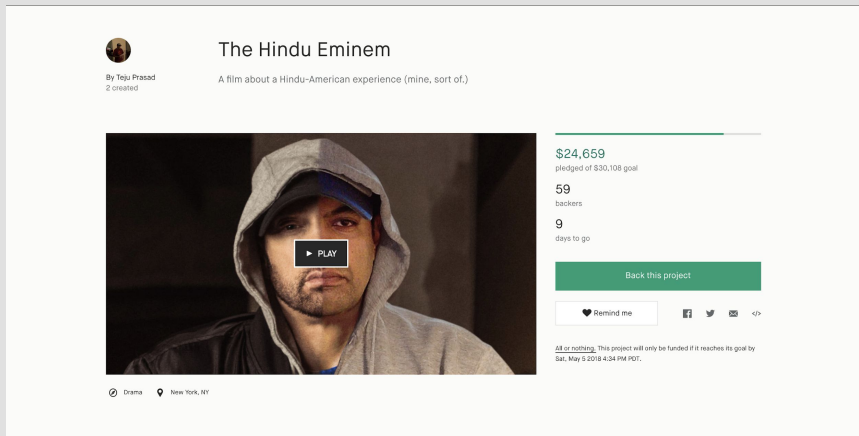
FAQ <sup>6</sup>

Updates <sup>0</sup>

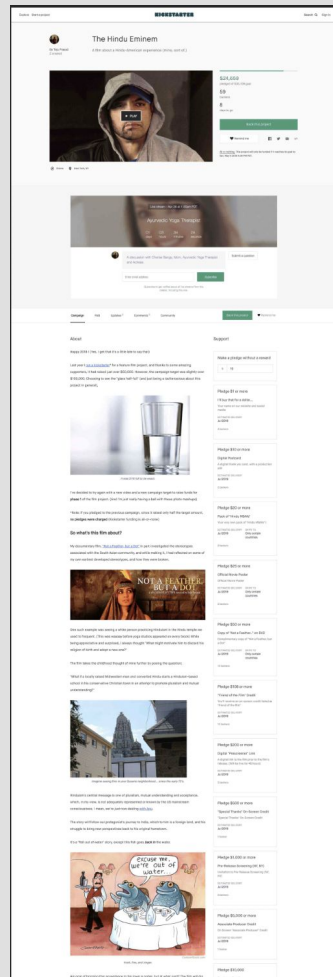
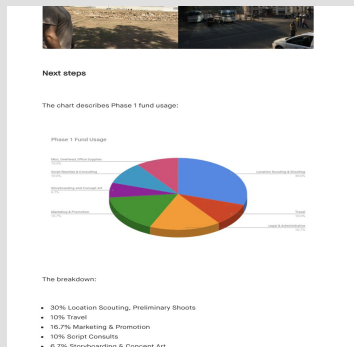
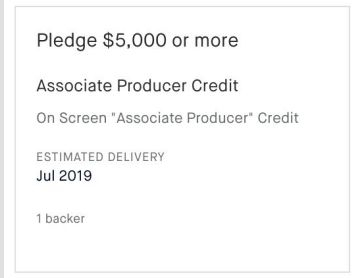
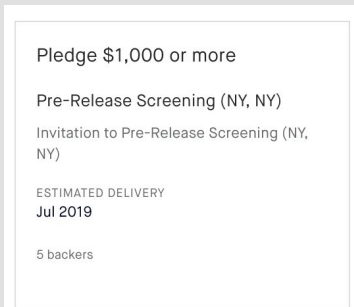
Comments <sup>0</sup>

