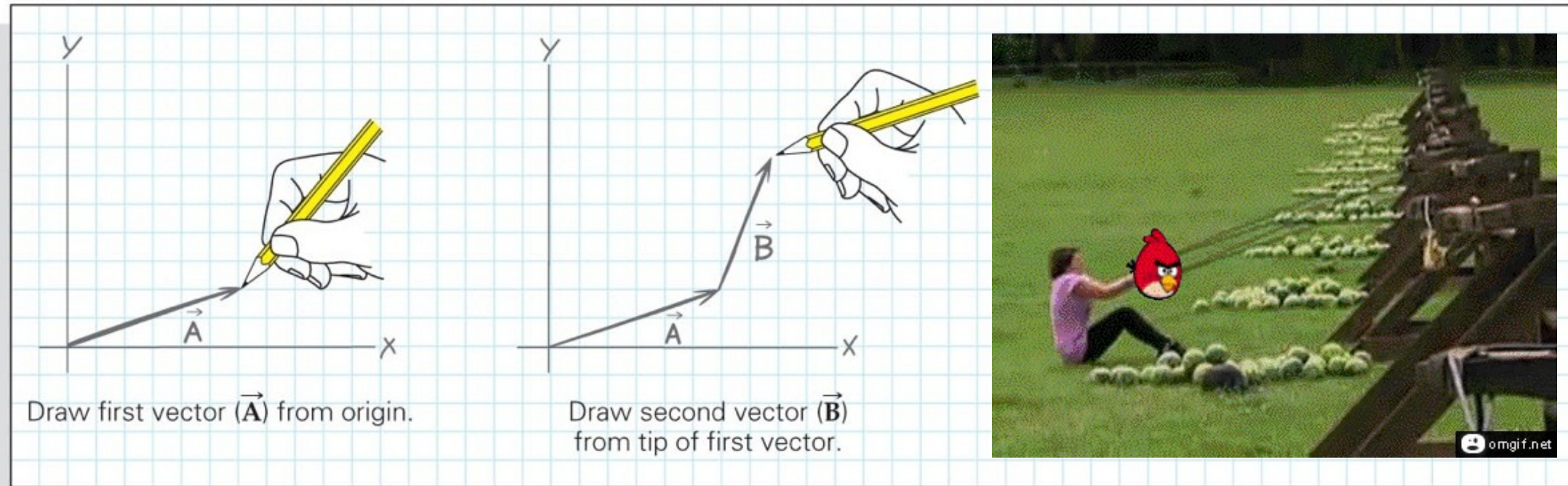


Physics 225

Section 2,
Spring Fall 2018
Lecture 4

Today: Vectors

$$\vec{R} = \vec{A} + \vec{B}$$

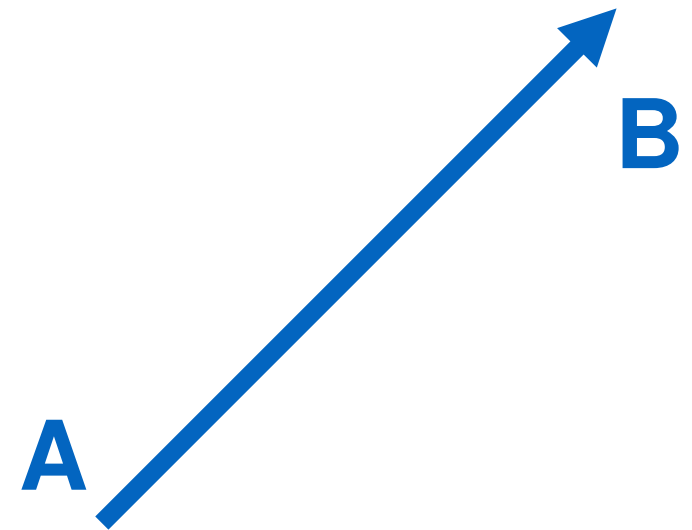


- **Take Home Message**

- Vectors have a magnitude **and** direction
- It “carries” a point from A to B
- Vectors require special care during math operations

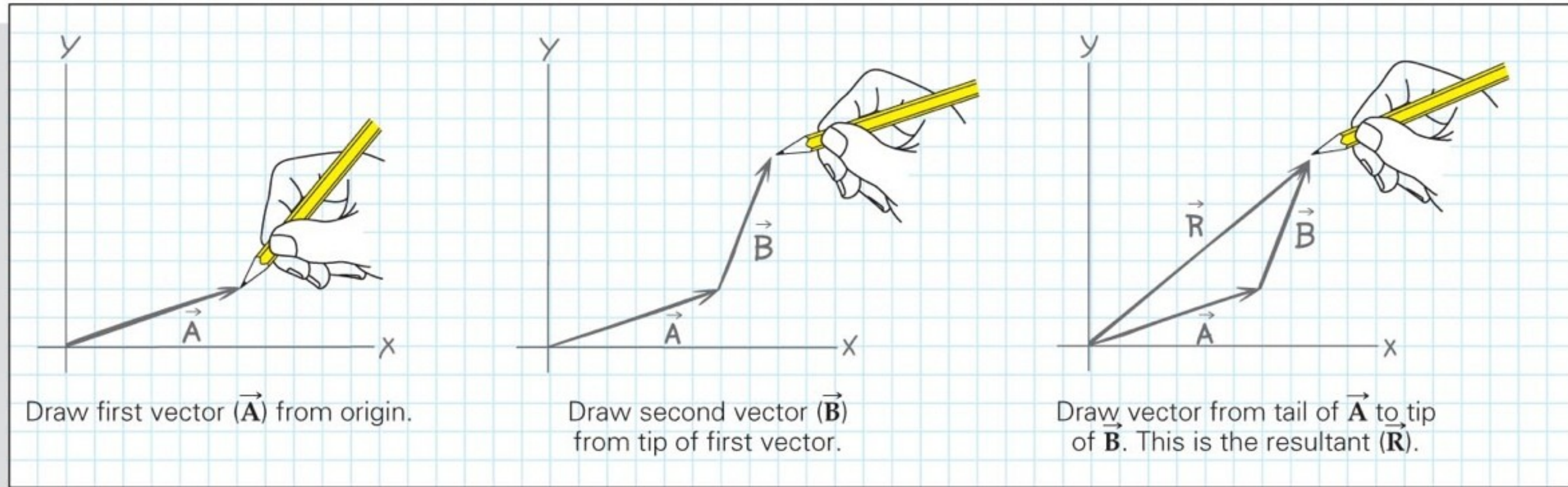
Vectors

- Magnitude + direction
- Represent as arrows
- New kind of object
- Operations
 - Addition +, subtraction –
 - Scaling
 - Later: multiplying two vectors (\cdot , \times)

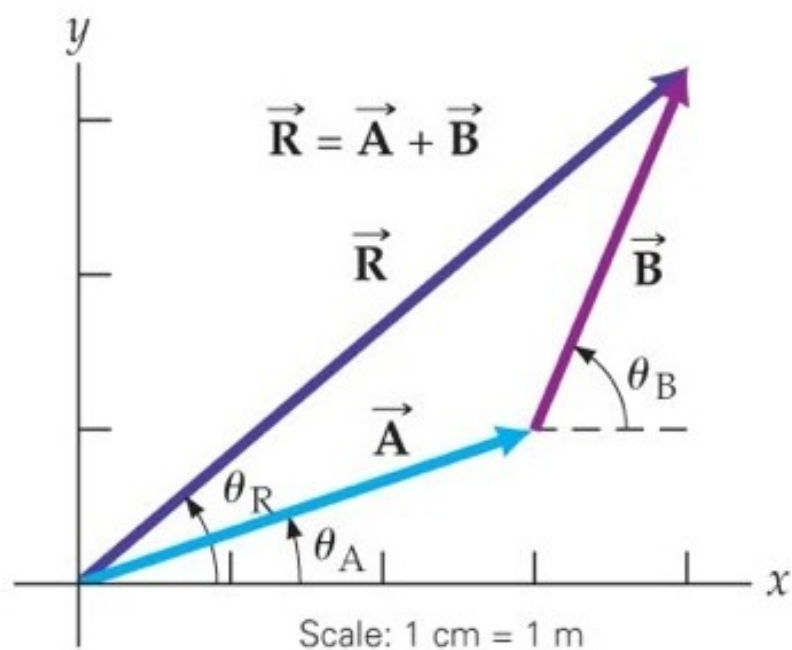


Vector addition

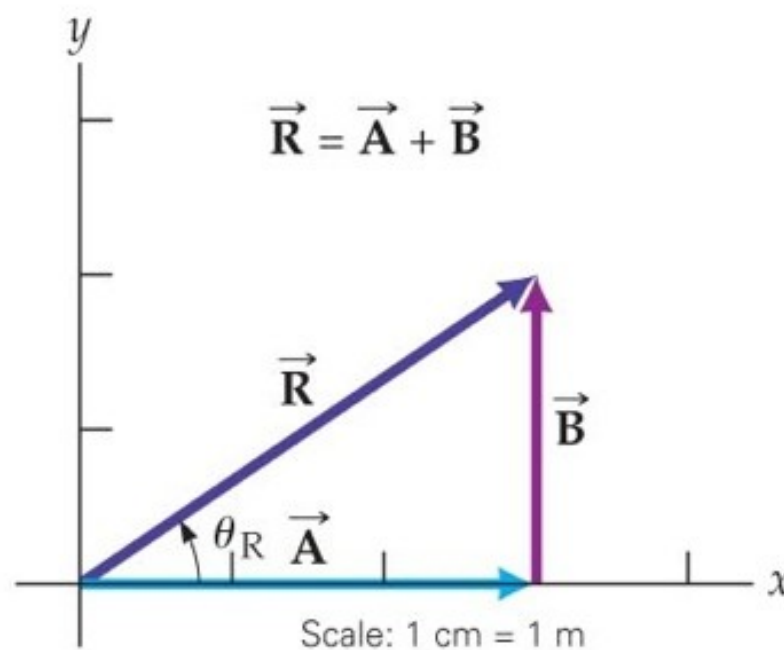
$$\vec{R} = \vec{A} + \vec{B}$$



(a)

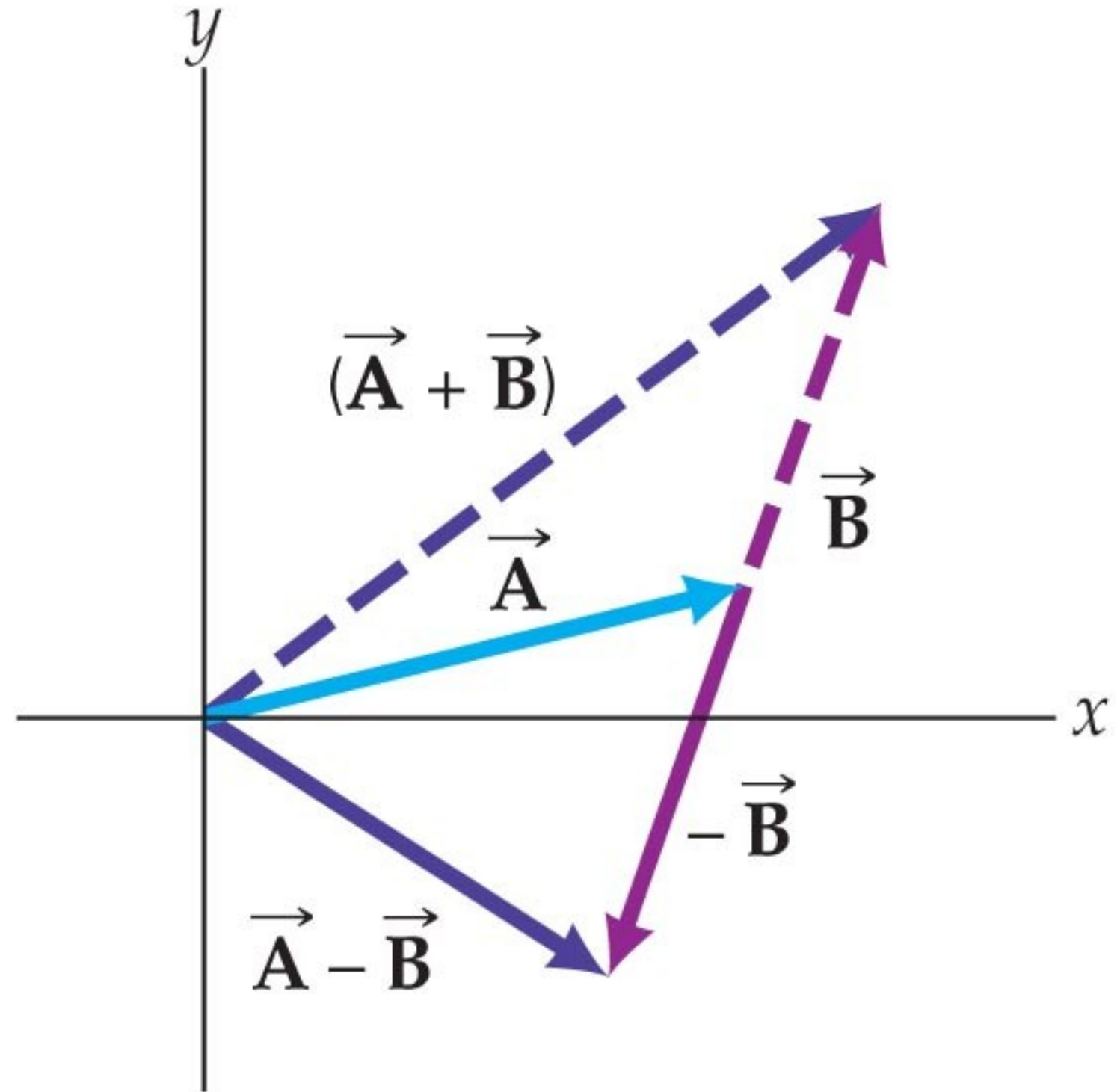
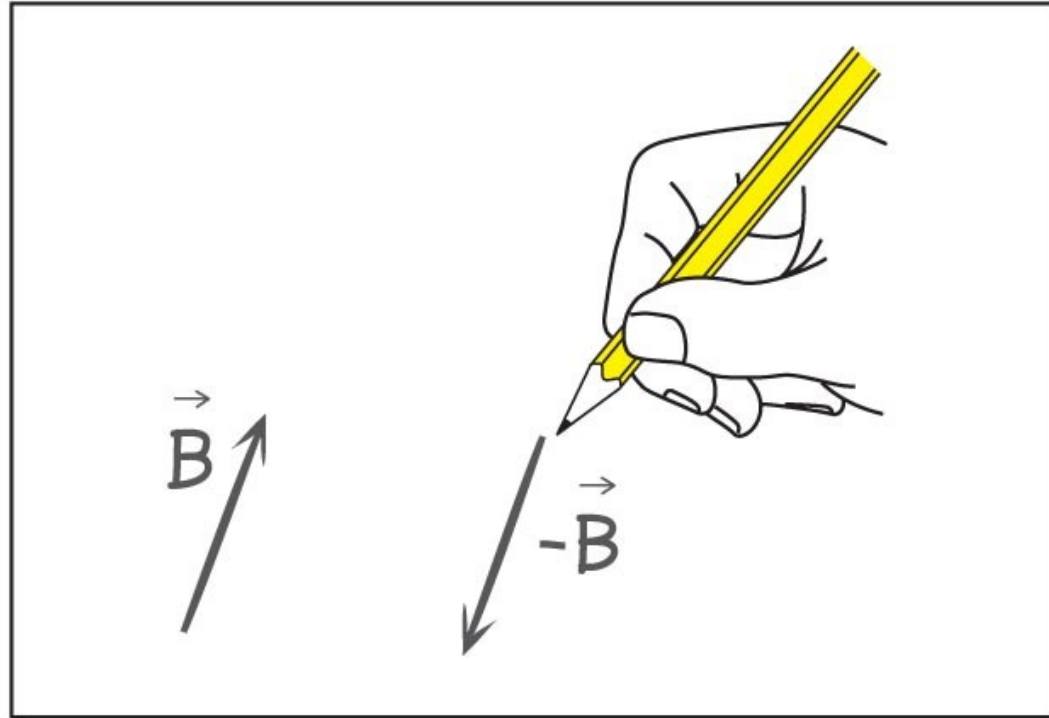


(b)

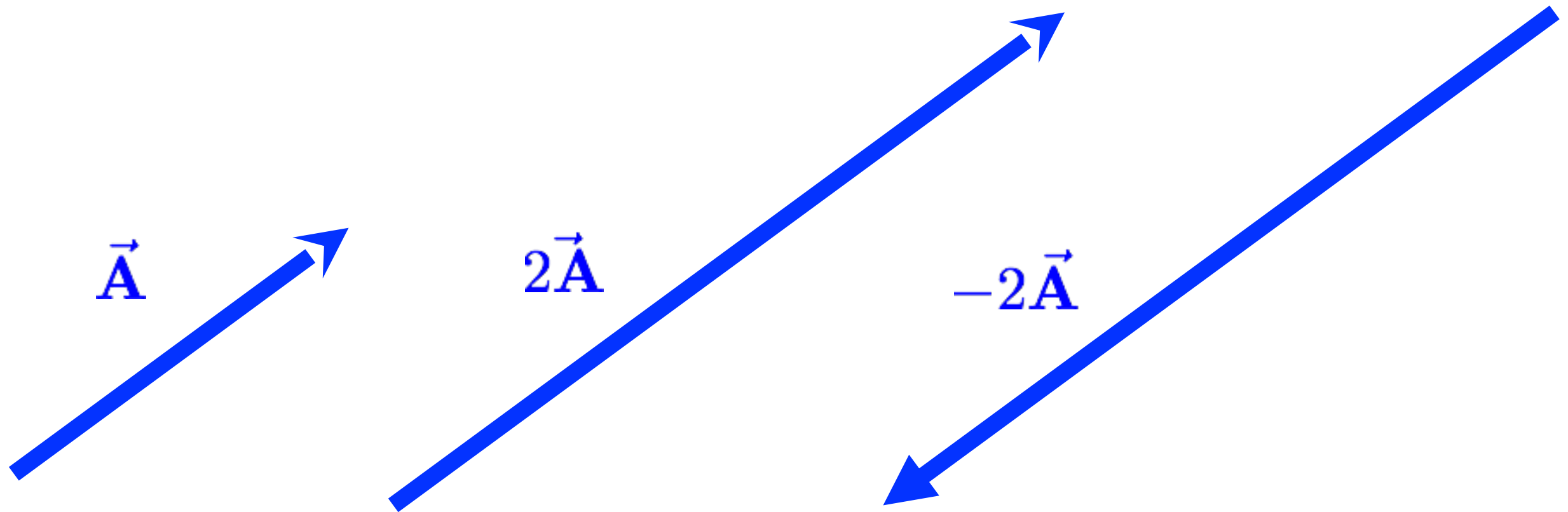


(c)

