

Deep Architectures for sampling ~~macro~~-molecules

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- Sampling? In what sense?
 ↪ sampling conformations !

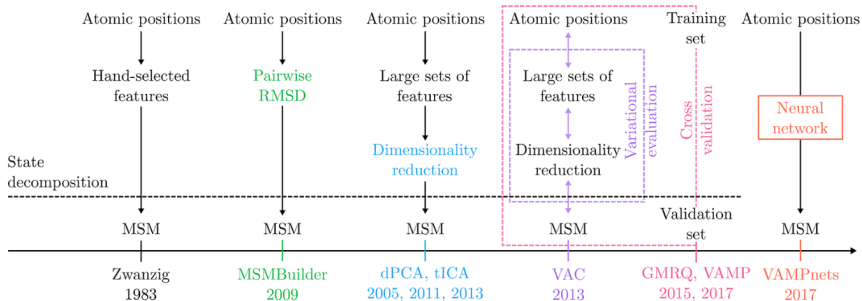
- Configuration of atoms of a molecule encoded as $x \in \mathbb{R}^D$
- Total Interaction potential $V : \mathbb{R}^D \rightarrow \mathbb{R}$
 - \hookrightarrow prescribes dynamics of the molecule
- Ideally, $t \gg 1 \rightsquigarrow$ equilibrium Boltzmann distribution $e^{-\beta V}$
- Sampling? $\rightsquigarrow (x_i, i = 1, \dots, n)$ such that $\frac{1}{n} \sum_{i=1}^n f(x_i) \approx \mathbb{E}_Q[f]$
- How sample?
 - \hookrightarrow Markov chain $(X_t, t \geq 1)$ such that $\frac{1}{n} \sum_t f(X_t) \approx \mathbb{E}_Q[f]$
- In this course we are interested in sampling:
 - \hookrightarrow significant conformations of molecules
 - \hookrightarrow one molecule at a time.

- $(X_t \in \mathbb{R}^d, t \in \mathbb{R}_+)$ is a Markov chain:

$$\mathbb{P}(X_{t_n+\delta t} \mid X_{t_n}, \dots, X_{t_1}) = \mathbb{P}(X_{\delta t} \mid X_0)$$
- Grouping together times and states:

$$Y_n = \phi(X_{[n\tau, (n+1)\tau]}) \in \{0, \dots, K\}$$

!!!! Y_1, \dots, Y_n are not, in general, a Markov chain
- Markov State Model: appropriate ϕ (state decomposition) and lags τ
 - \hookrightarrow with Y_1, \dots, Y_n that define a Markov chain
 - \hookrightarrow with $\{0, \dots, K\}$ characteristic configurations of molecules
 - \hookrightarrow $\mathbb{P}(Y_{n+1} = j \mid Y_n = i)$ characteristic transition
 - \hookrightarrow for modeling longer time dynamics of molecules



Timeline of MSM research: reproduction of Figure 2 [HP18]

Variational Approach to Conformational Dynamics (VAC)

- Discrete Markov chain $\pi(y | x), y, x \in E$, with stationary law μ , is reversible:
 $\hookrightarrow \pi(y | x)\mu(x) = \pi(x | y)\mu(y)$
- $P : \mathbb{R}^{|E|} \rightarrow \mathbb{R}^{|E|}$ defined as $P(f)(x) = \sum_{y \in E} f(y)\pi(y | x)$
- Scalar product $\langle f, g \rangle = \sum_{x \in E} \mu(x) f(x) \overline{g(x)}$
- Reversibility is equivalent to $P^\dagger = P$
 \hookrightarrow Eigenvalues of P are positive.

Variational Approach to Conformational Dynamics (VAC)

- $\pi(X_{t+\tau} = y \mid X_t = x) = e_{y,x}^{tM}$
- $p_{t+\tau}(y) = \sum_{x \in E} \pi(X_{t+\tau} = y \mid X_t = x) p_t(x)$
- When π is reversible (Equation 2 [WNP⁺16]):
 - ↪ $e^{-\tau/t_i}$ is an eigenvalue of P .
 - ↪ $\psi_i, i \in I$ are the eigenfunctions.
 - ↪ $p_{t+\tau}(x) = \sum_i e^{-\tau/t_i} \mu(x) \psi_i(x) \langle \psi_i, p_t \rangle$
- The m dominant eigenfunctions $\psi_1, \dots, \psi_m \rightsquigarrow m$ slow collective variables
 - ↪ Characterizes the behavior of a molecule on time scales $\tau \gg t_{m+1}$

Variational Approach to Conformational Dynamics (VAC)

- Dimensionality reduction:
 - ↪ Projection on eigenfunctions ordered by time scale
 - ↪ Approximation of eigenfunctions