Community

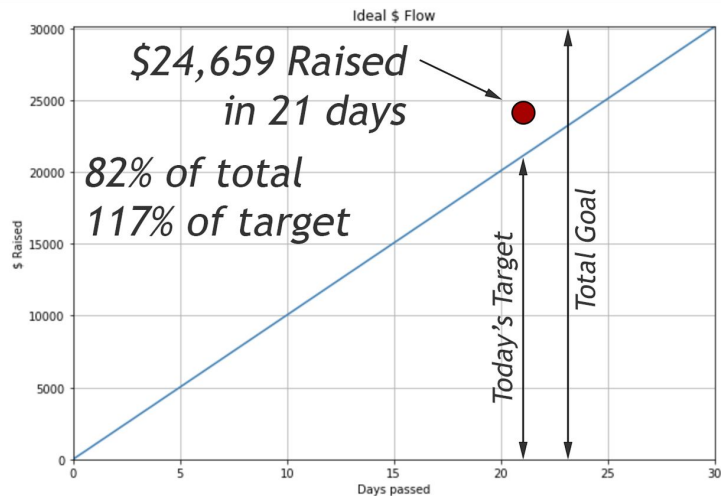




<https://www.kickstarter.com/projects/1475731975/the-hindu-eminem?ref=discovery&ref=discovery>



# Measuring “Success”



- Kickstarter does not allow search of failed campaigns
- We look at ongoing campaigns
- We estimate their success compared to a straight path toward their target
- This project is at 1.17
- 1.0 means “on track”



By Taj Prasad  
2 created

## The Hindu Eminem

A film about a Hindu-American experience (mine, sort of.)



\$24,659  
pledged of \$30,109 goal

59  
backers

9  
days to go

Back this project



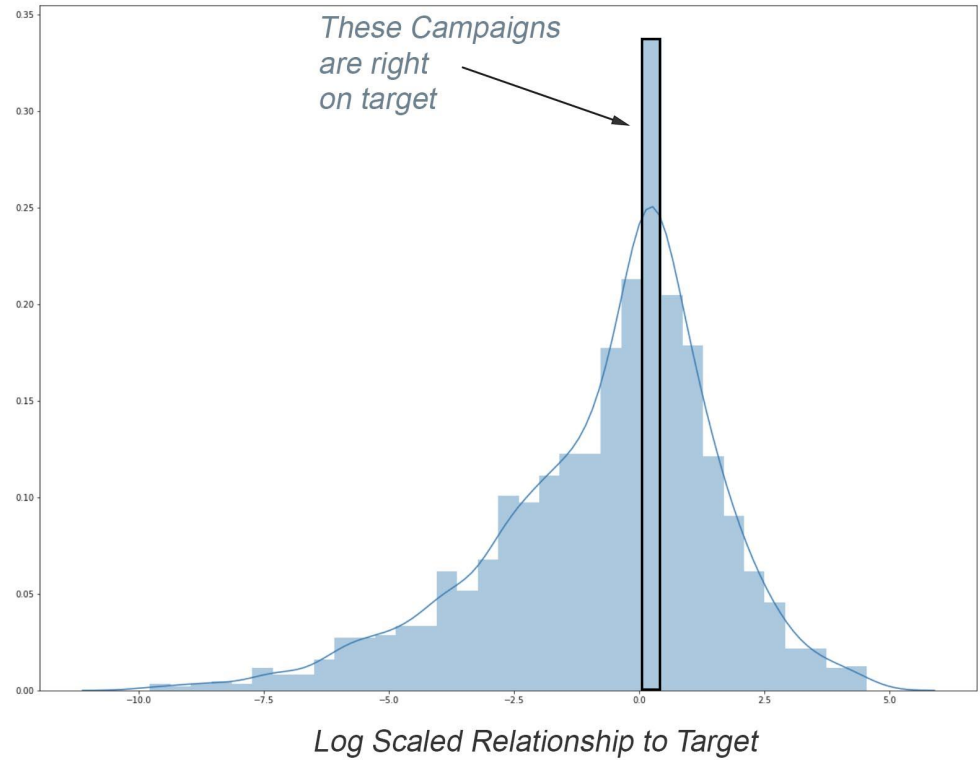
Remind me



All or nothing. This project will only be funded if it reaches its goal by Sat, May 5 2018 4:34 PM PDT.

