## 1b.iii: Detailed Bullet Points (Technical, Rephrased)

* **Policy π Structure:** w1​,w2​ execute t1​/t3​ tasks sequentially. r1​,r2​ execute t2​ tasks concurrently across partitioned spatial regions.
* **Pareto Optimization P:** The non-dominated set in the performance space, defining the optimal boundary for E[C] versus P(π).
* **Optimal Policy πopt​ for P(π)≥0.91 (Solution 15):**
  + **Reliability P(π):** 0.916
  + **Cost E[C]:** 37.10
  + **Fault Tolerance Nmax​(ti​):** t2​ tasks are prioritized: t2​l5 (Nmax​=9), t2​l9 (Nmax​=8), and t2​l8b (Nmax​=5).