Vector subtraction



Vector scaling



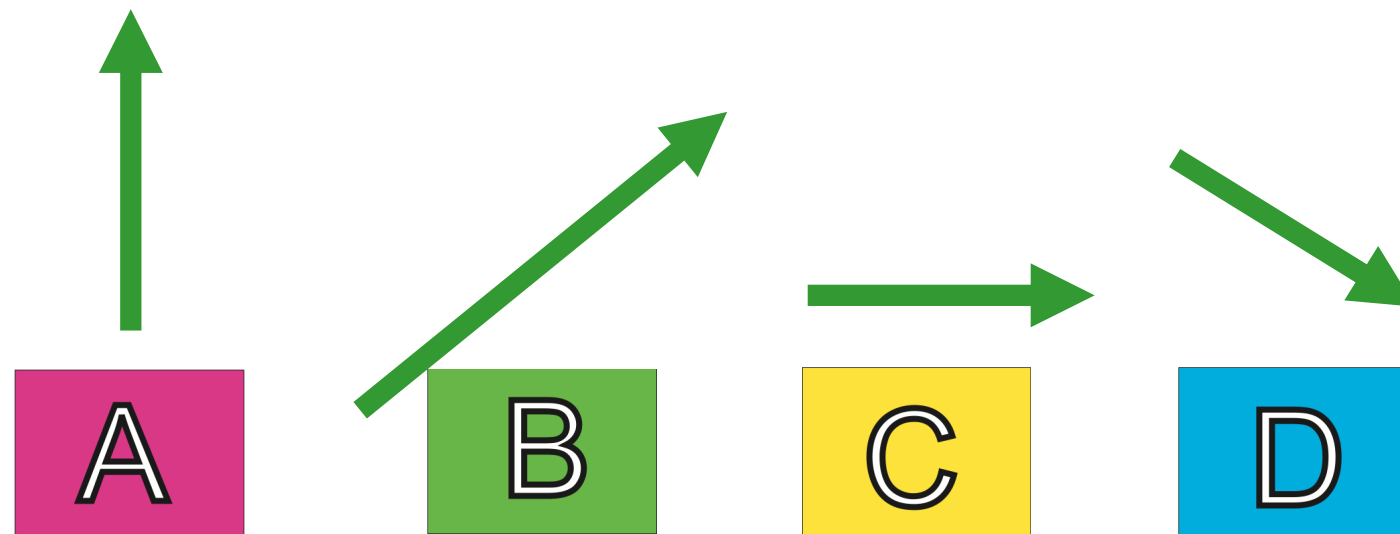
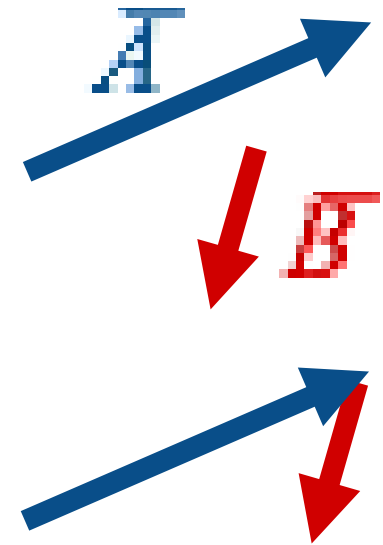
Scaling a vector
by a scalar
changes the
length

The direction
reverses also, if
the scalar is
negative

Clicker Question 1a



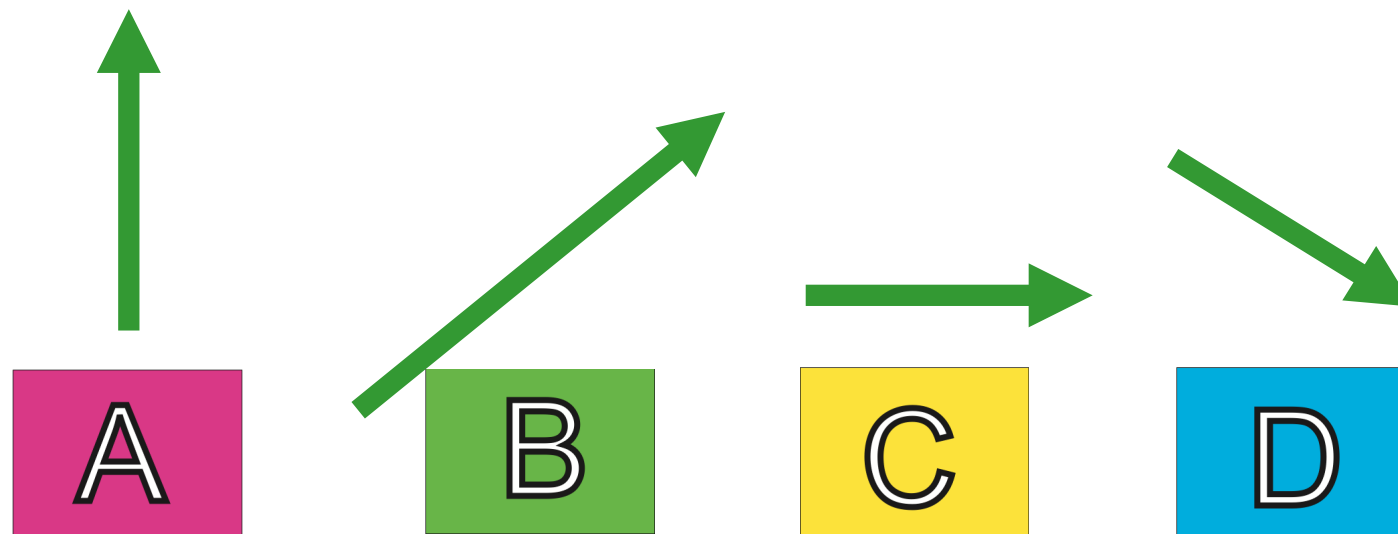
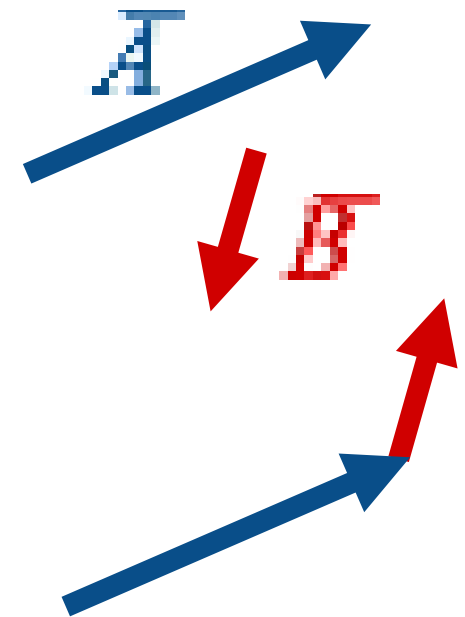
Vectors \vec{A} and \vec{B} are shown to the right.
Which of the following best describes $\vec{A} + \vec{B}$?



Clicker Question 1b



Vectors \vec{A} and \vec{B} are shown to the right.
Which of the following best describes $\vec{A} - \vec{B}$?



Clicker question #2

Question 3.1a Vectors I

If two vectors are given such that $\mathbf{A} + \mathbf{B} = 0$, what can you say about the magnitude and direction of vectors \mathbf{A} and \mathbf{B} ?



same magnitude, but can be in any direction



same magnitude, but must be in the same direction



different magnitudes, but must be in the same direction



same magnitude, but must be in opposite directions



different magnitudes, but must be in opposite directions

Clicker question #3

Question 3.1b Vectors II

Given that $\mathbf{A} + \mathbf{B} = \mathbf{C}$, and that $|\mathbf{A}|^2 + |\mathbf{B}|^2 = |\mathbf{C}|^2$, how are vectors \mathbf{A} and \mathbf{B} oriented with respect to each other?

- ☐ A they are perpendicular to each other
- ☐ B they are parallel and in the same direction
- ☐ C they are parallel but in the opposite direction
- ☐ D they are at 45° to each other
- ☐ they can be at any angle to each other

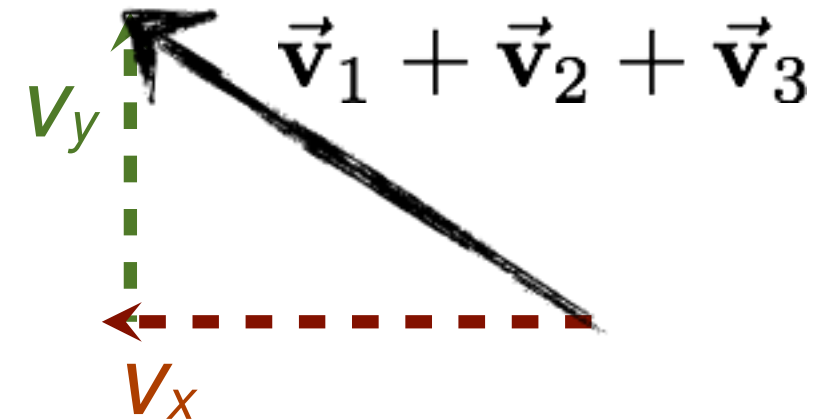
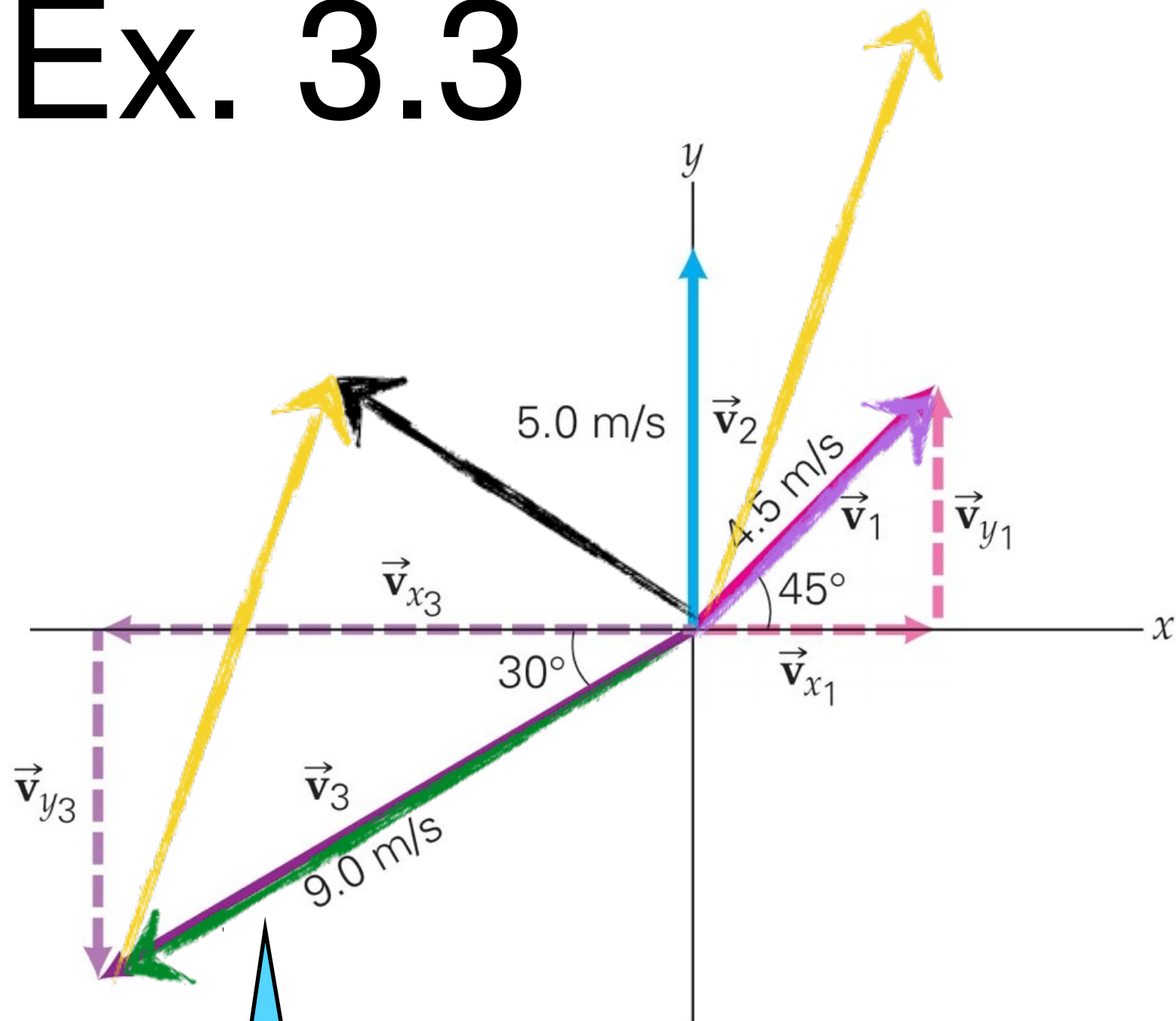
Clicker question #4

Question 3.3 Vector Addition

You are adding vectors of length **20** and **40** units. What is the only possible resultant magnitude that you can obtain out of the following choices?

- | | |
|---|-----|
| A | 0 |
| B | 18 |
| C | 37 |
| D | 64 |
| | 100 |

Ex. 3.3

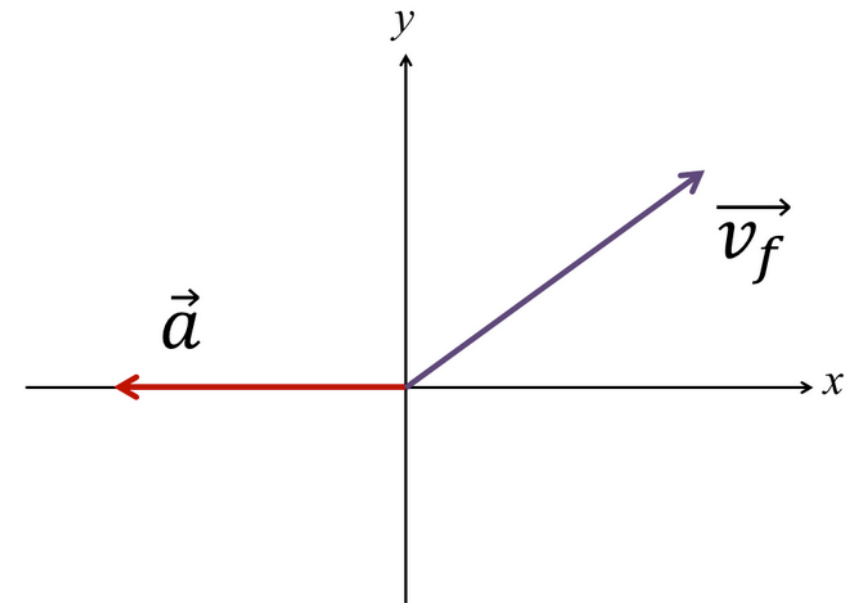


Graphically add the yellow and green vectors, compare with a partner next to you

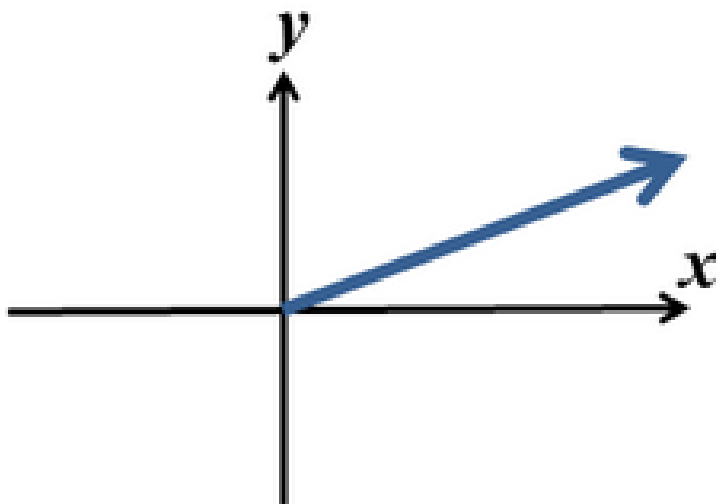
Clicker 5



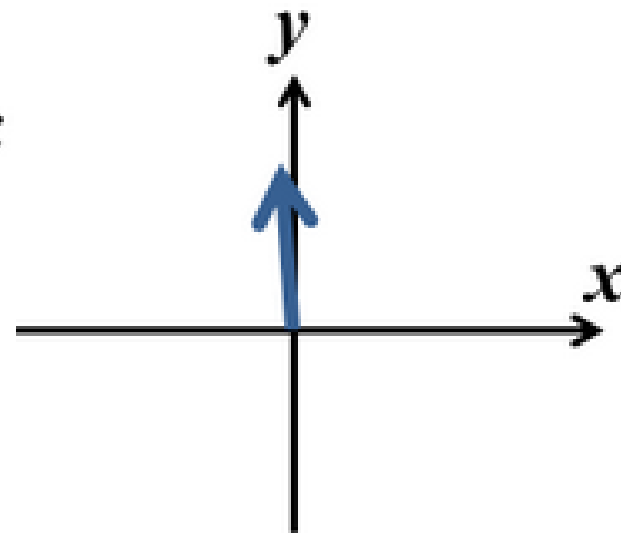
1. An object experiences a constant acceleration and attains a velocity as shown in the figure (right). Which of the following vectors best corresponds to the initial velocity of the object?