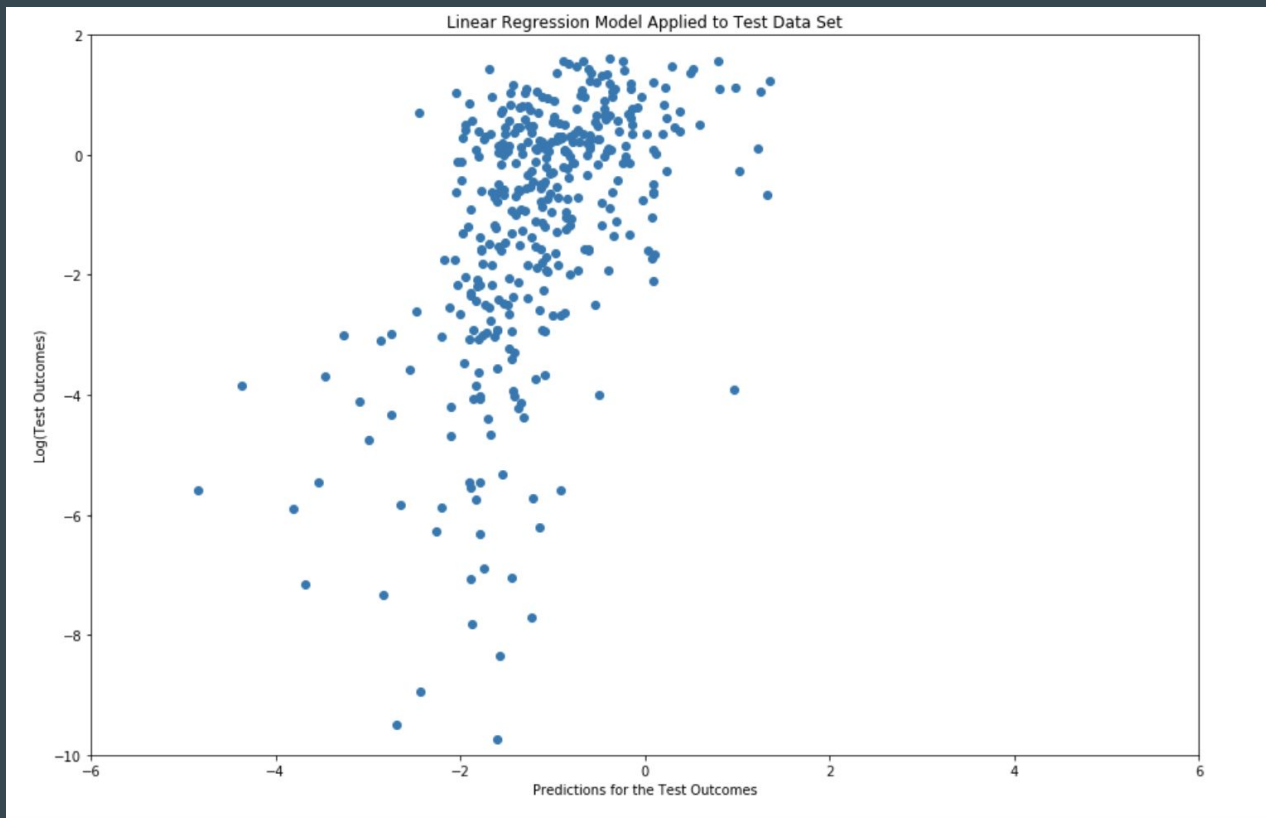
🎬 Drama 📍 New York, NY

# Distribution of 'y'



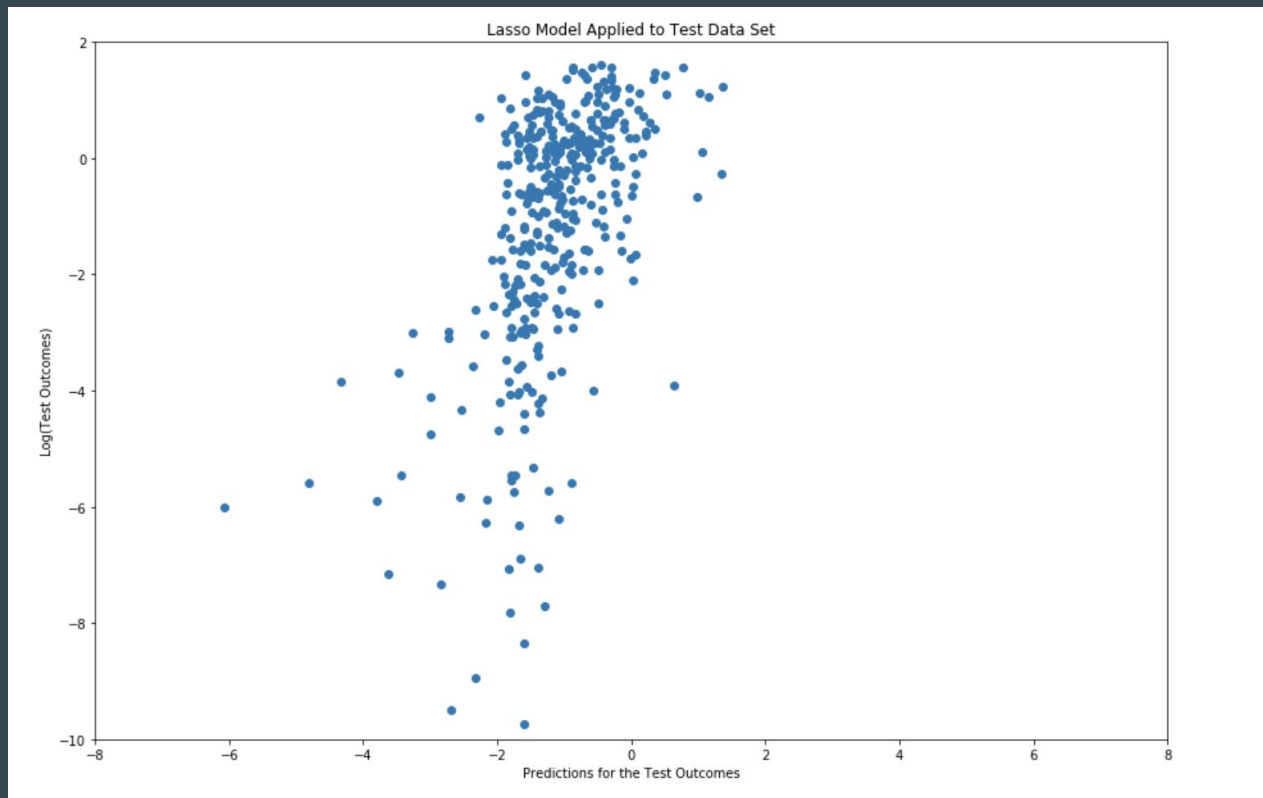
# Three Models

# Ordinary Least Squares Model



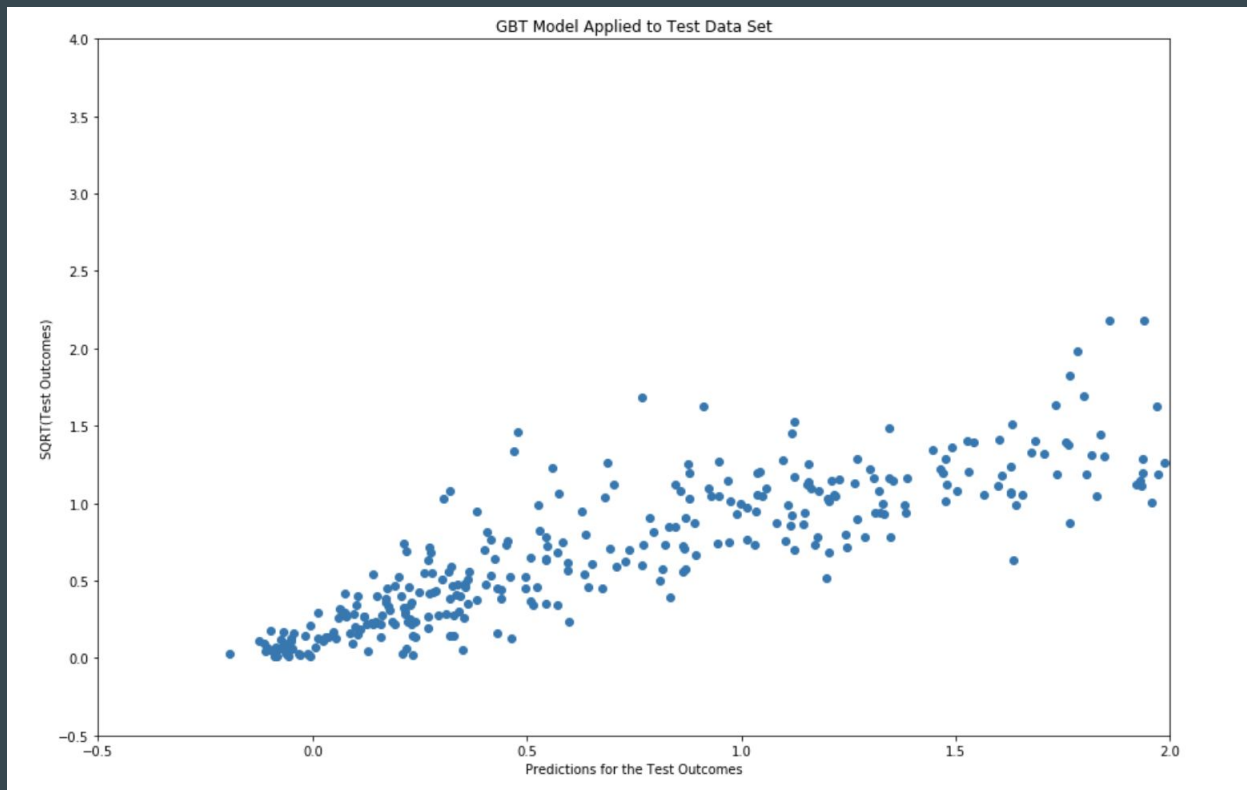
