### 2aiii. Domain Expert Response (Short, Technical, Formal, Precise, Bullet Points)

The automated planning results for the agricultural mission are summarized below:

* **Plan Allocation:** Agent worker2 (Human Worker) is tasked with all **Harvesting (t1)** and **Grapevine Identification (t3)** instances, following the path l1 -> l4 -> l7 -> l9 -> l6. Agent r1 (Robot) is assigned all **Observation (t2)** tasks at l5 and l8, following the path l1 -> l2 -> l5 -> l8.
* **Pareto Front Interpretation:** The Pareto front represents the set of non-dominated solutions optimizing the multi-objective problem of maximizing mission-level **Success Probability** against minimizing **Total Cost**.
* **Optimal Solution (ID 1) Metrics:** The highest reliability solution offers a **1.0 Probability of Success** at a **Cost of $38.177**.
* **Retry Strategy:** Task-specific retries are assigned proportional to risk: robot Observation tasks (t2l8b) are prioritized with up to **9 maximum retries**, whereas high-reliability human Harvesting tasks (t1l6b) are allocated **1 retry** for a minimal safety margin.