## 2b.ii: Concise Paragraph (Technical, Rephrased)

The policy π mandates sequential, path-optimized execution of t1​/t3​ tasks by w1​ and w2​, while r1​ and r2​ execute a concurrent, spatially partitioned decomposition of the t2​ task set. The solution was selected from the **Pareto Front P**, the non-dominated set representing the optimal boundary for P(π) versus E[C]. Enforcing the constraint P(π)≥0.91 yields **Solution ID 15**, which achieves P(π)=0.916 at E[C]=37.10. This reliability is maintained by prioritizing the local fault tolerance Nmax​(ti​), specifically assigning high retry budgets (up to Nmax​=9) to the most critical and failure-prone t2​ instances.