Adjusted RMSE = 0.96248723734544

# Polynomial Features and Lasso



Adjusted RMSE = 1.0268887720267705

# Gradient Boosted Trees



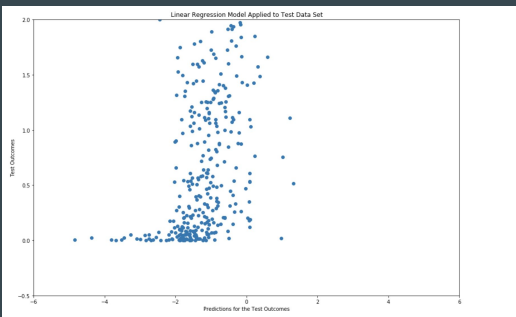
Adjusted RMSE = 0.735480310060743



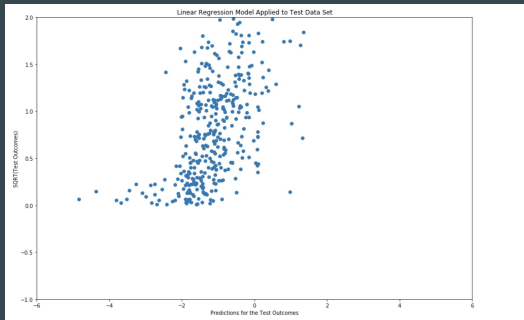
# Appendix: Response Variable Scaling

Ordinary  
Least  
Squares

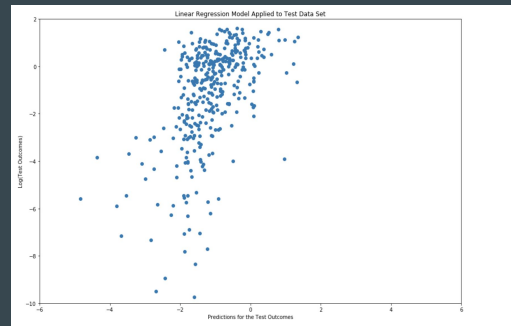
(y)



