

ISING

$$\max S = - \sum_{k=1}^{2^m} P(\mathbf{z}_k) \log P(\mathbf{z}_k)$$

$$\text{s.t. } \sum_{k=1}^{2^m} P(\mathbf{z}_k) = 1$$

$$\langle z_i \rangle = \sum_{k=1}^{2^m} z_i^k P(\mathbf{z}_k) = P_i^{obs}$$

$$\langle z_i z_j \rangle = \sum_{k=1}^{2^m} z_i^k z_j^k P(\mathbf{z}_k) = P_{ij}^{obs}$$

$$F = - \sum_{k=1}^{2^m} P(\mathbf{z}_k) \log P(\mathbf{z}_k) + \alpha \left(1 - \sum_{k=1}^{2^m} P(\mathbf{z}_k) \right) + \sum_{i=1}^m \left[h_i \left(P_i^{obs} - \sum_{k=1}^{2^m} z_i^k P(\mathbf{z}_k) \right) \right] + \sum_{i=1}^m \sum_{j=i+1}^m \left[J_{ij} \left(P_{ij}^{obs} - \sum_{k=1}^{2^m} z_i^k z_j^k P(\mathbf{z}_k) \right) \right]$$

$$\frac{\partial F}{\partial P(\mathbf{z}_k)} = 0 = -\log P(\mathbf{z}_k) - 1 + \alpha + \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k$$

$$\Rightarrow P(\mathbf{z}_k) = \frac{\exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)}{\exp(1-\alpha)}$$

$$\textcircled{1} \sum_{k=1}^{2^m} P(\mathbf{z}_k) = \frac{\sum_{k=1}^{2^m} \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)}{\exp(1-\alpha)} = 1$$

$$\Rightarrow \exp(1-\alpha) = \sum_{k=1}^{2^m} \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right) = Z$$

$$\therefore P(\mathbf{z}_k) = \frac{\exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)}{Z}$$

$$\textcircled{2} \langle z_i \rangle = \frac{\sum_{k=1}^{2^m} z_i^k \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)}{Z} = \sum_{k=1}^{2^m} z_i^k P(\mathbf{z}_k) = P_i^{obs}$$

$$\textcircled{3} \langle z_i z_j \rangle = \frac{\sum_{k=1}^{2^m} z_i^k z_j^k \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)}{Z} = \sum_{k=1}^{2^m} z_i^k z_j^k P(\mathbf{z}_k) = P_{ij}^{obs}$$

NEWTON

$$\log L(\{\mathbf{h}^*, \mathbf{J}^*\} | MSA) = \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA) + \frac{\partial \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial \{\mathbf{h}_i, \mathbf{J}_{ij}\}}$$

$$\times (\{\mathbf{h}_i^*, \mathbf{J}_{ij}^*\} - \{\mathbf{h}_i, \mathbf{J}_{ij}\}) + (\{\mathbf{h}_i^*, \mathbf{J}_{ij}^*\} - \{\mathbf{h}_i, \mathbf{J}_{ij}\})^T \frac{\partial^2 \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial^2 \{\mathbf{h}_i, \mathbf{J}_{ij}\}^2} \{\mathbf{h}_i^*, \mathbf{J}_{ij}^*\} + \text{h.o.t.}$$

$$\Rightarrow \frac{\partial \log L(\{\mathbf{h}_i^*, \mathbf{J}_{ij}^*\} | MSA)}{\partial \{\mathbf{h}_i, \mathbf{J}_{ij}\}} \bigg|_{\{\mathbf{h}_i^*, \mathbf{J}_{ij}^*\}} = 0$$

$$= \frac{\partial \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial \{\mathbf{h}_i, \mathbf{J}_{ij}\}} + \frac{\partial^2 \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial^2 \{\mathbf{h}_i, \mathbf{J}_{ij}\}^2} (\{\mathbf{h}_i^*, \mathbf{J}_{ij}^*\} - \{\mathbf{h}_i, \mathbf{J}_{ij}\}) + \text{h.o.t.}$$

$$\Rightarrow \{\mathbf{h}_i^*, \mathbf{J}_{ij}^*\} = \{\mathbf{h}_i, \mathbf{J}_{ij}\} - \frac{\partial \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial \{\mathbf{h}_i, \mathbf{J}_{ij}\}} \frac{\partial^2 \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial^2 \{\mathbf{h}_i, \mathbf{J}_{ij}\}^2}$$

$$\Rightarrow \{\mathbf{h}_i^{(n+1)}, \mathbf{J}_{ij}^{(n+1)}\} = \{\mathbf{h}_i, \mathbf{J}_{ij}\} - \frac{\partial \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial \{\mathbf{h}_i, \mathbf{J}_{ij}\}} \frac{\partial^2 \log L(\{\mathbf{h}_i, \mathbf{J}_{ij}\} | MSA)}{\partial^2 \{\mathbf{h}_i, \mathbf{J}_{ij}\}^2} \{\mathbf{h}_i^{(n)}, \mathbf{J}_{ij}^{(n)}\}$$

