Course 2: Supervised Learning



Summary

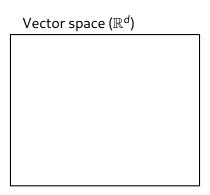
Last session

- Al definition
- 2 Applications
- 3 Deep learning
- Open issues

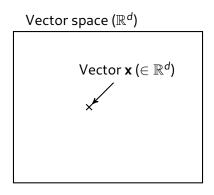
Today's session

- Learning from labeled examples
- Challenges of supervised learning

Notations

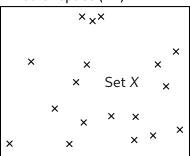


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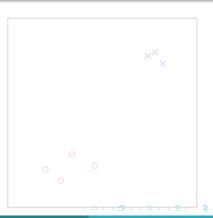
Vector space (\mathbb{R}^d)



Definition

Supervised learning methods use **labels** $\hat{\mathbf{y}}$ associated with examples \mathbf{x} to learn a function f such as $\hat{\mathbf{y}} \approx f(\mathbf{x})$, with the aim of **generalizing** (\neq memorizing) to unlabeled examples.

- Regression (y is scalar)
- Classification (y is categorical)
- Tons of applications
 - Pattern recognition
 - Prediction...



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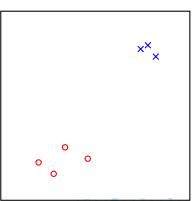
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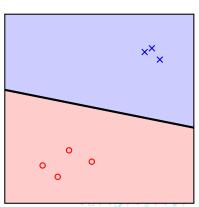
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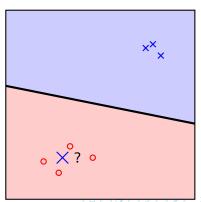
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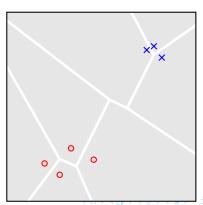
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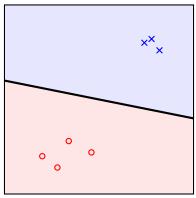
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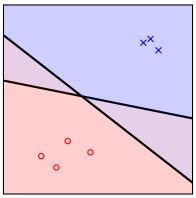
An ill-defined problem

- An infinity of potential solutions, one must be the "best one" but is unreachable,
- ⇒ requires **priors or constraints**.



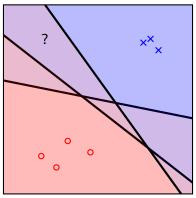
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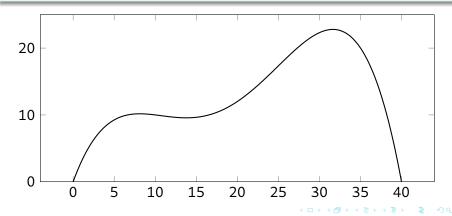


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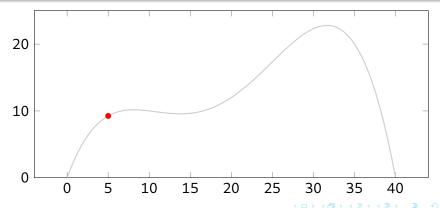
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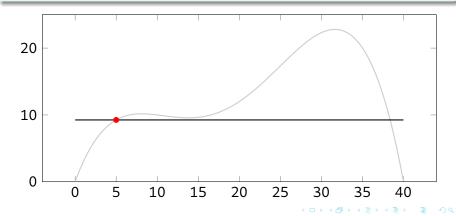
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- Mimicking is not learning: overfitting problem.