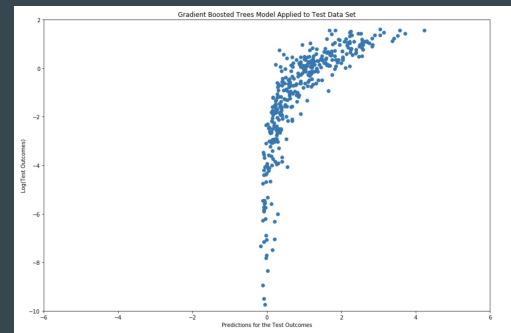
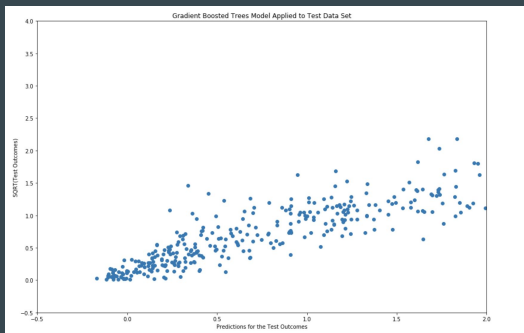
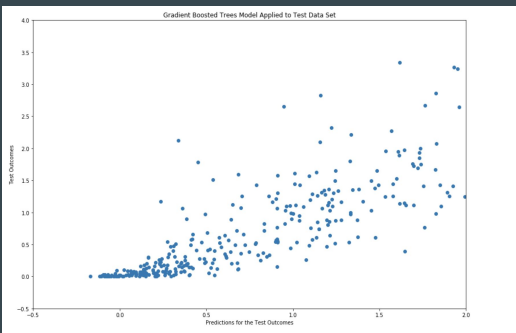
Sqrt(y)



Log(y)

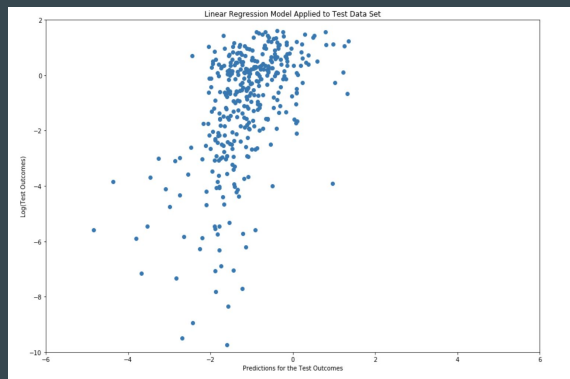


Gradient  
Boosted  
Trees



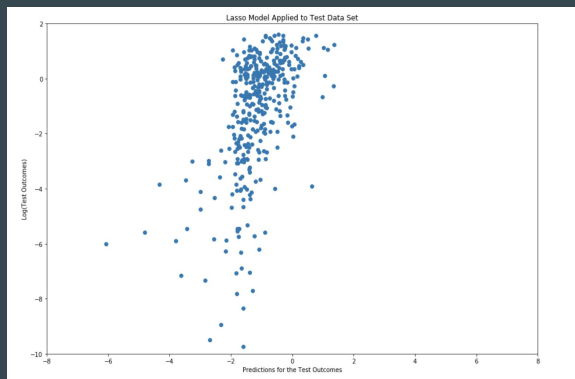
# Data Summary:

## Ordinary Least Squares



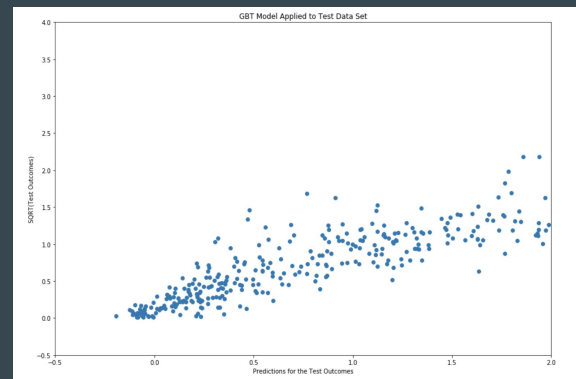
$R^2$  Max = .418  
Adjusted RMSE = 0.96248723734544

## L1 Norm (Lasso)



$R^2$  Max = .275  
Adjusted RMSE = 1.0268887720267705

## Gradient Boosted Trees



$R^2$  Max = .586  
Adjusted RMSE = 0.735480310060743

# Which Features Contain the Variance?

## Strong Effect

- Total Backers
- Total Goal
- Number of Images
- Total Text
- Updates

## Weak Effect

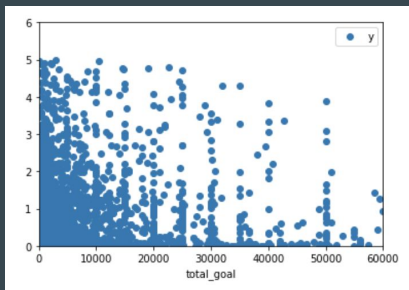
- Number of Tiers
- Length of Title
- Length of Campaign

