PayloadSDK Functions

- Table of contents
- Version history
- Connection functions
 - sdkInitConnection
 - checkPayloadConnection
 - sdkQuit
- Camera Control functions
 - setPayloadCameraParam
 - setPayloadCameraMode
 - setPayloadCameraCaptureImage
 - setPayloadCameraStopImage
 - setPayloadCameraRecordVideoStart
 - setPayloadCameraRecordVideoStop
 - setCameraZoom
 - setCameraFocus
 - getPayloadCameraSettingList
 - getPayloadCameraSettingByID
 - getPayloadCameraSettingByIndex
 - getPayloadCameraMode
 - getPayloadCameraInformation
 - getPayloadCameraStreamingInformation
 - getPayloadStorage
 - getPayloadCaptureStatus
 - setParamRate
- Gimbal Control functions
 - setPayloadGimbalParamByID
 - setGimbalSpeed
 - getPayloadGimbalSettingList
 - getPayloadGimbalSettingByID
 - getPayloadGimbalSettingByIndex
 - sendPayloadGimbalCalibGyro
 - $\circ \ \ send Payload Gimbal Calib Accel$
 - sendPayloadGimbalCalibMotor
 - sendPayloadGimbalSearchHome
 - sendPayloadGimbalAutoTune

- FFC Control functions
 - setPayloadCameraFFCMode
 - setPayloadCameraFFCTrigg
- GPS functions
 - sendPayloadGPSRawInt
 - sendPayloadGPSPosition
- System Time function
 - sendPayloadSystemTime
- SD Card function
 - setFormatSDCard
- Object Tracking function
 - setPayloadObjectTrackingParams
- Callback functions
 - regPayloadStatusChanged
 - regPayloadParamChanged
 - regPayloadStreamChanged

Version history

Version	Publish date	Description		
v1.0.0	05/23/2025	Add format SD card function		

Connection functions

sdkInitConnection

• Brief: Initialize the connection to the payload via UDP or UART.

Param	Type	Range	Default Value	Description
None	None	None	None	None

• Return: True if connection successful, False otherwise (bool)

check Payload Connection

• Brief: Check the connection to the payload within a specified timeout period.

Param	Туре	Range	Default Value	Description
timeout	float	> 0	5.0	Timeout in seconds

• Return: True if connection successful, False otherwise (bool)

sdkQuit

• Brief: Close the connection and stop the data receiving thread.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

Camera Control functions

set Payload Camera Param

• Brief: Set the parameter value for the payload's camera.

Param	Туре	Range	Default Value	Description
param_id	str	None	None	Parameter ID
param_value	int	None	None	Parameter value
param_type	int	(1) MAV_PARAM_TYPE_UINT8 (2) MAV_PARAM_TYPE_INT8 (3) MAV_PARAM_TYPE_UINT16 (4) MAV_PARAM_TYPE_INT16 (5) MAV_PARAM_TYPE_UINT32 (6) MAV_PARAM_TYPE_INT32 (7) MAV_PARAM_TYPE_UINT64 (8) MAV_PARAM_TYPE_UINT64 (9) MAV_PARAM_TYPE_REAL32 (10) MAV_PARAM_TYPE_REAL64	None	Data type of the parameter

• Return: None

set Payload Camera Mode

• Brief: Set the operating mode for the camera

Param	Туре	Range	Default Value	Description
mada	int	(0) CAMERA_MODE_IMAGE	None	Camasa mada
mode i	int	(1) CAMERA MODE VIDEO	None	Camera mode

• Return: None

set Payload Camera Capture Image

• Brief: Request the camera to capture an image.

Param	Туре	Range	Default Value	Description
interval_s	int	>= 0	0	Interval between captures in seconds

set Payload Camera Stop Image

• Brief: Stop the interval image capturing process.

Param	Type	Range	Default Value	Description
None	None	None	None	None

• Return: None

set Payload Camera Record Video Start

• Brief: Start video recording.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

set Payload Camera Record Video Stop

• Brief: Stop video recording.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

setCameraZoom

• Brief: Adjust the camera's zoom level.

Param	Туре	Range	Default Value	Description
zoom_type	float	(0) ZOOM_TYPE_STEP (1) ZOOM_TYPE_CONTINUOUS (2) ZOOM_TYPE_RANGE	None	Type of zoom
zoom_value	float	zoom_type equal ZOOM_TYPE_STEP and equal ZOOM_TYPE_CONTINUOUS (-1) ZOOM_OUT (0) ZOOM_STOP (1) ZOOM_IN	None	Zoom value
zoom_value	float	zoom_type equal ZOOM_TYPE_RANGE from 0.0% to 100.00%	None	Zoom value

setCameraFocus

• Brief: Adjust the camera's focus.

Param	Туре	Range	Default Value	Description
focus_type	float	(1) ZOOM_TYPE_CONTINUOUS (4) FOCUS_TYPE_AUTO	None	Type of focus
focus_value	float	zoom_type equal ZOOM_TYPE_CONTINUOUS (-1) FOCUS_OUT (0) FOCUS_STOP (1) FOCUS_IN (2) FOCUS_AUTO	0	Focus value

• Return: None

get Payload Camera Setting List

• Brief: Request the list of all camera parameters.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

get Payload Camera Setting By ID

• Brief: Request the value of a specific camera parameter by ID.

