

f)

$$* \dot{r} = \frac{p_r}{m}$$

$$\left. \dot{r} = \frac{p_r}{m} \right\} \dot{\tilde{r}} = \tilde{p}_r$$

$$* \dot{\phi} = \frac{p_\phi}{m r^2}$$

$$\tilde{r} d = r$$

$$p_\phi = \tilde{p}_\phi m d^2$$

$$\left. \dot{\phi} = \frac{\tilde{p}_\phi \times m d^2}{m \tilde{r}^2 d^2} \right\} \frac{\tilde{p}_\phi}{\tilde{r}^2}$$

$$* \ddot{\tilde{r}} = \frac{\tilde{p}_\phi^2 d^3}{r^3} - G \frac{M_t}{\tilde{r}^2 d^3} - G \frac{\left(\frac{m \cdot M_t}{d^2 M_t} \right)}{\left(\frac{\sqrt{r^2 + d^2 - 2rd \cos(\phi - \omega t)}{d} \right)^3} (\tilde{r} - \cos(\phi - \omega t))$$

$$= \frac{\tilde{p}_\phi^2 d^3}{r^3} - G \frac{M_t}{d^3} \left(\frac{1}{\tilde{r}^2} - \frac{M(\tilde{r} - \cos(\phi - \omega t))}{\sqrt{(r^2 + 1 - 2\tilde{r} \cos(\phi - \omega t))^3} M_t} \right)$$

$$\ddot{\tilde{r}} = \frac{\tilde{p}_\phi^2 d^3}{\tilde{r}^3} - \Delta \left(\frac{1}{\tilde{r}^2} - \frac{M(\tilde{r} - \cos(\phi - \omega t))}{\tilde{r}, 3} \right)$$

*

$$\frac{\dot{p}_\phi}{m d^2} = - G \frac{m M_t}{r^3} r d \sin(\phi - \omega t)$$

$$\dot{\tilde{p}}_\phi = - G \frac{(m M_t / m_t)}{r^3 d^2} \tilde{r} \sin(\phi - \omega t)$$

$$\dot{\tilde{p}}_\phi = - G \frac{(m M_t / m_t d^3)}{\sqrt{(r^2 + 1 - 2\tilde{r} \cos(\phi - \omega t))^3}} \tilde{r} \sin(\phi - \omega t)$$

$$\dot{\tilde{p}}_\phi = - \Delta \frac{M}{\tilde{r}^3} \tilde{r} \sin(\phi - \omega t)$$