

## Speed of the Robot

The robot’s speed [temporal average] $\pm$ [temporal standard deviation] as observed in each **experiment** with both **methods** is shown below.

	“Narrow passage”	“Row of pedestrians”	“Unidirectional crowd”
<b>RDS</b>	<b>0.59</b> $\pm$ 0.18	<b>0.72</b> $\pm$ 0.17	<b>0.70</b> $\pm$ 0.17
<b>Baseline</b>	0.12 $\pm$ 0.16	0.55 $\pm$ 0.27	0.55 $\pm$ 0.26