## Surprises

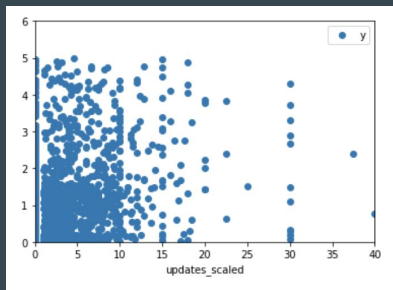
- Video has no effect at all!?

# Plots of Largest Predictors

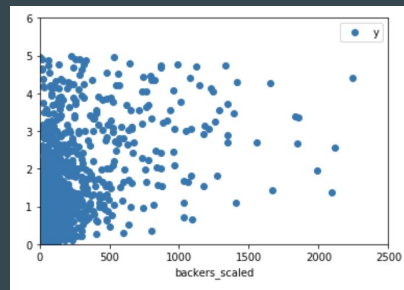
Goal Size



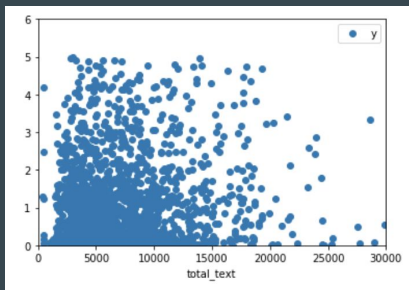
Updates



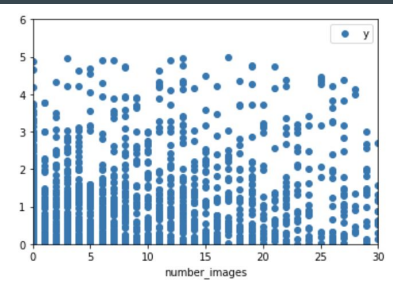
Number of Backers



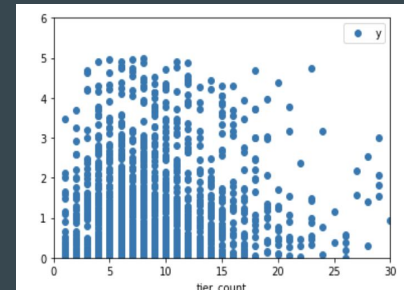
Total Text



Number of Images



Tier Count



$R^2 = 0.032$

$R^2 = 0.050$

# Conclusions:

- Features themselves are only lightly predictive
- Not improved by looking to simple feature transformations
- Gradient boosted trees model does better but it's hard to say why at this time
- Get the numerics right but they are clearly not the whole story so focusing on them to the exclusion of your content is a huge mistake.

# Future Directions (Data):

- Stretch Goal Size (\$)
- Video Length (seconds)
- Tier Dollar Amounts (\$)
- Backers per Tier (int)
- Price Point of Lowest Tier (\$)
- Prior Successful Campaigns (int)
- Prior Unsuccessful Campaigns (int)
- Video hosted on Youtube vs. Other (boolean)
- Number of Followers of Campaign Creator
- Time of Year (date)
- Video View Count (int)
- Pageviews (int)
- Mentions Burning Man (boolean)
- Category

