Thesis Proposal

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Literature Review and Framework
- Data-Consistent Inversion

Research Questions

Preliminary Results and Research Plan

Timeline

References

Notation

- We define a parameter space Λ with dimension N and a data space $\mathcal{D}$ with dimension M. Generally $M \leq N$.
- We define a parameter-to-data map f, which is noisy and ∇f may be inaccessible.
- We consider additive noise in f, which is modeled by draws $f(\lambda) = f(\lambda) + \epsilon(\lambda)$ for additive noise and $f(\lambda) = f(\lambda)(1 + \epsilon(\lambda))$ for multiplicative noise.

- We will follow

x

x

x

x