# K- Nearest Neighbors (K-NN)

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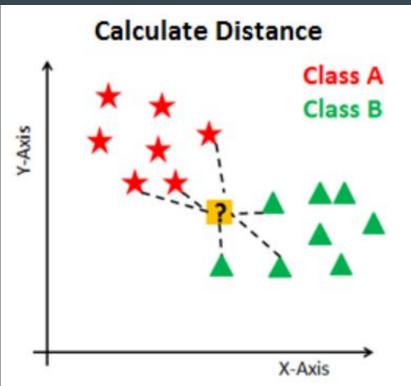
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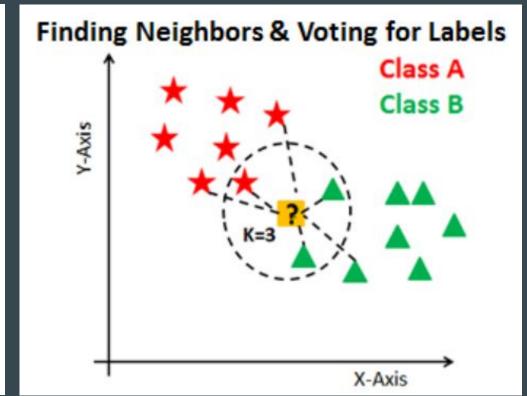
#### How Does The Algorithm Work?

- Makes the assumption that similar things exist in close proximity
- Uses **feature similarity** to predict the values of new data points
- Non-parametric: it means that it does not make any assumption of the data distribution.
- KNN can be used for regression and classification. However, it is mainly used for classification.

Step 1

Step 2





#### Advantages/Disadvantages of The Algorithm:

#### <u>Advantages</u>

- Simple and Effective
- Robust to data that contains a lot of noise (where decision boundary is irregular)
- Can perform both classification and regression
- As n → ∞, k-NN becomes increasingly accurate
- Unbiased in nature: makes no prior assumption of the underlying data

#### **Disadvantages**

- Curse of dimensionality, doesn't work well when there are many variables
- Costly computation
- Cannot Handle Missing Value without
  Imputation
- As  $n \rightarrow \infty$ , k-NN becomes increasingly slow
- As dimensionality increases, points tend to never be close together breaking down the assumptions of k-NN.

#### Data Processing Steps of The Algorithm:

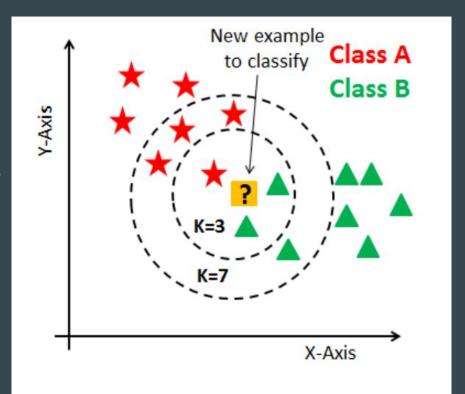
- To deal with the problem of the curse of dimensionality, must perform principal component analysis or use feature selection
- Scaling/Normalizing Variables (very important since this is distance based algorithm. Otherwise we will bias towards variables with larger values).

What Hyperparameters Can Be Tuned? What Does Each One

Represent?

#### n\_neighbors = int

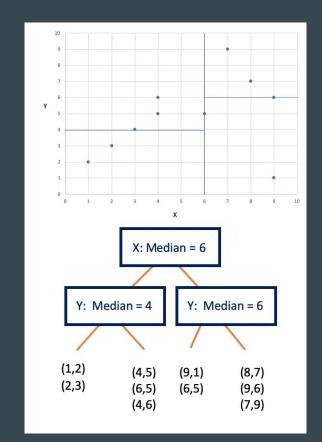
- This parameter sets how large k is.
- Determines how many neighbors are included in the vote
- "k" value is easier to measure when it is an positive odd integer.

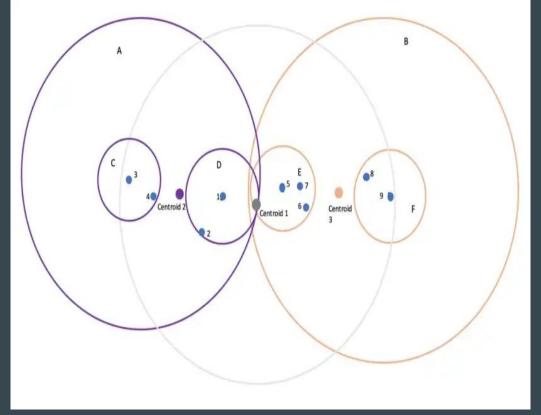


## algorithm = {auto, kd\_tree, ball\_tree, brute}

- Auto: attempts to find the 'best' algorithm based on the values passed in
- Kd\_tree: a binary search tree where data in each node represents a K-dimensional point in space.
- Ball\_tree: each ball represents a cluster around a centroid containing all data. The data is further clustered into increasingly distant clusters from the centroid.
- Brute: calculate the distance from the new point to every point in the training data, then take the specified K nearest hyperparameter and perform a vote.

# **KD** and Ball Tree Diagrams





#### weights = uniform, distance

- 'uniform': uniform weights. All distances of 'nearest neighbors' are weighted equally.
- 'distance': weight points by the inverse of their distance. In this case, closer neighbors of a test point will have a greater influence than neighbors which are further away.

Minkowski Distance 
$$D(X,Y) = \left(\sum_{i=1}^{n} |x_i - y_i|^p\right)^{\frac{1}{p}}$$
.

 $P = 1 \rightarrow Manhattan Distance$ 

 $P = 2 \rightarrow Euclidean Distance$ 

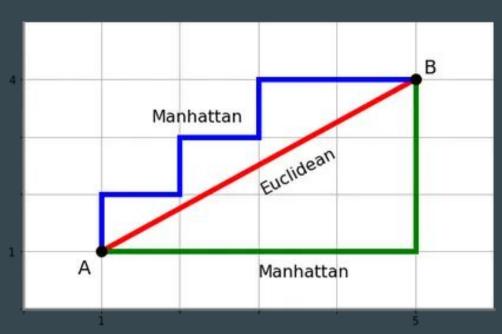
 $P = \infty \rightarrow Chebyshev Distance (Maximum Distance)$ 

Manhattan distance is usually preferred over the more common Euclidean distance when there is high dimensionality in the data.

## $p = 1 \longrightarrow Manhattan Distance$

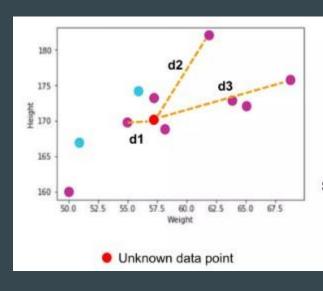
$$dist(d) = |x - a| + |y - b|$$

Manhattan Distance is longer than Euclidean, and can have more than one path



#### p = 2 → Euclidean Distance

$$dist(d) = \sqrt{(x - a)^2 + (y - b)^2}$$



$$dist(d1) = \sqrt{(170-167)^2 + (57-51)^2} = 6.7$$

Similarly, we will calculate Euclidean distance of unknown data point from all the points in the dataset

#### **Work Cited**

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