# Future Directions (Modeling):

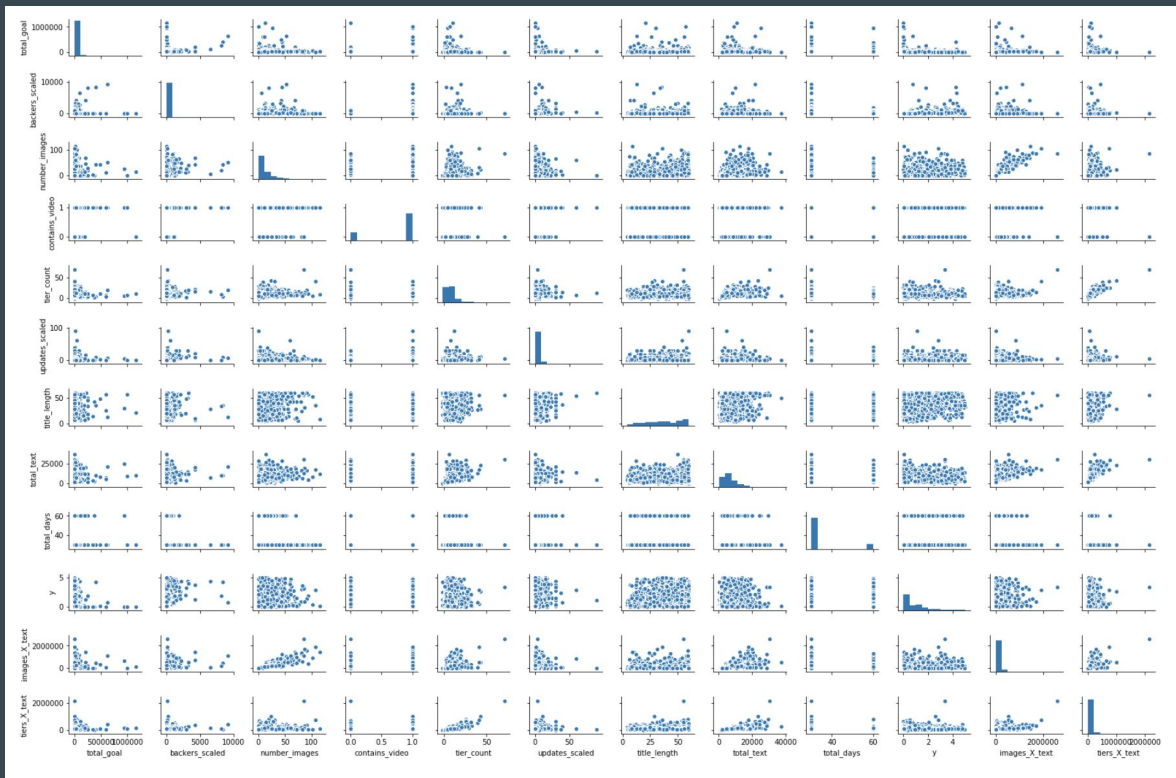
- Huber loss to give less weight to outliers
- Motivate the use of the Gradient Boosted Trees model
- Check the assumptions for linear regression
  - Regression is linear in parameters & correctly specified
  - Residuals ( ) should be normally distributed with zero mean
  - The error term must have constant variance
  - Assumption 4: Errors are uncorrelated across observations
  - No independent variable is a perfect linear function of any other independent variable (no perfect multi-collinearity)

# Fin!

(Questions)?



# Appendix: Feature Pair Plots



# Appendix: Correlation Matrix

	total_goal	backers_scaled	number_images	contains_video	tier_count	updates_scaled	title_length	total_text	total_days
total_goal	1.000000	0.262742	0.097397	0.063295	0.035208	0.001725	-0.007649	0.153234	0.050043
backers_scaled	0.262742	1.000000	0.263059	0.110473	0.137613	0.228440	0.005444	0.222911	-0.053239
number_images	0.097397	0.263059	1.000000	0.173836	0.297501	0.209192	0.130526	0.445501	-0.030529
contains_video	0.063295	0.110473	0.173836	1.000000	0.150150	0.129097	0.047185	0.193876	-0.017285
tier_count	0.035208	0.137613	0.297501	0.150150	1.000000	0.180116	0.064274	0.560014	-0.052054
updates_scaled	0.001725	0.228440	0.209192	0.129097	0.180116	1.000000	0.070169	0.223417	-0.070860
title_length	-0.007649	0.005444	0.130526	0.047185	0.064274	0.070169	1.000000	0.153803	-0.006166
total_text	0.153234	0.222911	0.445501	0.193876	0.560014	0.223417	0.153803	1.000000	-0.015411
total_days	0.050043	-0.053239	-0.030529	-0.017285	-0.052054	-0.070860	-0.006166	-0.015411	1.000000

# Appendix: OLS Residual Plot