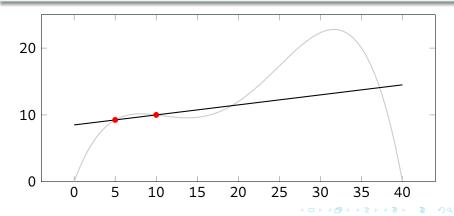
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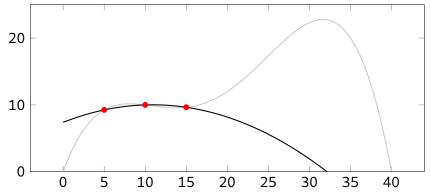
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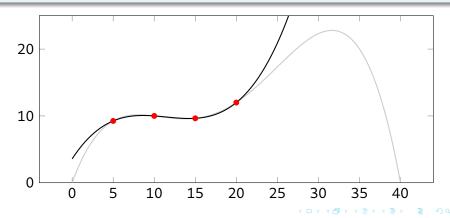
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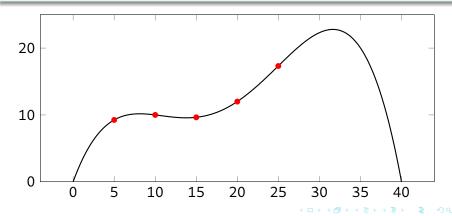
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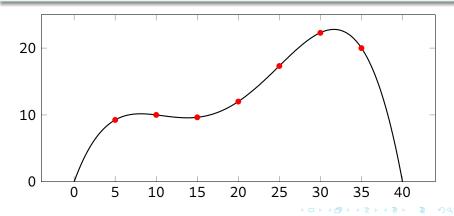
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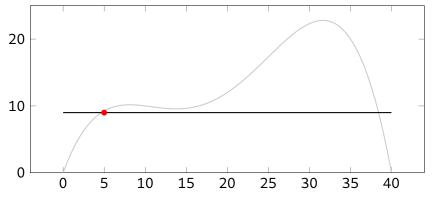
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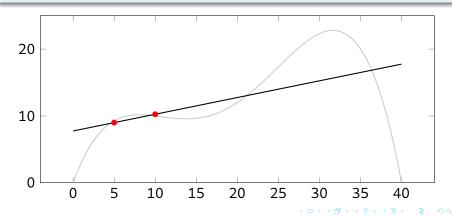
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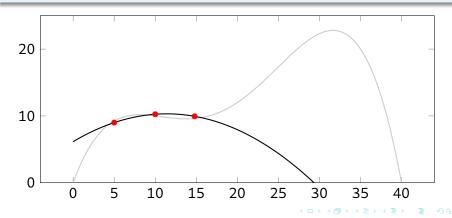
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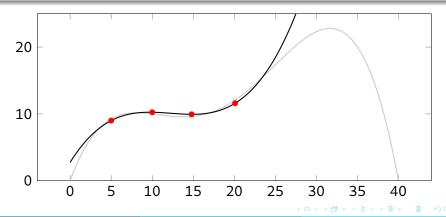
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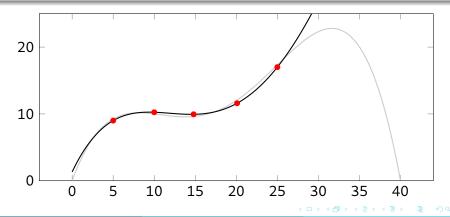
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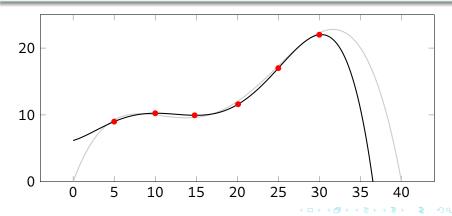
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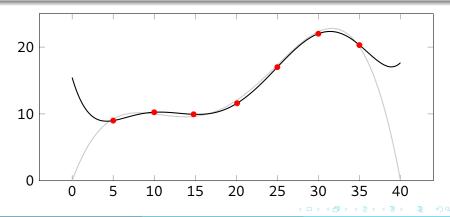
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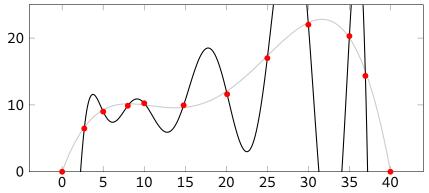
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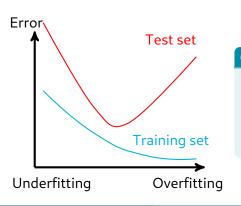


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Bias/variance trade-off

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Crossvalidation

- To detect overfitting, split training dataset in two parts:
 - A first part is used to train,
 - A second part is used to validate,