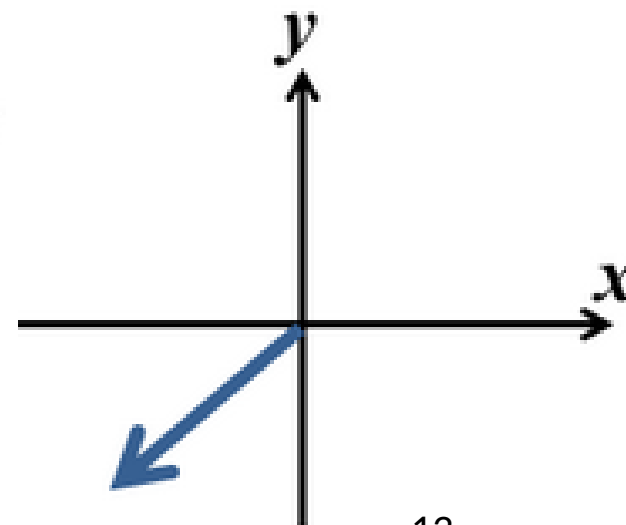
A



B

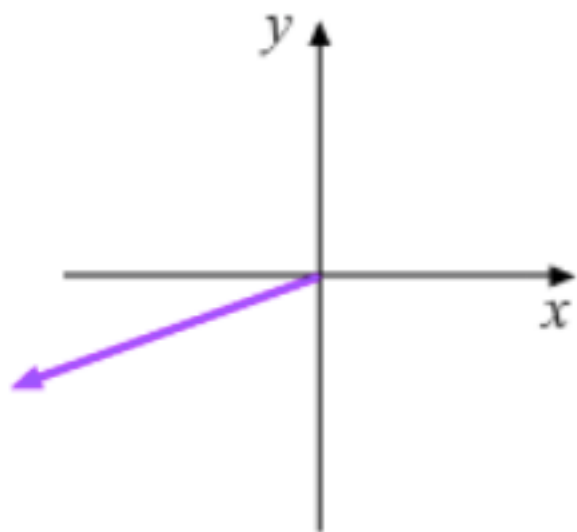
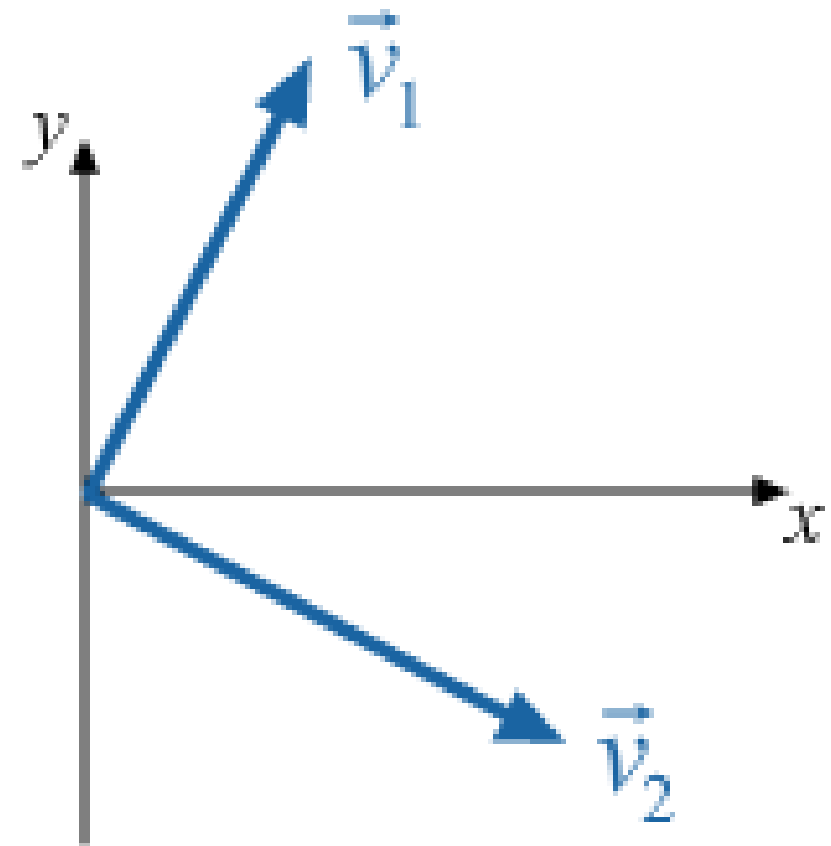


C

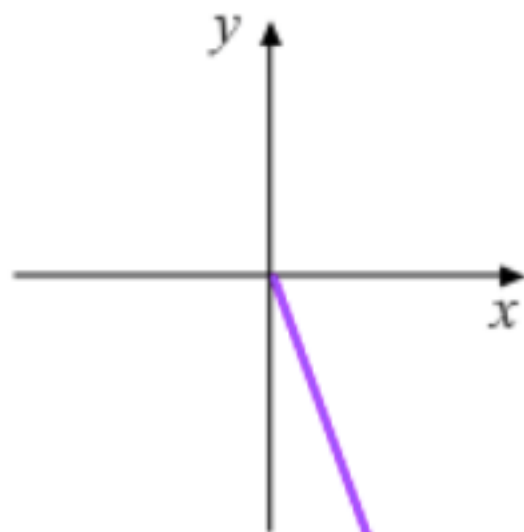


Clicker 6

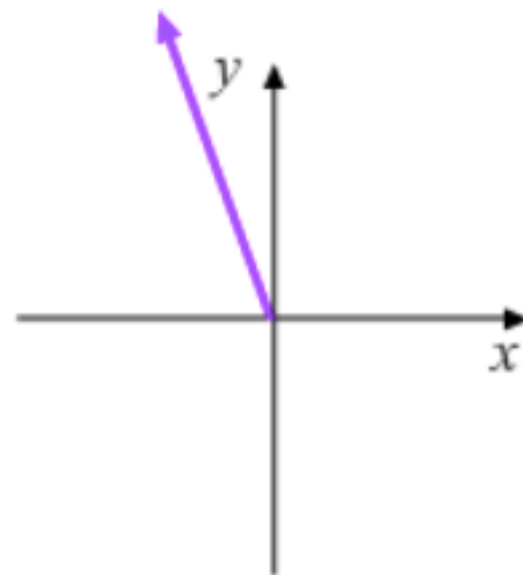
1. An object has velocity \vec{v}_1 at time $t=0$ and \vec{v}_2 at time $t=1$ s. Which of the following are the average acceleration?



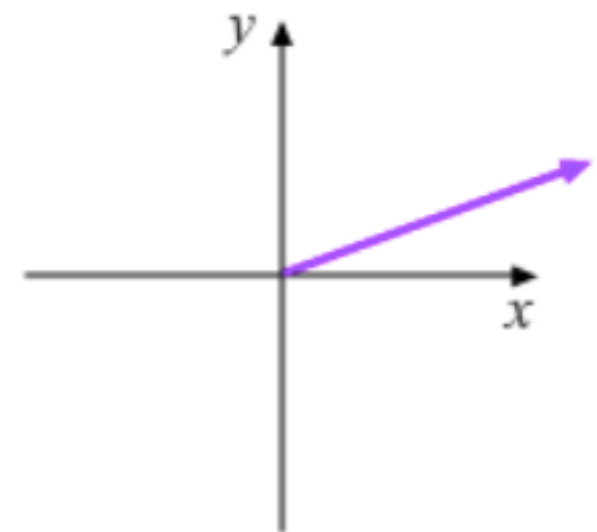
A



B



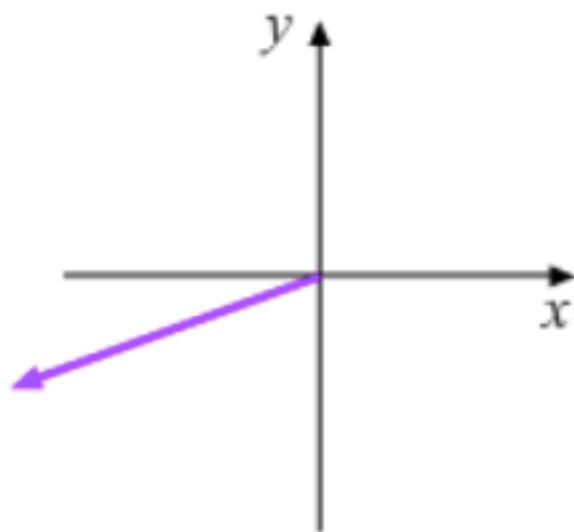
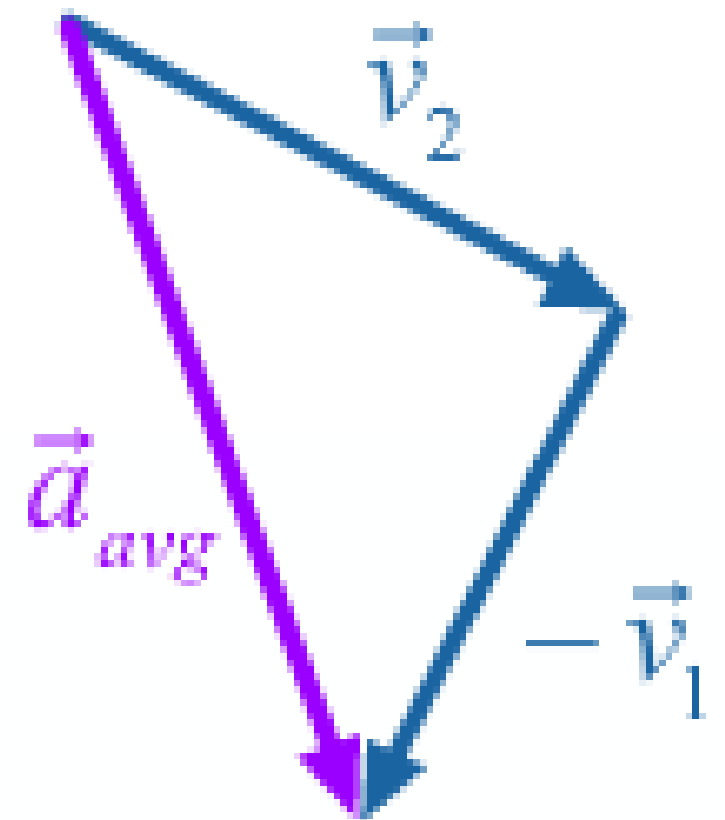
C



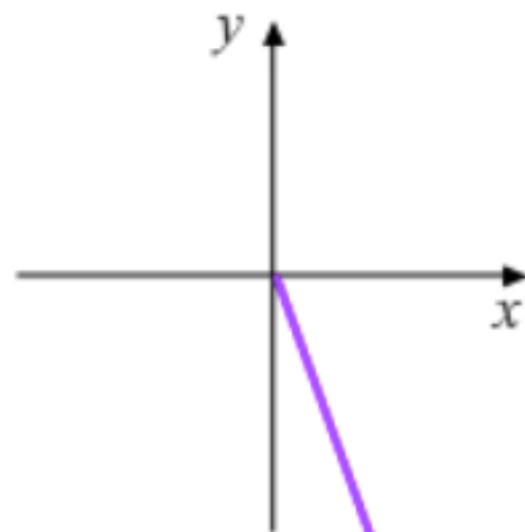
D

Clicker 6

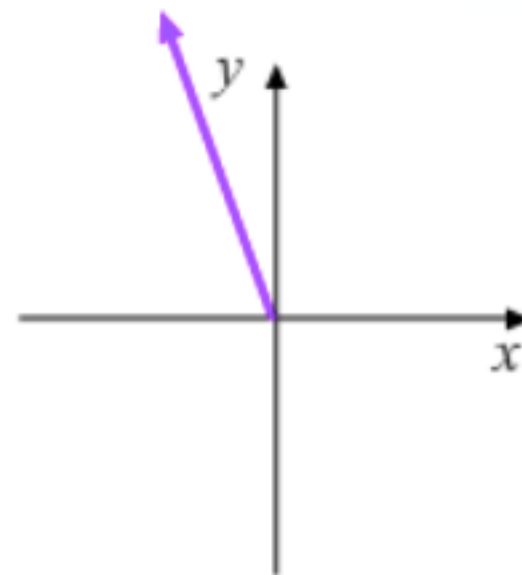
1. An object has velocity \vec{v}_1 at time $t=0$ and \vec{v}_2 at time $t=1$ s. Which of the following are the average acceleration?



