

Speed of the Robot

The *robot's speed* [temporal average] \pm [temporal standard deviation] in m/s as observed in each [experiment](#) with both [methods](#) is shown below.

	“Narrow passage”	“Row of pedestrians”	“Unidirectional crowd”
RDS	0.59 \pm 0.18	0.72 \pm 0.17	0.70 \pm 0.17
Baseline	0.12 \pm 0.16	0.55 \pm 0.27	0.55 \pm 0.26