- How? Optimize $\rightsquigarrow \max_{\substack{f_1, \dots, f_m \\ \|f_i\|=1 \\ \langle f_i, f_j \rangle = 0, i \neq j}} \sum_{i=1}^m \langle f_i, A f_i \rangle$

$$R_m = \max_{f_1, \dots, f_m} \sum_{i=1}^m \mathbb{E}_{\mu} [f_i(\mathbf{x}_t) f_i(\mathbf{x}_{t+\tau})], \quad (3)$$

s.t. $\mathbb{E}_{\mu} [f_i(\mathbf{x}_t)^2] = 1,$

$\mathbb{E}_{\mu} [f_i(\mathbf{x}_t) f_j(\mathbf{x}_t)] = 0, \text{ for } i \neq j,$

Variational Approach to Conformational Dynamics (VAC) [WNP⁺16]

Linear VAC

- A priori choice of functions $\chi : \Omega \rightarrow \mathbb{R}^M$, coordinates $\chi_i, i = 1, \dots, M$
- Find optimal linear combination:
 $\rightarrow f(x) = \sum_{j=1}^M b_j \chi_j(x)$

Pose,

$$C(0)_{i,j} = \mathbb{E}_\mu[\chi_i(X_t)\chi_j(X_t)]$$

$$C(\tau)_{i,j} = \mathbb{E}_\mu[\chi_i(X_t)\chi_j(X_{t+\tau})]$$

Then, optimal (b^1, b^2, \dots) are given by the eigenvectors of the matrix $K = C(0)^{-1}C(\tau)$,

$$C(\tau)B = C(0)B\Lambda$$

with $B_{i,j} = b_j^i$ and $\Lambda_{i,j} = \lambda_i \delta_{i,j}$ being the associated eigenvalues.

Linear VAC, two examples: TICA and MSM

- Time-lagged independent component analysis (TICA)
 - $\hookrightarrow \chi(x) = x - \mu$
- Markov State Model (MSM):
 - $\hookrightarrow \Omega = \bigsqcup_i A_i$
 - $\hookrightarrow \chi_i(x) = 1[x \in A_i]$

VAC Limitations!

- Not applicable to non-reversible processes
 - ↪ Eigenvalues can be complex
- In linear-VAC, χ is given a priori and not learned
- Most $\chi : \mathbb{R}^D \rightarrow \mathbb{R}^M$ do not allow for generation of configurations.

VAC Limitations!

- Not applicable to non-reversible processes
 - ↪ Eigenvalues can be complex
 - ↪ Variational principle for Markov processes (VAMP)
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Variational principle for Markov processes (VAMP)

- Idea: approximate the time evolution on observables:
 - Approximate: $K_\tau(f) = \mathbb{E}_\mu[f(X_{t+\tau})|X_t] \rightsquigarrow$ Koopman operator
 - Finding an optimal orthogonal basis $f_1, \dots, f_k \in L^2(\Omega, \mu)$ and $g_1, \dots, g_k \in L^2(\Omega, \mu)$ such $K_\tau \approx F\Lambda G^\dagger$ (Singular Value Decomposition)

Theorem 3. VAMP variational principle. *The k dominant singular components of a Koopman operator are the solution of the following maximization problem:*

$$\begin{aligned} \sum_{i=1}^k \sigma_i^r &= \max_{\mathbf{f}, \mathbf{g}} \mathcal{R}_r[\mathbf{f}, \mathbf{g}], \\ \text{s.t. } \langle f_i, f_j \rangle_{\rho_0} &= 1_{i=j}, \\ \langle g_i, g_j \rangle_{\rho_1} &= 1_{i=j}, \end{aligned} \tag{11}$$

where $r \geq 1$ can be any positive integer. The maximal value is achieved by the singular functions $f_i = \psi_i$ and $g_i = \phi_i$ and

$$\mathcal{R}_r[\mathbf{f}, \mathbf{g}] = \sum_{i=1}^k \langle f_i, K_\tau g_i \rangle_{\rho_0}^r \tag{12}$$

is called the VAMP- r score of \mathbf{f} and \mathbf{g} .

Variational principle for Markov processes (VAMP) [WN17]

- Pose $f = \chi_0$ and $g = \chi_1$

$$\mathbf{C}_{00} = \mathbb{E}_t \left[\chi_0(\mathbf{x}_t) \chi_0(\mathbf{x}_t)^\top \right] \quad (2)$$

$$\mathbf{C}_{01} = \mathbb{E}_t \left[\chi_0(\mathbf{x}_t) \chi_1(\mathbf{x}_{t+\tau})^\top \right] \quad (3)$$

$$\mathbf{C}_{11} = \mathbb{E}_{t+\tau} \left[\chi_1(\mathbf{x}_{t+\tau}) \chi_1(\mathbf{x}_{t+\tau})^\top \right] \quad (4)$$