Param	Туре	Range	Default Value	Description
param_id	str	None	None	Parameter ID

• Return: None

get Payload Camera Setting By Index

• Brief: Request the value of a camera parameter by index.

Param	Type	Range	Default Value	Description
idx	int	None	None	Parameter index

getPayloadCameraMode

• Brief: Request the current mode of the camera.

Param	Type	Range	Default Value	Description
None	None	None	None	None

• Return: None

get Payload Camera Information

• Brief: Request detailed information about the camera.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

get Payload Camera Streaming Information

• Brief: Request information about the camera's video stream.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

getPayloadStorage

• Brief: Request information about the camera's storage (SD card).

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

get Payload Capture Status

• Brief: Request the current capture status of the camera.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

setParamRate

• Brief: Set the message rate for a specific parameter.

Param	Туре	Range	Default Value	Description
param_index	int	None	Valid indices from PAYLOAD_PARAMS	Index of the parameter
time_ms	int	None	≥ 0	Time interval between messages in milliseconds

Gimbal Control functions

set Payload Gimbal Param By ID

• Brief: Set the value of a gimbal parameter by ID.

Param	Туре	Range	Default Value	Description
param_id	str	None	None	Parameter ID
param value	float	None	None	Parameter value

• Return: None

set Gimbal Speed

• Brief: Set the speed or angle for move gimbal

Param	Туре	Range	Default Value	Description
spd_pitch	float	-90 to 90	None	Pitch speed/angle in degrees
spd_roll	float	-180 to 180	None	Roll speed/angle in degrees
spd_yaw	float	-180 to 180	None	Yaw speed/angle in degrees
mode	input_mode_t	(1)INPUT_ANGLE (2)INPUT_SPEED	None	Input mode

• Return: None

getPayloadGimbalSettingList

• Brief: Request the list of all gimbal parameters

Param	Type	Range	Default Value	Description
None	None	None	None	None

• Return: None

getPayloadGimbalSettingByID

• Brief: Request the value of a specific gimbal parameter by ID.

Param	Туре	Range	Default Value	Description	
param id	str	None	None	Parameter ID	

get Payload Gimbal Setting By Index

• Brief: Request the value of a gimbal parameter by index.

Param	Туре	Range	Default Value	Description
idx	int	None	None	Parameter index

• Return: None

send Payload Gimbal Calib Gyro

• Brief: Send command to calibrate the gimbal's gyro.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

send Payload Gimbal Calib Accel

• Brief: Send command to calibrate the gimbal's accelerometer.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

send Payload Gimbal Calib Motor

• Brief: Send command to calibrate the gimbal's motor.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

• Return: None

sendPayloadGimbalSearchHome

• Brief: Send command to search for the gimbal's home position.

Param	Type	Range	Default Value	Description
None	None	None	None	None

send Payload Gimbal Auto Tune

• Brief: Send command to auto-tune the gimbal.

Param	Туре	Range	Default Value	Description
status	bool	True/False	None	True to enable, False to disable

FFC Control Functions

set Payload Camera FFC Mode

• Brief: Set the FFC mode for the camera.

Param	Туре	Range	Default Value	Description
mode	int	0-1	None	FFC mode (0: Manual, 1: Auto)

• Return: None

set Payload Camera FFCT rigg

• Brief: Trigger FFC calibration for the camera.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

GPS functions

send Payload GPS Raw Int

• Brief: Send the GPS RAW information to the payload.

Param	Туре	Range	Default Value	Description
gps_raw	mavlink_gps_raw_int_t	None	None	GPS raw data structure

• Return: None

send Payload GPS Position

• Brief: Send GPS position information to the payload.

Param	ram Type		Default Value	Description
gps_data	mavlink_global_position_int_t	None	None	GPS position data structure

System Time function

sendPayloadSystemTime

• Brief: Send system time information to the payload.

Param	Param Type		Default Value	Description
sys_time_data	mavlink_system_time_t	None	None	System time data structure

SD Card function

setFormatSDCard

• Brief: Format the camera's SD card.

Param	Туре	Range	Default Value	Description
None	None	None	None	None

Object Tracking function

set Payload Object Tracking Params

• Brief: Set parameters for object tracking functionality.

Param	Туре	Range	Default Value	Description
cmd	float	(0)TRACK_IDLE (1)TRACK_ACT (2)TRACK_LOST	None	Tracking command
pos_x	float	None	960	X position
pos_y	float	None	540	Y position

Callback functions

regPayloadStatusChanged

• Brief: Register a callback to receive notifications when the payload status changes.

Param	Туре	Range	Default Value	Description
callback	Callable	None	None	Function that takes payload_status_event_t and List[float] as parameters
Return: None				

regPayloadParamChanged

• Brief: Register a callback to receive notifications when a payload parameter changes.

Param	Туре	Range	Default Value	Description
callback	Callable	None	None	Function that takes payload_status_event_t, str, and List[float] as parameters
• Retu	rn. None			

Return: None

regPayloadStreamChanged

• Brief: Register a callback to receive notifications when the payload's video stream information changes.

Param	Туре	Range	Default Value	Description
callback	Callable	None	None	Function that takes payload_status_event_t, str, and List[float] as parameters