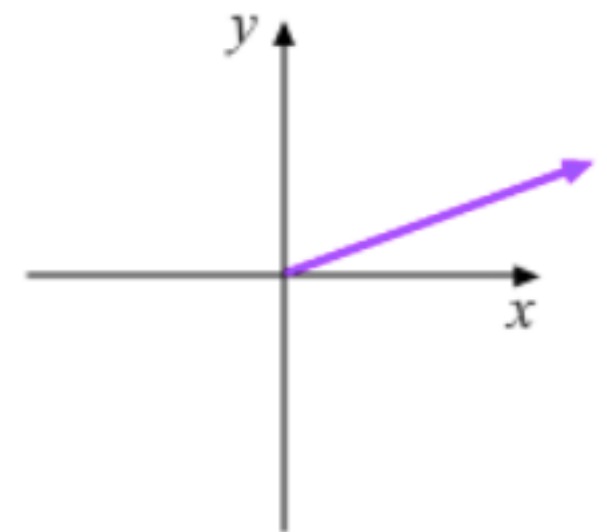
A



B

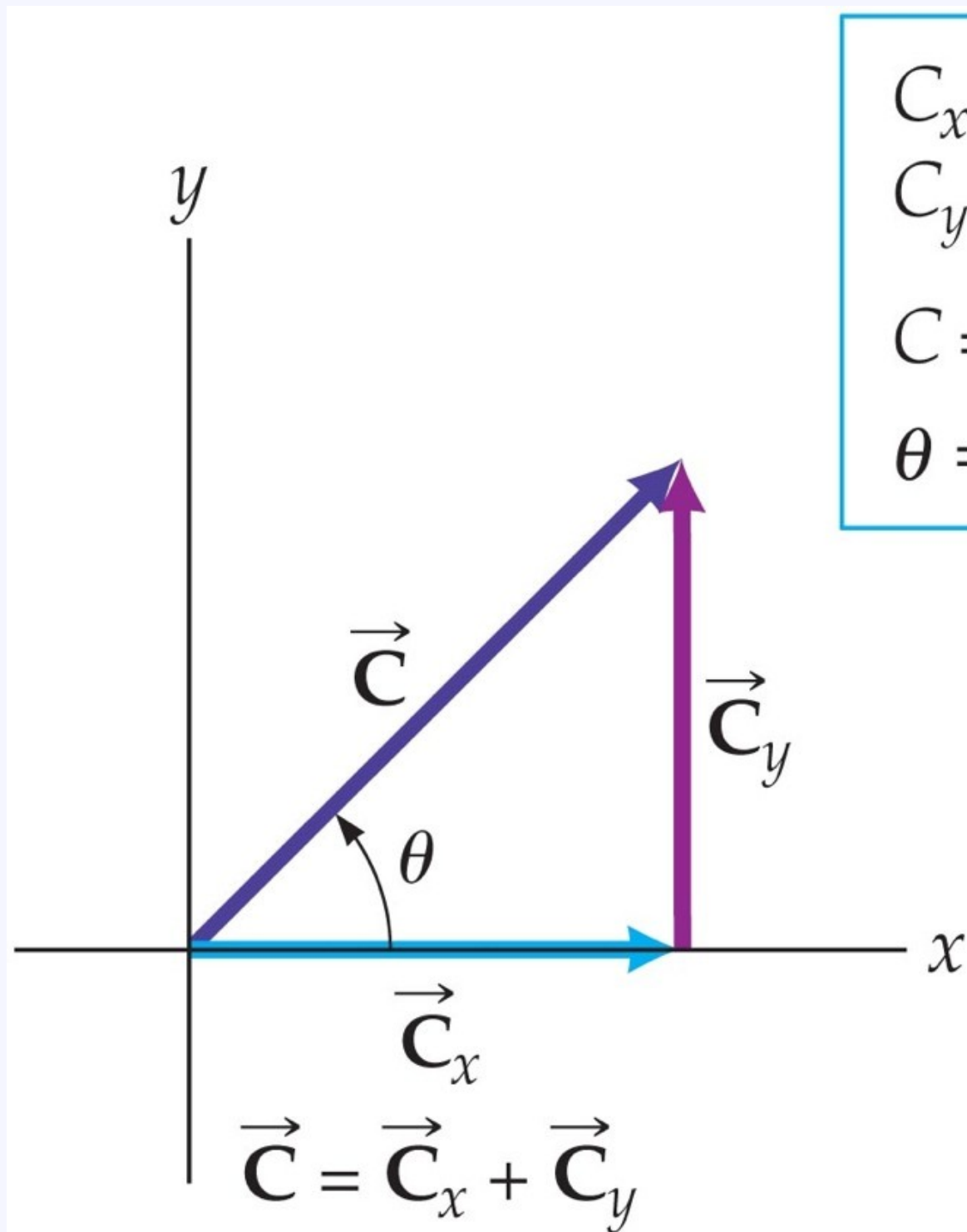


C



D

Vector components

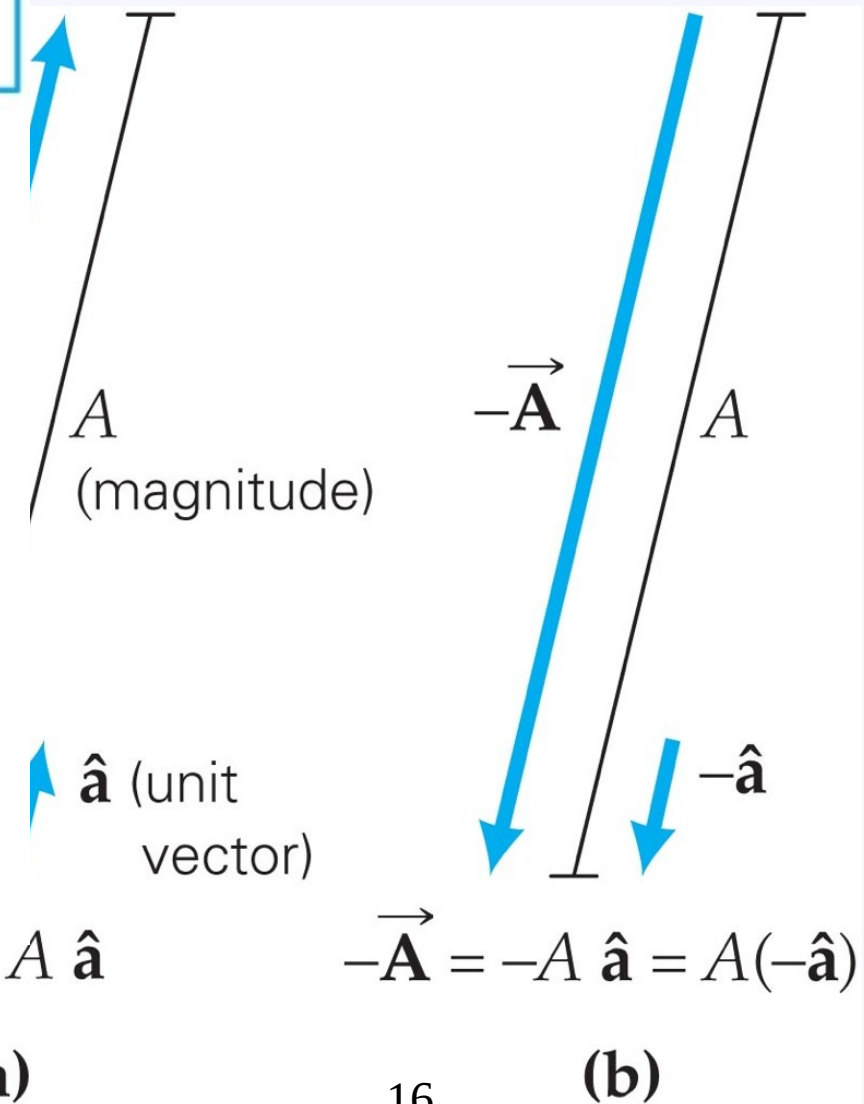


$$C_x = C \cos \theta$$

$$C_y = C \sin \theta$$

$$C = \sqrt{C_x^2 + C_y^2}$$

$$\theta = \tan^{-1} (C_y/C_x)$$



Clicker question #7

Question 3.2a

Vector Components I

If each component of a vector is doubled, what happens to the angle of that vector?

A

it doubles

B

it increases, but by less than double

C

it does not change

D

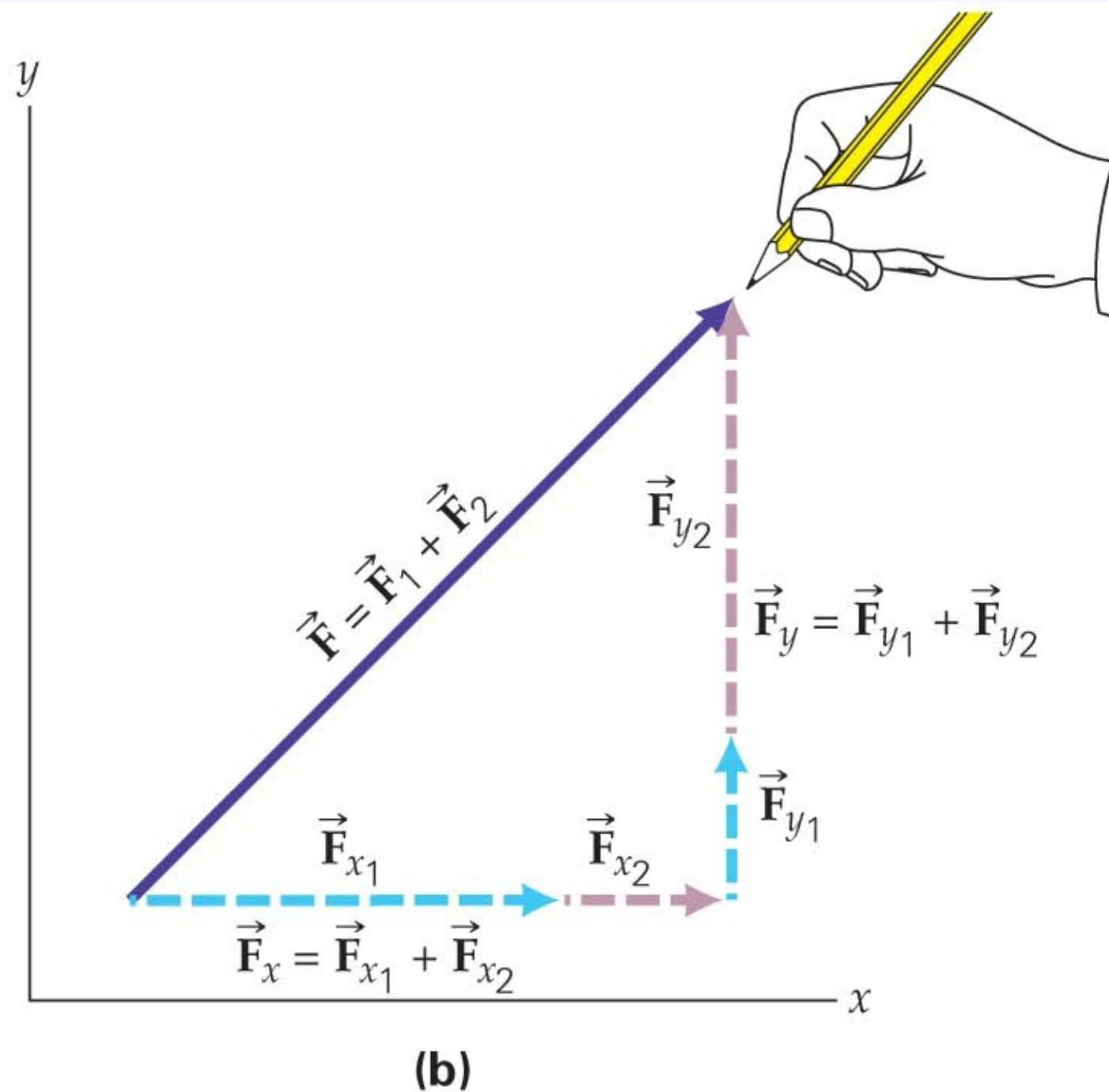
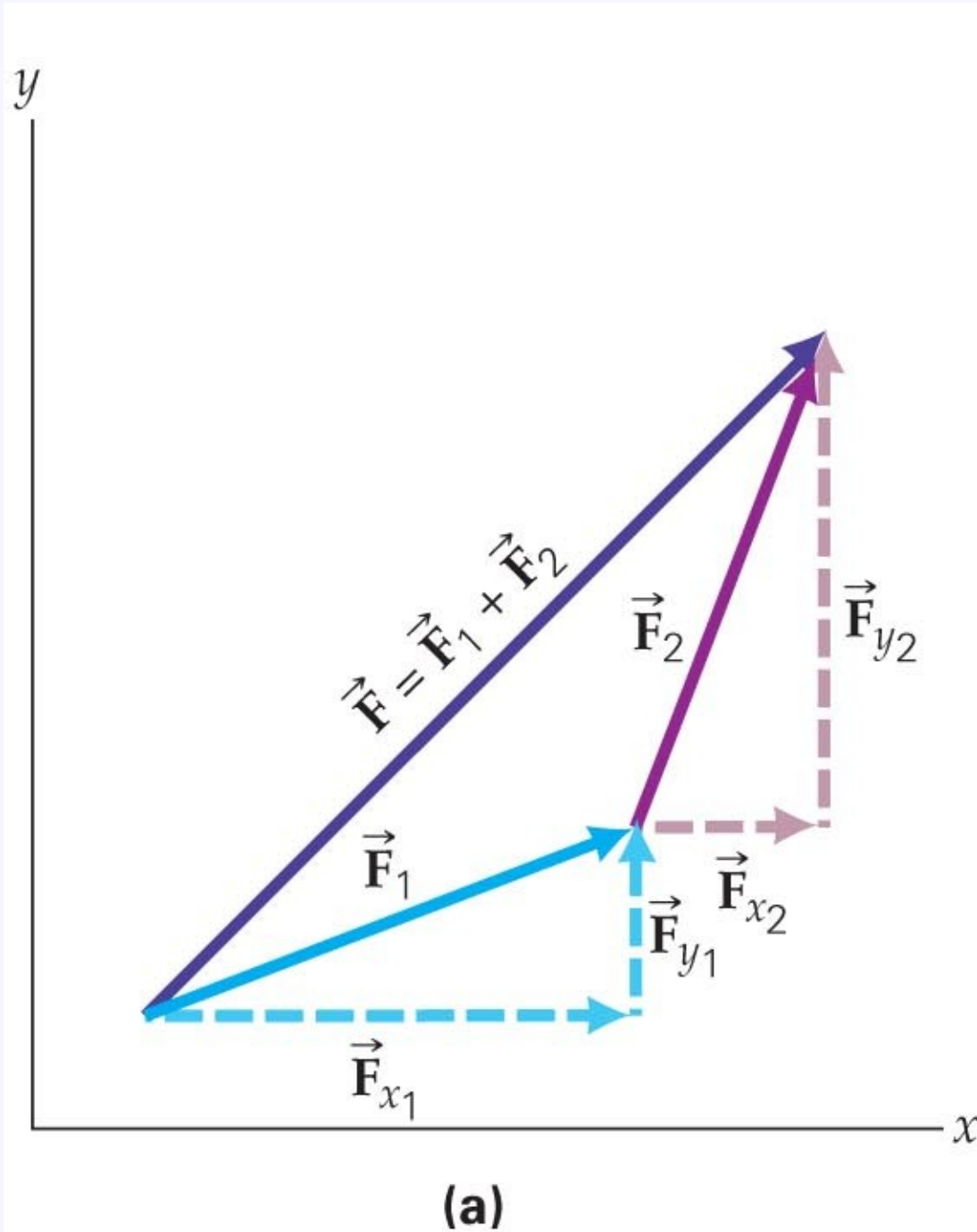
it is reduced by half



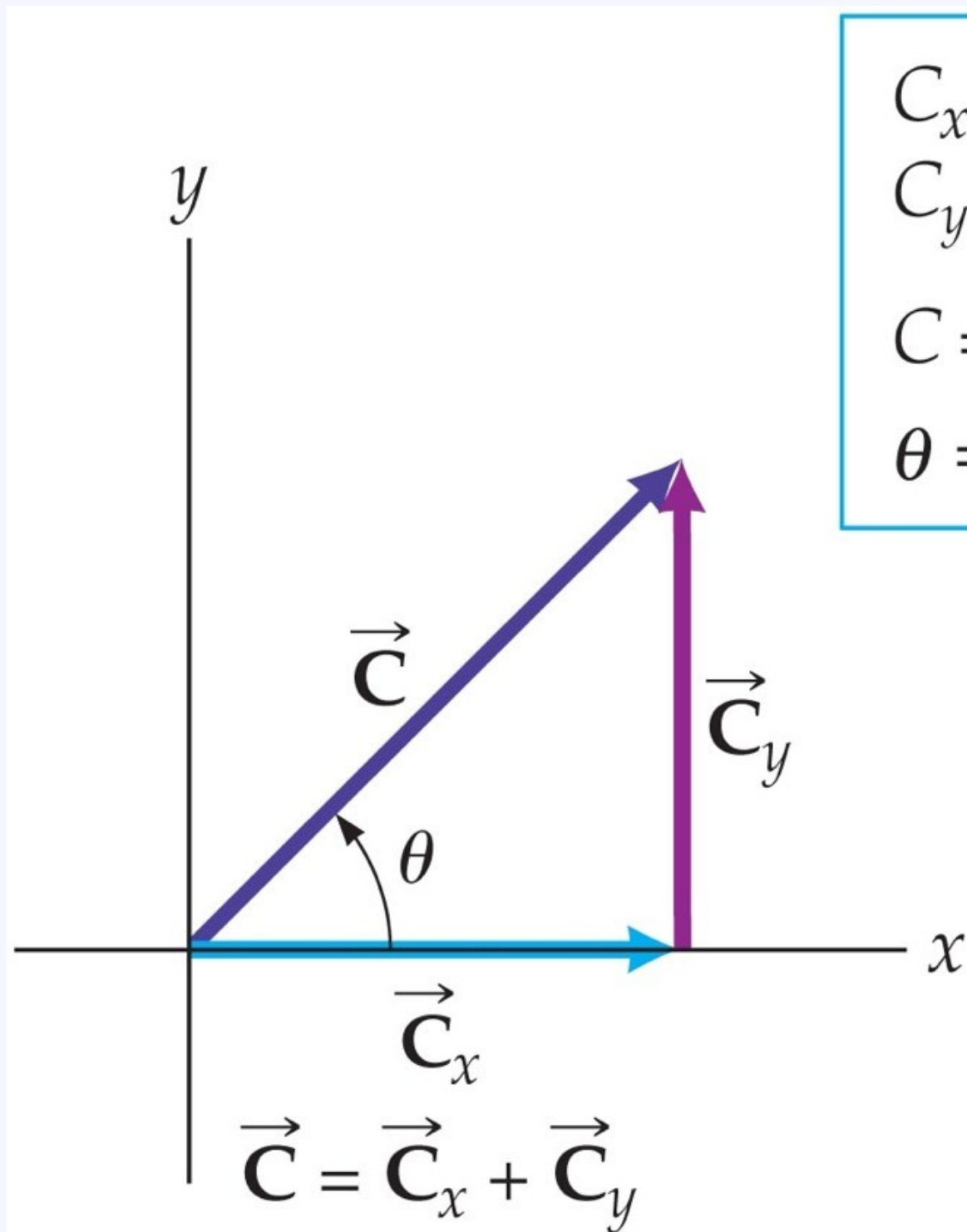
it decreases, but not as much as half

Add vectors by components

$$\vec{v}_1 + \vec{v}_2 = ([v_{x1} + v_{x2}])\hat{x} + ([v_{y1} + v_{y2}])\hat{y}$$