iteration

softening parameter

ISING

(2)

$$L(\{h_i, J_{ij}\} | \{z_i, p_{ij}\}) = \prod_{k=1}^{2^m} P(\underline{z}_k)^{p_{obs}(\underline{z}_k)K}$$

observations, $p_{obs}(\underline{z}_k)K = n^{obs}(\underline{z}_k)$
in MSA

$$P(MSA | \{h_i, J_{ij}\}) = \sum_{\underline{z}} \prod_{k=1}^{2^m} P(\underline{z}_k)^{p_{obs}(\underline{z}_k)K}$$

$$\frac{1}{K} \log L(\{h_i, J_{ij}\} | \{z_i, p_{ij}\}) = \sum_{k=1}^{2^m} p_{obs}(\underline{z}_k) \log P(\underline{z}_k) = \sum_{k=1}^{2^m} p_{obs}(\underline{z}_k) \left[- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k - \log Z \right]$$

$$= \sum_{k=1}^{2^m} p_{obs}(\underline{z}_k) \left[- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right] - \log Z$$

$$\frac{\partial \mathcal{L}}{\partial h_r} = - \frac{\partial \log Z}{\partial h_r} + \sum_{k=1}^{2^m} p_{obs}(\underline{z}_k) z_r^k$$

$$= - \frac{1}{Z} \frac{\partial}{\partial h_r} \sum_{k=1}^{2^m} \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)$$

$$= - \frac{1}{Z} \sum_{k=1}^{2^m} z_r^k \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)$$

$$= \langle z_r \rangle - p_r^{obs}$$

$$\frac{\partial \mathcal{L}}{\partial J_{rs}} = - \frac{\partial \log Z}{\partial J_{rs}} - \sum_{k=1}^{2^m} p_{obs}(\underline{z}_k) z_r^k z_s^k$$

$$= - p_{rs}^{obs} + \frac{1}{Z} \sum_{k=1}^{2^m} z_r^k z_s^k \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)$$

$$= \langle z_r z_s \rangle - p_{rs}^{obs}$$

$$\frac{\partial^2 \mathcal{L}}{\partial h_r \partial h_s} = \frac{1}{Z} \sum_{k=1}^{2^m} z_r^k z_s^k \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right) + \frac{1}{Z} \sum_{k=1}^{2^m} z_s^k \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right) \cdot \sum_{k=1}^{2^m} z_r^k \exp \left(- \sum_{i=1}^m h_i z_i^k - \sum_{i=1}^m \sum_{j=i+1}^m J_{ij} z_i^k z_j^k \right)$$

$$= \langle z_r \rangle \langle z_s \rangle - \langle z_r z_s \rangle = \frac{\partial^2 \mathcal{L}}{\partial h_s \partial h_r}$$

$$\frac{\partial^2 \mathcal{L}}{\partial J_{rs} \partial h_b} = \langle z_r z_s \rangle \langle z_b \rangle - \langle z_r z_s z_b \rangle = \frac{\partial^2 \mathcal{L}}{\partial h_b \partial J_{rs}}$$

$$\frac{\partial^2 \mathcal{L}}{\partial J_{rs} \partial J_{uv}} = \langle z_r z_s \rangle \langle z_u z_v \rangle - \langle z_r z_s z_u z_v \rangle = \frac{\partial^2 \mathcal{L}}{\partial J_{uv} \partial J_{rs}}$$

$$P(\underline{\underline{x}}_i, \underline{\underline{J}}_{ij}) | \text{MSA} = \frac{P(\text{MSA} | \underline{\underline{x}}_i, \underline{\underline{J}}_{ij}) P(\underline{\underline{x}}_i, \underline{\underline{J}}_{ij})}{P(\text{MSA})} \quad (\text{Bayes})$$

$$P(\underline{\underline{s}}_k | \underline{\underline{x}}_i, \underline{\underline{J}}_{ij}) = \frac{1}{Z} \exp\left(-\sum_{i=1}^m \underline{\underline{h}}_i^T \underline{\underline{z}}_i^{(k)} - \sum_{i=1}^m \sum_{j=i+1}^m \underline{\underline{z}}_i^T \underline{\underline{J}}_{ij} \underline{\underline{z}}_j^{(k)}\right)$$

↑
sequence, elements
 $s_k^i \in [0, Q]$, where
 Q is alphabet size

$$Z = \sum_{k=1}^{Q^m} \exp\left(-\sum_{i=1}^m \underline{\underline{h}}_i^T \underline{\underline{z}}_i^{(k)} - \sum_{i=1}^m \sum_{j=i+1}^m \underline{\underline{z}}_i^T \underline{\underline{J}}_{ij} \underline{\underline{z}}_j^{(k)}\right)$$

