

Speed of the Robot

The *robot's speed* [temporal average] \pm [temporal standard deviation] in m/s as observed in each experiment with both methods is shown below.

	“Narrow passage”	“Row of pedestrians”	“Unidirectional crowd”
RDS	0.6 \pm 0.2	0.7 \pm 0.2	0.7 \pm 0.2
Baseline	0.1 \pm 0.2	0.6 \pm 0.3	0.6 \pm 0.3