### 2bii. Domain Expert Response (Short, Casual, Conversational, Simple, Single Coherent Paragraph)

The plan efficiently splits the work: our human worker, **Worker 2**, handles all the **Harvesting (t1)** and **Grapevine Identification (t3)** along the main path of **l4**, **l7**, **l9**, and **l6**, while the robot, **r1**, manages all **Observation (t2)** tasks at **l5** and **l8**. The calculated "Pareto front" is simply the range of best possible plans, showing the perfect balance between mission reliability (**Success Probability**) and total budget spent (**Cost**). Our recommended solution (ID 1) maximizes success, offering a full **100% Mission Success Probability** for a total estimated **Cost of $38.177**. This high success rate is secured by strategically allowing retries for each task; for instance, the riskier robot tasks, like Observation at t2l8b, are given up to **9 retries**, whereas the highly reliable human Harvesting task at t1l6b is only assigned **1 retry** as a minimal safety precaution.