Vector components

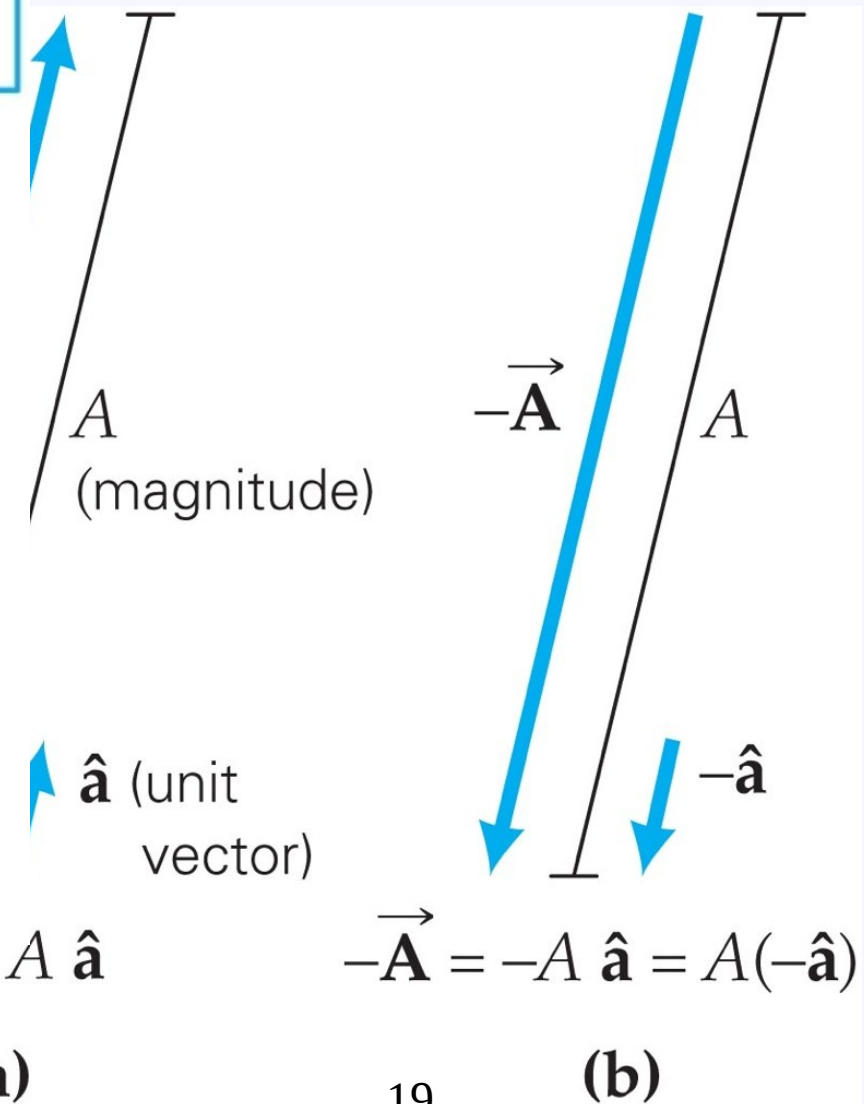


$$C_x = C \cos \theta$$

$$C_y = C \sin \theta$$

$$C = \sqrt{C_x^2 + C_y^2}$$

$$\theta = \tan^{-1} (C_y/C_x)$$



$$\vec{A} = A \hat{a}$$

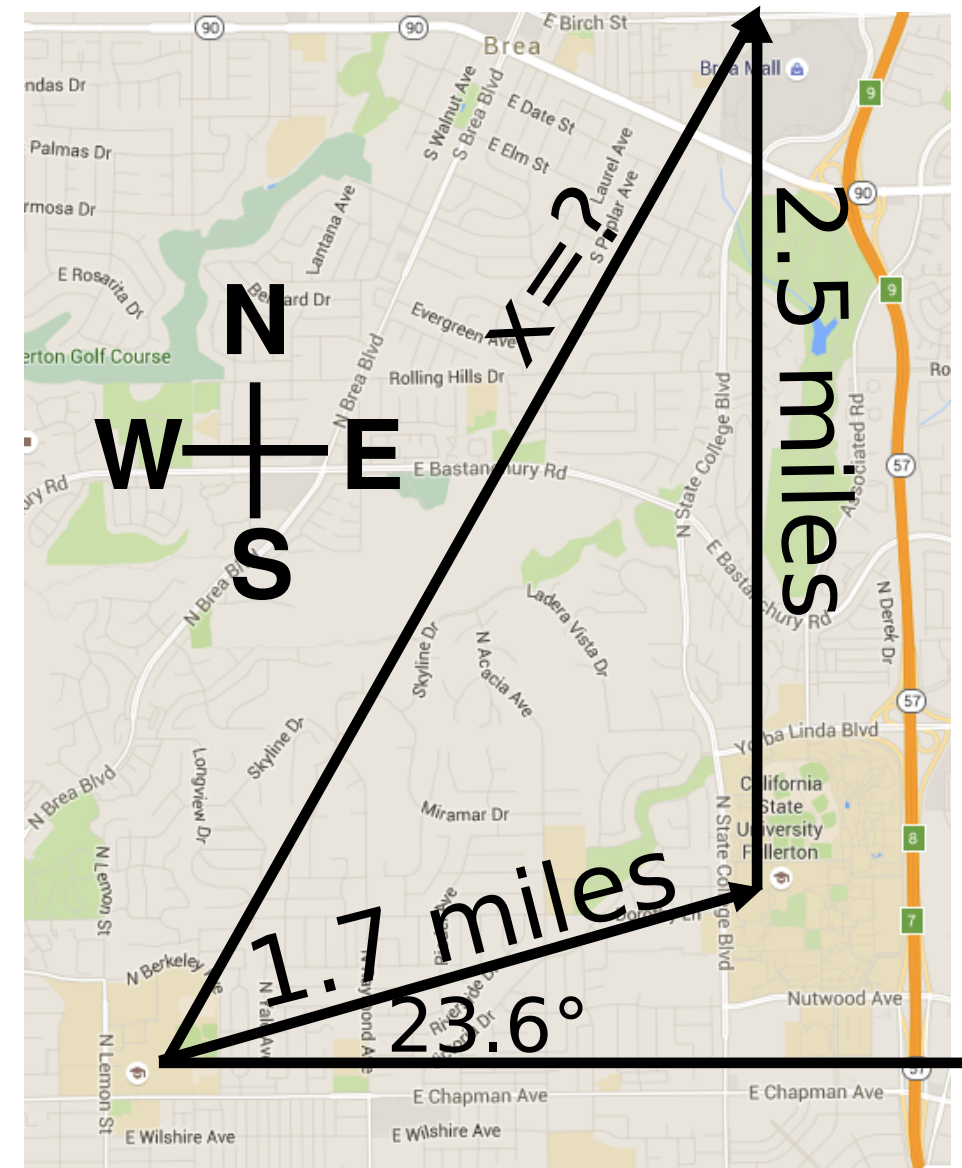
(a)

$$-\vec{A} = -A \hat{a} = A(-\hat{a})$$

(b)

Vector addition example

- Cal State Fullerton is 1.7 miles away from Fullerton College, at an angle 23.6° north of east. The Apple Store is 2.5 miles due north of Cal State Fullerton.
- A bird flies straight from Fullerton College to Cal State Fullerton, and then straight from Cal State Fullerton to the Apple Store. What is the bird's displacement?

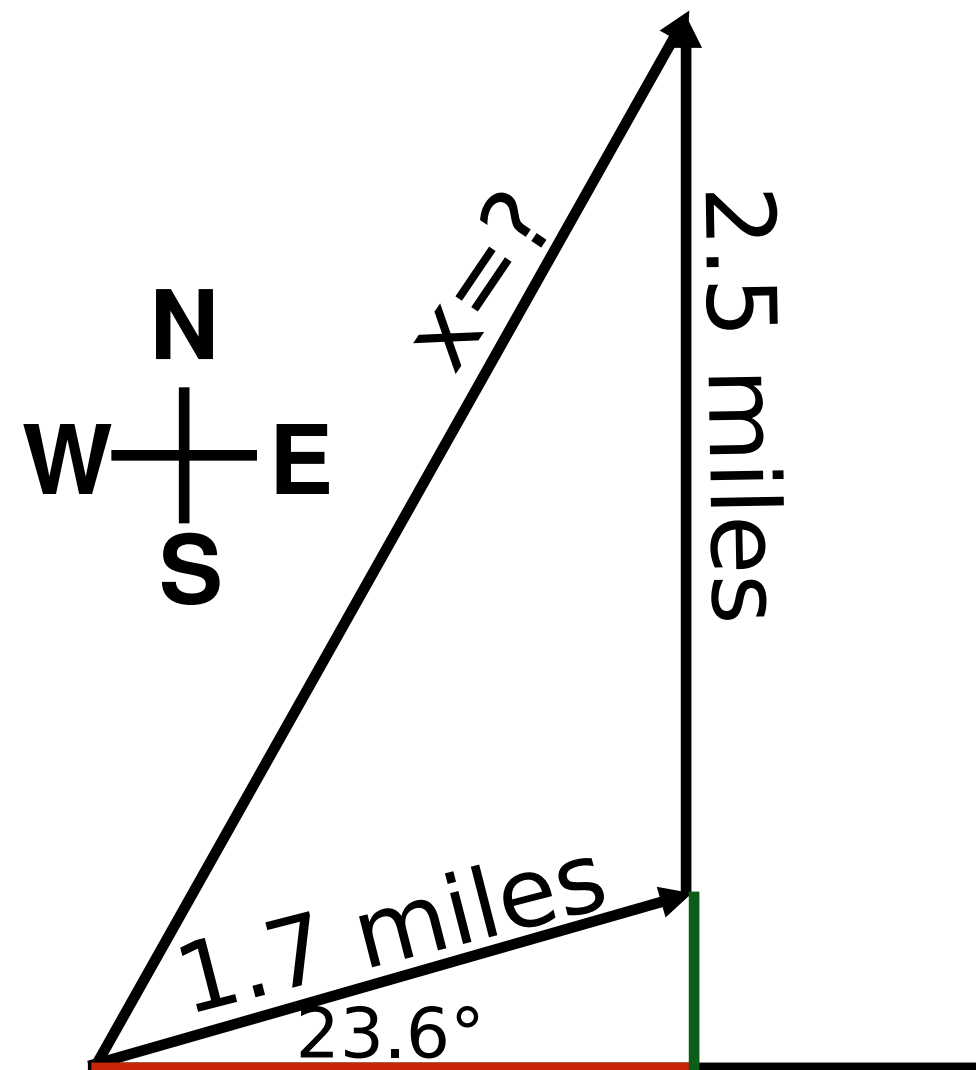


Vector addition example

- The black vector is the sum of a red vector (horizontal) and a green vector (vertical). Which way should the **red vector point**?



- A** Left
- B** Right
- C** Up
- D** Down
- ☐ None of ABCD

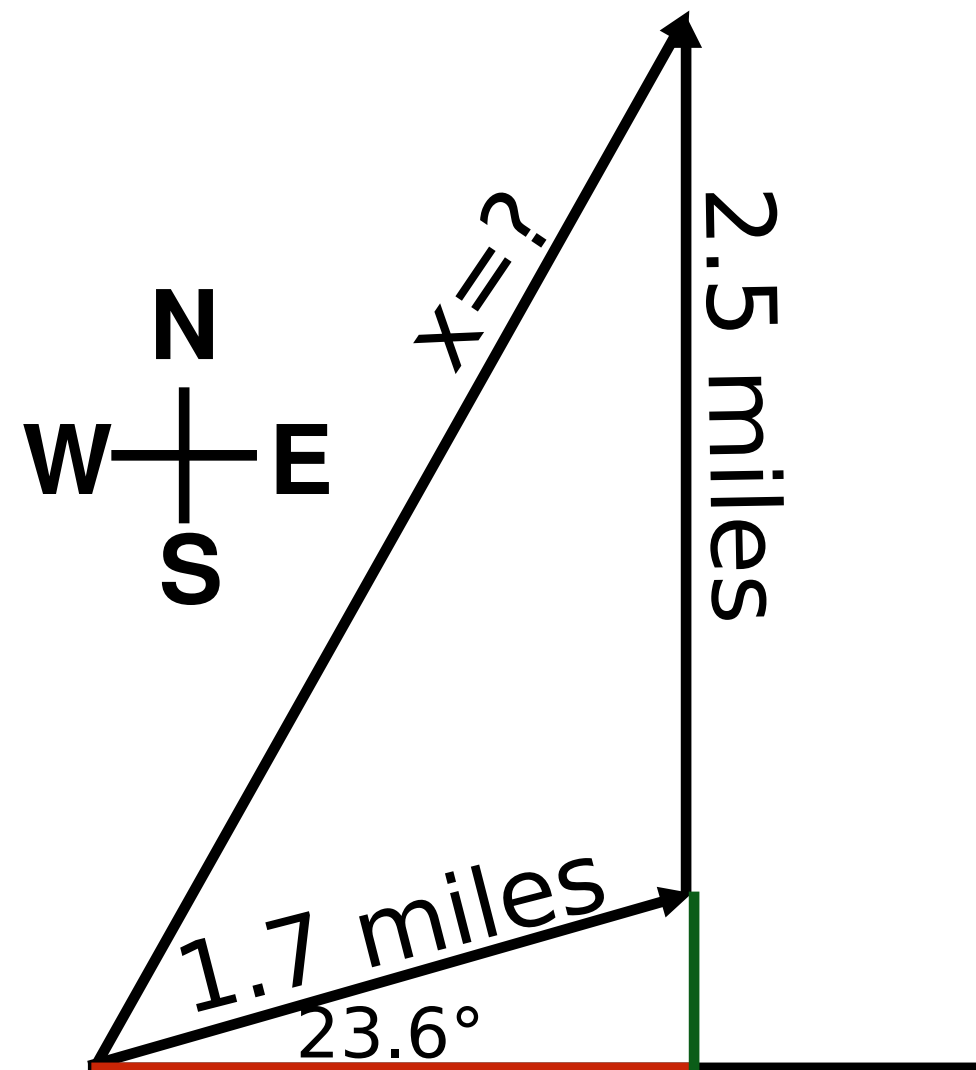


Vector addition example

- The black vector is the sum of a red vector (horizontal) and a green vector (vertical). Which way should the **green vector point**?



- A** Left
- B** Right
- C** Up
- D** Down
- None of ABCD



Vector addition example

- How long is the red arrow?



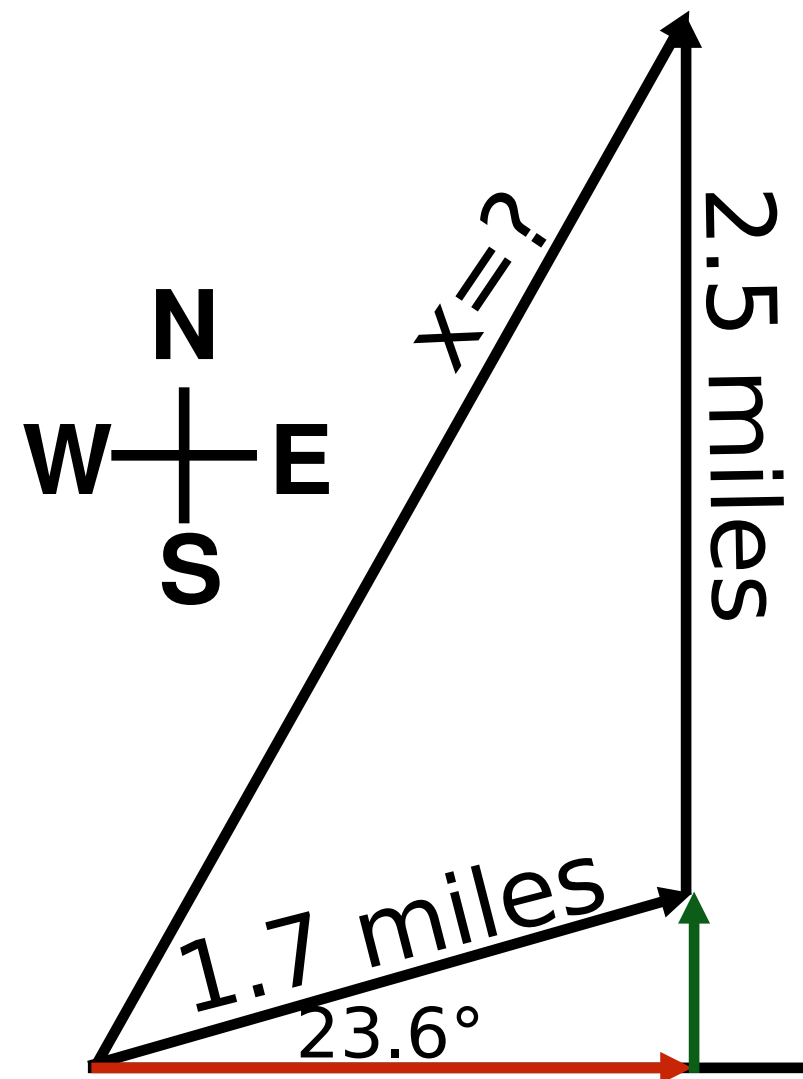
A $1.7 \text{ miles} \times \sin 23.6^\circ$

B $1.7 \text{ miles} \times \cos 23.6^\circ$

C $1.7 \text{ miles} \times \tan 23.6^\circ$

D 1.7 miles

None of ABCD



Vector addition example

- How long is the green arrow?



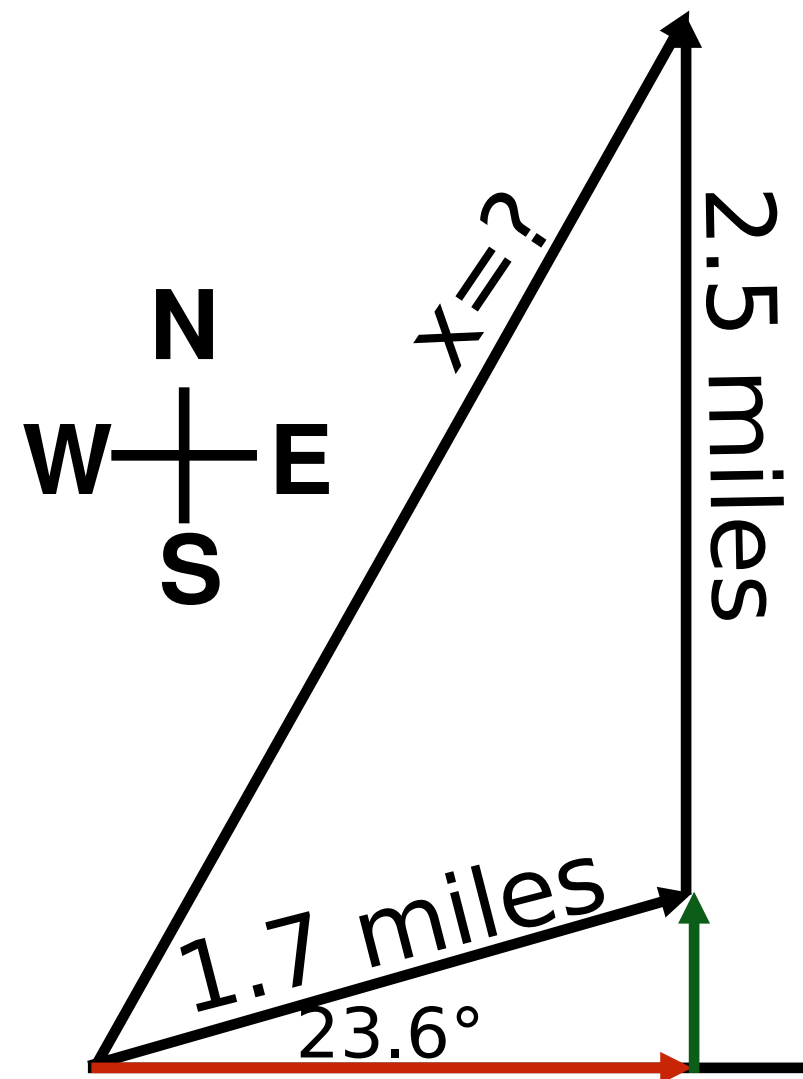
A $1.7 \text{ miles} \times \sin 23.6^\circ$

