ICPC Reference Notebook

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1 Template

1.1 Fast IO

```
ios::sync_with_stdio(false);
cin.tie(0); cout.tie(0);
```

1.2 Typedefs

```
typedef long long ll;
typedef pair<int, int> pii;
const int INF = 1e9;
```

2 Math

2.1 GCD / LCM

```
int gcd(int a, int b) {
    return b ? gcd(b, a % b) : a;
}
int lcm(int a, int b) {
    return a / gcd(a, b) * b;
}
```

2.2 Modular Exponentiation

```
11 modpow(11 a, 11 b, 11 m) {
    11 res = 1;
    while (b) {
        if (b & 1) res = res * a % m;
        a = a * a % m;
        b >>= 1;
    }
    return res;
}
```

3 Graphs

3.1 Dijkstra's Algorithm

```
vector<pii> adj[N];
int dist[N];
void dijkstra(int src) {
    priority_queue<pii, vector<pii>, greater<pii>> pq;
    fill(dist. dist + N. INF):
    dist[src] = 0:
    pq.push({0, src});
    while (!pq.empty()) {
        int d, u;
        tie(d, u) = pq.top(); pq.pop();
        if (d > dist[u]) continue;
        for (auto [v, w] : adj[u]) {
           if (dist[v] > dist[u] + w) {
                dist[v] = dist[u] + w;
                pq.push({dist[v], v});
   }
vector<pii> adj[N];
int dist[N];
void dijkstra(int src) {
    priority_queue<pii, vector<pii>, greater<pii>> pq;
    fill(dist, dist + N, INF);
    dist[src] = 0;
   pq.push({0, src});
    while (!pq.empty()) {
        int d, u;
        tie(d, u) = pq.top(); pq.pop();
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                pq.push({dist[v], v});
   }
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}vector<pii> adj[N];
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void dijkstra(int src) {
   priority_queue<pii, vector<pii>, greater<pii>> pq;
   fill(dist, dist + N, INF);
   dist[src] = 0;
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    while (!pq.empty()) {
       int d. u:
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            if (dist[v] > dist[u] + w) {
                dist[v] = dist[u] + w;
                pq.push({dist[v], v});
       }
   }
```