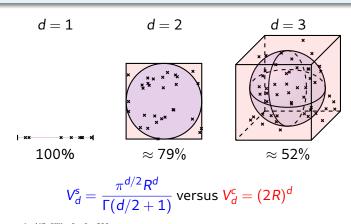
Curse of dimensionality

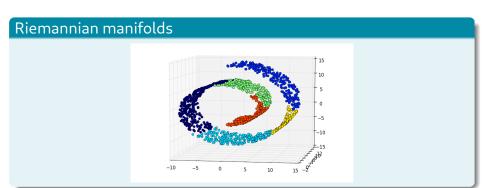
- Geometry is not intuitive in high dimension,
- Efficient methods in 2D are not necessarily still valid.

$$V_d^s = \frac{\pi^{d/2} R^d}{\Gamma(d/2 + 1)}$$
 versus $V_d^c = (2R)^d$

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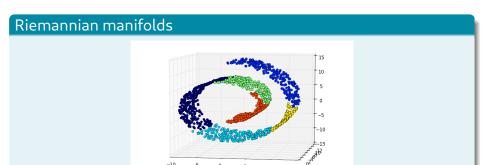




Linear separability and need for embedding







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Computation time

Example on ImageNet, simply going through all images:

- $n = 10.000.000, d \approx 1.000.000,$
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Scalability

- Finding the best solution to a problem would be feasible with unlimited computation time,
- But searching through the space of possible functions is often untractable,
- Solutions must be computationally reasonable, which is the true challenge today.

Challenges of supervised learning (5/5)

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- The VC dimension is a measure of the genericity of a method,
- It is the maximum cardinality of a set of vectors that the method is able to shatter in any possible way.

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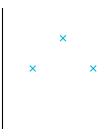






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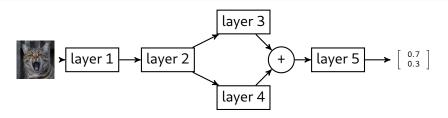


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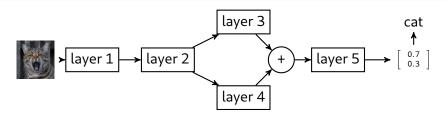
Inputs/outputs

- Often: inputs are raw signals or feature vectors,
- Often: outputs are vectors which highest value indicate the category of the input.



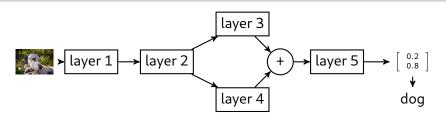
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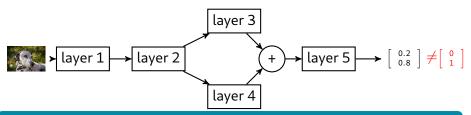
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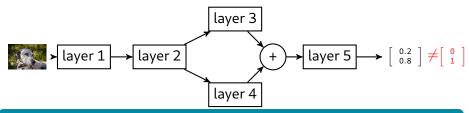


Loss and targets

- Labels are encoded as one-hot-bit vectors and called targets,
- Outputs are **softmaxed**: $\mathbf{y}_i \leftarrow \exp(\mathbf{y}_i) / \sum_j \exp(\mathbf{y}_j)$,
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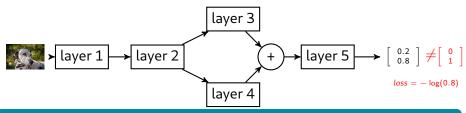


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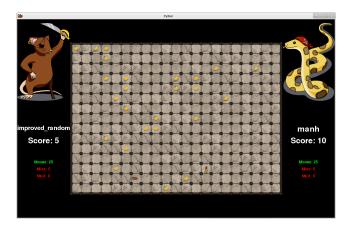
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Non-symmetric PyRat without walls / mud



Both players follow a deterministic greedy algorithm. Supervised learning - Two tasks

- Predict the outcome of a game from the start configuration.
- Learn the next move using a dataset of winners

Lab Session 2 and assignments for Session 3

TP Supervised Learning (TP1)

- Basics of machine learning using sklearn (including new definitions / concepts) and pytorch
- Tests on PyRat datasets using the two tasks (predicting winner and predicting moves to play)

Project 1 (P1)

You will choose a supervised learning method. You have to prepare a Jupyter Notebook on this method, including:

- A brief description of the theory behind the method,
- Basic tests on simulated data to show the influence of parameters and hyperparameters
- Tests on PyRat Datasets on at least ONE of the two tasks (predicting winner or playing)

During Session 3 you will have 7 minutes to present your notebook.