B $1.7 \text{ miles} \times \cos 23.6^\circ$

C $1.7 \text{ miles} \times \tan 23.6^\circ$

D 1.7 miles

None of ABCD



Vector addition example

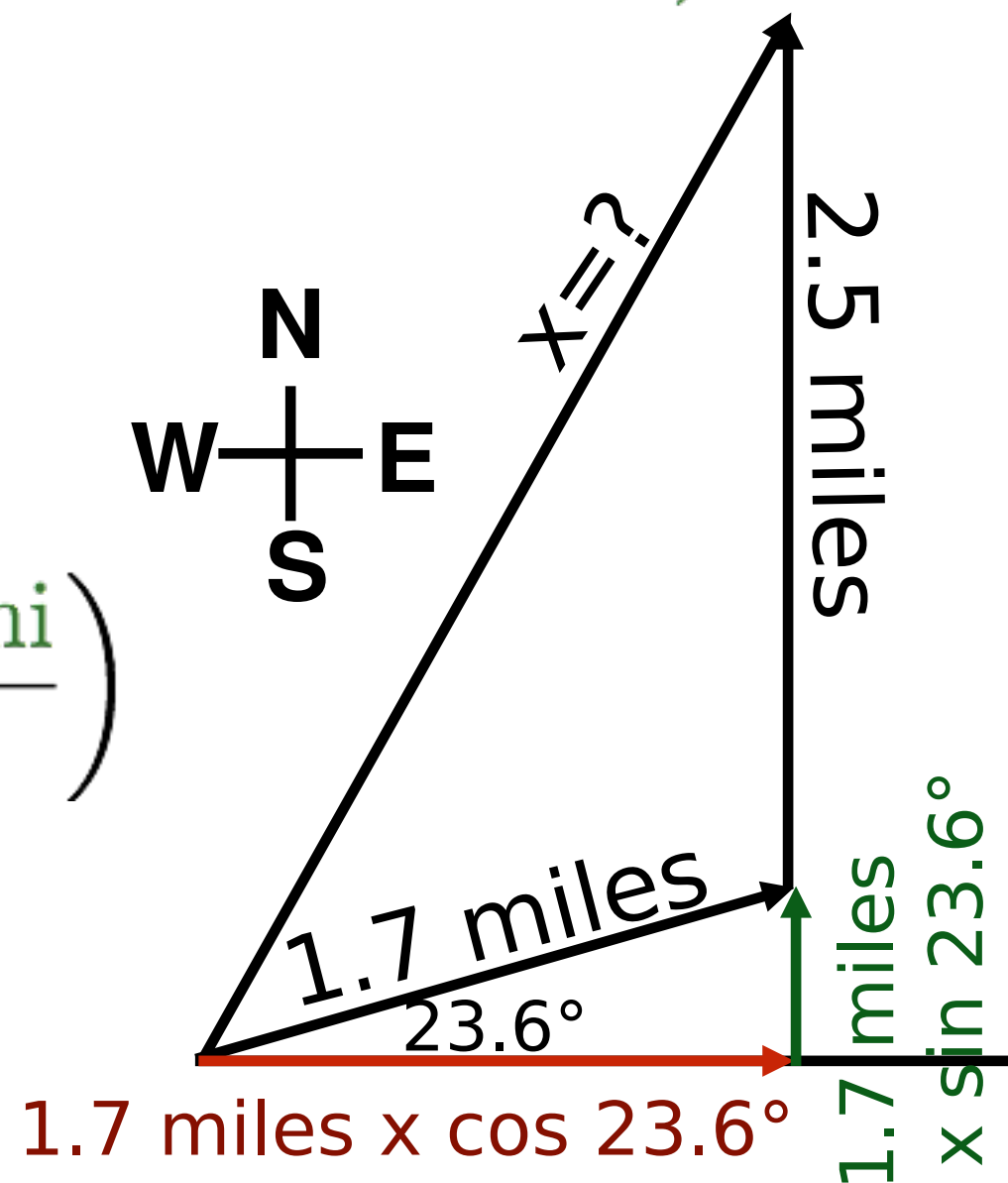
$$\mathbf{x} = (1.7\text{mi} \cos 23.6^\circ)\hat{\mathbf{x}} + (1.7\text{mi} \sin 23.6^\circ + 2.5 \text{ mi})\hat{\mathbf{y}}$$

Magnitude of displacement:

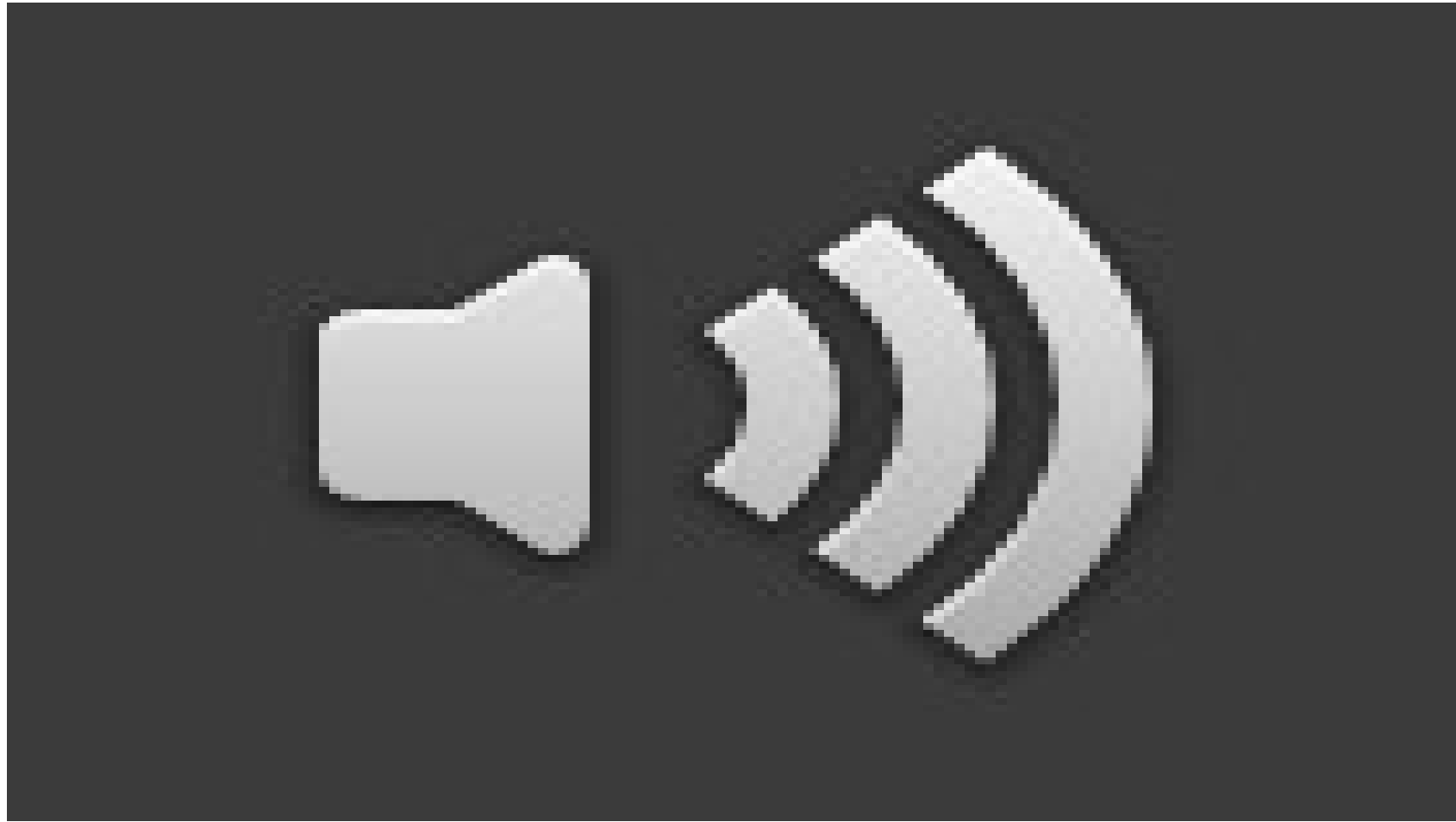
$$|\mathbf{x}| = \sqrt{(1.7\text{mi} \cos 23.6^\circ)^2 + (1.7\text{mi} \sin 23.6^\circ + 2.5 \text{ mi})^2}$$
$$= 3.5 \text{ mi}$$

Direction of displacement (angle counter-clockwise
= angle “north of east”:

$$\theta = \tan^{-1} \left(\frac{1.7 \text{ mi} \sin 23.6^\circ + 2.5 \text{ mi}}{1.7 \text{ mi} \cos 23.6^\circ} \right)$$
$$= 64^\circ$$

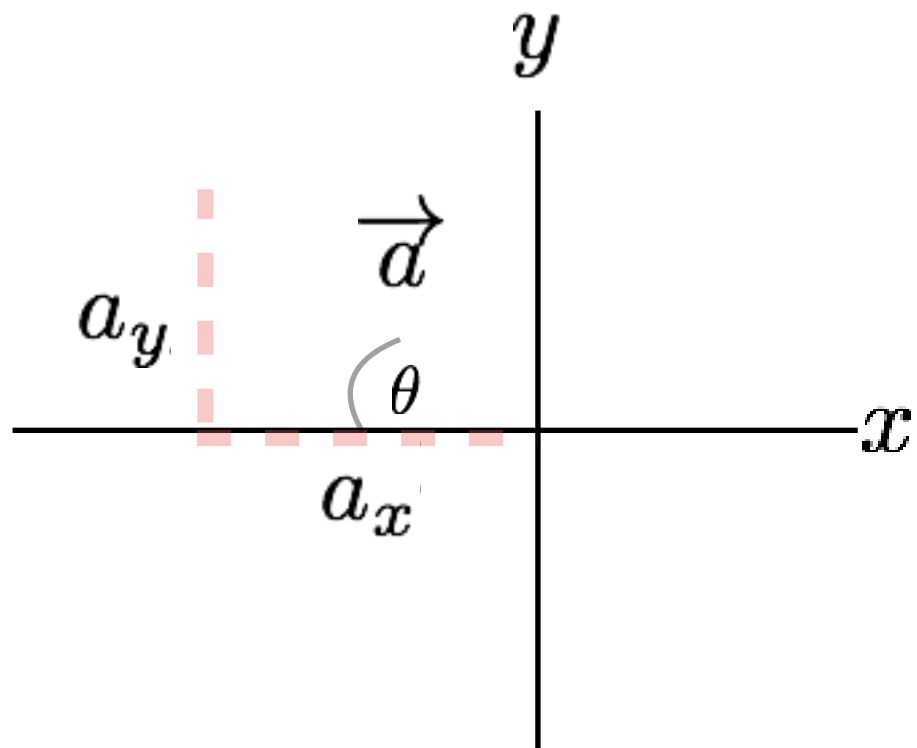


Next: Vector Multiplication & 2D Motion



- **Take Home Message** [reddit.com](https://www.reddit.com)
- There are **two ways** to multiply vectors!
 - Dot-product and Cross-product
- Vector components allow you to simplify 2D and 3D motion

Unit vectors and components



$$\vec{a} = a_x \hat{i} + a_y \hat{j}$$

Diagram illustrating the decomposition of a vector \vec{a} into its components. The equation $\vec{a} = a_x \hat{i} + a_y \hat{j}$ is shown. Arrows point from the terms to their classifications: \vec{a} is a vector, a_x is a scalar, \hat{i} is a unit vector, a_y is a scalar, and \hat{j} is a unit vector.

Unit vectors:

$$x, y, z \rightarrow \hat{i}, \hat{j}, \hat{k}$$

Components:

$$a_x = a \cos \theta$$
$$a_y = a \sin \theta$$

- A **unit** vector has a magnitude of 1
 - Its sole purpose is to point in a direction
- A vector **component** includes a scalar value and a unit vector

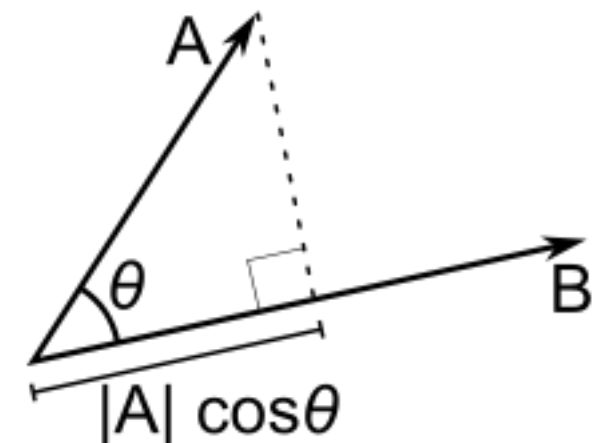
Vector multiplication

- Dot Product - creates a new **scalar**

$$\begin{aligned} \vec{a} \cdot \vec{b} &= (a_x \hat{i} + a_y \hat{y} + a_z \hat{k}) \cdot (b_x \hat{i} + b_y \hat{y} + b_z \hat{k}) \\ &= a_x b_x + a_y b_y + a_z b_z \end{aligned}$$

Diagram annotations: Red arrows point from the word "vector" to \vec{a} and \vec{b} . Blue arrows point from the word "scalar" to a_x , b_x , a_y , b_y , a_z , and b_z .

$$\vec{a} \cdot \vec{b} = |\vec{a}| |\vec{b}| \cos \theta$$



Vector multiplication

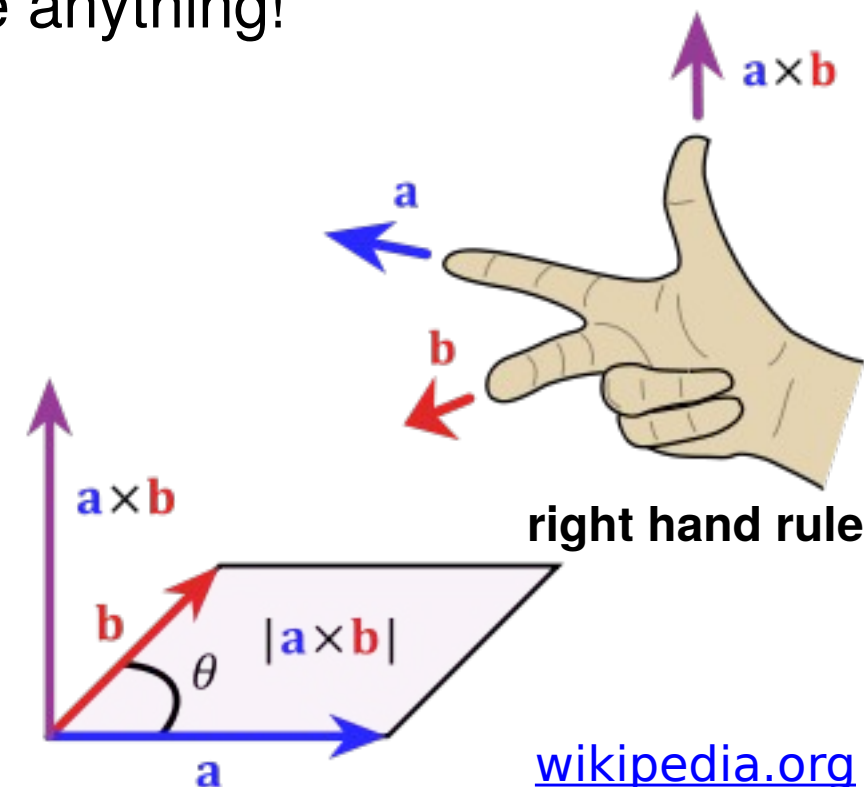
- Cross Product - creates a new **vector**

$$\begin{aligned}
 \vec{a} \times \vec{b} &= (a_x \hat{i} + a_y \hat{j} + a_z \hat{k}) \cdot (b_x \hat{i} + b_y \hat{j} + b_z \hat{k}) \\
 &= \underbrace{(a_y b_z - a_z b_y)}_{\text{vector component}} \hat{i} + \underbrace{(a_z b_x - a_x b_z)}_{\text{vector component}} \hat{j} + \underbrace{(a_x b_y - a_y b_x)}_{\text{vector component}} \hat{k}
 \end{aligned}$$

vector vector

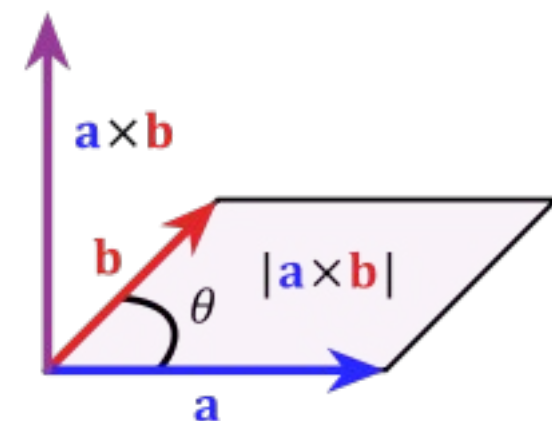
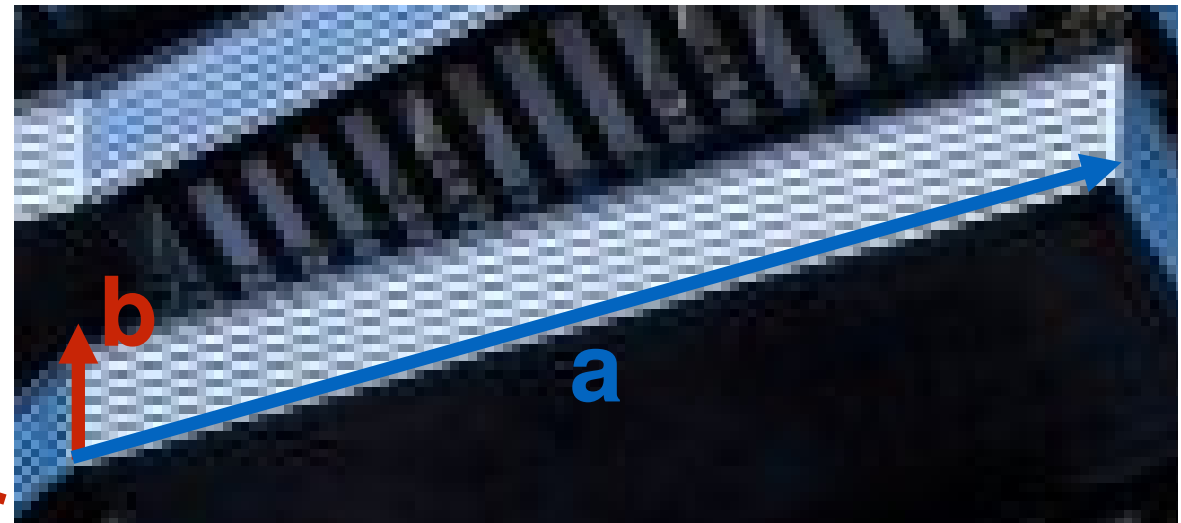
- umm... WHAT?!?! I thought we didn't have to memorize anything!
- you don't

$$\vec{a} \times \vec{b} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$



Vector multiplication

Why is the cross-product useful?



it help us define surfaces

$$\vec{a} = -3\hat{i} - 4\hat{j} + 5\hat{k} \text{ and } \vec{b} = -1\hat{i} + 4\hat{j} - 2\hat{k} \text{ and } \vec{c} = 3\hat{i} + 2\hat{j} - 5\hat{k}$$

1. Find: $\vec{a} \cdot (\vec{b} + \vec{c})$

2. Find: $\vec{a} \cdot (\vec{b} \times \vec{c})$

very similar to a HW problem

Next time...

