

Basic constrained gradient-based optimization

```
clear
x0 = rand(1,3);
penalty = 2.^[10:20];
for ii = 1:length(penalty)
    disp("Penalty = " + num2str(penalty(ii)))
    options = optimoptions("fminunc","Display","iter-detailed");
    objFun = @(x) computeLagrangian(x, penalty(ii));
    solVector = fminunc(objFun, x0, options);
    x0 = solVector;
    disp("    Unconstrained solution: ")
    disp("r_1 = " + num2str(solVector(1)) + " || r_2 = " + num2str(solVector(2)) + " || theta = ")
    disp("%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%")
end
```

Penalty = 1024

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-132.906		49.9
1	12	-133.032	0.0020032	40
2	16	-134.237	1	9.03
3	20	-134.318	1	7.97
4	24	-134.572	1	12.8
5	32	-136.466	0.213174	50.3
6	36	-136.793	1	45
7	40	-138.176	1	21.6
8	44	-138.457	1	4.78
9	48	-138.472	1	1.98
10	52	-138.474	1	0.0365
11	56	-138.474	1	0.00865
12	60	-138.474	1	7.63e-05
13	64	-138.474	1	1.91e-06

Optimization completed: The first-order optimality measure, 3.745774e-08, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.073978 || r_2 = -0.080944 || theta = 0.46882

%%

Penalty = 2048

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-121.364		185
1	16	-130.336	0.000438598	32.1
2	20	-130.533	1	17.5
3	24	-130.592	1	8.59
4	28	-130.62	1	5.65
5	32	-130.654	1	4.85
6	36	-130.725	1	9.55
7	40	-130.803	1	11.6
8	44	-130.867	1	8.44
9	48	-130.905	1	4.1
10	84	-137.641	17.3358	42.3
11	100	-137.641	0.001	42.5
12	108	-142.127	10	14.2
13	112	-142.2	1	3.21
14	116	-142.208	1	0.8
15	120	-142.209	1	0.00978
16	124	-142.209	1	0.000156

Optimization completed: The first-order optimality measure, 8.369223e-07, is less

than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.074277 || r_2 = 0.30852 || theta = 3.2284

Penalty = 4096

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.749		56.6
1	20	-141.468	0.000225393	4.49
2	24	-141.476	1	4
3	28	-141.482	1	3.56
4	32	-141.496	1	4.39
5	36	-141.502	1	2.97
6	40	-141.504	1	0.746
7	44	-141.504	1	0.0622
8	48	-141.504	1	0.00258
9	52	-141.504	1	0.000267
10	56	-141.504	1	7.63e-06

Optimization completed: The first-order optimality measure, 1.324285e-07, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.087709 || r_2 = 0.29343 || theta = 3.1838

Penalty = 8192

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.825		55
1	20	-140.994	0.000207343	39.6
2	24	-141.163	1	2.12
3	32	-141.168	10	1.37
4	36	-141.171	1	0.138
5	40	-141.171	1	0.00661
6	44	-141.171	1	5.72e-06

Optimization completed: The first-order optimality measure, 1.021538e-07, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.094001 || r_2 = 0.28559 || theta = 3.1623

Penalty = 16384

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.846		54
1	24	-141.006	5.35499e-05	6.32
2	28	-141.008	1	1.09
3	36	-141.009	10	0.971
4	40	-141.01	1	1.41
5	44	-141.01	1	0.47
6	48	-141.01	1	0.0444
7	52	-141.01	1	0.00077
8	56	-141.01	1	6.65e-05
9	60	-141.01	1	3.8e-06

Optimization completed: The first-order optimality measure, 6.907372e-08, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.097037 || r_2 = 0.28162 || theta = 3.1519

Penalty = 32768

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.851		53.5
1	24	-140.929	3.50041e-05	8.07
2	28	-140.93	1	0.55

3	36	-140.931	10	0.501
4	40	-140.931	1	0.455
5	44	-140.931	1	0.0911
6	48	-140.931	1	0.00128
7	52	-140.931	1	1.14e-05

Optimization completed: The first-order optimality measure, 2.098964e-07, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.098528 || r_2 = 0.27963 || theta = 3.1467

