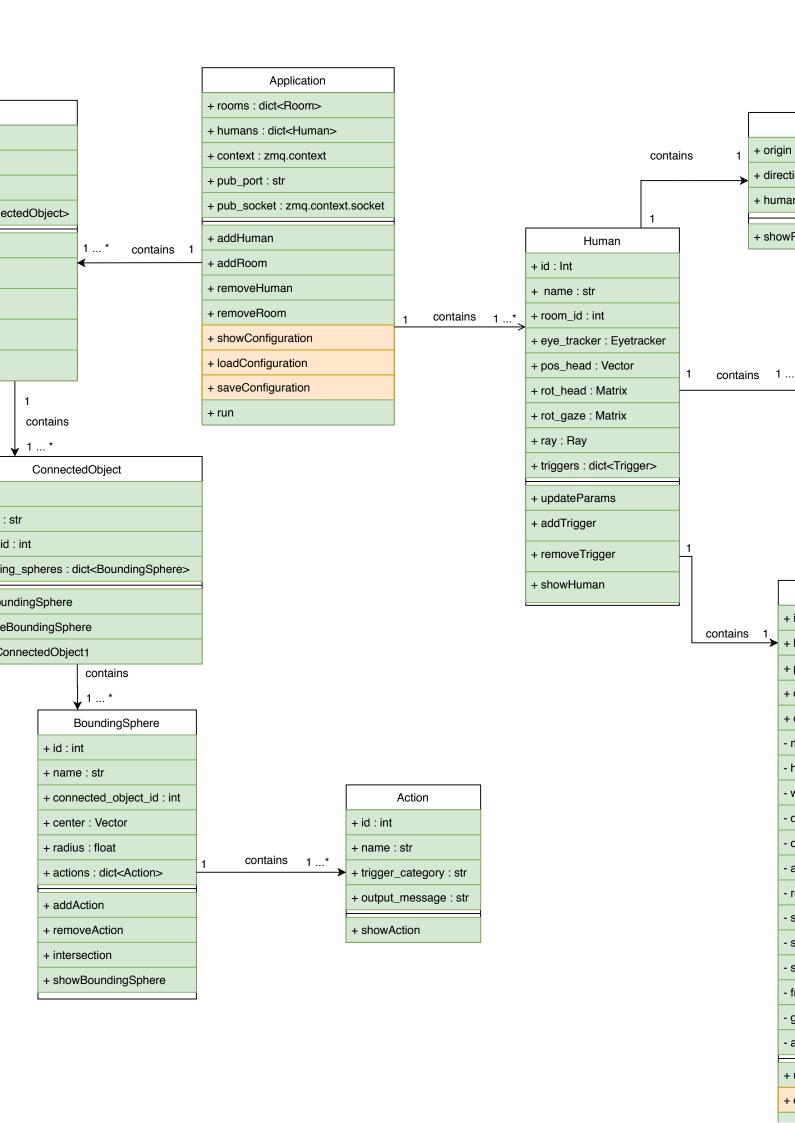
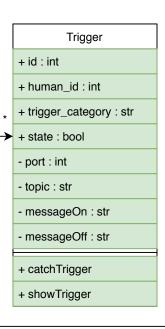
	Room					
	+ id : Int					
	+ name : str					
	+ tags : dict <tag></tag>					
	+ connected_objects : dict <conr< td=""></conr<>					
	+ addTag					
	+ addConnectedObject					
	+ removeTag					
	+ removeConnectedObject					
	+ showRoom					
1						
	cor	ntains				
_	↓ 1	. * I				
L	Tag					
	+ family : str		+ id : int			
	+ family_id : int		+ name			
	+ id : int		+ room_			
	+ name : str		+ bound			
	+ room_id : int		+ addBo			
_	+ size : float		+ remov			
_	+ pos : Vector		+ show(
	+ rot : Matrix					
	+ showTag					



Ray
: Vector
on : Vector
n_id : int





EyeTracker

d:int

numan_id:int

port:int

detected_tags:dict<DetectedTag>
detected_norm_pos:[float,float]

ntx:Matrix

n:int

v:int

dist:np.array

context:zmq.context

addr:string

eq:zmq.context.socket

Matrix + showMatrix

addr: string
eq: zmq.context.socket
sub_port: string
sub_frame: zmq.context.socket
sub_gaze: zmq.context.socket
rames_reader: Thread
st_detector: detector

DetectedTag
+ family : str
+ family_id : int
+ id : int
+ translation : Vector
+ rotation : Matrix
+ showDetectedTag

checkConnection

updateFrame

+ 6

+:

always_recv_trame
always_recv_gaze
showEyeTracker