- Vectors and 2D Motion

Due dates

- **Assignments**
 - Should have already read **Ch.3** of the book
 - **HW1** due friday at 11:45PM

extra slides

In-Class Example

Name _____

$$a = (-3, -4, 5) \quad b = (-1, 4, -2) \quad c = (3, 2, -5)$$

① $\underline{\vec{a} \cdot (\vec{b} + \vec{c})}$

$$\text{start w } (\vec{b} + \vec{c}) = (-1+3, 4+2, -2-5) = (2, 6, -7)$$

$$\vec{a} \cdot (\vec{b} + \vec{c}) = (-3, -4, 5) \cdot (2, 6, -7) = -6 - 24 - 35 = \boxed{-65}$$

② $\underline{\vec{a} \cdot (\vec{b} \times \vec{c})}$

$$\begin{aligned} \text{start w } (\vec{b} \times \vec{c}) &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & 4 & -2 \\ 3 & 2 & -5 \end{vmatrix} \begin{matrix} i & j \\ -1 & 4 \\ 3 & 2 \end{matrix} = (-20)\hat{i} + (-6)\hat{j} + (-2)\hat{k} \\ &\quad - (5)\hat{j} - (-4)\hat{i} - (12)\hat{k} \\ &= (-20+4)\hat{i} + (-6-5)\hat{j} + (-2-12)\hat{k} \\ &= (-16, -11, -14) \end{aligned}$$

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = (-3, -4, 5) \cdot (-16, -11, -14)$$

$$= 48 + 44 - 70 = \boxed{22}$$

Reminder - Vector multiplication

- Dot Product - creates a new **scalar**

$$\begin{aligned} \vec{a} \cdot \vec{b} &= (a_x \hat{i} + a_y \hat{j} + a_z \hat{k}) \cdot (b_x \hat{i} + b_y \hat{j} + b_z \hat{k}) \\ &= a_x b_x + a_y b_y + a_z b_z \end{aligned}$$

Diagram labels: Red arrows point from the word "vector" to \vec{a} and \vec{b} . Blue arrows point from the word "scalar" to a_x , b_x , a_y , b_y , a_z , and b_z .

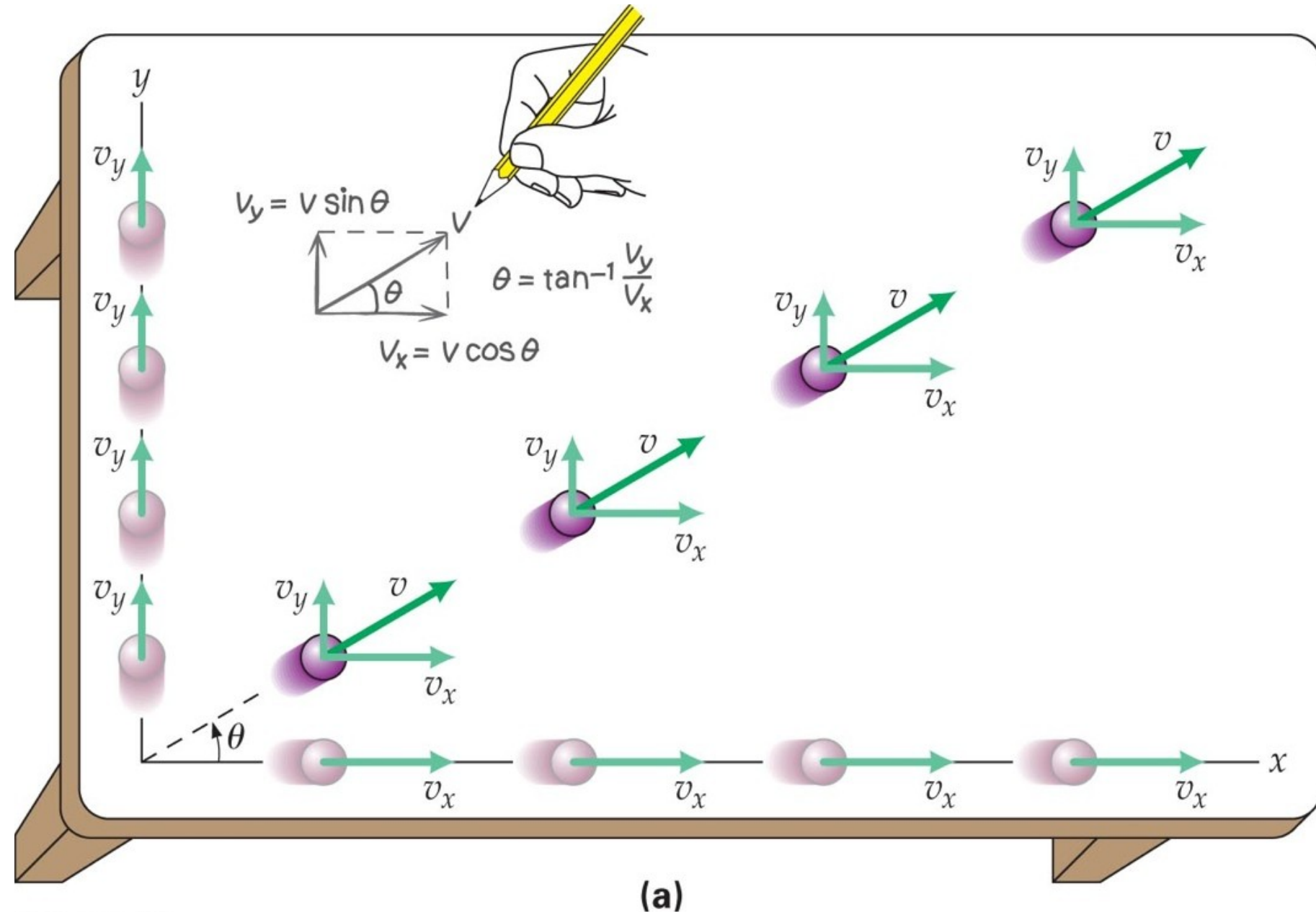
- Cross Product - creates a new **vector**

$$\begin{aligned} \vec{a} \times \vec{b} &= (a_x \hat{i} + a_y \hat{j} + a_z \hat{k}) \cdot (b_x \hat{i} + b_y \hat{j} + b_z \hat{k}) \\ &= \underbrace{(a_y b_z - a_z b_y)}_{\text{vector component}} \hat{i} + \underbrace{(a_z b_x - a_x b_z)}_{\text{vector component}} \hat{j} + \underbrace{(a_x b_y - a_y b_x)}_{\text{vector component}} \hat{k} \end{aligned}$$

Diagram labels: Red arrows point from the word "vector" to \vec{a} and \vec{b} . Red arrows point from the word "vector component" to each of the three bracketed terms in the second equation.

Motion in 2 dimensions

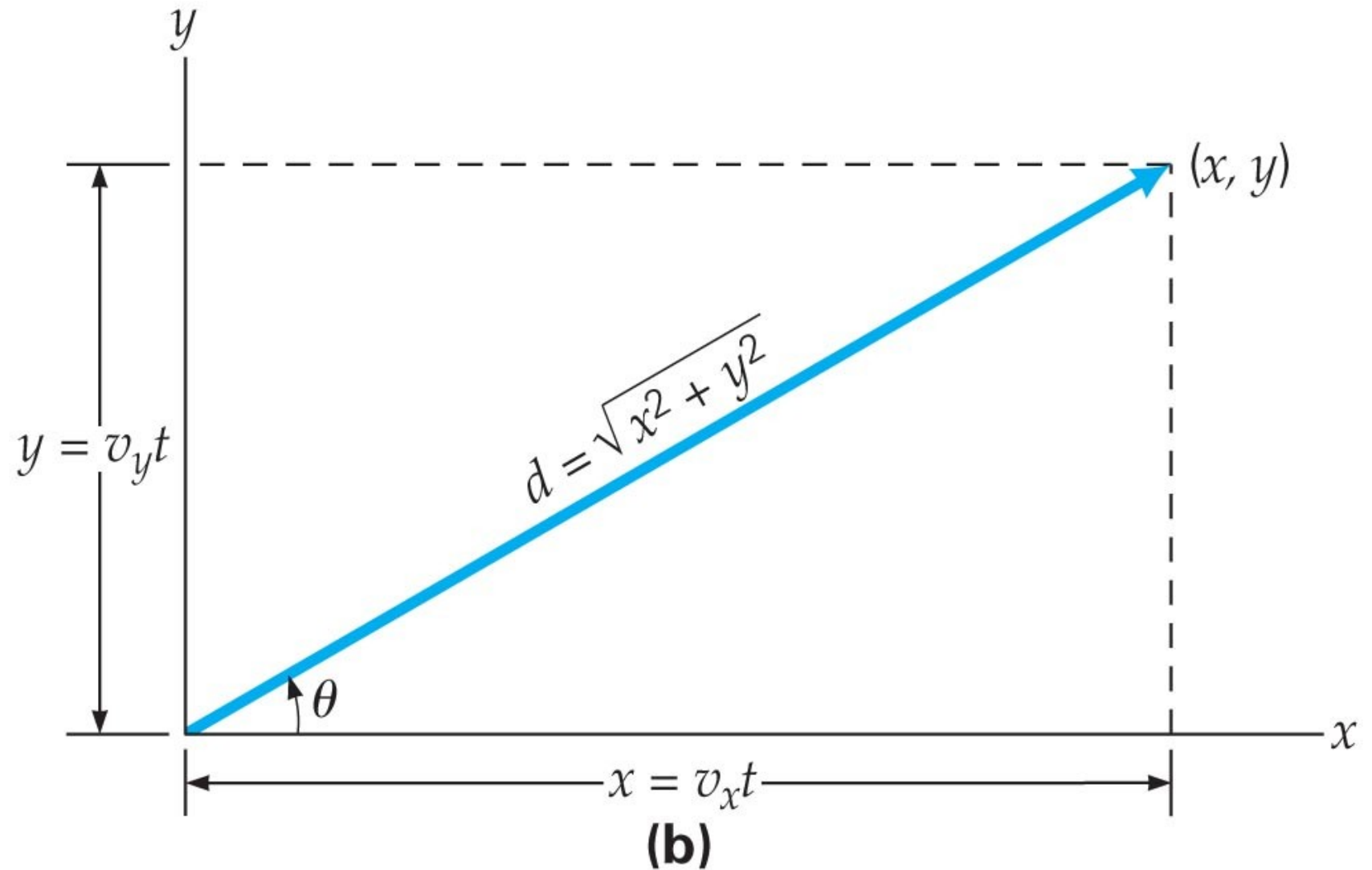
- Horizontal & vertical motion *independent*
 - Break vectors into components
 - Treat each component separately



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Motion in 2 dimensions

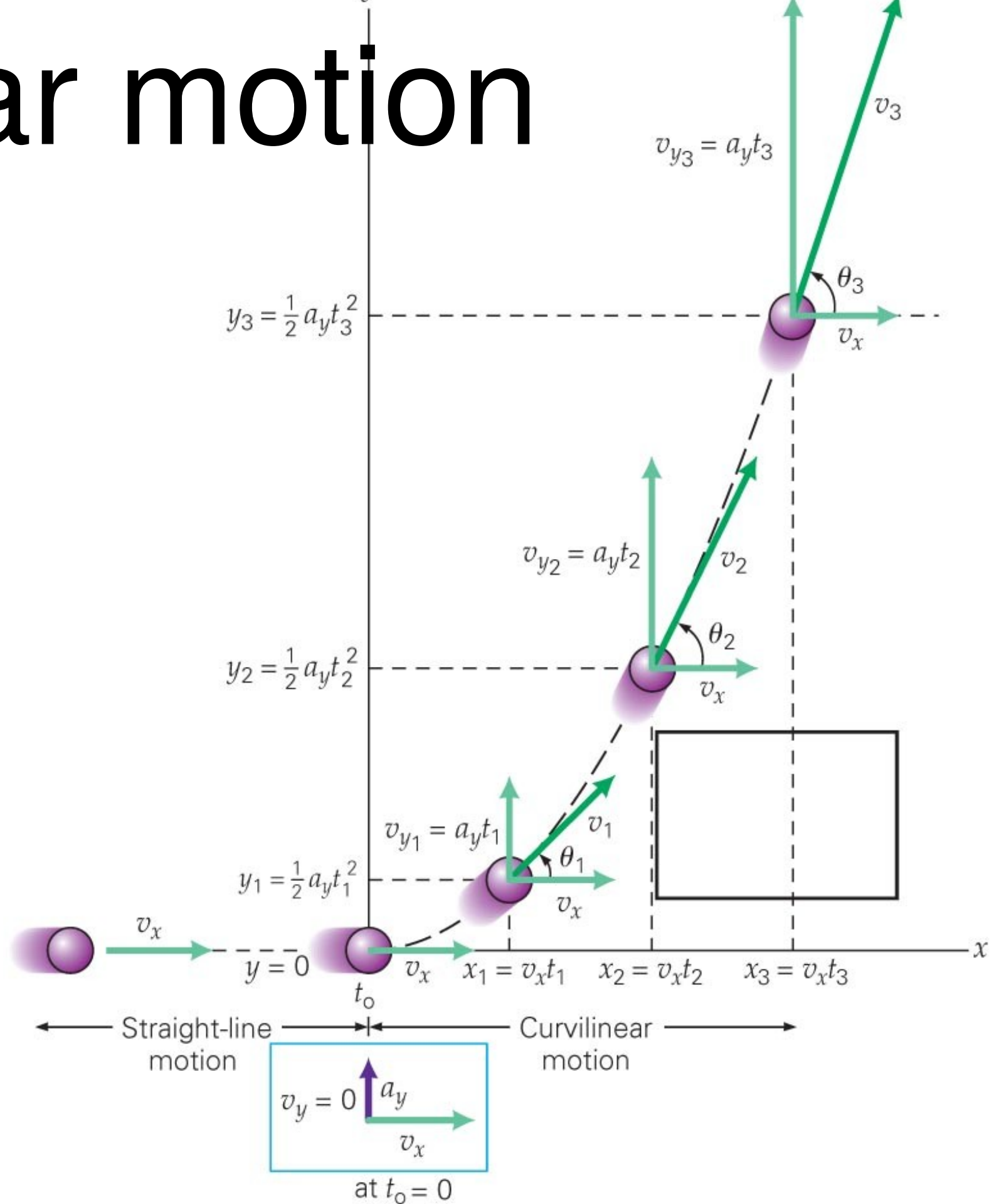
- Horizontal & vertical motion *independent*
 - Break vectors into components
 - Treat each component separately



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Curvilinear motion

- If velocity, acceleration not parallel, then motion is along a curve (“curvilinear motion”)

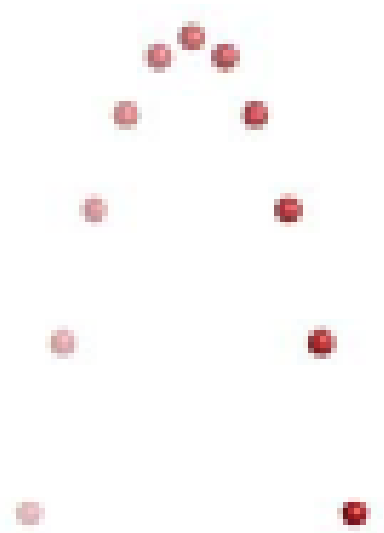




Main Points – Projectile Motion

Projectile motion is the superposition of two independent motions:

- 1) **Horizontal:** constant velocity
- 2) **Vertical:** constant acceleration

Projectile motion can be understood simply as free fall viewed from a moving reference frame.

