GNU Radio Zedboard Implementation with FPGA Acceleration

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Outline

- Overview
- Accomplishments
- Milestones
- Two week sprint
- Quarter Plan
- Conclusion

Overview

Deliverable Status

Xillybus Integration with GNU Radio (GR) Successes and Hurdles

Function Replacement

Accomplishments

- Modified Low Pass Filter Block Created
- Verified FIR in Test Bench
- FPGA with Xillybus Loopback
- Host code for FPGA integrated into GR
- Throughput measurements



Measurements

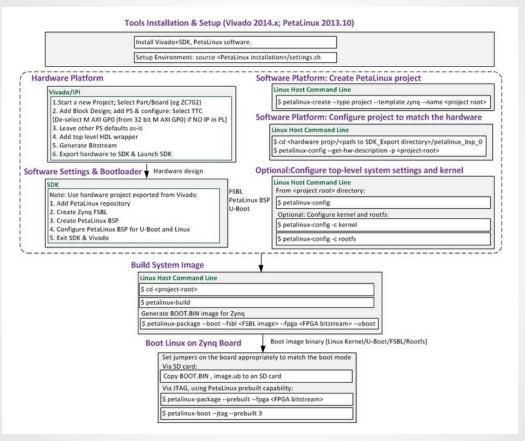
```
Nishant Filter al=2.d ntaps=73 size=4. long=4.delta = 645126 input=0xaca0f838
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 645126 input=0xaca107d8
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 645126 input=0xaca11778
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 663558 input=0xaca12718
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 6451<u>25 input=0xaca136b8</u>
Nishant Filter al=2,d_ntaps=73    size=4, long=4,delta = 663557 input=0xaca14658
Nishant Filter al=2.d ntaps=73 size=4. long=4.delta = 1511801016 input=0xaca055f
Nishant Filter al=2,d_ntaps=73 size=4, long=4,delta = 6635<u>58 input=0xaca06598</u>
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 681990 input=0xaca07538
Nishant Filter al=2,d_ntaps=73 size=4, long=4,delta = 681990 input=0xaca084d8
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 645126 input=0xaca09478
Nishant Filter al=2,d_ntaps=73 size=4, long=4,delta = 663558 input=0xaca0a418
Nishant Filter al=2.d ntaps=73 size=4. long=4.delta = 4423718 input=0xaca0b3b8
Nishant Filter al=2.d ntaps=73 size=4. long=4.delta = 1583336231 input=0xaca0c35
                                                                                    -40.0020.00 0.00 20.0040.00
Nishant Filter al=2.d ntaps=73 size=4. long=4.delta = 663558 input=0xaca0d2f8
                                                                                      Frequency (kHz)
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 663558 input=0xaca0e298
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 663558 input=0xaca0f238
Nishant Filter al=2,d ntaps=73 size=4, long=4,delta = 976905 input=0xaca101d8
Nishant Filter al=2,d_ntaps=73 size=4, long=4,delta = 681990 input=0xaca11178
                                                                                  double)start_proc.tv
Nishant Filter al=2,d_ntaps=73 size=4, long=4,delta = 663557 input=0xaca12118
Nishant Filter al=2,d_ntaps=73 size=4, long=4,delta = 663558 input=0xaca130b8
                                                                                  ec - (double)start p
                                      clock gettime(CLOCK REALTIME, &start proc);
                                      for(i=0: i<500: i++)
                                        donebytes = 0:
                                        while (donebytes < sizeof(float)) =</pre>
                                          rc = write(fdw, (char *)&data + donebytes, sizeof(float)-do
                                          if (rc < 0 && (errno == FINTR)) {
```

Measurements

```
write nsec: 1548.302000
                                                🖺 test.c 💥
read nsec: 1290.252000
                                               clock_gettime(CLOCK_REALTIME, &end_proc);
data = 1.000000, rdata = 3.000000
                                               printf("write nsec: %f\n", (double)( 1000000000*(end proc.
input data=2
                                               +(end proc.tv nsec - start proc.tv nsec) )/500 );
write nsec: 1548.302000
read nsec: 1290.252000
data = 2.000000, rdata = 4.000000
input data=2.5
                                               usleep(10000); //around 10ms
write nsec: 1548.302000
                                               clock gettime(CLOCK REALTIME, &start proc);
read nsec: 1253.388000
                                               for(i=0; i<500; i++)</pre>
data = 2.500000. rdata = 4.500000
input data=2.55
write nsec: 1548.302000
read nsec: 1290.250000
                                                //read
data = 2.550000, rdata = 4.550000
                                                 donebytes = 0:
                                                 while (donebytes < sizeof(float)) {</pre>
input data=2.566
write nsec: 1548.300000
                                                   rc = read(fdr, (char *)&rdata + donebytes, sizeof(floa
                                                   if (rc < 0 && (errno == EINTR)) {
read nsec: 1253.388000
data = 2.566000, rdata = 4.566000
                                                     printf("read error\n"):
input data=2.579345
                                                     continue:
write nsec: 1548.302000
read nsec: 1253.388000
                                                   if (rc <= 0)
data = 2.579345, rdata = 4.579345
                                                     break;
input data=
                                                   donebytes += rc;
                                               clock_gettime(CLOCK_REALTIME, &end_proc);
                                               printf("read nsec: %f\n", (double)( 1000000000*(end_proc.
                                               +(end proc.tv nsec - start proc.tv nsec) )/500 );
                                                 printf("data = %f, rdata = %f\n",data, rdata);
                                               }//end input number
```

Xillybus Throughput: Approximately 1.5 MB/sec (max supported 200MBps)

About the PetaLinux



Examples:

Using QEMU for Gnu Radio embedded applications
FPGA-based Implementation of Multiple PHY Layers of IEEE 802.15.4 Targeting SDR

Upcoming Two Week Sprint

- Optimize speed of Xillybus (Jun, Ali)
- Identify Blocks to Recreate (Team)
- Create test benches using captured data (Keyur, Nishant)
- Prove blocks will fit on FPGA via simulation(Team)

Quarter Plan

Two demonstration goals at the end of this project

- show that data is processed to nearly the same fidelity on the Zedboard as on a laptop
- Integrate Verilog code with GNU Radio and demo
 - with previously recorded samples
 - in real-time (stretch goal)

Conclusion

- Proven we can work with Xillybus from within GNU Radio.
- The function we choose to implement performed faster on arm processor than FPGA.