

# System view

Project Kitchen Occupation

TSBB11 HT 2013

Version 0.1



Status

Reviewed	–	2013-09-24
Approved		

**2013-09-24**

# Project Kitchen Occupation

Bilder och Grafik CDIO, HT 2013  
Department of Electrical Engineering (ISY), Linköping University

## Participants

Name	Responsibilities	Phone	E-mail
Mattias Tiger	Project manager	073-695 71 53	matti166@student.liu.se
Erik Fall	–	076-186 98 84	erifa226@student.liu.se
Gustav Häger	System integration	070-649 03 97	gusha124@student.liu.se
Malin Rudin	–	–	malru103@student.liu.se
Alexander Sjöholm	–	076-225 11 74	alesj050@student.liu.se
Martin Svensson	Documentation	070-289 01 49	marsv106@student.liu.se
Nikolaus West	Testing	073-698 92 60	nikwe491@student.liu.se

**Homepage:** nohomepage.asdf.asdf

**Customer:** Joakim Nejdeby, Linköping University, Origo 3154

**Customer contact:** 013-28 17 57, joakim.nejdeby@liu.se

**Project supervisor:** Fahad Khan, Linköping University, fahad.khan@liu.se

**Examiner:** Michael Felsberg, michael.felsberg@liu.se

## Contents

<b>1</b>	<b>Introduction</b>	<b>1</b>
1.1	About this document . . . . .	1
<b>2</b>	<b>Project Overview</b>	<b>2</b>
2.1	Main program . . . . .	2
<b>3</b>	<b>Hardware</b>	<b>3</b>
3.1	Camera type . . . . .	3
3.2	Camera placement . . . . .	3
3.3	Platform . . . . .	3
<b>4</b>	<b>Network module</b>	<b>4</b>
4.1	Camera API . . . . .	4
4.2	Network communication . . . . .	4
<b>5</b>	<b>Image processing</b>	<b>5</b>
5.1	Software . . . . .	5
5.2	Tracking . . . . .	5
5.3	Counting people . . . . .	5
<b>6</b>	<b>Estimation of waiting time</b>	<b>6</b>
6.1	Queue detection . . . . .	6
6.2	Mathematical models . . . . .	6
6.3	Machine learning (?) . . . . .	6
<b>7</b>	<b>User interface</b>	<b>7</b>
7.1	Presentation of results . . . . .	7
7.2	Webpage . . . . .	7
<b>8</b>	<b>Installation program</b>	<b>8</b>
8.1	Milestones . . . . .	8
8.2	Deliveries . . . . .	8
	<b>References</b>	<b>9</b>

## List of Figures

2.1	This text ends up at the table of figures . . . . .	2
-----	---	---

## Document history

Version	Date	Changes	Sign	Reviewed
0.1	2013-09-10	Initial draft	MS	
1.0	2013-05-24	Final Document	All	

# 1 Introduction

Text here.

## 1.1 About this document

Text here.

## 2 Project Overview

Text here.

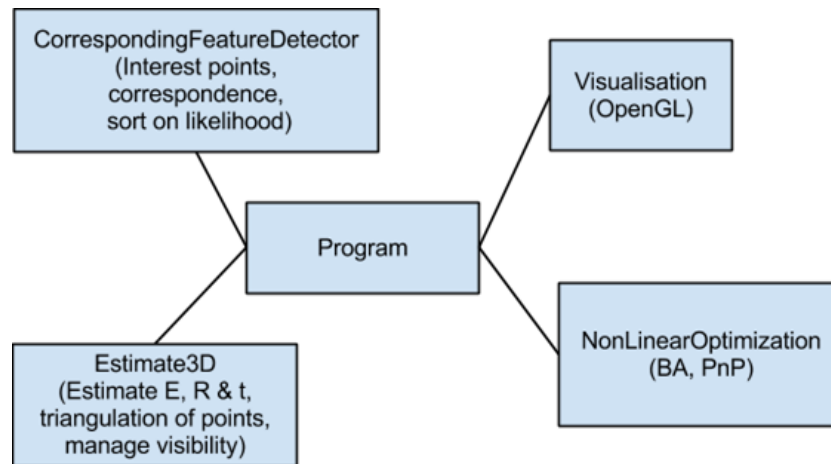


Figure 2.1: *Image of entire system and its modules (THIS IS AN EXAMPLE IMAGE)*

### 2.1 Main program

Text here.

## **3 Hardware**

Text here.

### **3.1 Camera type**

Text here

### **3.2 Camera placement**

Text here

### **3.3 Platform**

Text here

## **4 Network module**

Text.

### **4.1 Camera API**

Text here

### **4.2 Network communication**

Text here



## 5 Image processing

Text here.

### 5.1 Software

Text here

### 5.2 Tracking

Text here

### 5.3 Counting people

Text here.

## **6 Estimation of waiting time**

Text about this part of the system

### **6.1 Queue detection**

Text here

### **6.2 Mathematical models**

Text here

### **6.3 Machine learning (?)**

Text here

## **7 User interface**

Text about the UI and result presentation.

### **7.1 Presentation of results**

Text here

### **7.2 Webpage**

Text here

## **8 Installation program**

Text about the different deliveries and deadlines

### **8.1 Milestones**

Text here

### **8.2 Deliveries**

Text here

## References

- [1] Sonka, M., Hlavac, V. & Boyle, R.  
*Image Processing, Analysis, and Machine Vision*.  
Toronto: Thompson Learning,  
cop. 2008, 3rd ed.,  
ISBN 0495244384.
- [2] Lourakis, M.I.A.  
*levmar: Levenberg-Marquardt nonlinear least squares algorithms in C/C++*  
<http://www.ics.forth.gr/~lourakis/levmar/>,  
Jul. 2004  
Accessed on May 14th 2005.
- [3] Manolis I.A. Lourakis  
“Sparse Non-linear Least Squares Optimization for Geometric Vision,”  
*European Conference on Computer Vision*,  
vol. 2, 2010, pages 43-56  
DOI [http://dx.doi.org/10.1007/978-3-642-15552-9\\_4](http://dx.doi.org/10.1007/978-3-642-15552-9_4)
- [4] Hartley, R & Zisserman, A  
*Multiple View Geometry in Computer Vision*.  
Cambridge University Press, West Nyack, NY, USA  
March 2003, 2nd ed.  
ISBN 978-05-11-18711-7
- [5] Nordberg, K  
*Introduction to Homogeneous Representations and Estimation in Geometry*  
Apr. 2013  
Computer Vision Laboratory, Department of Electrical Engineering  
Linköping University