↑
Indicator vector of length Q (where Q is size of alphabet) containing one 1 and $(Q-1)$ zeros indicating identity of an residue in position;
 $\underline{\underline{z}}_i(\alpha) = 1$ if $s_i = \alpha$, = 0 else

$$P(\underline{\underline{x}}_i, \underline{\underline{J}}_{ij}) = \prod_{i=1}^m \prod_{q=1}^Q \exp(-\lambda_h \|h_i^q\|) \prod_{i=1}^m \prod_{j=i+1}^m \prod_{q=1}^Q \prod_{r=1}^Q \exp(-\lambda_J \|J_{ij}^{qr}\|)$$

$$P(\text{MSA} | \underline{\underline{x}}_i, \underline{\underline{J}}_{ij}) = \prod_{k=1}^{Q^m} P(\underline{\underline{s}}_k)^{p^{obs}(\underline{\underline{s}}_k) K}$$

observations in MSA,
 $p^{obs}(\underline{\underline{s}}_k) K = n^{obs}(\underline{\underline{s}}_k)$

$$\therefore P(\underline{\underline{x}}_i, \underline{\underline{J}}_{ij} | \text{MSA}) P(\text{MSA}) = \prod_{k=1}^{Q^m} P(\underline{\underline{s}}_k)^{p^{obs}(\underline{\underline{s}}_k) K} \prod_{i=1}^m \prod_{q=1}^Q e^{-\lambda_h \|h_i^q\|} \prod_{i=1}^m \prod_{j=i+1}^m \prod_{q=1}^Q \prod_{r=1}^Q e^{-\lambda_J \|J_{ij}^{qr}\|}$$

$$\Rightarrow \log(P(\underline{\underline{x}}_i, \underline{\underline{J}}_{ij} | \text{MSA}) P(\text{MSA})) = K \sum_{k=1}^{Q^m} p^{obs}(\underline{\underline{s}}_k) \log P(\underline{\underline{s}}_k)$$

$$- \lambda_h \sum_{i=1}^m \sum_{q=1}^Q \|h_i^q\|$$

$$- \lambda_J \sum_{i=1}^m \sum_{j=i+1}^m \sum_{q=1}^Q \sum_{r=1}^Q \|J_{ij}^{qr}\|$$

$$\Rightarrow \mathcal{L}(\underline{\underline{x}}_i, \underline{\underline{J}}_{ij}) = \frac{1}{K} \log(P(\underline{\underline{x}}_i, \underline{\underline{J}}_{ij} | \text{MSA}) P(\text{MSA})) = \sum_{k=1}^{Q^m} p^{obs}(\underline{\underline{s}}_k) \log P(\underline{\underline{s}}_k) - \frac{\lambda_h}{K} \sum_{i=1}^m \sum_{q=1}^Q \|h_i^q\| - \lambda_J \sum_{i=1}^m \sum_{j=i+1}^m \sum_{q=1}^Q \sum_{r=1}^Q \|J_{ij}^{qr}\|$$

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$$\Rightarrow \mathcal{L}(\mathbf{h}, \mathbf{J}, \mathbf{z}) = \sum_{k=1}^{Q^m} P^{obs}(\mathbf{z}_k) \left[- \sum_{i=1}^m h_i^T \mathbf{z}_i^{(k)} - \sum_{i=1}^m \sum_{j=i+1}^m \mathbf{z}_i^T \mathbf{J}_{ij} \mathbf{z}_j^{(k)} \right] - \log Z$$

$$- \frac{\lambda_h}{K} \sum_{i=1}^m \sum_{q=1}^Q \|h_i^{(q)}\| - \frac{\lambda_J}{K} \sum_{i=1}^m \sum_{j=i+1}^m \sum_{q=1}^Q \sum_{r=1}^Q \|J_{ij}^{(qr)}\|$$

$\sum_{k=1}^{Q^m} P^{obs}(\mathbf{z}_k) = 1$

$$\frac{\partial \mathcal{L}}{\partial h_i^\alpha} = - \frac{1}{Z} \frac{\partial Z}{\partial h_i^\alpha} - \sum_{k=1}^{Q^m} P^{obs}(\mathbf{z}_k) z_i^{\alpha(k)} - \frac{\lambda_h}{K} \left[\text{sgn}(h_i^\alpha) \right] \text{ for } \|h_i^{(q)}\| = |h_i^{(q)}|$$

$$- \frac{\lambda_h}{K} \frac{1}{(h_i^{(q)})^2} \text{ for } \|h_i^{(q)}\| = (h_i^{(q)})^2$$