VAMP variational principle: For any two sets of linearly independent functions $\chi_0(\mathbf{x})$ and $\chi_1(\mathbf{x})$, let us call

$$\hat{R}_2[\chi_0, \chi_1] = \left\| \mathbf{C}_{00}^{-\frac{1}{2}} \mathbf{C}_{01} \mathbf{C}_{11}^{-\frac{1}{2}} \right\|_F^2$$

their VAMP-2 score, where $\mathbf{C}_{00}, \mathbf{C}_{01}, \mathbf{C}_{11}$ are defined by Eqs. (2-4) and $\|\mathbf{A}\|_F^2 = n^{-1} \sum_{i,j} A_{ij}^2$ is the Frobenius norm of $n \times n$ matrix \mathbf{A} . The maximum value of VAMP-2 score is achieved when the top m left and right Koopman singular functions belong to $\text{span}(\chi_{01}, \dots, \chi_{0m})$ and $\text{span}(\chi_{11}, \dots, \chi_{1m})$ respectively.

VAMP reformulation [MPWN17]

- Samples (e.g. short time MD)

$$\mathbf{X} = \begin{pmatrix} \chi_1(\mathbf{x}_1) & \cdots & \chi_m(\mathbf{x}_1) \\ \vdots & & \vdots \\ \chi_1(\mathbf{x}_{T-\tau}) & \cdots & \chi_m(\mathbf{x}_{T-\tau}) \end{pmatrix}, \quad \mathbf{Y} = \begin{pmatrix} \chi_1(\mathbf{x}_{\tau+1}) & \cdots & \chi_m(\mathbf{x}_{\tau+1}) \\ \vdots & & \vdots \\ \chi_1(\mathbf{x}_T) & \cdots & \chi_m(\mathbf{x}_T) \end{pmatrix},$$

- $\hat{C}(0) = \frac{1}{N} \mathbf{X}^T \mathbf{X}$, $\hat{C}(\tau) = \frac{1}{N} \mathbf{X}^T \mathbf{Y}$
- **VAMPnet** $\rightsquigarrow \chi_0 = \chi_1$ learned with a neural network.

VAC Limitations!

- Not applicable to non-reversible processes
 - ↪ Eigenvalues can be complex
 - ↪ VAMP
- In linear-VAC, χ is given a priori and not learned
 - ↪ use VAMPnet
- Most $\chi : \mathbb{R}^D \rightarrow \mathbb{R}^M$ do not allow for generation of configurations.
 - ↪ Generative model

Generative model

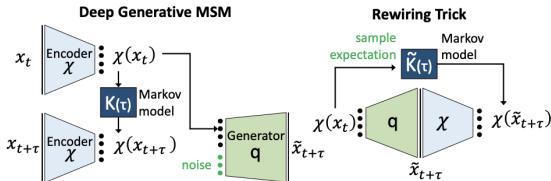


Figure 1: Schematic of Deep Generative Markov State Models (DeepGenMSMs) and the rewiring trick. The function χ , here represented by neural networks, maps the time-lagged input configurations to metastable states whose dynamics are governed by a transition probability matrix K . The generator samples the distribution $x_{t+\tau} \sim q$ by employing a generative network that can produce novel configurations (or by resampling $x_{t+\tau}$ in DeepResampleMSMs). The rewiring trick consists of reconnecting the probabilistic networks q and χ such that the time propagation in latent space can be sampled: From the latent state $\chi(x_t)$, we generate a time-lagged configuration $x_{t+\tau}$ using q , and then transform it back to the latent space, $\chi(x_{t+\tau})$. Each application of the rewired network samples the latent space transitions, thus providing the statistics to estimate the Markov model transition matrix $K(\tau)$, which is needed for analysis. This trick allows $K(\tau)$ to be estimated with desired constraints, such as detailed balance.

Generative methodology [WMPN18]

$$\mathbb{P}(x_{t+\tau} = y | x_t = x) = \boldsymbol{\chi}(x)^\top \mathbf{q}(y; \tau) = \sum_{i=1}^m \chi_i(x) q_i(y; \tau). \quad (1)$$

Here, $\boldsymbol{\chi}(x)^\top = [\chi_1(x), \dots, \chi_m(x)]$ represent the probability of configuration x to be in a metastable (long-lived) state i

$$\chi_i(x) = \mathbb{P}(x_t \in \text{state } i \mid x_t = x).$$

with $q_i(y; \tau) = P(x_{t+\tau} = y | x_t \in \text{state } i)$. γ_i up to normalizing is q_i .

→ Trained with maximum likelihood

→ Better results than VAMP





Now we can optimize χ_i and γ_i by maximizing the likelihood (ML) of generating the pairs $(x_t, x_{t+\tau})$ observed in the data. The log-likelihood is given by:

$$LL = \sum_{t=1}^{T-\tau} \ln \left(\sum_{i=1}^m \chi_i(x_t) \bar{\gamma}_i^{-1} \gamma_i(x_{t+\tau}) \right), \quad (8)$$

Thank you very much for your attention

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References I

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