

08/02/2024

Autonomous System Responsible Form

University: University of Leeds (UoL) Car/Team No: 77

Contact E-Mail: abdolahmed710@gmail.com

Autonomous System Responsible Information

Name: Abdullah Omar Omran Ahmed


Leeds Gryphons Formula Team - Formula Student AI (Second Year Mechatronics and Robotics Engineering)

- Installed Lidar and Depth camera for testing on different sized vehicles
- Collaborated in research to select electronic and mechanical vehicle components meeting specifications and budget.
- Implemented ROS and Ubuntu, on Raspberry Pi 2 and 4, for advanced system integration,

Faculty Advisor Name: Krzysztof Kubiak

Signature: 

Team Leader Name: Kwan Ho Kenneth Liu

Signature: 

Instructions: 1. Add Team name, Car number, Contact e-mail address, ASR name; 2. Delete text highlighted in yellow and replace with your text - expand the text boxes if necessary; 3. Team leader and faculty advisor to sign the form; 4. Submit by due date as documented in 'Key Dates'

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Autonomous System Responsible Form

University: _____ University of Leeds _____ Car/Team No: 77 _____

Contact E-Mail: _____ mn232jh@leeds.com _____

Autonomous System Responsible Information


Name: _____ JIAWEI HE _____

I have previously represented Brunel University in FSAI 23, competing in DDT Static category. I have achieved an undergraduate degree, BEng Automotive Engineering, from Brunel University.

Faculty Advisor Name: Krzysztof Kubiak

Signature: 

Team Leader Name: Kwan Ho Kenneth Liu

Signature: 

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University: University of Leeds Car/Team No: 77

Contact E-Mail: el20khkl@leeds.ac.uk

Autonomous System Responsible Information

Name: Kwan Ho Kenneth Liu

I am a fourth-year MEng Electronic and Electrical Engineering student at the University of Leeds. My experience includes developing an autonomous photogrammetry robotics system aimed at heritage preservation. This project was undertaken as part of a small team and was funded by the Hong Kong Government.

Faculty Advisor Name: Krzysztof Kubiak

Signature: 

Team Leader Name: Kwan Ho Kenneth Liu

Signature: 

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FORMULA STUDENT

Institution of
**MECHANICAL
ENGINEERS**

08/02/2024

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University: University of Leeds

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Contact E-Mail: mn23by@leeds.ac.uk

Autonomous System Responsible Information


Name: __Bingzhang Yue_____

I completed my undergraduate degree at North China university of Science and Technology.

Faculty Advisor Name: Krzysztof Kubiak

Signature: 

Team Leader Name: Kwan Ho Kenneth Liu

Signature: 

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Autonomous System Responsible Form

University: _____ University of Leeds _____ Car/Team No: _____ 77 _____

Contact E-Mail: _____ el20db@leeds.ac.uk _____

Autonomous System Responsible Information

Name: _____ Daniel Bara _____

I am an Undergraduate Mechatronics student (year 3). I completed a placement year between years 2 and 3.


I have participated in the Formula Student team before in 2020-2021.

I have both competed in and judged First Lego League tournaments between 2016 and 2019.

Faculty Advisor Name: Krzysztof Kubiak

Signature: 

Team Leader Name: Kwan Ho Kenneth Liu

Signature: 

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Contact E-Mail: mn20m2r@leeds.ac.uk

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Name: Mohammed Rayyan

I am a final year MEng mechanical Engineering student. I have had experience in building and manufacturing buggies. In year 2 I handled the buggy's power supply wire throughout the race which our team achieved 3rd place out of 17 teams. During the race/demonstration I will take responsibility to oversee the car during its operation.

Faculty Advisor Name: Krzysztof Kubiak

Signature: 

Team Leader Name: Kwan Ho Kenneth Liu

Signature: 

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