$$= \frac{\sum_{k=1}^{Q^m} z_i^{\alpha(k)} \exp \left(- \sum_{i=1}^m h_i^T \mathbf{z}_i^{(k)} - \sum_{i=1}^m \sum_{j=i+1}^m \mathbf{z}_i^T \mathbf{J}_{ij} \mathbf{z}_j^{(k)} \right)}{Z} - \sum_{k=1}^{Q^m} P^{obs}(\mathbf{z}_k) z_i^{\alpha(k)} - \frac{\lambda_h}{K} g(h_i^\alpha)$$

$$g(h_i^\alpha) = \text{sgn}(h_i^\alpha) \text{ for L1 reg}$$

$$= 2h_i^\alpha \text{ for L2 reg}$$

$$= \underbrace{\langle z_i^\alpha \rangle}_{\substack{\uparrow \\ \text{model probability of residue } \alpha \text{ in position } i}} - \underbrace{P^{obs}(\mathbf{z}_i^\alpha)}_{\substack{\uparrow \\ \text{observed}}} - \frac{\lambda_h}{K} g(h_i^\alpha)$$

$$\frac{\partial \mathcal{L}}{\partial J_{is}^{\alpha\delta}} = - \frac{1}{Z} \frac{\partial Z}{\partial J_{is}^{\alpha\delta}} - \sum_{k=1}^{Q^m} P^{obs}(\mathbf{z}_k) z_i^{\alpha(k)} z_s^{\delta(k)} - \frac{\lambda_J}{K} g(J_{is}^{\alpha\delta})$$

$$= \langle z_i^\alpha z_s^\delta \rangle - P^{obs}(\mathbf{z}_i^\alpha \mathbf{z}_s^\delta) - \frac{\lambda_J}{K} g(J_{is}^{\alpha\delta})$$

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$$\frac{\partial^2 \mathcal{L}}{\partial h_l^\alpha \partial h_s^\sigma} = \frac{- \sum_{k=1}^{Q^m} z_l^{\alpha(k)} z_s^{\sigma(k)} \exp(\sim) \cdot Z + \sum_{k=1}^{Q^m} z_s^{\sigma(k)} \exp(\sim) \cdot \sum_{k=1}^{Q^m} z_l^{\alpha(k)} \exp(\sim)}{Z^2}$$

$$- \frac{\lambda_h}{K} \frac{\partial g(h_l^\alpha)}{\partial h_s^\sigma}$$

$$= \langle z_l^\alpha \rangle \langle z_s^\sigma \rangle - \langle z_l^\alpha z_s^\sigma \rangle - \frac{\lambda_h}{K} \frac{\partial g(h_l^\alpha)}{\partial h_s^\sigma}$$

$$\frac{\partial g(h_l^\alpha)}{\partial h_s^\sigma} = 0 \quad \text{for } \alpha \neq \sigma \text{ \& } s \neq l$$

$$= 0 \quad \text{for } \alpha = \sigma \text{ \& } s = l \text{ \& } L1 \text{ reg}$$

BUT undefined at $h_l^\alpha = 0$

$$= 2 \quad \text{for } \alpha = \sigma \text{ \& } s = l \text{ \& } L2 \text{ reg}$$

$$\frac{\partial^2 \mathcal{L}}{\partial h_l^\alpha \partial J_{st}^{\sigma\tau}} = \langle z_l^\alpha \rangle \langle z_s^\sigma z_t^\tau \rangle - \langle z_l^\alpha z_s^\sigma z_t^\tau \rangle$$

$$\frac{\partial^2 \mathcal{L}}{\partial J_{ls}^{\alpha\sigma} \partial J_{tu}^{\sigma\tau}} = \langle z_l^\alpha z_s^\sigma \rangle \langle z_t^\sigma z_u^\tau \rangle - \langle z_l^\alpha z_s^\sigma z_t^\sigma z_u^\tau \rangle - \frac{\lambda_J}{K} \frac{\partial g(J_{ls}^{\alpha\sigma})}{\partial J_{tu}^{\sigma\tau}}$$

$$\frac{\partial g(J_{ls}^{\alpha\sigma})}{\partial J_{tu}^{\sigma\tau}} = 0 \quad \text{for } \alpha \neq \sigma \text{ \& } \sigma \neq \tau$$

$$\text{ \& } l \neq t \text{ \& } s \neq u$$

$$= 0 \quad \text{for } \alpha = \sigma \text{ \& } \sigma = \tau$$

$$\text{ \& } l = t \text{ \& } s = u$$

$$\text{ \& } L1 \text{ reg}$$

BUT undefined at $J_{ls}^{\alpha\sigma} = 0$

$$= 2 \quad \text{for } \alpha = \sigma \text{ \& } \sigma = \tau$$

$$\text{ \& } l = t \text{ \& } s = u$$

$$\text{ \& } L2 \text{ reg}$$