Penalty = 65536

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.852		53.3
1	28	-140.892	1.52483e-05	0.278
2	36	-140.892	9.69499	0.48
3	40	-140.892	1	0.68
4	44	-140.892	1	1.09
5	48	-140.892	1	0.591
6	52	-140.892	1	0.0888
7	56	-140.892	1	0.00442
8	60	-140.892	1	0.000269
9	64	-140.892	1	1.91e-05

Optimization completed: The first-order optimality measure, 3.515795e-07, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.099266 || r_2 = 0.27863 || theta = 3.1441

Penalty = 131072

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.853		53.1
1	28	-140.872	6.82629e-06	5.55
2	32	-140.872	1	0.139
3	44	-140.872	91	0.173
4	48	-140.872	1	0.107
5	52	-140.872	1	0.0123
6	56	-140.872	1	4.96e-05

Optimization completed: The first-order optimality measure, 9.164427e-07, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.099634 || r_2 = 0.27813 || theta = 3.1429

Penalty = 262144

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.853		53
1	28	-140.862	4.7281e-06	12.7
2	32	-140.862	1	0.0694
3	48	-140.862	820	0.17
4	52	-140.862	1	0.00298
5	56	-140.862	1	1.14e-05

Optimization completed: The first-order optimality measure, 2.117170e-07, is less than options.OptimalityTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.099817 || r_2 = 0.27788 || theta = 3.1422

Penalty = 524288

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.853		53

1	32	-140.858	1.85698e-06	1.39
2	36	-140.858	1	0.0347
3	52	-140.858	820	0.388
4	56	-140.858	1	0.213
5	60	-140.858	1	0.0131
6	64	-140.858	1	0.000639

Optimization stopped because the norm of the current step, 3.742823e-07, is less than options.StepTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.099909 || r_2 = 0.27775 || theta = 3.1419

Penalty = 1048576

Iteration	Func-count	f(x)	Step-size	First-order optimality
0	4	-140.853		53
1	32	-140.855	8.78939e-07	4.15
2	36	-140.855	1	0.0174
3	52	-140.855	820	0.0338
4	56	-140.855	1	0.00575
5	60	-140.855	1	0.000204

Optimization stopped because the norm of the current step, 1.351273e-07, is less than options.StepTolerance = 1.000000e-06.

Unconstrained solution:

r_1 = 0.099954 || r_2 = 0.27769 || theta = 3.1418

Function definitions

Lagrangian evaluation

```
function LAG = computeLagrangian(x, penalty)
r1 = x(1);
r2 = x(2);
theta = x(3);

f = -1*computeFreq(r1, r2, pi*theta);
g = constraintFunctions(r1, r2, theta);

LAG_F = f;
LAG_G = sum(g.^2);
LAG = LAG_F + penalty/2 * LAG_G;
end
```

Function evaluation (additive inverse is objective function)

```
function freq = computeFreq(r1,r2,theta)
%surface fit for frequency on radial disk with 2 supports
%r1 refers to the distance from center of the first support (0.1 - 0.9)
%r2 is the distance from center to the second support (0.1 - 0.9)
%theta is the angle between the supports (from center) (0 - pi)
freq = (140.93-r1*25)+(-7.458*r1+9.1185)*theta+(-170)*r2+ ...
(5.783*r1-10.367)*theta^2+(-8.1)*theta*r2+(117)*r2^2+ ...
(4.2)*theta^3+(-28.075*r1+31.5125)*theta^2*r2+(15.63*r1-2.26)*theta*r2^2+ ...
(-.7)*theta^4+(-.35)*theta^3*r2+(21.77*r1-27.862)*theta^2*r2^2;
end
```

Constraint functions

```
function g = constraintFunctions(r1, r2, theta)
    g(1) = max(0, r1 - 0.9); % Radius < 0.9
    g(2) = max(0, r2 - 0.9); % Radius < 0.9
    g(3) = max(0, 0.1 - r1); % Radius > 0.1
    g(4) = max(0, 0.1 - r2); % Radius > 0.1
    g(5) = max(0, 0.1 - sqrt(r1^2 + r2^2 - 2*r1*r2*cos(pi*theta))); % Minimum distance between
    g(6) = max(0, -theta); % Theta > 0
    g(7) = max(0, theta - 1); % Theta < 1*pi
end
```