Recorded at time: 1530023214.987 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1530023214.987 sec old) Buffer length: 0.000 sec ur3_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (1530023214.987 sec old) Most recent transform: 1530023214.896 (0.091 sec old) Buffer length: 0.000 sec Buffer length: 4.900 sec ur3_base ur3_shoulder_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1530023214.896 (0.091 sec old) Buffer length: 4.900 sec ur3_upper_arm_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1530023214.896 (0.091 sec old) Buffer length: 4.900 sec ur3_forearm_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1530023214.896 (0.091 sec old) Buffer length: 4.900 sec ur3_wrist_1_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1530023214.896 (0.091 sec old) Buffer length: 4.900 sec ur3_wrist_2_link Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1530023214.896 (0.091 sec old) Buffer length: 4.900 sec ur3_wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1530023214.987 sec old) Most recent transform: 0.000 (1530023214.987 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ur3_tool0 ur3_ee_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1530023214.987 sec old) Most recent transform: 0.000 (1530023214.987 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec camera_link melkarm_plate Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /camera_base_link Broadcaster: /camera_base_link1 Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.194 Hz Average rate: 10.194 Hz Most recent transform: 0.000 (1530023214.987 sec old) Most recent transform: 0.000 (1530023214.987 sec old) Most recent transform: 1530023215.076 (-0.089 sec old) Most recent transform: 1530023215.076 (-0.089 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.905 sec Buffer length: 4.905 sec melkarm_camera_holder melkarm_becherhalter camera_depth_frame camera_rgb_frame Broadcaster: /robot_state_publisher Broadcaster: /camera_base_link2 Broadcaster: /camera_base_link3 Average rate: 10000.000 Hz Average rate: 10.194 Hz Average rate: 10.198 Hz Most recent transform: 1530023214.996 (-0.009 sec old) Most recent transform: 0.000 (1530023214.987 sec old) Most recent transform: 1530023214.999 (-0.012 sec old) Buffer length: 4.905 sec Buffer length: 0.000 sec Buffer length: 4.805 sec melkarm_melkbecher camera_rgb_optical_frame camera_depth_optical_frame Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1530023214.987 sec old) Buffer length: 0.000 sec teatcup_tcp

view_frames Result