TitanLegs Microcontroller (ESP32) 3 Phased Gate MOSFET Switches DRV8305 - Gate Driver Decoupling caps, keep close to power pins 3.3V Input Power F Z DS ×⁴ SENSOR_VP ×⁵ SENSOR_VN D2 LED GND RX U4 U6 U8 DRV_SPI_MISO

DRV_SPI_MOSI DRV_VREG: Internal amplifier reference voltage and SDO pull DRV_SPI_CLK High Side MOSFET Drain GND DRV_EN_GATE ENC_DIR R1 10k 21 SDO/SDO 22 SDI/SD1 17 SHD/SD2 23 SWP/SD3 20 SCK/CLK 29 SCS/CMD DRV_HA Connect with->
3.3V or 5V, 50-mA LDO:
connect 1-µF to GND
Reference voltage;
LDO disabled DRV_HA L_(GHB) GLA GHB 5 INLB INHC DRV_HB DRV_LB> 1uF 6.3V DRV_HC 8 NFAULI 9 NSCS DRV_SPI_mSCS >
DRV_SPI_MOSI > - $\begin{vmatrix} \delta_{SW1} \\ \rho_{B00T} \end{vmatrix}$ SW2 RESET DRV SPI nSCS SO1, SO2 and SO3 are current amplifier output pins SP1, SP2 and SP3 are positive current sense input pins for amplifers 1,2 and 3 respectively U5 U7 U9 PWRG GND AVDD SO1 SO3 SN3 SN3 SN2 SN2 SN2 SN2 SN2 GND D3 D3 D? **Confirm Usage of 10 5, 12, and 15 J1 Conn_01x04_Female 3V3_ISOLATED is used to power ESP32 when board isn't being powered by VIN. (while programming) 3V3_ISOLATED> Temperature Sensor (DS18S20Z+) Magnetic Encoder (AS5600) Connect VDD to GND for Parasite Power Mode: Deriving Power from DQ Data line U? DS18S20Z+ U2 A55600-ASOT 3V3_IN ENC_DIR => GND, then Clockwise TEMP_DQ> ENC_SDA DQ - 1 Wire Line Communication Interface Power Supply (VIN to 3.3v) Keep Inductor away from Feedback Route Input Voltage-8V to 40V POWER_IN 50V 0.01uF 1 47uH C3 Output Voltage-3.3V 1A C6 100uF 100V 3V3_REGULATED 68uF 10V SS - Soft Start Connect Capacitor for soft start Pull ON/OFF High To enable Switching NC - Internal Default Pull Up Society of Robotics and Automation, VJTI Sheet: / File: bldc_pcb_design.sch

Title: Titan Legs PCB Design
Size: A3 Date:
KiCad E.D.A. kicad 5.1.5+dfsg1-2build2