<p>Projectile Motion</p> 	=	<p>Vertical Motion with Constant Acceleration</p> 	+	<p>Horizontal Motion with Constant Velocity</p> 
<p>Acceleration of Gravity</p> $g = +9.8 \frac{\text{m}}{\text{s}^2}$		$a_y = -g$ $v_y = v_{iy} - gt$ $y = y_o + v_{iy}t - \frac{1}{2}gt^2$		$a_x = 0$ $v_x = v_{ix}$ $x = x_o + v_{ix}t$

Projectile Motion

Horizontal

$$a_x = 0$$

$$v_x = v_{ox}$$

$$x = x_o + v_{ox} t$$

Vertical

$$a_y = -g$$

$$v_y = v_{oy} - gt$$

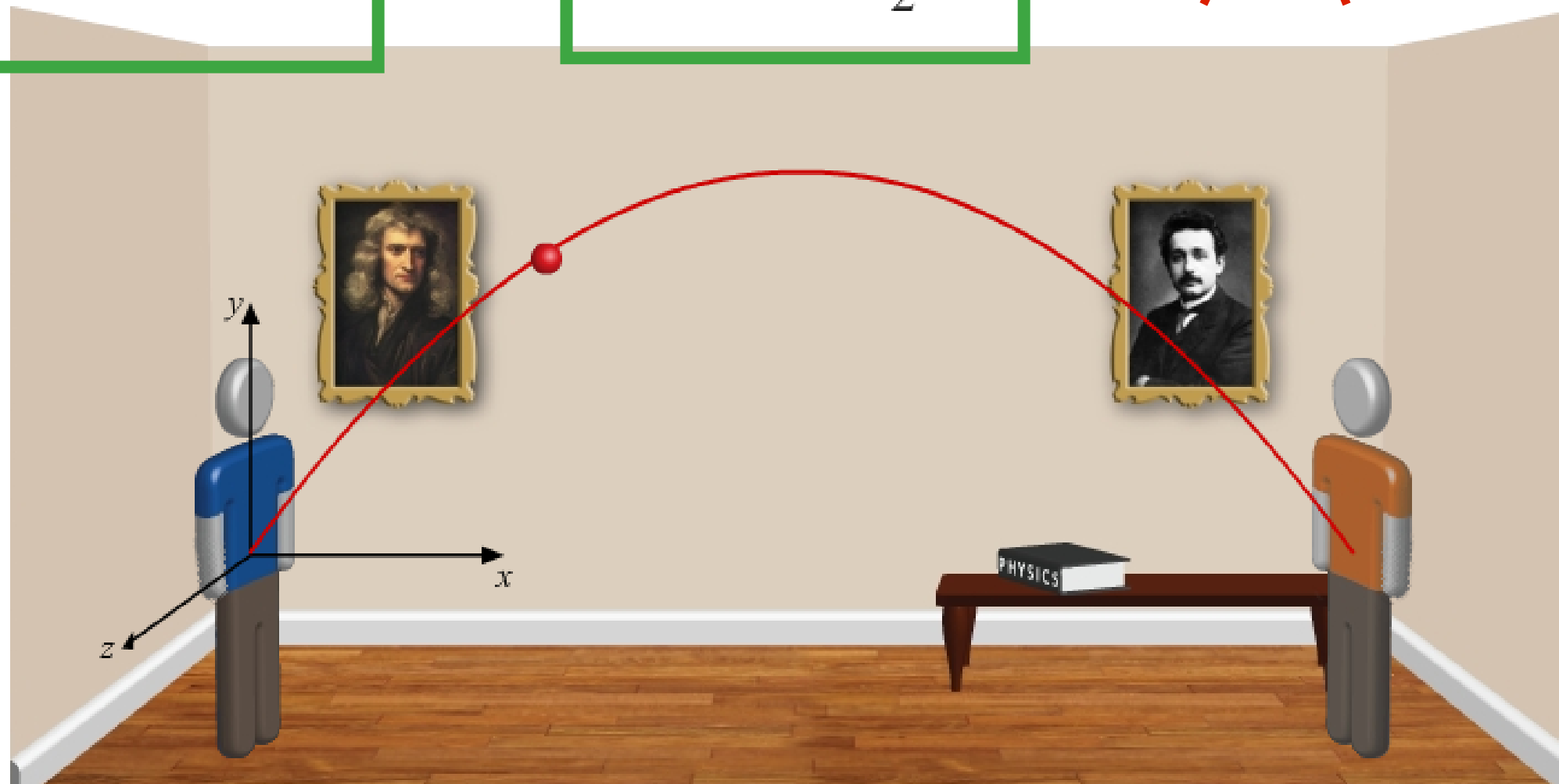
$$y = y_o + v_{oy} t - \frac{1}{2} g t^2$$

~~Boring~~

~~$$a_z = 0$$~~

~~$$v_z \neq 0$$~~

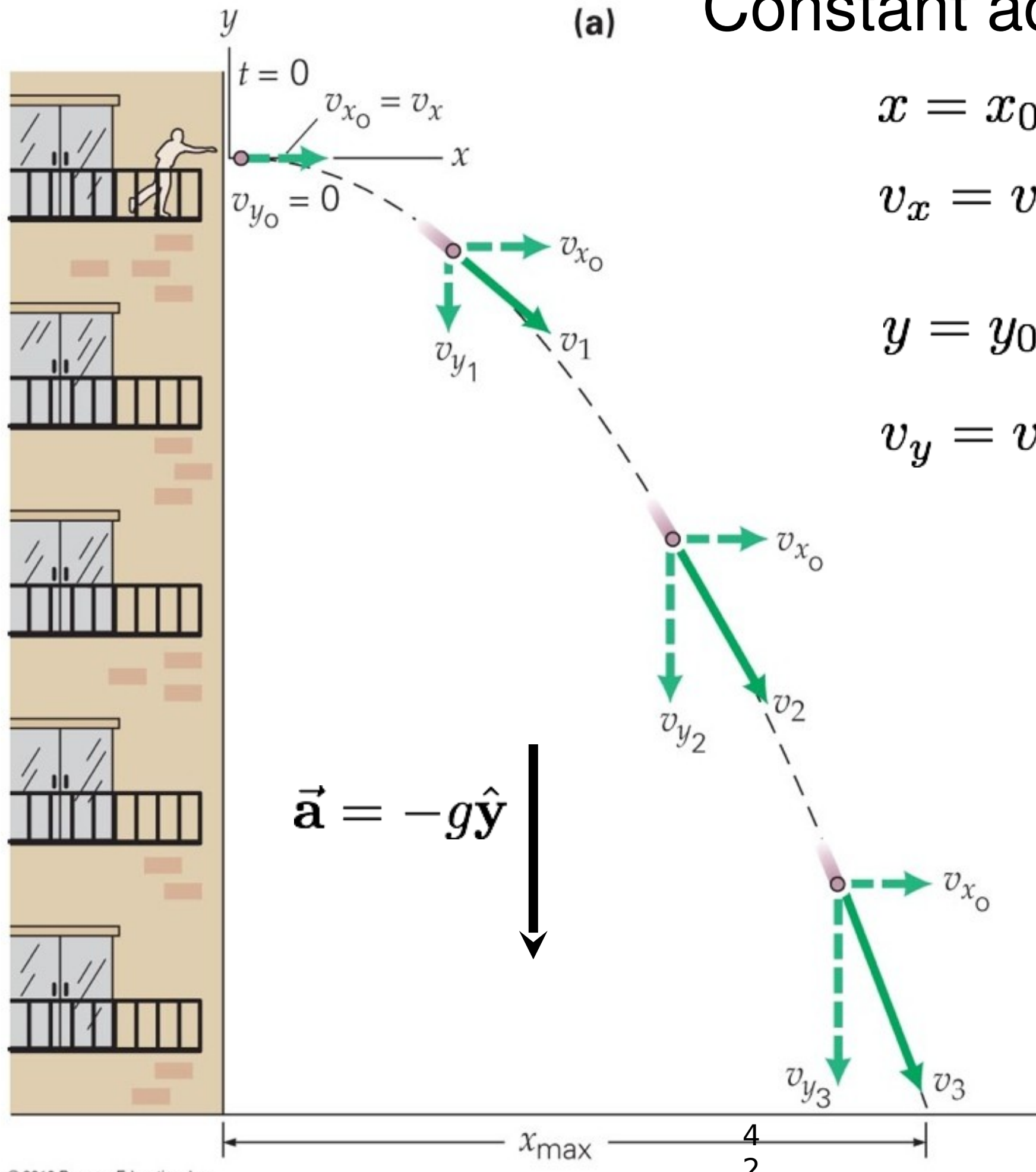
~~$$z = z_o$$~~





Constant acceleration in 2D:

(a)



$$x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$$

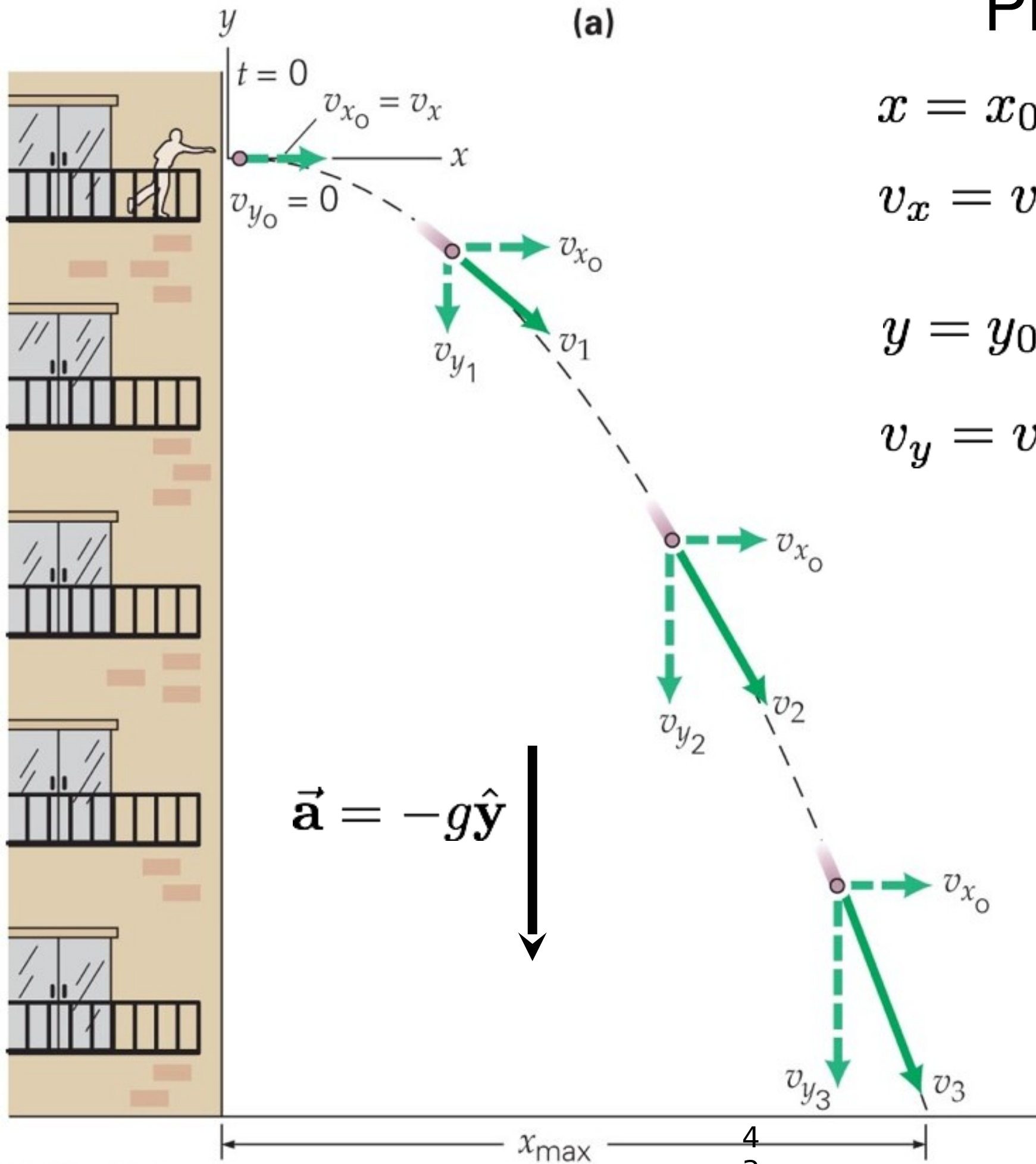
$$v_x = v_{x0} + a_x t$$

$$y = y_0 + v_{y0}t + \frac{1}{2}a_y t^2$$

$$v_y = v_{y0} + a_y t$$

Projectile

(a)

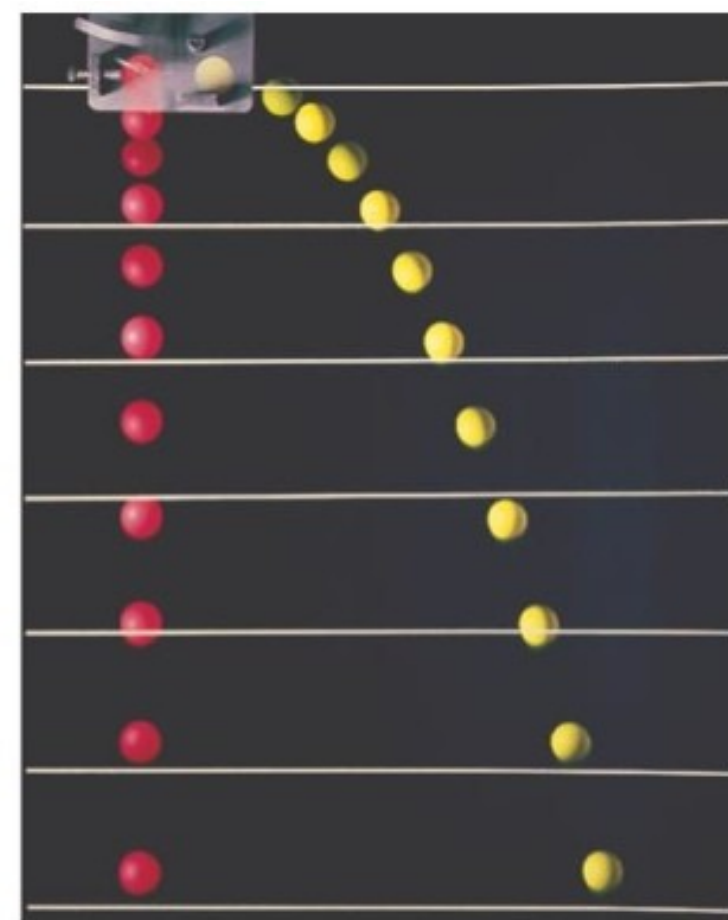
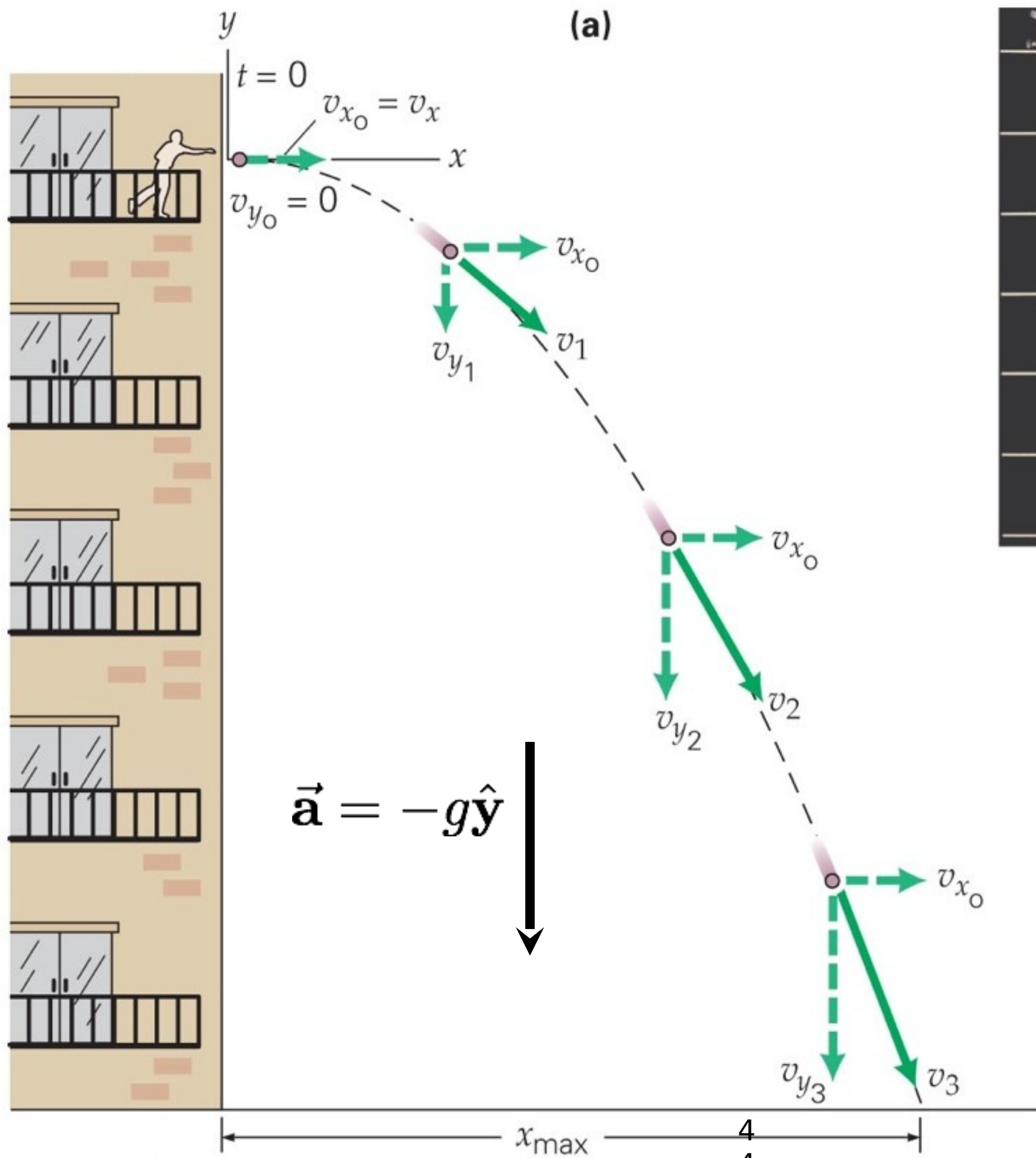


$$x = x_0 + v_{x0}t$$

$$v_x = v_{x0}$$

$$y = y_0 + v_{y0}t - \frac{1}{2}gt^2$$

$$v_y = v_{y0} - gt$$



(b)